Eigenvalue inequalities for graphs and convex subgraphs

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For an induced subgraph $S$ of a graph, we show that its Neumann eigenvalue $\lambda_S$ can be lower-bounded by using the heat kernel $H_t(x,y)$ of the subgraph. Namely,

$$\lambda_S \geq \frac{1}{2t} \sum_{x \in S} \inf_{y \in S} \frac{H_t(x,y)\sqrt{d_x} \sqrt{d_y}}{d_x}$$

where $d_x$ denotes the degree of the vertex $x$. In particular, we derive lower bounds of eigenvalues for convex subgraphs which consist of lattice points in an $d$-dimensional Riemannian manifolds $M$ with convex boundary. The techniques involve both the (discrete) heat kernels of graphs and improved estimates of the (continuous) heat kernels of Riemannian manifolds. We prove eigenvalue lower bounds for convex subgraphs of the form $c\epsilon^2/(dD(M))^2$ where $\epsilon$ denotes the distance between two closest lattice points, $D(M)$ denotes the diameter of the manifold $M$ and $c$ is a constant (independent of the dimension $d$ and the number of vertices in $S$, but depending on the how "dense" the lattice points are). This eigenvalue bound is useful for bounding the rates of convergence for various random walk problems. Since many enumeration problems can be approximated by considering random walks in convex subgraphs of some appropriate host graph, the eigenvalue inequalities here have many applications.

1. Introduction.

We consider the Laplacian and eigenvalues of graphs and induced subgraphs. Although an induced subgraph can also be viewed as a graph in its own right, it is natural to consider an induced subgraph $S$ as having a boundary (formed by edges joining vertices in $S$ and vertices not in $S$ but in

\textsuperscript{1}Research supported in part by NSF Grant No. DMS 95-04834
the "host" graph). The host graph then can be regarded as a special case of a subgraph with no boundary.

This paper consists of three parts. In the first part (Section 2-5), we give definitions and describe basic properties for the Laplacian of graphs. We introduce the Neumann eigenvalues for induced subgraphs and the heat kernel for graphs and induced subgraphs. Then we establish the following lower bound for the Neumann eigenvalues of induced subgraphs.

**Theorem 1:** For $t > 0$,

\[
\lambda_S \geq \frac{1}{2t} \sum_{x \in S} \inf_{y \in S} \frac{H_t(x,y) \sqrt{d_x}}{\sqrt{d_y}}
\]

where the detailed definitions for the eigenvalue $\lambda_S$, the heat kernel $H_t$ and the degree $d_v$ will be given later.

In the second part (Section 6-9) of the paper, we focus upon convex subgraphs. Roughly speaking, a convex subgraph has vertex set consisting of lattice points in a Riemannian manifold with a convex boundary. Our plan is to use the (continuous) heat kernel of the convex manifold to lower-bound the (discrete) heat kernel of the induced subgraphs. To this end, we will derive an improved estimate for heat kernels of Riemannian manifold with convex boundary. Although this result is heavily motivated by the discrete problems, it is of independent interest as well. As we shall see, the discrete problems often contain additional variables, such as the number of vertices. The (continuous) heat kernel estimates in the literature usually involve constants depending (exponentially) in the dimension of the manifold. The dimension of the manifold are intimated related to the number of vertices. Consequently, such lower bounds are often too weak and too small for applications in discrete problems. In Section 9, we derive estimates with constants independent of the dimension using and strengthening a theorem of Li and Yau [8] for lower bounds of the heat kernel of a convex manifold. Under some mild conditions (e.g. the lattice points are “dense enough”), we can use the results in the continuous case to obtain eigenvalue bounds for convex subgraphs:

\[
\lambda_S \geq \frac{c \epsilon^2}{(d \, D(M))^2}
\]

where $\epsilon$ denotes the distance of two closest lattice points, $d$ is the dimension of the manifold $M$ that $S$ is embedded into, $D(M)$ denotes the diameter of $M$ and $c$ denotes an absolute constant (see Section 9 for details). Usually, the maximum degree $k$ of the convex subgraph is about $d$. The diameter
$D(S)$ of the convex subgraph $S$ is between $D(M)/\epsilon$ and $\sqrt{dD(M)}/\epsilon$. So, we have a lower bound for $\lambda_S$ of the form $c/(kD(S))^2$ for a general graph and of the form $c/kD(S)^2$ for some graphs.

In the third part of the paper (Section 10), we discuss the relationship of Neumann eigenvalues to random walk problems. In particular, we introduce the Neumann random walk in an induced subgraph of a graph. We also generalize all the results to weighted graphs with loops. The eigenvalue lower bound then can be used to derive upper bounds for the rate of convergence for these random walks.

In the last section, we briefly discuss the applications of random walk problems to efficient approximation algorithms. In particular, we discuss the classical problems of approximating the volume of a convex body and also the problem of sampling matrices with non-negative integral entries having given row and column sums. We will use our eigenvalue inequalities to derive polynomial time upper bounds for the sampling problem which can then be used to derive efficient approximation algorithms for the enumeration problem. Since many sampling and enumeration problems often involve families of combinatorial objects which can be regarded as vertices of convex subgraphs of some appropriate host graphs, the eigenvalue bounds and the methods we describe here can be useful for many problems of this type. There are many recent developments [7, 10, 11] in approximating difficult counting problems by using the methods of random walks. The heat kernels and eigenvalue bounds in this paper offers a direct approach for bounding the eigenvalues. A number of applications in this direction will be discussed in [4].

We remark that in this paper we mainly consider Neumann eigenvalues because of the relationship with random walks. Results on Dirichlet eigenvalues will be described in a separate paper with different applications.

2. Preliminaries.

We consider a graph $G = (V, E)$ with vertex set $V = V(G)$ and edge set $E = E(G)$. Let $d_v$ denote the degree of $v$. Here we assume that $G$ contains no isolated vertices, no loops or multiple edges (the generalizations to weighted graphs with loops will be discussed in Section 10). We define the matrix $L$ with rows and columns indexed by vertices of $G$ as follows.

\[
L(u, v) = \begin{cases}
  d_v & \text{if } u = v, \\
  -1 & \text{if } u \text{ and } v \text{ are adjacent,} \\
  0 & \text{otherwise.}
\end{cases}
\]
Let $T$ denote the diagonal matrix with the $(v,v)$-entry having value $d_v$. The Laplacian $\mathcal{L}$ of $G$ is defined to be

$$\mathcal{L} = T^{-1/2}LT^{-1/2}.$$ 

In other words, we have

$$\mathcal{L}(u,v) = \begin{cases} 
1 & \text{if } u = v, \\
-\frac{1}{\sqrt{d_u d_v}} & \text{if } u \text{ and } v \text{ are adjacent}, \\
0 & \text{otherwise}.
\end{cases}$$

The eigenvalues of $\mathcal{L}$ are denoted by $0 = \lambda_0 \leq \lambda_1 \leq \cdots \leq \lambda_{n-1}$. When $G$ is $k$-regular (i.e., $d_v = k$ for all $v$), it is easy to see that

$$\mathcal{L} = I - \frac{1}{k}A$$

where $A$ is the adjacency matrix of $G$.

Let $g$ denote a function which assigns to each vertex $v$ of $G$ some complex value $g(v)$. Then

$$\frac{\langle g, \mathcal{L}g \rangle}{\langle g, g \rangle} = \frac{\langle g, T^{-1/2}LT^{-1/2}g \rangle}{\langle g, g \rangle} = \frac{\langle f, Lf \rangle}{\langle T^{1/2}f, T^{1/2}f \rangle} = \sum_{u \neq v} (f(u) - f(v))^2 \sum_v d_v f(v)^2$$

where $f$ satisfies $g = T^{1/2}f$ and the inner product is just $\langle f_1, f_2 \rangle = \sum_x f_1(x)f_2(x)$.

Let $1$ denote the constant function which assumes the value 1 on each vertex. Then $T^{1/2}1$ is an eigenfunction of $\mathcal{L}$ with eigenvalue 0. Also,

$$\lambda := \lambda_1 = \inf_{f \perp 1} \frac{\sum_{u \neq v} (f(u) - f(v))^2}{\sum_v d_v f(v)^2} = \sup_f \inf_c \frac{\sum_{u \neq v} (f(u) - f(v))^2}{\sum_v d_v (f(v) - c)^2}.$$
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Various facts about the $\lambda_i$ can be found in [5]. In particular, an eigenfunction $g$ having the eigenvalue $\lambda$ satisfies, for all $v \in V(G)$,

$$Lg(v) = \frac{1}{\sqrt{d_v}} \sum_{u \sim v} \left( \frac{g(v)}{\sqrt{d_v}} - \frac{g(u)}{\sqrt{d_u}} \right) = \lambda g(v)$$

3. The Neumann eigenvalues of a subgraph of a graph.

Let $S$ denote a subset of the vertex set $V(G)$ of $G$. The induced subgraph on $S$ has vertex set $S$ and edges $\{u, v\}$ of $E(G)$ with $u, v \in S$. We will often denote the induced subgraph on $S$ also by $S$. There are two types of boundaries of $S$. The edge boundary, denoted by $\partial S$, consists of edges with one endpoint in $S$ and the other endpoint not in $S$. The (vertex) boundary of $S$, denoted by $\delta S$, is defined by $\delta S = \{v \in V(G) : v \notin S$ and $\{u, v\} \in E(G)$ for some $u \in V(G)\}$. Let $S'$ denote the union of edges in $S$ and edges in $\partial S$. For a vertex $x$ in $\delta S$, we let $d'_x$ denote the number of neighbors of $x$ in $S$. We define the Neumann eigenvalue of an induced subgraph $S$ as follows:

$$\lambda_S = \inf_{\Sigma_{x \in S} f(x)d_x = 0} \frac{\sum_{x \in S} (f(x) - f(y))^2}{\sum_{x \in S} f^2(x)d_x}$$

$$= \inf_{f} \sup_{c} \frac{\sum_{x \in S} (f(x) - c)^2d_x}{\sum_{x \in S} (f(x) - c)^2d_x}$$

In general, we define the $i$-th Neumann eigenvalue $\lambda_{S,i}$ to be

$$\lambda_{S,i} = \inf_{f} \sup_{f' \in G_{i-1}} \frac{\sum_{x \in S} (f(x) - f'(x))^2}{\sum_{x \in S} (f(x) - f'(x))^2d_x}$$
where $C_k$ is the subspace spanned by functions $\phi_j$ achieving $\lambda_{S,j}$, for $0 \leq j \leq k$. Clearly, $\lambda_{S,0} = 0$. We use the notation that $\lambda_{S,1} = \lambda_S$.

From the discrete point of view, it is often useful to express the $\lambda_{S,i}$ as eigenvalues of a matrix $L_S$. To achieve this, we first derive the following facts:

**Lemma 1.** Let $f$ denote a function $f : S \cup \delta S \to \mathbb{R}$ satisfying (4) with eigenvalue $\lambda$. Then $f$ satisfies:

(a) for $x \in S$,
\[
Lf(x) = \sum_{y \in S'} (f(x) - f(y)) = \lambda f(x) d_x,
\]

(b) for $x \in \delta S$,
\[
Lf(x) = 0
\]

This is the so-called Neumann condition that $x \in \delta S$ satisfies
\[
\sum_{y \in \delta S} (f(x) - f(y)) = 0
\]

or, equivalently,
\[
f(x) = \frac{1}{d_x} \sum_{y \in \delta S} f(y)
\]

(c) for any function $h : S \cup \delta S \to \mathbb{R}$, we have
\[
\sum_{x \in S} h(x) Lf(x) = \sum_{\{x,y\} \in S'} (h(x) - h(y)) \cdot (f(x) - f(y))
\]

We remark that the proofs of (a) and (b) follow by variational principles (cf. [5]) and (c) is a consequence of (b).

Using Lemma 1 and equation (4), we can rewrite (4) as follows by considering the operator acting on the space of functions $\{f : S \to \mathbb{R}\}$, or the
space of functions \( \{f : S \cup \delta S \to \mathbb{R} \text{ and } f \text{ satisfies the Neumann condition} \} \).

\[
\lambda_S = \inf_f \frac{\sum_{x \in S} f(x)Lf(x)}{\sum_{x \in S} f(x)d_x} = \inf_{g \perp T^{1/2}} \frac{\sum_{x \in S} g(x)Lg(x)}{\sum_{x \in S} g(x)^2} = \inf_{g \perp T^{1/2}} \frac{\langle g, Lg \rangle_S}{\langle g, g \rangle_S}
\]

where \( L \) is the Laplacian for the host graph \( G \) and \( \langle f_1, f_2 \rangle_S = \sum_{x \in S} f_1(x)f_2(x) \).

For \( X \subseteq V \), we let \( L_X \) denote the submatrix of \( L \) restricted to columns and rows indexed by vertices in \( X \). We define the following matrix \( N \) with rows indexed by vertices in \( S \cup \delta S \) and columns indexed by vertices in \( S \).

\[
N(x, y) = \begin{cases} 
1 & \text{if } x = y, \\
0 & \text{if } x \in S \text{ and } x \neq y, \\
\frac{1}{d_x^*} & \text{if } x \in \delta S, y \in S \text{ and } x \sim y, \\
0 & \text{otherwise.}
\end{cases}
\]

Further, we define an \(|S| \times |S|\) matrix

\[
L_S = T^{-1/2} N^* L_{S \cup \delta S} N T^{-1/2}
\]

where \( N^* \) denotes the transpose of \( N \).

It is easy to see from equation (5) that the \( \lambda_{S,i} \) are exactly the eigenvalues of \( L_S \).

4. The heat kernel of a subgraph.

Suppose for a graph \( G \) and an induced subgraph \( S \) of \( n \) vertices of \( G \), we write the Laplacian of \( S \) in the form:

\[
L = L_S = \sum_{i=0}^{n-1} \lambda_i P_i
\]
where \( P_i \) is the projection of \( \mathcal{L} \) to the \( i \)-th Neumann eigenfunction \( \varphi_i \) of the induced subgraph \( S \). The heat kernel \( H_t \) of \( S \), for \( t \geq 0 \), is defined to be the following \( n \times n \) matrix:

\[
H_t = \sum_i e^{-\lambda_i t} P_i = e^{-t\mathcal{L}} = I - t\mathcal{L} + \frac{t^2}{2} \mathcal{L}^2 - \ldots
\]

In particular, \( H_0 = I \). In the special case that \( S \) is taken to be the vertex set of \( G \), \( H_t \) is the heat kernel of the host graph \( G \).

For a function \( f : S \cup \delta S \to \mathbb{R} \), we consider

\[
F(t, x) = \sum_{y \in S \cup \delta S} H_t(x, y) f(y)
\]

(7) \( = (H_t f)(x) \).

Here are some useful facts about \( F \) and \( H_t \).

**Lemma 2.**

(i) \( F(0, x) = f(x) \)

(ii) For \( x \in S \cup \delta S \),

\[
\sum_{y \in S \cup \delta S} H_t(x, y) \sqrt{d_y} = \sqrt{d_x}
\]

(iii) \( F \) satisfies the heat equation

\[
\frac{\partial F}{\partial t} = -\mathcal{L}F
\]

(iv) For any vertex \( x \) in \( \delta S \),

\[
\mathcal{L}F(t, x) = \sum_y \left( \frac{F(t, x)}{\sqrt{d_x}} - \frac{F(t, y)}{\sqrt{d_y}} \right) = 0
\]
(v) For any function $G : \mathbb{R} \times V \rightarrow \mathbb{R}$, we have

$$\sum_{x,y \in S'} \left( \frac{G(t, x)}{\sqrt{d_x}} - \frac{G(t, y)}{\sqrt{d_y}} \right) \left( \frac{F(t, x)}{\sqrt{d_x}} - \frac{F(t, y)}{\sqrt{d_y}} \right) = \sum_{x \in S} G(t, x) \mathcal{L} F(t, x)$$

Proof. (i) is obvious and (ii) follows by considering the function $T^{1/2}1$ as the function $f$ in (6):

$$\sum_y H_t(x, y) \sqrt{d_y} = (H_t T^{1/2}1)(x)$$

$$= T^{1/2}1(x)$$

$$= \sqrt{d_x}$$

To see (iii) we have

$$\frac{\partial F}{\partial t} = \frac{\partial}{\partial t} H_t f$$

$$= \frac{\partial}{\partial t} e^{-t\mathcal{L}} f$$

$$= -\mathcal{L} F$$

The proof of (iv) follows from the fact that all eigenfunctions $\phi_i$ with corresponding $F_i$ in (6) satisfy (iv).

To prove (v), we have

$$\sum_{x \in S} G(t, x) \mathcal{L} F(t, x) = \sum_{x \in S} F(t, x) T^{-1/2} L T^{-1/2} F(t, x)$$

$$= \sum_{x \in S} G(t, x) \left( \sum_{y \in S} \left( \frac{F(t, x)}{\sqrt{d_x}} - \frac{F(t, y)}{\sqrt{d_y}} \right) \right)$$

$$= \sum_{z \in S \cup S} G(t, x) \left( \sum_{y \in S'} \left( \frac{F(t, x)}{\sqrt{d_x}} - \frac{F(t, y)}{\sqrt{d_y}} \right) \right)$$

$$= \sum_{y \in S'} \left( \frac{G(t, x)}{\sqrt{d_x}} - \frac{G(y, t)}{\sqrt{d_y}} \right) \left( \frac{F(t, x)}{\sqrt{d_x}} - \frac{F(y, t)}{\sqrt{d_y}} \right)$$

by using (iv).
Lemma 3. For all $x, y \in S \cup \delta S$, we have $H_t(x, y) \geq 0$.

Proof. The matrix $M = I - L$ has all entries non-negative. Therefore $e^{tM}$ has all non-negative entries. Since

$$H_t = e^{-t}e^{tM},$$

all entries of $H_t$ are non-negative. Lemma 3 is proved.

5. An eigenvalue inequality.

In this section, we will prove the following inequality involving the eigenvalue $\lambda_S$ of an induced subgraph $S$ with a heat kernel $H_t(x, y)$.

$$\lambda_S \geq \frac{1}{2t} \sum_{x \in S} \inf_{y \in S} \frac{H_t(x, y)\sqrt{d_x}}{\sqrt{d_y}}$$

To do so, we consider a given function $f : S \cup \delta S \to \mathbb{R}$, and we define

$$g(x, t) = \sum_{y \in S} H_t(x, y) \sqrt{d_x d_y} \left( \frac{f(y)}{\sqrt{d_y}} - \frac{F(t, x)}{\sqrt{d_x}} \right)^2.$$

where $F(t, x) = H_t f(x)$. By using Lemma 2 (ii), we have

$$g(x, t) = \sum_{y \in S} H_t(x, y) \sqrt{d_x/d_y} f^2(y) - F^2(t, x)$$

By summing over $x$ in $S$, we obtain

$$\sum_{x \in S} g(x, t) = \sum_{x \in S} \sum_{y \in S} H_t(x, y) \sqrt{d_x/d_y} f^2(y) - \sum_{x \in S} F^2(t, x)$$
Using Lemma 2 (i), (ii), (iv) and (v), we get

\[ \sum_{x \in S} g(t, x) = \sum_{y \in S} f^2(y) - \sum_{x \in S} F^2(t, x) \]

\[ = - \int_0^t \frac{d}{ds} \sum_{x \in S} F^2(s, x) \, ds \]

\[ = -2 \int_0^t \sum_{x \in S} F(s, x) \frac{d}{ds} F(s, x) \, ds \]

\[ = 2 \int_0^t \sum_{x \in S} F(s, x) \mathcal{L} F(s, x) \, ds \]

\[ = 2 \int_0^t \sum_{\{x, y\} \in S'} \left( \frac{F(s, x)}{\sqrt{d_x}} - \frac{F(s, y)}{\sqrt{d_y}} \right)^2 \, ds \]

We claim that for any \( t \geq 0 \), we have

**Fact 1.** \[ \sum_{\{x, y\} \in S'} \left( \frac{F(t, x)}{\sqrt{d_x}} - \frac{F(t, y)}{\sqrt{d_y}} \right)^2 \leq \sum_{\{x, y\} \in S'} \left( \frac{f(x)}{\sqrt{d_x}} - \frac{f(y)}{\sqrt{d_y}} \right)^2 \]

To see this, we consider

\[ \frac{d}{dt} \sum_{\{x, y\} \in S'} \left( \frac{F(t, x)}{\sqrt{d_x}} - \frac{F(t, y)}{\sqrt{d_y}} \right)^2 \]

\[ = 2 \sum_{\{x, y\} \in S'} \left( \frac{F(t, x)}{\sqrt{d_x}} - \frac{F(t, y)}{\sqrt{d_y}} \right) \left( \frac{d}{dt} \frac{F(t, x)}{\sqrt{d_x}} - \frac{d}{dt} \frac{F(t, y)}{\sqrt{d_y}} \right) \]

\[ = 2 \sum_{x \in S \cup S} \frac{d}{dt} F(t, x) \sum_{\{x, y\} \in S'} \left( \frac{F(t, x)}{\sqrt{d_x}} - \frac{F(t, y)}{\sqrt{d_y}} \right) \]

\[ = 2 \sum_{x \in S \cup S} \frac{d}{dt} F(t, x) \mathcal{L} F(t, x) \]

\[ = -2 \sum_{x \in S} \frac{d}{dt} F(t, x) \cdot \frac{d}{dt} F(t, x) \]

\[ = -2 \sum_{x \in S} \left( \frac{d}{dt} F(t, x) \right)^2 \]

\[ \leq 0 \]
Therefore
\[
\sum_{\{x,y\} \in S'} \left( \frac{F(t,x)}{\sqrt{d_x}} - \frac{F(t,y)}{\sqrt{d_y}} \right)^2 \leq \sum_{\{x,y\} \in S'} \left( \frac{F(0,x)}{\sqrt{d_x}} - \frac{F(0,y)}{\sqrt{d_y}} \right)^2 \\
= \sum_{\{x,y\} \in S'} \left( \frac{f(x)}{\sqrt{d_x}} - \frac{f(y)}{\sqrt{d_y}} \right)^2
\]

Thus, Fact 1 is proved.

Substituting the inequality of Fact 1 into (10), we obtain
\[
\sum_{x \in S} g(t,x) = 2 \int_0^t \sum_{\{x,y\} \in S'} \left( \frac{F(s,x)}{\sqrt{d_x}} - \frac{F(s,y)}{\sqrt{d_y}} \right)^2 ds \\
\leq 2t \sum_{\{x,y\} \in S'} \left( \frac{f(x)}{\sqrt{d_x}} - \frac{f(y)}{\sqrt{d_y}} \right)^2
\]

(11)

In the other direction, we consider the lower bound:
\[
\sum_{x \in S} g(t,x) = \sum_{x \in S} \sum_{y \in S} H_t(x,y) \sqrt{d_x d_y} \left( \frac{f(y)}{\sqrt{d_y}} - \frac{F(t,x)}{\sqrt{d_x}} \right)^2 \\
\geq \sum_{x \in S} \left( \inf_{y \in S} H_t(x,y) \sqrt{d_x d_y} \right) \sum_{y \in S} \left( \frac{f(y)}{\sqrt{d_y}} - \frac{F(t,x)}{\sqrt{d_x}} \right)^2 d_y \\
\geq \sum_{x \in S} \left( \inf_{y \in S} \frac{H_t(x,y) \sqrt{d_x}}{\sqrt{d_y}} \right) \left( \inf_{c \in \mathbb{R}} \sum_{y \in S} \left( \frac{f(y)}{\sqrt{d_y}} - c \right)^2 d_y \right)
\]

(12)

Combining (11) and (12), we have
\[
\sup_{\{x,y\} \in S'} \sum_{x \in S} \left( \frac{f(x)}{\sqrt{d_x}} - \frac{f(y)}{\sqrt{d_y}} \right)^2 \geq \sum_{x \in S} \inf_{y \in S} \frac{H_t(x,y) \sqrt{d_x}}{\sqrt{d_y}} \left( \inf_{c \in \mathbb{R}} \sum_{y \in S} \left( \frac{f(y)}{\sqrt{d_y}} - c \right)^2 d_y \right) \\
\geq \frac{1}{2t} \sum_{y \in S} \left( \frac{f(y)}{\sqrt{d_y}} - c \right)^2 d_y
\]

From the definition in (3), the left-hand side of the above inequality is exactly \( \lambda s \). Therefore we have proved the following:
Theorem 1. The Neumann eigenvalue $\lambda_S$ for an induced subgraph $S$ satisfies

$$\lambda_S \geq \frac{1}{2t} \sum_{x \in S} \inf_{y \in S} \frac{H_t(x, y) \sqrt{d_x}}{\sqrt{d_y}}$$


In this section, we will discuss various techniques of using the eigenvalue inequality in Theorem 1. To lower bound $\lambda_S$, one approach is to find some other function to serve as a lower bound for $H_t$. We will describe several sufficient conditions for establishing lower bounds for $H_t$.

Let $k$ denote a function

$$k : \mathbb{R} \times V \times V \rightarrow \mathbb{R}$$

For convenience, we will sometimes suppress the variable $y$ and write

$$k(t, x) = k(t, x, y)$$

for a fixed $y$. Suppose $k$ satisfies the following three conditions (A), (B) and (C), for a fixed $\epsilon > 0$ and $t \geq 0$.

(A) $$\frac{\partial}{\partial t} k(t, x) \leq -\mathcal{L}k(t, x) + \epsilon k(t, x)$$

(B) $$k(\epsilon', x, x) = 1 \text{ and } k(\epsilon', x, y) = 0 \text{ for } x, y \in S \text{ and } x \neq y.$$ (C) For all $x \in \delta S$,

$$\sum_{x' \in S} \left( \frac{k(t, x)}{\sqrt{d_x}} - \frac{k(t, x')}{\sqrt{d_{x'}}} \right) \leq 0$$

Theorem 2. Suppose $S$ is an induced subgraph with the heat kernel $H_t$. If $k$ satisfies (A), (B) and (C) for fixed $\epsilon$ and for all $t \geq 0$, then for $x, y \in S$, we have

$$H_t(x, y) \geq k(t, x, y) e^{-\epsilon t}$$

Proof. Suppose we define

$$\hat{k}(t, x, y) = e^{\epsilon t} H_t(x, y)$$
Then we have

\[ \frac{\partial}{\partial t} \hat{h} = \epsilon \hat{h} - \mathcal{L} \hat{h} \]  

(13)

Using (B), we find:

\[
\int_0^t \frac{\partial}{\partial s} \sum_{z \in S} \hat{h}(t-s,x,z)k(s,z,y)ds \\
= \sum_{z \in S} [\hat{h}(0,x,z) \cdot k(t,z,y) - \hat{h}(t,x,z) \cdot k(0,z,y)] \\
= k(t,x,y) - \hat{h}(t,x,y)
\]

Therefore, for fixed \( x \) and \( y \) in \( S \), we have

\[
- \hat{h}(t,x,y) + k(t,x,y) = \int_0^t \frac{\partial}{\partial s} \sum_{z \in S} \hat{h}(t-s,x,z)k(s,z,y)ds \\
\leq \int_0^t \sum_{z \in S} \left[ \frac{\partial}{\partial s} \hat{h}(t-s,x,z) \cdot k(s,z,y) + \hat{h}(t-s,x,z) \cdot \frac{\partial}{\partial s} k(s,z,y) \right] ds \\
\leq \int_0^t \sum_{z \in S} \left[ \mathcal{L}_z \hat{h}(t-s,x,z) \cdot k(s,z,y) - \epsilon \hat{h}(t-s,x,z)k(s,z,y) \\
+ \hat{h}(t-s,x,z) \frac{\partial}{\partial s} k(s,z,y) \right] ds \quad \text{[by (13)]} \\
\leq \int_0^t \left[ \sum_{z \in S} \mathcal{L}_z \hat{h}(t-s,x,z) \cdot k(s,z,y) - \sum_{z \in S} \hat{h}(t-s,x,z) \cdot \mathcal{L}_z k(s,z,y) \right] ds \quad \text{[by (A)]}
\]

Since the Neumann condition implies

\[ \mathcal{L}_z(t-s,x,z) = 0 \]
Eigenvalue Inequalities for Graphs and Convex Subgraphs

For $z \in \delta S$, the above sum is equal to

$$\int_0^t \left[ \sum_{x \in S \cup \delta S} \mathcal{L}_x \hat{h}(t-s, x, z) \cdot k(s, z, y) - \sum_{x \in S} \hat{h}(t-s, x, z) \cdot \mathcal{L}_x k(s, z, y) \right] \, ds$$

$$= \int_0^t \left[ \sum_{\{z, z'\} \in S'} \left( \frac{\hat{h}(t-s, x, z)}{\sqrt{d_z}} - \frac{\hat{h}(t-s, x, z')}{\sqrt{d_{z'}}} \right) \cdot \left( \frac{k(s, z, y)}{\sqrt{d_z}} - \frac{k(s, z', y)}{\sqrt{d_{z'}}} \right) 
- \sum_{x \in S} \hat{h}(t-s, x, z) \cdot \mathcal{L}_x k(s, z, y) \right] \, ds$$

$$= \int_0^t \sum_{z \in S} \frac{\hat{h}(t-s, x, z)}{\sqrt{d_z}} \left( \sum_{z' \in S} \frac{k(s, z, y)}{\sqrt{d_z}} - \frac{k(s, z', y)}{\sqrt{d_{z'}}} \right) \, ds$$

$$\leq 0$$

where the last inequality follows from the fact that $\hat{h} \geq 0$ and the last term

$$\sum_{\{z, z'\} \in S'} \frac{k(s, z, y)}{\sqrt{d_z}} - \frac{k(s, z', y)}{\sqrt{d_{z'}}}$$

is $\leq 0$ by using condition (C). Therefore we have

$$\hat{h}(t, x, y) \geq k(t, x, y)$$

as desired. The proof of Theorem 2 is complete.

We now consider a modified version of (B). For some $\epsilon' > 0$,

$$(B') \quad k(\epsilon', x, x) = 1 \text{ and } k(\epsilon', x, y) < \epsilon'' \sqrt{d_x d_y} \quad \text{for } x, y \in S \text{ and } x \neq y.$$

**Theorem 3.** Suppose $S$ is an induced subgraph with the heat kernel $H_t$. If $k$ satisfies (A), (B') and (C) for fixed $\epsilon, \epsilon', \epsilon''$ and for all $t \geq \epsilon'$, then for $x, y \in S$, we have

$$H_{t-\epsilon'}(x, y) + \epsilon'' \sqrt{d_x d_y} \geq k(t, x, y) e^{-\epsilon t}$$
Proof. We follow the proof of Theorem 2. By (B'), we have:

\[
\int_{t'}^t \frac{\partial}{\partial s} \sum_{z \in S} \hat{h}(t - s, x, z)k(s, z, y) ds
\]

\[
= \sum_{z \in S} \left[ \hat{h}(0, x, z) \cdot k(t, z, y) - \hat{h}(t - t', x, z) \cdot k(t', z, y) \right]
\]

\[
\geq k(t, x, y) - \hat{h}(t - t', x, y) - \epsilon'' \sum_z \hat{h}(t - t', x, z) \sqrt{d_y d_z}
\]

\[
\geq k(t, x, y) - \hat{h}(t - t', x, y) - \epsilon'' \sqrt{d_x d_y} e^{t(t' - t')}
\]

by using the fact that \( \sum_y H_t(x, y) \sqrt{d_y} = \sqrt{d_x} \). Therefore, for fixed \( x \) and \( y \)
in \( S \), we have

\[
- \hat{h}(t - t', x, y) + k(t, x, y) - \epsilon'' \sqrt{d_x d_y} e^{t(t' - t')}
\]

\[
\leq \int_{t'}^t \frac{\partial}{\partial s} \sum_{z \in S} \hat{h}(t - s, x, z)k(s, z, y) ds
\]

\[
\leq \int_{t'}^t \sum_{z \in S} \left[ \frac{\partial}{\partial s} \hat{h}(t - s, x, z) \cdot k(s, z, y) + \hat{h}(t - s, x, z) \cdot \frac{\partial}{\partial s} k(s, z, y) \right] ds
\]

\[
\leq \int_{t'}^t \sum_{z \in S} \left[ \mathcal{L}_z \hat{h}(t - s, x, z) \cdot k(s, z, y) - \epsilon \hat{h}(t - s, x, z)k(s, z, y) + \hat{h}(t - s, x, z) \cdot \frac{\partial}{\partial s} k(s, z, y) \right] ds
\]

[by (13)]

\[
\leq \int_{t'}^t \left[ \sum_{z \in S} \mathcal{L}_z \hat{h}(t - s, x, z) \cdot k(s, z, y) - \sum_{z \in S} \hat{h}(t - s, x, z) \cdot \mathcal{L}_z k(s, z, y) \right] ds
\]

[by (A)]

\[
= \int_{t'}^t \left[ \sum_{\{z, z'\} \in S'} \frac{\hat{h}(t - s, x, z)}{\sqrt{d_z}} - \frac{\hat{h}(t - s, x, z')}{\sqrt{d_{z'}}} \right] \cdot \left( \frac{k(s, z, y)}{\sqrt{d_z}} - \frac{k(s, z', y)}{\sqrt{d_{z'}}} \right) ds
\]

\[
- \sum_{z \in S} \hat{h}(t - s, x, z) \cdot \mathcal{L}_z k(s, z, y) \right] ds
\]

\[
= \int_{t'}^t \sum_{z \in S} \frac{\hat{h}(t - s, x, z)}{\sqrt{d_z}} \left( \sum_{z' \in S} \frac{k(s, z, y)}{\sqrt{d_z}} - \frac{k(s, z', y)}{\sqrt{d_{z'}}} \right) ds
\]

\[
\leq 0
\]
Therefore we have

\[ H_{t-e'}(x, y) + \epsilon'' \sqrt{d_x d_y} \geq k(t, x, y) e^{-e'} \]

Next, we consider the following variation of condition (A):

\[ \frac{\partial}{\partial t} k(t, x) \leq -\mathcal{L} k(t, x) + \frac{\epsilon_0}{t^2} k(t, x) \quad \text{for} \ t \text{ satisfying} \ t_0 \geq t \geq \epsilon'. \]

**Theorem 4.** Suppose \( S \) is an induced subgraph with the heat kernel \( H_t \).
If \( k \) satisfies \((A'),(B')\) and \((C)\) for fixed \( t_0, \epsilon_0, \epsilon', \epsilon'' \) and for all \( t_0 \geq t \geq \epsilon' \).
Then for \( x, y \in S \), we have

\[ H_{t_0-e'}(x, y) + \epsilon'' \sqrt{d_x d_y} \geq (1 - \epsilon'') k(t_0, x, y) e^{-3\epsilon_0/\epsilon'} \]

**Proof.** We consider the following function

\[ \bar{h}(t, x, y) = e^{3\epsilon_0/(t_0+2\epsilon'-t)} H_t(x, y) \]

Then we have

\[ \frac{\partial}{\partial t} \bar{h} = \frac{3\epsilon_0}{(t_0 + 2\epsilon' - t)^2} \bar{h} - \mathcal{L} \bar{h} \]

The following calculation is similar but slightly different to that in the proof of Theorem 3. For \( t \) satisfying \( t_0 \geq t \geq \epsilon' \), we have

\[ -\bar{h}(t_0 - \epsilon', x, y) + k(t_0, x, y) - \epsilon'' \sqrt{d_x d_y} d^{2\epsilon_0/\epsilon'} \]

\[ \leq \int_{t_0}^{t_0} \frac{\partial}{\partial s} \sum_{z \in S} \bar{h}(t-s, x, z) k(s, z, y) ds \]

\[ \leq \int_{t'}^{t_0} \sum_{z \in S} \left[ \frac{\partial}{\partial s} \bar{h}(t_0 - s, x, z) \cdot k(s, z, y) + \bar{h}(t_0 - s, x, z) \cdot \frac{\partial}{\partial s} k(s, z, y) \right] ds \]

\[ \leq \int_{t'}^{t_0} \sum_{z \in S} \left[ \mathcal{L}_z \bar{h}(t_0 - s, x, z) \cdot k(s, z, y) - \frac{3\epsilon_0}{(2\epsilon' + s)^2} \bar{h}(t_0 - s, x, z) k(s, z, y) \right] ds \]

\[ + \bar{h}(t_0 - s, x, z) \frac{\partial}{\partial s} k(s, z, y) \right] ds \]

\[ \leq \int_{t'}^{t_0} \sum_{z \in S} \left[ \mathcal{L}_z \bar{h}(t_0 - s, x, z) \cdot k(s, z, y) - \frac{\epsilon_0}{s^2} \bar{h}(t_0 - s, x, z) k(s, z, y) \right] ds \]

\[ + \bar{h}(t_0 - s, x, z) \frac{\partial}{\partial s} k(s, z, y) \right] ds \]
\[ \leq \int_{t_0}^{t_0'} \left[ \sum_{z \in S \cup S'} L_z \tilde{h}(t_0 - s, x, z) \cdot k(s, z, y) \right. \\
\left. - \sum_{z \in S} \tilde{h}(t_0 - s, x, z) \cdot L_z k(s, z, y) \right] ds \]

\[ = \int_{t_0}^{t_0'} \left[ \sum_{\{z, z'\} \in S'} \left( \frac{\tilde{h}(t_0 - s, x, z)}{\sqrt{d_z}} - \frac{\tilde{h}(t_0 - s, x, z')}{\sqrt{d_{z'}}} \right) \cdot \left( \frac{k(s, z, y)}{\sqrt{d_z}} - \frac{k(s, z', y)}{\sqrt{d_{z'}}} \right) \right. \\
\left. - \sum_{z \in S} \tilde{h}(t_0 - s, x, z) \cdot L_z k(s, z, y) \right] ds \]

\leq 0

Therefore we have

\[ H_{t_0 - \epsilon'}(x, y) + \epsilon'' \sqrt{d_x d_y} \geq k(t, x, y) e^{-3\epsilon_0/\epsilon'} \]

and Theorem 4 is proved.

We consider another variation of condition (C):

\[ (C') \left| \sum_{\{x, x'\} \in S'} \frac{k(t, x)}{\sqrt{d_x}} - \frac{k(t, x')}{\sqrt{d_{x'}}} \right| \leq \epsilon_1 k(t, x) \sqrt{d_x} \quad \text{for } x \in S. \]

**Theorem 5.** Suppose \( k \) satisfies (A'), (B') and (C') for fixed \( t_0, \epsilon_0, \epsilon', \epsilon'' \) and all \( t \) satisfying \( t_0 > t \geq \epsilon' \). Then, we have

\[ H_{t_0 - \epsilon'}(x, y) + \epsilon'' \sqrt{d_x d_y} \geq \left( 1 - \frac{2c' \epsilon_1}{\sqrt{t_0}} \right) \min_{|t_0 - s| \leq \epsilon'} k(s, x, y) e^{-3\epsilon_0/\epsilon'} \]

provided for some \( c' \geq 1, c' \epsilon_1/\sqrt{t_0} \leq 1/4 \) and for \( t_0 > t \geq \epsilon' \),

\[ \sum_{z \in \partial S} k(t - s, x, z) k(s, z, y) \leq \frac{c'}{t} k(t, x, y) \quad \text{for } x, y \in S. \]
Proof. Suppose the contrary. Following the proof of Theorem 4, we have

\[ |\tilde{h}(t_0 - \epsilon', x, y) - k(t, x, y) + \epsilon'' \sqrt{d_x d_y} e^{\frac{3\epsilon_0}{\epsilon'}}| \]

\[ \leq \int_{\epsilon'}^{t_0} \sum_{z \in \delta S} \frac{\tilde{h}(t_0 - s, x, z)}{\sqrt{d_z}} \left( \sum_{(z', z') \in S'} \left| \frac{k(s, z, y)}{\sqrt{d_z}} - \frac{k(s, z', y)}{\sqrt{d_{z'}}} \right| \right) ds \]

\[ \leq \epsilon_1 \int_{\epsilon'}^{t_0} \frac{1}{\sqrt{s}} \sum_{z \in \delta S} \tilde{h}(t_0 - s, x, z) k(s, z, y) ds \]

We consider

\[ X = \sup_{x, y, t_0 \geq \epsilon'} \frac{|\tilde{h}(t, x, y) - k(t, x, y)|}{k(t, x, y)} \]

We have, by using (15)

\[ |\tilde{h}(t - \epsilon', x, y) - k(t, x, y) + \epsilon'' \sqrt{d_x d_y} e^{\frac{3\epsilon_0}{\epsilon'}}| \]

\[ \leq \epsilon_1 \int_{\epsilon'}^{t_0} \frac{1}{\sqrt{s}} \sum_{z \in \delta S} |\tilde{h}(t_0 - s, x, z) - k(t_0 - s, x, z)| \]

\[ + k(t_0 - s, x, z) k(s, z, y) ds \]

\[ \leq \epsilon_1 \int_{\epsilon'}^{t_0} \frac{1}{\sqrt{s}} \sum_{z \in \delta S} \frac{\epsilon c'}{\sqrt{s}} (X + 1) k(t_0, x, y) ds \]

\[ \leq \frac{\epsilon_1 c'}{\sqrt{t_0}} (X + 1) k(t_0, x, y) \]

Therefore we have

\[ H_{t_0 - \epsilon'}(x, y) + \epsilon'' \sqrt{d_x d_y} \geq \left( 1 - \frac{2\epsilon c'}{\sqrt{t_0}} \right) \min_{|t_0 - s| \leq \epsilon'} k(s, x, y) e^{-3\epsilon_0/\epsilon'} \]

and Theorem 5 is proved.

7. Convex subgraphs embedded in a manifold.

In previous sections, we considered general graphs. In the remainder of this paper, we will restrict ourselves to special subgraphs of homogeneous graphs that are embedded in Riemannian manifolds. Such a restriction will allow us to derive eigenvalue bounds for graphs using known results for eigenvalues of Riemannian manifolds. The restricted classes of graphs
still include many families of graphs which arise in various applications in enumeration and sampling. Roughly speaking, our plan here is to modify the heat kernels of the Riemannian manifolds with convex boundary which can then serve as lower-bound functions of \( k(t, x, y) \) in Section 3.

We start with some definitions. Let \( \Gamma = (V, E) \) denote a graph with vertex set \( V = V(\Gamma) \) and edge set \( E = E(\Gamma) \). We say that \( \Gamma \) is a homogeneous graph with an associated group \( \mathcal{H} \) acting on \( V \) if the following two conditions are satisfied:

(i) for any \( g \in \mathcal{H} \), \( \{gu, gv\} \in E \) if and only if \( \{u, v\} \in E \),

(ii) for any two vertices \( u \) and \( v \), there is a \( g \in \mathcal{H} \) such that \( gu = v \).

Thus \( \Gamma \) is vertex-transitive under the action of \( \mathcal{H} \) and the vertex set \( V \) can be identified with the coset space \( \mathcal{H}/I \) where \( I = \{g \in \mathcal{H} : gv = v\} \), for a fixed vertex \( v \), is the isotropy group. We note that a Cayley graph is the special case of a homogeneous graph with \( I \) trivial. The edge set of a homogeneous graph \( \Gamma \) can be described by an edge generating set \( K \subset \mathcal{H} \) such that each edge of \( \Gamma \) is of the form \( \{v, gv\} \) for some \( v \in V \) and \( g \in K \). We also require the generating set \( K \) to be symmetric, i.e., \( g \in K \) if and only if \( g^{-1} \in K \).

We will first define a simple version of a lattice graph. Suppose the vertices of \( \Gamma \) can be embedded into a flat Riemannian manifold \( \mathcal{M} \) with a distance function \( \mu \) such that

\[
\mu(x, gx) = \mu(y, g'y) \leq \mu(x, y)
\]

for any \( g, g' \in K \) and \( x, y \in V(\Gamma) \) with \( x \neq y \). Then \( \Gamma \) is called a simple lattice graph. We say that \( \Gamma \) is a lattice graph if for a vertex \( x \), every vertex of \( \Gamma \) in the convex hull formed by the set \( \{gx, g \in K\} \) is adjacent to \( x \). Here we assume that \( \mathcal{M} \) is flat, although very similar approaches can be used for manifolds with non-negative Ricci curvature.

An induced subgraph on a subset \( S \) of a lattice graph \( \Gamma \) is said to be convex if there is a submanifold \( \mathcal{M} \subset \mathcal{M} \) with a convex boundary \( \partial \mathcal{M} \neq \emptyset \) such that \( S \) consists of all vertices of \( \Gamma \) in the interior of \( \mathcal{M} \). Furthermore, we require that for any vertex \( x \), the Voronoi region \( R_x = \{y : \mu(y, x) < \mu(y, z) \text{ for all } z \in \Gamma \cap \mathcal{M}\} \) is contained in \( \mathcal{M} \).

Example 1. We consider the space \( S \) of all \( m \times n \) matrices with non-negative integral entries having column sums \( c_1, \ldots, c_n \), and row sums \( r_1, \ldots, r_m \). First, we construct a homogeneous graph \( \Gamma \) with the vertex set
consisting of all \( m \times n \) matrices with integral (possibly negative) entries. Two vertices \( u \) and \( v \) are adjacent if they differ at four entries in some submatrix determined by two columns \( i, j \) and rows \( k, m \) satisfying

\[
\begin{align*}
    u_{ik} &= v_{ik} + 1, \\
    u_{jk} &= v_{jk} - 1, \\
    u_{im} &= v_{im} - 1, \\
    u_{jm} &= v_{jm} + 1
\end{align*}
\]

It is easy to see that \( \Gamma \) is a homogeneous graph with the edge generating set consisting of all \( 2 \times 2 \) submatrices \(
\begin{pmatrix}
1 & -1 \\
-1 & 1
\end{pmatrix}
\). Obviously, \( \Gamma \) can be viewed as being embedded in the \( mn \)-dimensional Euclidean space \( M = \mathbb{R}^{mn} \). In fact, \( \Gamma \) is embedded in the submanifold \( M \) of the \( (mn-m-n+1) \)-dimensional subspace containing the vertices of \( \Gamma \). \( M \) is determined by

\[
\begin{align*}
\sum_j x_{ij} &= r_i \\
\sum_i x_{ij} &= c_i \\
x_{ij} &\geq -\frac{1}{2}
\end{align*}
\]

It is easy to verify that \( S \) is a convex subgraph of the lattice graph \( \Gamma \).

**Remark 1.** In [3], the authors consider a "strongly" convex subgraph \( S \) of a homogeneous graph. An eigenvalue bound was derived by using an entirely different approach. Namely, the following Harnack inequality was established for an eigenfunction \( f \) of \( S \) and for any vertex \( x \),

\[
\sum_{y \sim x} (f(x) - f(y))^2 \leq 8\lambda \max_{y \in S} f^2(y)
\]

This can be used to show

\[
\lambda \geq \frac{1}{8kD^2}
\]

where \( k \) is the maximum degree of \( T \) and \( D \) denotes the diameter of \( T \). The differences between the two definitions of convexity can be described as follows: In [3], a strongly convex subgraph \( T \) requires that for any two vertices \( u \) and \( v \) in \( T \), all shortest paths joining \( u \) and \( v \) in the homogeneous graph must be contained in \( T \). Here, the convexity condition requires the embedding of the subgraph into a Riemannian manifold with a convex boundary. We remark that various applications involving random walks on graphs which can often be interpreted as occurring in convex subgraphs (but not strongly
8. Bounding the discrete heat kernel by the continuous heat kernel.

Let $S$ denote a convex subgraph of a lattice graph $\Gamma$ with edge-generating set $K$. Let $M$ denote the associated $d$-dimensional manifold $M$ with a convex boundary and let $\mu$ denote the distance function on $M$. In this section, we restrict ourselves to the case of convex subgraphs of simple lattice graphs so that the discussions are simpler but contain the essence of the general case.

Let $h(t, x, y)$ denote the heat kernel of $M$ and suppose $u(t, x) = h(t, x, y)$ satisfies the heat equation

$$\left( \Delta - \frac{\partial}{\partial t} \right) u(t, x) = 0$$

with the Neumann boundary condition

$$\frac{\partial}{\partial n} u(t, x) = 0$$

where $\Delta$ denotes the Laplace operator of the form

$$\Delta = \sum_{i,j} a_{i,j} \frac{\partial^2}{\partial x_i \partial x_j}$$

and $a_{i,j}$ depends on the edge generating set $K$ as described later in (19).

We remark that the convexity condition (17) is later on used to give heat kernel estimates. Our results can be applied to subgraphs corresponding to manifolds with weaker convexity conditions as long as the heat kernel estimates for manifolds can still be derived.

We assume that $\mu(x, gx) = \epsilon$ for all $x \in V(\Gamma)$ and $g \in K$. To proceed, we define the function $k(t, x, y)$ which will be used later with Theorem 2. (In a neighborhood of a point $x$ in $M$, we use the simplified notation of associating the points with the corresponding normal ordinates so that the expression, (e.g., $x - z$) in the following definition makes sense.)

$$k(t, x, y) = c_1 \int_M h(c_2 t, x - z, y) \varphi(z) dz$$

where $\varphi$ is a bell-shaped function (such as a modified Gaussian function $\exp(-c'|z|/\epsilon^2)$ ) with compact support, say, $\{ |z| < \epsilon/4 \}$, and which satisfies

$$c_1 \int \varphi(z) dz = c_3 (c_4 \epsilon)^d$$
where \(c_3\) and \(c_4\) are chosen so that the above quantity is within a constant factor of the volume of the Voronoi region \(R_x = \{y : \mu(y, x) \leq \mu(y, z) \text{ for all } z \in \Gamma \cap M\}\), for a vertex \(x\). So, \(k(t, x, y)\) can be approximated by \(h(c_2 t, x, y)U\) or

\[
\int_{R_x} h(c_2 t, z, y)dz
\]

when \(t\) is not too small, by using the gradient estimates of \(h\) in the next section. Here \(U\) denotes the maximum over \(x\) of the volume of \(R_x\).

In order to use Theorem 2, we need to verify conditions \((A')\), \((B')\) and \((C')\). First we want to show:

\[
\frac{\partial}{\partial t} k(t, x) \leq -\mathcal{L} k(t, x) + \frac{\epsilon_0}{t^2} k(t, x)
\]

for \(t_0 \geq t \geq \epsilon' = d \log \text{vol} S\). Where \(\epsilon_0 = \frac{c_3 \epsilon^d d}{c_2}\). Here we suppress \(y\) and write \(k(t, x, y) = k(t, x)\). Note that we have

\[
\frac{\partial}{\partial t} k(t, x) = c_1 \int_M \frac{\partial}{\partial t} h(c_2 t, x - z) \varphi(z)dz
\]

\[
= c_1 \int_M c_2 \Delta h(c_2 t, x - z) \varphi(z)dz
\]

Also,

\[
\mathcal{L} k(t, x) = k(t, x) - \frac{1}{d_x} \sum_{y \sim x} k(t, y)
\]

\[
= c_1 \int_M \mathcal{L} h(c_2 t, x - z) \varphi(z)dz
\]

Here we use the convention of identifying a vertex with the associated point in the \(d\)-dimensional manifold \(M\). For simplicity, we write \(gx = g + x\). (Formally we should use an appropriate mapping \(\sigma\) from \(V\) to \(M\) so that \(\sigma(gx) = \sigma(g) + \sigma(x)\). For a fixed \(g \in K\), we consider the two terms in the sum involving \(g\) and \(g^{-1}\):

\[
[\varphi(y) - \varphi(y + g)] + [\varphi(y) - \varphi(y - g)] = -[\varphi(y + g) - \varphi(y)] + [\varphi(y) - \varphi(y - g)]
\]

which can be approximated by the second partial derivative in the direction of \(g\) scaled by a factor of \(\epsilon^2\). Therefore the Laplace operator involves coefficients \(a_{i,j}\)'s depending on the edge generating set \(K\). Namely, the Laplace
operator $\Delta$ satisfies

\begin{equation}
\Delta = \sum_{i,j} a_{ij} \frac{\partial^2}{\partial x_i \partial x_j}
= \frac{2d}{|K|} \sum_{g \in K^*} \frac{\partial^2}{\partial g^2}
\sim -\frac{2d}{\epsilon^2} \mathcal{L}
\end{equation}

Here we use $K^*$ to denote a subset of $K$ so that at most one of $a$ and $a^{-1}$ is in $K^*$ for each $a$ in $K$. The edge generators should be “evenly distributed” in the sense that the matrix $(a_{i,j})$ satisfies

$$C_1 I \leq (a_{i,j}) \leq C_2 I$$

for some constants $C_1$ and $C_2$ where $I$ denotes the identity matrices. By choosing

$$c_2 = \frac{2\epsilon^2}{d}$$

we have

$$|c_2 \Delta h + \mathcal{L} h| \leq c_2 \epsilon^4 \frac{d}{|K|} \sum_{g \in K^*} \left| \frac{\partial^4}{\partial g^4} h \right|$$

Note that in the Taylor series expansion, the $\frac{\partial^3}{\partial g^3}$ terms cancel since the generators $g$ and $g^{-1}$ are simultaneously in $K$. After substituting for $\frac{\partial^4}{\partial g^4} h$, we get

$$|c_2 \Delta h + \mathcal{L} h| \leq \frac{c_2 \epsilon^4 \epsilon dh}{\epsilon^2}$$

where $c_5$ depends on $C_1$ and $C_2$.

For the general case of lattice graphs (without the condition that $\mu(x, gx) = \epsilon$ for all vertex $x$ and edge generator $g$), the Laplacian of the lattice graph is related to the Laplace-Beltrami operator as follows:

$$-\frac{2d}{\epsilon^2} \mathcal{L} \sim \frac{2d}{|K|} \sum_{g \in K^*} \left( \frac{\epsilon}{\mu(x, gx)} \right)^2 \frac{\partial^2}{\partial g^2}
= \sum_{i,j} a_{ij} \frac{\partial^2}{\partial x_i \partial x_j}$$

where $\epsilon = \min\{\mu(x, gx) : g \in K\}$. Then, we have

$$c_8 \leq \min\{C_1, C_2^{-1}\}$$
Hence, we have
\[ \frac{\partial}{\partial t} k(t, x) + \mathcal{L}k(t, x) \leq \frac{c_1 c_5 \epsilon_0 d}{c_2 t^2} \int_M h(c_2 t, x - z) \varphi(z) dz \]
\[ = \frac{c_5 \epsilon_0 d}{c_2 t^2} k(t, x) \]

And,
\[ \frac{\partial}{\partial t} k(t, x) + \mathcal{L}k(t, x) \leq \frac{\epsilon_0}{t^2} k(t, x) \]

where \( \epsilon_0 = \frac{c_5 \epsilon_0 d}{c_2} \).

To establish (B') for \( \epsilon' = \frac{c'd}{\log vol \ S} \) and \( \epsilon'' = \frac{c''}{(\log vol \ |K|)} \), we can choose \( c_1 \) so that
\[ k(\epsilon', x, x) = c_1 \int_M h(c_2 \epsilon', x - z, x) \varphi(z) dz = 1 \]
and for \( x \neq y \), we use the heat kernel estimates in Theorem 8 and 9 (proved later), to get
\[ k(\epsilon', x, y) = c_1 \int_M h(c_2 \epsilon', x - z, y) \varphi(z) dz \]
\[ \leq \exp\left(-\frac{\epsilon^2}{4c_2 \epsilon'}\right) k(\epsilon', x, x) \]
\[ \leq \frac{\epsilon'}{\log vol \ S} \]

We remark that we can make \( \epsilon'' \) arbitrarily small by adjusting \( c' \) in \( \epsilon' \).

To prove (C'), we need to show that
\[ \left| \sum_{\{x, x' \} \in S'} k(t, x, y) - k(t, x', y) \right| \leq \frac{\epsilon_1 |K|}{\sqrt{t}} \frac{k(t, x, y)}{\sqrt{t}} \]

where \( \epsilon_1 = \epsilon d/2\sqrt{c_2 |K|} \). The above inequality follows from that fact that \( |\mu(x, x')| = \epsilon \) and the following estimate for the gradient of the heat kernel which will be proved later in the next section:
\[ |\nabla h|(t, x, y) \leq c_6 \frac{d}{\sqrt{t}} h(t, x, y) \]
We consider
\[
\sum_{ \{x, x'\} \in S'} k(t, x, y) - k(t, x', y)
\]
\[
\leq c_1 \sum_{ \{x, x'\} \in S'} \left| \int [h(c_2 t, x, y - z) - h(c_2 t, x', y - z)] \varphi(z) \, dz \right|
\]
\[
\leq c_1 \epsilon \sqrt{d_x} \int |\nabla h|(c_2 t, x, y - z) \varphi(z) \, dz
\]
\[
\leq c_1 \epsilon \sqrt{d_x} \int \frac{d}{\sqrt{c_2 t}} h(c_2 t, x, y - z) \varphi(z) \, dz
\]
\[
\leq \frac{\epsilon \sqrt{d_x} \, d}{\sqrt{c_2 t}} k(t, x, y)
\]

Now, we need to estimate \( \sum_{z \in \partial S} k(t - s, x, z) k(s, z, y) \). First we consider
\[
|k(t, x, y) - U h(t, x, y)|
\]
\[
= |c_1 \int h(c_2 t, x, y - z) \varphi(z) \, dz - h(c_2 t, x, y) c_1 \int \varphi(z) \, dz|
\]
\[
\leq c_1 \int |h(c_2 t, x, y - z) - h(c_2 t, x, y)| \varphi(z) \, dz
\]
\[
\leq c_1 \int \epsilon |\nabla h|(c_2 t, x, y - z) \varphi(z) \, dz
\]
\[
\leq c_1 \int \frac{\epsilon d}{\sqrt{c_2 t}} h(c_2 t, x, y - z) \varphi(z) \, dz
\]
\[
= \frac{\epsilon d}{\sqrt{c_2 t}} k(t, x, y)
\]

We will use the fact that \( |k(t, x, y) - U h(t, x, y)| \) is small when \( c_2 t \) is large.

Now we consider \( \sum_{z \in \partial S} k(t - s, x, z) k(s, z, y) \) for a fixed \( s \). Without loss of
generality, we may assume that \( s \leq t/2 \). We have
\[
\sum_{z \in \partial S} k(t - s, x, z) k(s, z, y)
\]
\[
\leq \sum_{z \in \partial S} U h(c_2(t - s), x, z) c_1 \int h(c_2 s, z - z', y) \varphi(z') \, dz' + \text{l.o.t.}
\]
\[ \leq c_1 U \int_{z' \in U \cap \partial S \cup z} h(c_2(t-s), x, z-z') h(c_2s, z-z', y) \varphi(z') \, dz' + \text{l.o.t.} \]
\[ \leq U \frac{\varepsilon}{c_2 t} h(c_2 t, x, y) + \text{l.o.t.} \]
\[ \leq \frac{\varepsilon}{c_2 t} k(t, x, y) + \text{l.o.t.} \]

Here \text{l.o.t.} denotes a small fraction of the first term. From Theorem 5, we have

\[ (20) \]
\[ H_t(x, y) \geq \left( 1 - \frac{2c' \varepsilon_1}{\sqrt{t}} \right) \left( \min_{|t-s| \leq \varepsilon'} k(s, x, y) - \varepsilon'' |K| \right) \exp(-3\varepsilon_0/\varepsilon') \]

where \( H \) is the heat kernel of the convex subgraph \( S \).

In [8], Li and Yau proved the following lower bound for \( h \).

**Theorem [Li-Yau].** Let \( M \) denote a d-dimensional compact manifold with boundary \( \partial M \). Suppose the Ricci curvature of \( M \) is nonnegative, and if \( \partial M \neq \emptyset \), we assume that \( \partial M \) is convex. Then the fundamental solution of the heat equation with the Neumann boundary condition \( \frac{\partial}{\partial \nu} u(t, x) = 0 \), satisfies

\[ h(t, x, y) \geq \frac{C}{B_x(\sqrt{t})} \exp \frac{-\mu^2(x, y)}{(4 - \varepsilon') t} \]

for some constant \( C \) depending on \( d \) and \( \varepsilon' \). Here, \( B_x(r) \) denotes the volume of the intersection of \( M \) and the ball of radius \( r \) centered at \( x \).

However, the above version of the usual estimates for the heat kernel can not be directly used for our purposes here since the constant \( C \) is exponentially small depending on \( d \). A more careful analysis of the heat kernel is needed. We will give a complete proof of the heat kernel estimates in a general terms in the next section. The proofs are partly based on the proofs in [8] and both the upper and lower bound estimates are given.

To lower-bound the discrete heat kernel, we will use the following lower bound estimates for the (continuous) heat kernel which will be proved later in Section 6. For any \( \alpha > 0, \sigma \geq c d \alpha \),

\[ (21) \]
\[ h(t, x, y) \geq \frac{(1 + \alpha)^{-d}}{4B_x(\sqrt{\sigma t})} \exp \frac{-(1 + \alpha) \mu^2(x, y)}{\alpha t} \]

We choose

\[ \alpha = \frac{1}{d} \]
\[ \alpha c_2 t_0 = D^2(M) \]
where $D(M)$ denotes the diameter of $M$. (We may assume $D(M) \geq 1$).
Therefore, by using (21) we have

$$h(c_2 t_0, x, y) \geq \frac{c_7}{\text{vol } M}$$

Also,

$$e^{-\frac{3\epsilon_0}{\epsilon'}} < \text{const.}$$

and

$$h(t_1, x, y) \leq \text{const.} \cdot h(t_2, x, y)$$

if $t_1 \geq t_0/2$ and $|t_1 - t_2| \leq \epsilon'$. Using (20), we have

$$k(t_0 - \epsilon', x, y) = c_1 \int_M h(c_2 (t_0 - \epsilon'), x - z, y) \varphi(z)dz$$

$$\geq \frac{c_1 c_8}{\text{vol } M} \int_M \varphi(z)dz$$

$$\geq \frac{c_8}{\text{vol } M} U$$

where $c$'s denote some appropriate absolute constants. We then have

$$H_t(x, y) \geq \frac{c_9 U}{\text{vol } M}$$

From 1, we then have

$$\lambda \geq \sum_{x \in S} \sum_{y \in S} \inf_{y \in S} H_t(x, y) \exp(-\frac{3\epsilon_0}{\epsilon'})$$

$$\geq \frac{c_9}{t \text{vol } M} U |S|$$

$$\geq \frac{c_9}{d^2 D(M)^2} \epsilon^2 r$$

where $U$ denotes the volume of the Voronoi region and $r$ denotes the ratio of $U|S|/\text{vol } M$. As a consequence, we have proved the following:

**Theorem 6.** Let $S$ denote a convex subgraph of a simple lattice graph $\Gamma$ and suppose $S$ is embedded into a $d$-dimensional flat manifold $M$ with a convex boundary and a distance function $\mu$. Suppose for any edge $\{u, v\}$ of $S$ we have $\mu(u, v) = \epsilon$. Then the Neumann eigenvalue $\lambda$ of $S$ satisfies the following inequality:

$$\lambda \geq \frac{c_0 r \epsilon^2}{d^2 D(M)^2}$$
where $c_0$ is an absolute constant (depending only on $\Gamma$ and is independent of $S$), $K$ is the set of edge generators of the lattice graph,

$$r = \frac{U \cdot |S|}{\text{vol } M}$$

and $U$ denotes the volume of the Voronoi region.

To get a simpler lower bound for $\lambda$, we note that the diameter $D(S)$ of the convex subgraph $S$ and the diameter of the manifold are related by

$$D(M) \leq \epsilon \cdot D(S) \quad (22)$$

Therefore, we have the following:

**Corollary 1.** Let $S$ denote a convex subgraph of a simple lattice graph and suppose $S$ is embedded into a $d$-dimensional flat manifold $M$ with a convex boundary. Then the Neumann eigenvalue $\lambda_S$ of $S$ satisfies the following inequality:

$$\lambda \geq \frac{c_0 \cdot r}{d^2 \cdot D^2(S)}$$

where

$$r = \frac{U \cdot |S|}{\text{vol } M},$$

$D(S)$ denotes the (graph) diameter of $S$, $K$ denotes the set of edge generators and $c_0$ is an absolute constant depending only on the simple Lattice graph.

For the general case of the lattice graphs, we have the following:

**Theorem 7.** Let $S$ denote a convex subgraph of a lattice graph and suppose $S$ is embedded into a $d$-dimensional flat manifold $M$ with a convex boundary and a distance function $\mu$. Let $K$ denote the set of edge generators and suppose $\epsilon = \min\{\mu(x, gx) : g \in K\}$. Assume that

$$-\frac{2d}{\epsilon^2} \mathcal{L} \sim \frac{2d}{|K|} \sum_{g \in K^*} \left( \frac{\epsilon}{\mu(x, gx)} \right)^2 \frac{\partial^2}{\partial g^2}$$

$$= \sum_{i,j} a_{i,j} \frac{\partial^2}{\partial x_i \partial x_j}$$

and

$$C_1 I \leq (a_{i,j}) \leq C_2 I$$
where $I$ is the identity matrix.

$$c_5 \leq \min\{C_1, C_2^{-1}\}$$

Then the Neumann eigenvalue $\lambda$ of $S$ satisfies the following inequality:

$$\lambda \geq \frac{c_0 \, r \, \varepsilon^2}{d^2 D(M)^2}$$

where

$$r = \frac{U \, |S|}{\text{vol} \, M}$$

$U$ denotes the volume of the Voronoi region, and $c_0$ is an absolute constant satisfying

$$c_0 \leq C_0 \min\{C_1, C_2^{-1}\}$$

for an absolute constant $C_0$.

**Remark 2.** The constant $C_0$ can be roughly estimated with a value of $1/100$.

**Remark 3.** For a polytope in $\mathbb{R}^d$, we can rescale and choose the lattice points to be dense enough to approximate the volume of the polytope. For example, if we have

$$(23) \quad C \, \varepsilon \leq D_1(M)/d$$

where $D_1$ denote the diameter of $M$ measured by the $L_1$ norm and $C$ is some absolute constant, then the number of lattice points provides a good approximation for the volume of the polytope. This implies that $r \geq c$ for some constant $c$. The above inequality (23) can be replaced by a slightly simpler inequality:

$$C \, d \leq D(S)$$

for some constant $C$. These facts are useful for approximation algorithms for the volume of a convex body which will be discussed in the next section.

**Remark 4.** There are many graphs $G$ that can be embedded in a lattice graph such that the diameter of $G$ satisfies

$$D(G) \sim \frac{\sqrt{d} \, D(M)}{\varepsilon}$$
For such graphs, Theorem 6 implies a somewhat stronger result:

\[ \lambda \geq \frac{\alpha r}{d^2 D(G)^2} \]

where \( r \) is as defined in Theorem 6.


In this section, we will analyze the (continuous) heat kernel. We remark that there is a large literature on the estimates of the heat kernel. However, in such estimates, the dimension \( d \) is usually taken as a constant and the approximations are often crude. Here, we will give upper and lower bound estimates which are quite sharp in a general setting. The methods here are partly based on the proofs in [8]. It is anticipated that these estimates can be useful for many other problems as well. We will first prove an upper bound for the heat kernel. This bound will be used later for establishing the lower bounds.

Throughout this section, we use the following notation:

Let \( M \) denote a \( d \)-dimensional compact manifold with boundary \( \partial M \). Suppose the Ricci curvature of \( M \) is nonnegative, and if \( \partial M \neq \emptyset \), we assume that \( \partial M \) is convex. The fundamental solution \( h \) of the heat equation satisfies the Neumann boundary condition \( \frac{\partial}{\partial \nu} u(t, x) = 0 \) for \( x \in \partial M \). We let \( B_x(r) \) denote the ball centered at \( x \) of radius \( r \). For simplicity, the volume of \( B_x(r) \) is also denoted by \( B_x(r) \).

**Theorem 8.** For any \( \alpha > 0 \) and \( t > 0 \),

\[
h(t, x, y) \leq (1 + \alpha)^d \, B_x^{-1/2}(\sqrt{\alpha(2 + \alpha)t}) \, \left( \frac{1}{B_y^{-1/2}(\sqrt{\alpha t})} \right) \\
\exp \left( \frac{-\mu^2(x, y)}{4(1 + 2\alpha)(1 + \alpha)^2 t} \right) \exp \left( \frac{3}{4} \, \frac{1}{4(1 + 2\alpha)(1 + \alpha)} \right)
\]

**Proof.** We follow from the proof of Theorem 3.1 on p. 175 of [8] with the value for \( \alpha, \tau \) and \( \theta \) in [8] to be \( \alpha = 1, \tau = 0, \theta = 0 \), in order to derive the following inequality:

\[
h(t, x, y) \leq (1 + \alpha)^d \, B_x^{-1/2}(S_1) \, B_y^{-1/2}(S_2) \, \exp \left( 2 \, \tilde{\rho}(x, S_2, (1 + \alpha)t) \right) \, \exp \left( \tilde{\rho}(y, S_1, (1 + \alpha)t) \right) \, \exp \left( \rho(x, S_1, (1 + 2\alpha)(1 + \alpha)t) \right)
\]

Here we choose \( S_1 \) and \( S_2 \) as follows:

\[
S_1 = B_y \left( \sqrt{\alpha t} \right), \quad S_2 = B_x \left( \sqrt{\alpha(2 + \alpha)t} \right)
\]
Then
\[ 2 \, \bar{\rho}(y, S_2, \alpha(2 + \alpha)t) \leq \frac{1}{2} \]
\[ \bar{\rho}(x, S_1, \alpha t) \leq \frac{1}{4} \]

We define \( W \) to be
\[ W = \rho(x, S_1, (1 + 2\alpha)(1 + \alpha)t) = \inf_{x \in B_y(\sqrt{\alpha t})} \frac{\mu^2(x, z)}{4(1 + 2\alpha)(1 + \alpha)t} \]

If \( x \in B_y(\sqrt{\alpha t}) \), then we have
\[ W = 0 \geq \frac{\mu^2(x, z)}{4(1 + 2\alpha)(1 + \alpha)t} - \frac{\alpha}{4(1 + 2\alpha)(1 + \alpha)^2} \]

If \( x \not\in B_y(\sqrt{\alpha t}) \), then \( \mu(x, y) \geq \sqrt{\alpha t} \) and
\[ W \geq \frac{(\mu(x, y) - \sqrt{\alpha t})^2}{4(1 + 2\alpha)(1 + \alpha)t} \]

Since
\[ (\mu(x, y) - \sqrt{\alpha t})^2 \geq \frac{\mu^2(x, y)}{1 + \alpha} - t \]

we have
\[ W \geq \frac{\mu(x, y)^2}{4(1 + 2\alpha)(1 + \alpha)^2t} - \frac{1}{4(1 + 2\alpha)(1 + \alpha)} \]

Therefore, from Theorem 3.1 (ii) in [8], we have
\[ h(t, x, y) \leq (1 + \alpha)^d \, B_x^{-1/2} \left( \sqrt{\alpha(2 + \alpha)t} \right) \, B_y^{-1/2} \left( \sqrt{\alpha t} \right) \exp \frac{-\mu^2(x, y)}{4(1 + 2\alpha)(1 + \alpha)^2t} \exp \left( \frac{3}{4} + \frac{1}{4(1 + 2\alpha)(1 + \alpha)} \right) \]
as claimed.

Before proceeding to prove the lower bound, we need the following assumption:

\[ c_{11}^{-1} B_y \left( \sqrt{\alpha t} \right) \leq B_x \left( \sqrt{\alpha t} \right) \leq c_{11} B_y \left( \sqrt{\alpha t} \right) \]

for some constant \( c_{11} \). We note that the above assumption holds for \( c_{11} = 1 \) if \( \alpha t \) is larger than the square of the diameter of \( M \).
Theorem 9. For any $\alpha > 0$, $t \geq 0$, and $\sigma$ satisfying $\sigma \geq c\alpha$, 

$$h(t, x, y) \geq \frac{(1 + \alpha)^{-d/2}}{4B_x \left(\sqrt{\frac{\sigma t}{2}}\right)} \exp \left(\frac{-(1 + \alpha)\mu^2(x, y)}{4\sigma t}\right)$$

provided (24) holds.

Proof. Using (24), we have 

$$h(t, x, y) \leq c_{11}^{-1/2} (1 + \alpha)^d B_x^{-1/2} \left(\sqrt{\alpha(2 + \alpha)t}\right) B_x^{-1/2} \left(\sqrt{\alpha t}\right) \exp \left(\frac{-\mu^2(x, y)}{4(1 + 2\alpha)(1 + \alpha)^2 t}\right) \exp \left(\frac{3}{4} + \frac{1}{4(1 + 2\alpha)(1 + \alpha)}\right)$$

Since 

$$\int h(t, x, y) dy = 1,$$

we have 

$$1 \leq \int_{\mu(x, y) \leq \sqrt{\sigma t}} h(t, x, y) dy$$

$$+ c_{11}^{-1/2} (1 + \alpha)^d B_x^{-1/2} \left(\sqrt{\alpha(2 + \alpha)t}\right) B_x^{-1/2} \left(\sqrt{\alpha t}\right) \exp \left(\frac{3}{4} + \frac{1}{4(1 + 2\alpha)(1 + \alpha)}\right) \int_{\mu(x, y) \leq \sqrt{\sigma t}} \exp \frac{-\mu^2(x, y)}{4(1 + 2\alpha)(1 + \alpha)^2 t} dy$$

$$\leq \int_{\mu(x, y) \leq \sqrt{\sigma t}} h(t, x, y) dy$$

$$+ c_{11}^{-1/2} (1 + \alpha)^d B_x^{-1/2} \left(\sqrt{\alpha(2 + \alpha)t}\right) B_x^{-1/2} \left(\sqrt{\alpha t}\right) \exp \left(\frac{3}{4} + \frac{1}{4(1 + 2\alpha)(1 + \alpha)}\right) \int_{\sqrt{\sigma t}}^{\infty} \exp \frac{-r^2}{4(1 + 2\alpha)(1 + \alpha)^2 t} dB(r)$$

Assume for $r_2 \geq r_1$, the following holds: 

$$\frac{B(r_2)}{B(r_1)} \leq \frac{r_2}{r_1}$$

we obtain 

$$\int_{\sqrt{\sigma t}}^{\infty} \exp \frac{-r^2}{4(1 + 2\alpha)(1 + \alpha)^2 t} dB(r)$$
Therefore we have

\[
c_{11}^{-1/2} (1 + \alpha)^d B_\alpha^{-1/2} \left( \sqrt{\alpha (2 + \alpha) t} \right) B_\alpha^{-1/2} \left( \sqrt{\alpha t} \right)
\]

\[
\exp \left( \frac{3}{4} + \frac{1}{4(1 + 2\alpha)(1 + \alpha)} \right) \int_{\sqrt{\sigma t}}^{\infty} \exp \left( \frac{-r^2}{4(1 + 2\alpha)(1 + \alpha)^2 t} \right) \frac{dB(r)}{\sqrt{\sigma t}}
\]

\[
\leq c_{11}^{-1/2} (1 + \alpha)^{d+1} \sqrt{1 + 2\alpha}
\]

\[
\exp \left( \frac{3}{4} + \frac{1}{4(1 + 2\alpha)(1 + \alpha)} \right) \int_{\sqrt{\sigma t}}^{\infty} \exp \left( -r \right) \frac{r^2}{\sqrt{\sigma t}} \frac{d\tau}{\sqrt{\sigma t}}
\]

We choose \( \sigma > c\alpha \) so that the above term is no more than 1/2. Hence

\[
\int_{\mu(x,y) \leq \sqrt{\sigma t}} h(t, x, y) \geq \frac{1}{2}
\]

But

\[
h(2t, x, x) = \int_M h^2(t, x, y)
\]

Hence

\[
h(2t, x, x) \geq \int_{\mu(x,y) \leq \sqrt{\sigma t}} h^2(t, x, y)
\]

\[
\geq B_\alpha^{-1} \left( \sqrt{\alpha t} \right) \left( \int_{\mu(x,y) \leq \sqrt{\sigma t}} h(t, x, y) \right)^2
\]

\[
\geq \frac{1}{4B_\alpha \left( \sqrt{\alpha t} \right)}
\]

This implies

\[
h(t, x, x) \geq \frac{1}{4B_\alpha \left( \sqrt{\alpha t} \right)}
\]
By the Harnack inequality in Theorem 2.3 in [8], we have

\begin{equation}
(25) \quad h(t_1, x, x) \leq h(t_2, x, y) \left( \frac{t_2}{t_1} \right)^{d/2} \exp \left( \frac{\mu^2(x, y)}{4(t_2 - t_1)} \right)
\end{equation}

for $t_2 > t_1$. Hence for any $\alpha > 0$, we have

\[
h(t, x, y) \geq h \left( \frac{t}{1 + \alpha}, x, x \right) (1 + \alpha)^{-d/2} \exp \left( \frac{-(1 + \alpha)\mu^2(x, y)}{4\alpha t} \right) \geq \frac{(1 + \alpha)^{-d/2}}{4B_x \left( \sqrt{\frac{\alpha t}{2}} \right)} \exp \left( \frac{-(1 + \alpha)\mu^2(x, y)}{4\alpha t} \right)
\]

This completes the proof of Theorem 9.

We will also need estimates for the gradient of $h$. First, we will prove a useful Fact.

**Theorem 10.** For any $r > 0$ and $\sigma > 0$, we have

\[
\int_{B_y(r)} |\nabla h|^2 (t, x, z) dz \leq \left( \frac{1}{\sigma^2 r^2} + \frac{d}{2t} \right) \int_{B_y((1+\sigma)r)} h^2(t, x, z) dz
\]

**Proof.** We start with the following inequality which was established on page 163, as Theorem 1.3 of [8] (for the special case of $\tau = 0 = \theta = q$).

\[
|\nabla h|^2 \leq h_t + \frac{d}{2t} h^2
\]

Therefore we have

\[
\int \rho^2(z) |\nabla h|^2(t, x, z) dz \leq \int \rho^2(z) h(t, x, z) h_t(t, x, z) dz + \frac{d}{2t} \int \rho^2(z) h^2(t, x, z) dz = \int \rho^2(z) h(t, x, z) \Delta h(t, x, z) dz + \frac{d}{2t} \int \rho^2(z) h^2(t, x, z) dz
\]

Here we define

\[
\rho(z) = \begin{cases} 
1 & \text{if } \mu(y, z) \leq r \\
0 & \text{if } \mu(y, z) \geq (1 + \sigma)r
\end{cases}
\]
and
\[|\nabla \rho| \leq \frac{1}{\sigma r}\]

We note that
\[
\int \rho^2(z)h(t, x, z)\Delta h(t, x, z)dz = - \int \rho^2(z)|\nabla h|^2(t, x, z)dz + 2 \int \rho(z)h(t, x, z)\nabla\rho(z)\nabla h(t, x, z)dz = \int |\nabla\rho|^2h^2(t, x, z)dz
\]

Hence, we have
\[
\int \rho^2(z)|\nabla h|^2(t, x, z)dz \leq \int \left(|\nabla\rho|^2 + \frac{d}{2t}\rho^2\right)h^2(t, x, z)dz
\]

Therefore,
\[
\int_{B_{y}(r)}|\nabla h|^2(t, x, z)dz \leq \left(\frac{1}{\sigma^2 r^2} + \frac{d}{2t}\right)\int_{B_{y}((1+\sigma) r)}h^2(t, x, z)dz
\]

**Theorem 11.** For \( \sigma > 0, \alpha > 0, \)
\[
|\nabla h|(t, x, y) \leq 3(1 + \alpha)^{2d}\left(\frac{1}{\sigma^2 r^2} + \frac{d}{2t}\right)^{1/2}h((1 + \alpha)t, x, y)
\]

if \((1 + \sigma)^2 r^2 \leq \alpha^2 t\) and \( \alpha < 1/d.\)

**Proof.** For a fixed \( x, \) we consider \( f(t, y) = |\nabla h|(t, x, y). \) Let \( \rho \) be defined as in Theorem 9. We have
\[
f(t, y) = \int_{t_1}^t f(t_1, z)h(t - t_1, z, y)\rho(z)dz
\]

\[
= \int_{t_1}^t \frac{\partial}{\partial s} \int f(s, z)h(t - s, z, y)\rho(z)dz ds
\]

\[
= \int_{t_1}^t \int [\Delta f(s, z)h(t - s, z, y)\rho(z) - f(s, z)(\Delta h)(t - s, z, y)\rho(z)] dz ds
\]

\[
= \int_{t_1}^t \int [f(s, z)\Delta(h(t - s, z, y)\rho(z)) - f(s, z)(\Delta h)(t - s, z, y)\rho(z)] dz ds
\]

\[
= \int_{t_1}^t \int f(s, z)[2\nabla h(t - s, z, y)\nabla\rho(z) + h(t - s, z, y)\nabla\rho(z)] dz ds
\]
\[
= \int_{t_1}^{t} \left[ \frac{1}{\sigma r} \int_{B_y((1+\sigma)r)} 2f(s,z) \nabla h(t-s,z,y) \right] dz \\
+ \frac{1}{\sigma^2 r^2} \int_{B_y((1+\sigma)r)} f(s,z) h(t-s,z,y) \right] dz \, ds
\]

To complete the proof, it suffices to establish upper bounds of

\[(1 + \alpha)^{2d} \left( \frac{1}{\sigma^2 r^2} + \frac{d}{2t} \right)^{1/2} h((1 + \alpha)t, x, y)\]

for the following three items separately, under the assumption that \(t - t_1 = \alpha t\).

(a) \[
\int_{B_y((1+\sigma)r)} f(t_1, z) h(t - t_1, z, y) \, dz,
\]

(b) \[
\int_{t_1}^{t} \frac{1}{\sigma r} \int_{B_y((1+\sigma)r)} f(s, z) \nabla h(t - s, z, y) \, dz \, ds
\]

(c) \[
\int_{t_1}^{t} \frac{1}{\sigma^2 r^2} \int_{B_y((1+\sigma)r)} f(s, z) h(t - s, z, y) \right] dz \, ds
\]

First, we consider (a)

\[
\left( \int_{B_y((1+\sigma)r)} f(t_1, z) h(t - t_1, z, y) \, dz \right)^2 \]

\[
\leq \int_{B_y((1+\sigma)r)} f^2(t_1, z) \, dz \int_{B_y((1+\sigma)r)} h^2(t - t_1, z, y) \, dz
\]

\[
\leq \left( \frac{1}{\sigma^2 r^2} + \frac{d}{2t} \right) \int_{B_y((1+\sigma)r)} h^2(t_1, x, z) \, dz \, h(2(t - t_1), y, y)
\]

\[
\leq \left( \frac{1}{\sigma^2 r^2} + \frac{d}{2t} \right) (1 + \alpha)^d h^2((1 + \alpha)t_1, x, y)
\]

\[
\int_{B_y((1+\sigma)r)} \exp \left( \frac{(1 + \sigma)\mu(y,z)^2}{2t\alpha} \right) \, dz \, h(2(t - t_1), y, y)
\]

Here we use the Harnack inequality (25) for upper bounding \(h(s, x, z)\). Using the assumption that \((1 + \sigma)^2 r^2 \leq \alpha(t - t_1)\)
we have

\[
\left( \int_{B_y((1+\sigma)r)} f(t_1, z) h(t - t_1, z, y) dz \right)^2 \\
\leq \left( \frac{1}{\sigma^2 r^2} + \frac{d}{2t} \right) (1 + \alpha)^d h^2((1 + \alpha)t_1, x, y) B_y((1 + \sigma)r) h(2(t - t_1), y, y) \\
\leq \left( \frac{1}{\sigma^2 r^2} + \frac{d}{2t} \right) (1 + \alpha)^d h^2((1 + \alpha)t_1, x, y) \\
B_y((1 + \sigma)r)(1 + \alpha)^{d/2} \frac{1}{B_y(\sqrt{2\alpha(t - t_1)})} \\
\leq \left( \frac{1}{\sigma^2 r^2} + \frac{d}{2t} \right) (1 + \alpha)^{2d} h^2((1 + \alpha)t_1, x, y)
\]

Therefore we have

\[
\int_{B_y((1+\sigma)r)} f(t_1, z) h(t - t_1, z, y) dz \\
\leq \left( \frac{1}{\sigma^2 r^2} + \frac{d}{2t} \right)^{1/2} (1 + \alpha)^d h((1 + \alpha)t_1, x, y) \\
\leq \left( \frac{1}{\sigma^2 r^2} + \frac{d}{2t} \right)^{1/2} (1 + \alpha)^{2d} h((1 + \alpha)t, x, y)
\]

To bound (b), we have

\[
\int_{t_1}^t \frac{1}{\sigma r} \int_{B_y((1+\sigma)r)} f(s, z) \nabla h(t - s, z, y) \, dz \, ds \\
\leq \frac{(t - t_1)^{1/2}}{\sigma r} \left( \int_{B_y((1+\sigma)r)} f^2(s_0, z) \, dz \right)^{1/2} \\
\left( \int_{t_1}^t \int_{B_y((1+\sigma)r)} \nabla h^2(t - s, z, y) \, dz \, ds \right)^{1/2} \\
\leq \frac{(t - t_1)^{1/2}}{\sigma r} \left( \frac{1}{\sigma^2 r^2} + \frac{2d}{t} \right)^{1/2} h((1 + \alpha)s_0, x, y) B_y((1 + \sigma)r) \\
\left( \int_{t_1}^t \int_{B_y((1+\sigma)r)} \nabla h^2(t - s, z, y) \, dz \, ds \right)^{1/2}
\]
It can be checked that

\[
\int_{t_1}^{t} \int_{B_y((1+\sigma)r)} \nabla h^2(t-s,z,y) \, dz \, ds \\
\leq \int_{t_1}^{t} \int_{B_y((1+\sigma)r)} \left( \frac{1}{\sigma^2 r^2} + \frac{d}{t-s} \right) h^2(t-s,z,y) \, dz \, ds
\]

\[
\leq \int_{0}^{(1+\sigma)r} \int_{t_1}^{t} \left( \frac{1}{\sigma^2 r^2} + \frac{d}{t-s} \right) \frac{(1+\alpha)^d \exp \left( \frac{-q^2}{2\alpha(t-s)} \right)}{B_y^2(\sqrt{\alpha(t-s)})} \, ds \, d B_y(q)
\]

\[
\leq \int_{0}^{(1+\sigma)r} (1+\alpha)^d \left( \frac{1}{\alpha \sigma^2 r^2} \frac{q^{n-3}}{(\alpha(t-t_0))^{n-2}} + \frac{1}{\alpha} \frac{q^{n-3}}{(\alpha(t-t_0))^{n-3}} \right) \, dq
\]

\[
\leq (1+\alpha)^d \frac{1}{\alpha \sigma^2 r^2 (\alpha(t-t_0))^{n/2-1}}
\]

Since \( t - t_1 = \alpha t \), \( r^2 < \alpha^2 t \) we have

\[
\int_{t_1}^{t} \frac{1}{\sigma r} \int_{B_y((1+\sigma)r)} f(s,z) \nabla h(t-s,z,y) \, dz \, ds
\]

\[
\leq \left( \frac{1}{\sigma^2 r^2} + \frac{d}{2t} \right)^{1/2} (1+\alpha)^d h((1+\alpha)t_1,x,y)
\]

\[
\leq \left( \frac{1}{\sigma^2 r^2} + \frac{d}{2t} \right)^{1/2} (1+\alpha)^2 d h((1+\alpha)t,x,y)
\]

Very similar arguments are used for upper bounding (c):

\[
\int_{t_1}^{t} \frac{1}{\sigma^2 r^2} \int_{B_y((1+\sigma)r)} f(s,z) h(t-s,z,y) \, dz \, ds
\]

\[
\leq \frac{(t-t_1)^{1/2}}{\sigma^2 r^2} \left( \int_{B_y((1+\sigma)r)} f^2(s_0,z) \, dz \right)^{1/2}
\]

\[
\left( \int_{t_1}^{t} \int_{B_y((1+\sigma)r)} h(t-s,z,y) \, dz \, ds \right)^{1/2}
\]

\[
\leq \left( \frac{1}{\sigma^2 r^2} + \frac{2d}{t} \right)^{1/2} (1+\alpha)^2 d h((1+\alpha)t,x,y)
\]

As a corollary of Theorem 11, by choosing \( \alpha = \frac{1}{d} \), \( r^2 = \alpha^2 t \), and \( \sigma \) a small constant, we have
Corollary 2.

\[ |\nabla h| (t, x, y) \leq c \frac{d}{t^{1/2}} h(t, x, y) \]

for some constant \( c \).


This section consists of four subsections: First, we give a brief discussion on random walks and, especially, on the associated weighted graphs. Then, we generalize the Laplacian, and heat kernels for weighted graphs and induced subgraphs. All results in previous sections can be extended to the weighted graphs. Finally, we will illustrate the relationship between the eigenvalues of the Laplacian and the rate of convergence of the corresponding random walk.

10.1. Random walks on graphs.

In a graph \( G \), a walk is just a sequence of vertices \((v_0, v_1, \cdots, v_s)\) with \( \{v_{i-1}, v_i\} \in E(G) \), for \( 1 \leq i \leq s \). A random walk is determined by the transition probability \( \pi(u, v) = \text{Prob}(x_{i+1} = v | x_i = u) \) which is independent of \( i \). Clearly, for each vertex \( u \)

\[ \sum_v \pi(u, v) = 1 \]

For any initial distribution \( f : V \to \mathbb{R} \) with \( \sum_v f(v) = 1 \), the distribution after \( k \) steps is just \( f P^k \) (in the notation of matrix multiplication by viewing \( f \) as a row vector where \( P \) is the matrix of transition probability). The random walk is said to be ergodic if there is a stationary distribution \( \pi(v) \) satisfying

\[ \lim_{s \to \infty} f P^s(v) = \pi(v) \]

Necessary and sufficient conditions for ergodicity are (i) irreducible, i.e., for any \( u, v \in V \), there exists some \( s \) such that \( P^s(u, v) > 0 \); (ii) aperiodic, i.e., \( \gcd \{ s : P^s(u, v) > 0 \} = 1 \). The problem of interest is to determine, from any initial distribution, the number of steps \( s \) required for \( P^s \) to be close to its stationary distribution.

In particular, we say the ergodic random walk is reversible if

\[ \pi(u) \pi(u, v) = \pi(v) \pi(v, u) \]
An alternative description for a reversible random walk is given by considering a weighted connected graph with edge weights

\[ w(u, v) = w(v, u) = \pi(v)\pi(v, u) / c \]

where \( c \) is the average of \( \pi(v)\pi(v, u) \) over all \((v, u)\) with \( \pi(v, u) \neq 0 \). A random walk in a weighted graph has as transition probability

\[ \pi(u, v) = \frac{w(u, v)}{d_u} \]

where \( d_u = \sum_z w(u, z) \) is the (weighted) degree of \( u \). The two conditions for ergodicity are equivalent to (i) connectivity and (ii) that the graph is not bipartite. We remark that an unweighted graph has \( \pi(u, v) \) either 0 or 1. A typical random walk has transition probability \( 1/d_v \) of moving from a vertex \( v \) to one of its neighbors. The transition matrix \( P = (\pi(u, v)) \) satisfies

\[ fP(v) = \sum_{u \sim v} \frac{1}{d_u} f(u) \]

for any \( f : V(G) \to \mathbb{R} \). In other words,

\[ P(u, v) = \begin{cases} 1/d_u & \text{if } u \text{ and } v \text{ are adjacent,} \\ 0 & \text{otherwise.} \end{cases} \]

It is easy to check that

\[ P = T^{-1} A = T^{-1/2}(I - \mathcal{L})T^{1/2} . \]

where \( A \) is the adjacency matrix.

For an induced subgraph \( S \) of a graph \( G \), we consider the following random walk: The probability of moving from a vertex \( v \) in \( S \) to a neighbor \( u \) of \( v \) is \( 1/d_v \) if \( u \) is in \( S \). If \( u \) is not in \( S \), we then move from \( v \) to each neighbor of \( u \) in \( S \) with the (additional) probability \( 1/d_v d'_u \) where \( d'_u \) denotes the number of neighbors of \( u \) in \( S \). The transition matrix \( P \) for this walk, whose columns and rows are indexed by \( S \), is defined as follows:

\[ fP(v) = \sum_{u \in S, u \sim v} \frac{1}{d_u} f(u) + \sum_{u \in S, w \sim v \notin S} \frac{1}{d_u d'_w} f(u) \]
The stationary distribution is \(d_v / \sum_d u\) at a vertex \(v\). The eigenvalues \(\rho_i\) of \(P\) are closely related to the Neumann eigenvalues \(\lambda_{S,i}\) as follows:

\[
\rho_i \leq 1 - \lambda_{S,i}
\]

In particular, we have

\[
(27) \quad \rho = \rho_1 \leq 1 - \lambda_{S,1} = 1 - \lambda_S
\]

This can be proved by using the Neumann condition as follows:

\[
1 - \rho = \inf_f \frac{\sum_{x\sim y} (f(x) - f(y))^2 + \sum_{x\sim z\sim y} (f(x) - f(y))^2/d_z}{\sum_{x\in S} f^2(x)dx}
\]

\[
\geq \inf_f \frac{\sum_{x\sim y} (f(x) - f(y))^2 + \sum_{z\notin S} \sum_{x\sim z} (f^2(x) - f^2(z))}{\sum_{x\in S} f^2(x)dx}
\]

\[
\geq \inf_f \frac{\sum_{x\sim y} (f(x) - f(y))^2 + \sum_{z\notin S} \sum_{x\sim z} (f(x) - f(z))^2}{\sum_{x\in S} f^2(x)dx}
\]

\[
= \inf_{\{x,y\}\in \delta S \cup S} \frac{\sum_{x\in S} (f(x) - f(y))^2}{\sum_{x\in S} f^2(x)dx}
\]

\[
= \lambda_S
\]

where \(f\) ranges over all functions \(f : \delta S \cup S \to \mathbb{R}\) satisfying

\[
\sum_{x\in S} f(x) = 0
\]
and for $x \in \delta S$

$$
\sum_{y \in S, y \sim x} (f(x) - f(y)) = 0
$$

The inequality (27) is quite useful in bounding the rate of convergence of random walks and the rapid mixing of Markov chains.

Suppose $S$ is an induced subgraph of a $k$-regular graph. The above random walk can be described as follows: At an interior vertex $v$ of $S$, the probability of moving to each neighbor is equal to $1/k$. (An interior vertex of $S$ is a vertex not adjacent to any vertex not in $S$.) At a boundary vertex of $v \in \delta S$, the probability of moving to a neighbor $u$ of $v$ is $1/k$ unless $u$ is not in $S$ and, in this case, the (additional) probability of $1/(kd_u)$ is assigned for moving from $v$ to each neighbor of $u$ in $S$. The stationary distribution of the above random walk is just the uniform distribution.

For the general case for random walks, we need to generalize the definitions for Laplacian and heat kernels to weighted graphs and subgraphs.

10.2. Eigenvalues for weighted graphs and subgraphs.

A weighted undirected graph $G$ with loops allowed has associated with it a weight function $w : V \times V \rightarrow \mathbb{R}^+ \cup \{0\}$ satisfying

$$
w(u, v) = w(v, u)
$$

and

$$
w(u, v) \geq 0.
$$

We note that if $\{u, v\} \not\in E(G)$, then $w(u, v) = 0$. Also $w(v, v)$ can be positive. For unweighted graphs, they are just the special case of taking the weights to be 0 or 1.

The degree $d_v$ of a vertex $v$ is just:

$$
d_v = \sum_u w(u, v).
$$

We generalize the definitions of previous sections so that

$$
L(u, v) = \begin{cases} 
d_v - w(v, v) & \text{if } u = v, \\
-w(u, v) & \text{if } u \text{ and } v \text{ are adjacent}, \\
0 & \text{otherwise.}
\end{cases}
$$
In particular, for a function \( f : V \to \mathbb{R} \), we have
\[
Lf(x) = \sum_{y \in \partial V} \frac{(f(x) - f(y))w(x, y)}{d_y}
\]

Let \( T \) denote the diagonal matrix with the \((v, t;)-th\) entry having value \( d_v \). The Laplacian of \( G \) is defined to be
\[
\mathcal{L} = T^{-1/2}L T^{-1/2}.
\]

In other words, we have
\[
\mathcal{L}(u, v) = \begin{cases}
1 - \frac{w(u, v)}{d_u} & \text{if } u = v, \\
\frac{w(u, v)}{\sqrt{d_u d_v}} & \text{if } u \text{ and } v \text{ are adjacent}, \\
0 & \text{otherwise}.
\end{cases}
\]

Therefore, by using the generalized version of \( L \) and \( \mathcal{L} \), the previous definitions for the eigenvalues for an induced subgraph \( S \) can still be utilized:
\[
\lambda_S = \inf_{\sum f(x)d_x = 0} \frac{\sum_{x \in S} (f(x) - f(y))^2 w(u, v)}{\sum_{x \in S} f^2(x)d_x}
\]

The Neumann condition is then
\[
\sum_{\{x, y\} \in \partial S} (f(x) - f(y))w(x, y) = 0
\]
for \( x \in \partial S \). We can define the heat kernel for weighted graphs in the same way as in Section 4. All the proofs in previous sections work in similar fashion and we obtain the same eigenvalue inequalities for weighted graphs:
Theorem 12. In a graph with edge weights \( w(x, y) \), for \( t > 0 \), we have

\[
\lambda_s \geq \frac{1}{2t} \sum_{x \in S} \inf_{y \in S} \frac{H_t(x, y)\sqrt{d_x}}{\sqrt{d_y}}
\]

10.3. Eigenvalues and the rate of convergence.

In a random walk with the associated weighted connected graph \( G \), the transition matrix \( P \) satisfies

\[1TP = PT1 = T1\]

and therefore the stationary distribution is exactly \( T1/volG \) where \( vol(G) = \sum_x d_x \). We want to show that when \( k \) is large enough, for any initial distribution \( f : V \rightarrow \mathbb{R} \), \( fP^k \) converges to the stationary distribution \( \phi_0 = T1/vol(G) \). Suppose we write

\[fT^{-1/2} = \sum_i a_i \phi_i\]

where \( \phi_i \) denotes the eigenfunction associated with \( \lambda_i \).

We have

\[
\|f P^s - a_0 \phi_0\| = \|f T^{-1/2}(I - \mathcal{L})^s T^{1/2} - T1/vol G\|
\]

\[
= \|\sum_{i \neq 0} (1 - \lambda_i)^s a_i \phi_i T^{1/2}\|
\]

\[
\leq (1 - \lambda)^s \|f\|
\]

\[
\leq e^{-s\lambda} \|f\|
\]

where \( \lambda = \lambda_1 \) if \( 1 - \lambda_1 \geq \lambda_{n-1} - 1 \) and \( \lambda = 2 - \lambda_{n-1} \), otherwise.

So, after \( s \geq (1/\lambda) + \log(1/\epsilon) \) steps, the \( L_2 \) distance between \( fP^s \) and its stationary distribution is less than \( \epsilon \|f\| \).

Although \( \lambda \) occurs in the above upper bound for the distance between the stationary distribution and the \( s \)-step distribution, in fact, only \( \lambda_1 \) is crucial in the following sense. Note that \( \lambda \) is either \( \lambda_1 \) or \( 2 - \lambda_{n-1} \). Suppose the latter holds (when \( \lambda_{n-1} - 1 \geq 1 - \lambda_1 \)). We can consider a modified random walk on the graph \( G' \) formed by adding \( d_v \) loops to each vertex \( v \). The new graph has Laplacian \( \lambda'_k = \lambda_k/2 \leq 1 \) which follows from equation (28). Therefore,

\[1 - \lambda'_1 \geq 1 - \lambda'_{n-1} \geq 0\]
The convergence bound for the modified random walk becomes \(2/\lambda_1 + \log(1/\varepsilon)\). The constant 2 can be further improved [5].

A stronger notion of convergence is measured by \(L_1\) or the relative pointwise distance which is defined as follows (also see [11]): After \(s\) steps, the relative pointwise distance (r.p.d.) of \(P\) to the stationary distribution \(\pi(x)\) is given by

\[
\Delta(s) = \max_{x,y} \frac{|P^s(y,x) - \pi(x)|}{\pi(x)}
\]

It is not difficult to show [5] that

\[
\Delta(t) \leq e^{-s\lambda_1/2} \frac{\text{vol } G}{\min_x d_x}
\]

So, if we choose \(t\) such that

\[
s \geq \frac{2}{\lambda_1} \log \frac{\text{vol } G}{\varepsilon \min_x d_x}
\]

then after \(s\) steps, we have \(\Delta(s) \leq \varepsilon\). For Neumannn walks, we can derive a similar inequality

\[
\Delta(s) \leq \rho^s \frac{\text{vol } G}{\min_x d_x} \\
\leq (1 - \lambda s)^s \frac{\text{vol } G}{\min_x d_x} \\
\leq e^{-s\lambda} \frac{\text{vol } G}{\min_x d_x}
\]

10.4. Applications on random walks and rapidly mixing Markov chains.

Many combinatorial and computational problems involve enumerating families of combinatorial objects. Such enumeration problems are often difficult and are widely believed to be computationally intractable (e. g., the class of the so-called \#P-complete problems [13]). An alternative approach is to consider approximation algorithms. In this direction, there has been a great deal of progress in recent years in developing efficient approximation algorithms by using sampling algorithms. Roughly speaking, if we can generate a "random" member of the family in polynomial time, then a polynomial approximation algorithm for the enumeration problem can be obtained, provided that certain technical conditions are satisfied (see [11]).
A sampling algorithm can often be described in terms of a random walk on a graph. Namely, the vertex set of the graph consists of the combinatorial objects which we wish to sample. The edges are usually determined by some "local" rules. For example, from each vertex, we define its neighboring vertices by choosing some simple transformations of the object. The random walk can then be described by its transition matrix $P$ where $P(u, v)$ denotes the probability of moving from vertex $u$ to its neighbor $v$ at each step. The problem of interest is to determine how many steps are required to move from a starting vertex to eventually reach a "random" vertex. In other words, how fast can an initial distribution converge to the stationary distribution by repeatedly applying the transition rules? A good bound of the rate of convergence often leads to polynomial approximation algorithms for the original enumeration problem.

To demonstrate the use of Theorem 6, we consider a classical problem of computing the volume of a convex body in $d$-dimensional Euclidean space. Although this problem is known to be computationally difficult, there have been a great deal of progress in obtaining randomized approximation algorithms based on the first polynomial time ($O(d^{27})$) algorithm by Dyer, Frieze and Kannan [7] (also see [10]). The main part of the algorithm is basically a random walk problem on the lattice points inside of the convex body. There have been a series of papers improving the volume algorithms with complexity lowered to $O(n^5 \log n)$ [9]. The eigenvalue inequality of Theorem 5 provides a more direct way of bounding the eigenvalues and the rate of convergence of the random walks.

Another example is the problem of random walks on matrices with non-negative integral entries having given row and column sums, arising in connection with exact inferences of contingency tables and their probability distributions (see [1, 6]). This problem can be reduced to a problem of bounding eigenvalues of convex subgraphs of the homogeneous graphs as described in Example 1. The diameter of the convex subgraph for contingency tables with given row and column sums can be easily evaluated and is bounded above by the sum of all column sums minus the maximum column sum. Using Theorem 6, for $n \times n$ tables with column and row sums equal to $s$, the eigenvalue $\lambda$ can be upper-bounded by $\frac{c}{n^{3} s^{2}}$, provided $s$ is at least $cn^{2}$. Therefore, a random walk on the subgraph converges in $cn^{3} s^{2}$ steps. More details on the contingency table problem can be found in [4].

In a subsequent paper [4], a variety of sampling and enumeration problems will be examined. By using the eigenvalue inequality established in Theorem 6, the upper bound for the convergence of the random walks on the corresponding convex subgraphs can often be improved by a factor of...
a power of \( n \) which then sometimes can lead to a better approximation algorithm.

**Acknowledgement.** The authors wish to thank Peter Li for numerous stimulating discussions which were instrumental in the preparation of this paper.

**References.**


RECEIVED OCTOBER 18, 1995. [March 29, 1996]

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