MORSE THEORY AND STOKES’ THEOREM

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Abstract

We present a new, intrinsic approach to Morse Theory which has interesting applications in geometry. We show that a Morse function \( f \) on a manifold determines a submanifold \( T \) of the product \( X \times X \), and that (in the sense that Stokes theorem is valid) \( T \) has boundary consisting of the diagonal \( \Delta \subset X \times X \) and a sum

\[
P = \sum_{p \in \text{Crit}(f)} U_p \times S_p
\]

where \( S_p \) and \( U_p \) are the stable and unstable manifolds at the critical point \( p \). In the language of currents,

(Stokes Theorem) \[
\partial T = \Delta - P.
\]

This current (or kernel) equation on \( X \times X \) is equivalent to an operator equation

(Chain Homotopy) \[
d \circ T + T \circ d = I - P,
\]

where \( P \) is a chain map onto the finite complex of currents \( S_f \) spanned by (integration over) the stable manifolds of \( f \). The operator \( P \) can be defined on an exterior form \( \alpha \) by

\[
P(\alpha) = \lim_{t \to \infty} \varphi_t^* \alpha
\]

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where $\varphi_t$ is a gradient flow for $f$. The de Rham differential in the complex $S_f$ is easily computed in terms of the flow lines. The chain homotopy equation also holds on certain integral chain complexes. Poincaré duality over $\mathbb{Z}$ follows from time-reversal in our operator equations. The method has many generalizations and applications. Residue theorems are established for functions with critical manifolds of higher dimension. The methods apply immediately to equivariant cohomology. Cup product formulas and a Lefschetz-type theorem are proved for the Thom-Smale Complex. Other applications include a new proof of the Carrell-Lieberman Theorem and a proof of a local version of the MacPherson Formula for characteristic classes and bundle maps.

**Introduction**

We present in this paper a new approach to Morse Theory which is stronger than the classical theory and has some interesting applications. It leads to formulas relating characteristic forms and singularities, and it unifies a body of results on holomorphic actions. It applies directly to the equivariant case. It also has the virtue of fitting neatly into the modern theory of invariants arising from topological quantum field theory.

This work resulted from addressing the following.

**Question.** Consider a flow $\varphi_t : X \to X$ generated by a smooth vector field on a compact manifold $X$. Under what circumstances does the limit

$$\alpha_{\infty} \equiv \lim_{t \to \infty} \varphi_t^{*} \alpha$$

exist for a given smooth differential form $\alpha$ on $X$?

We do not demand that $\alpha_{\infty}$ be smooth. Even so, one would expect the answer to be "rarely, if ever". However, we shall prove that for generic gradient dynamical systems, this limit does exist and has a beautiful, simple structure.

In fact we shall show that setting

\[
(0.1) \quad P(\alpha) \overset{\text{def}}{=} \lim_{t \to \infty} \varphi_t^{*} \alpha
\]

defines a continuous operator of degree 0

$$P : \mathcal{E}^\ast(X) \to \mathcal{D}'^\ast(X)$$

from smooth forms to generalized forms, i.e., currents. Furthermore, we shall show that this operator is chain homotopic to the inclusion $I : \mathcal{E}^\ast(X) \hookrightarrow \mathcal{D}'^\ast(X)$. That is, using the flow we shall construct a continuous operator

$$T : \mathcal{E}^\ast(X) \to \mathcal{D}'^\ast(X)$$
of degree $-1$ such that

\[(0.2) \quad d \circ T + T \circ d = I - P.\]

By de Rham [11], $I$ induces an isomorphism in cohomology. Hence so does $P$.

The existence of $P$ and $T$ satisfying (0.1) and (0.2) is established for any flow of finite volume. This concept, which is central to our paper, is introduced in §2. A flow $\varphi_t$ is said to have finite volume if the graph of the relation $x \bowtie y$, defined by the forward motion of the flow, has finite $(n + 1)$-dimensional volume in $X \times X$, where $n = \dim(X)$. Any flow whose space-time graph

\[T_{\varphi} \equiv \{(t, \varphi_t(x), y) : 0 < t \leq 1 \text{ and } x \in X\} \subset \mathbb{R} \times X \times X\]

is of finite volume has this property.

Consider now a Morse function $f : X \to \mathbb{R}$ with (finite) critical set $Cr(f)$. Suppose there is a riemannian metric on $X$ for which the gradient flow $\varphi_t$ of $f$ has the following properties:

1. $\varphi_t$ is of finite volume.

2. The stable and unstable manifolds, $S_p$, $U_p$ for $p \in Cr(f)$, are of finite volume in $X$.

3. $p \prec q \Rightarrow \lambda_p < \lambda_q$ for all $p, q \in Cr(f)$, where $\lambda_p$ denotes the index of $p$ and where $\prec$ is the closure of the relation $\bowtie$.

Note that $p \prec q$ means there is a piecewise flow line connecting $p$ in forward time to $q$.

We shall prove in §14 that such metrics always exist. They can be taken to be canonically flat in some neighborhood of $Cr(f)$ (see §2) thereby making the gradient flow particularly tractable. In fact properties (1)–(3) are shown to be generic in the space of such metrics.

Under these assumptions the operator $P$ is shown to have the following simple form:

\[(0.3) \quad P(\alpha) = \sum_{p \in Cr(f)} r_p(\alpha)[S_p]\]

for all $\alpha \in \mathcal{E}^*(X)$, where

\[r_p(\alpha) = \begin{cases} \int_{U_p} \alpha & \text{if } \deg \alpha = \lambda_p \\ 0 & \text{otherwise} \end{cases}\]
and where \([S_p]\) denotes the current defined by integration over \(S_p\). Note that the image of \(P\) is the finite dimensional vector subspace

\[ S_f = \text{span}_R\{[S_p]\}_{p \in CR(f)}. \]

From (0.2) we see that \(S_f\) is \(d\)-invariant, i.e., that \((S_f, d)\) is a complex, and we show that the inclusion \(S_f \subset D'^*(X)\) induces an isomorphism

\[ H^*(S_f) \cong H^*_{de Rham}(X) \]

This immediately yields the classical strong Morse inequalities.

The exterior derivative restricted to \(S_f\) has the form

\[ d[S_p] = \sum_{q \in CR(f)} n_{pq}[S_q]. \]

By a result of Federer the constants \(n_{pq}\) are integers, and so

\[ S^*_f = \text{span}_Z\{[S_p]\}_{p \in CR(f)} \]

is a finite-rank subcomplex of the integral currents \(I_*(X)\) on \(X\). Using (0.2) we show that the inclusion \(S^*_f \subset I_*(X)\) induces an isomorphism

\[ H^*(S^*_f) \cong H^*(X; \mathbb{Z}). \]

In the special case of Morse-Smale flows the integers \(n_{pq}\) can be computed by counting flow lines from \(p\) to \(q\). This follows from Stokes’ Theorem (cf. [25] and §4).

Poincaré duality (over \(\mathbb{Z}\)) is now directly deduced from time-reversal in the flow (§5).

The analogous relative theorems for a Morse exhaustion function on a non-compact manifold, including Alexander-Lefschetz duality, are proved in §7.

Our method of proof involves converting the operator equation (0.2) to a kernel equation

\[ \partial T = [\Delta] - P \]

on \(X \times X\), where \(\Delta\) denotes the diagonal. There is a general correspondence between operators \(K : E^*(X) \to D'^*(X)\) of degree \(\ell\) and currents \(K\) of dimension \(n - \ell\) on \(X \times X\) ([23], See Appendix A.) Under this transformation: \(I\) corresponds to \([\Delta]\), the pull-back of forms by \(\varphi_t\) corresponds to the graph of \(\varphi_t\), and the chain homotopy \(d \circ K + K \circ d\)
corresponds to the current boundary $\partial K$. Thus equation (0.4) carries
back directly to equation (0.2).

The current $T$ in (0.4) is simply defined by integration over the graph
of the relation $\zeta$. If the space-time graph $\mathcal{T}_\varphi$ has finite volume, then
$T = \text{pr}_\ast \mathcal{T}_\varphi$ where $\text{pr} : \mathbb{R} \times X \times X \to X \times X$ is the projection. Our
finite-volume assumption on $T$ implies that $T$ is a rectifiable current and
therefore that its current boundary is flat in the sense of Federer [13].
Applying the Federer Support Lemma, we conclude that

$$(0.5) \quad P = \sum_{p \in \mathcal{C}(f)} [U_p] \times [S_p].$$

Thus, $T$ provides a homology between the diagonal and the sum of
Künneth currents in $X \times X$ given by products of the unstable and sta-
able manifolds of the flow. In other words, our Morse function gives a
canonical chain approximation to the diagonal together with an explicit
homology. This “transgression current” $T = T_f$ plays a role in defining
more subtle invariants of manifolds and knots.

The entire procedure outlined above can be applied to functions with
non-degenerate critical manifolds, i.e., functions of Bott-type. Suppose
$f$ is such a function and $F_j$, $j = 1, \ldots, \nu$ are the connected components
of the critical set. In this case the kernel $P$ in (0.4) is written as a sum
of fibre-products

$$(0.6) \quad P = \sum_{j=1}^{\nu} [U_j \times F_j, S_j].$$

of the stable and unstable manifolds of the flow. Here the subcomplex
image$(P)$ is not finite-dimensional. However, for each smooth form $\alpha$
we have

$$P(\alpha) = \sum_{j=1}^{\nu} \text{Res}_j(\alpha)[S_j]$$

where $\text{Res}_j(\alpha)$ is a smooth, integrable residue form on the manifold $S_j$
computed directly in terms of $\alpha$.

This approach works nicely in the case of holomorphic $\mathbb{C}^*$-actions
with fixed-points on Kähler manifolds. Here there is an underlying func-
tion of Bott-type. One finds a complex analogue of the current $T$ and
replaces equation (0.4) with a $\partial\bar{\partial}$-equation. General results of Sommese
imply that $T$ and all of the stable and unstable manifolds of the flow
are subvarieties of finite-volume. One retrieves, in particular, classical
results of Bialynicki-Birula [5] and of Carrell-Lieberman-Sommese [8],
[9]. The approach also fits directly into MacPherson’s Grassmann graph construction and Gillet-Soule’s construction of transgression classes appearing in the refined Riemann-Roch Theorem [16].

The arguments apply literally without change to the case of equivariant cohomology. It yields rapid calculations in certain cases and has been used by J. Latschev to derive a spectral sequence associated to functions in the equivariant case.

The method can be applied to derive an equation of forms and currents which relates the singularities of a smooth bundle map $A : E \to F$ to characteristic forms of $E$ and $F$. For normal bundle maps, i.e., those which are transversal to the universal singularity sets in Hom$(E, F)$, this yields local proof of a classical topological formula of MacPherson [27],[28]. However, the method also yields formulas in many other cases, such as generic direct sum and tensor product mappings [19], [20]. This work, which is discussed briefly in §9, began in [17] and led to the Morse Theory presented here.

Much has been written about assigning topological invariants of manifolds and knots to “Feynman graphs”. Primary invariants of this type, such as those discussed in [3] and [4], can be constructed using operators $P$. The invariants of Kontsevich and Vasseliev (cf. [26], [7]) involve the currents $T$.

It should be remarked that while the Morse Theory due to Ed Witten [36] involves the de Rham complex, it is distinctly different from the approach presented here. Witten considers the conjugates $d_t$ of exterior differentiation $d$ by the function $e^{-tf}$ for $t \geq 0$ and examines the asymptotics of the associated Hodge laplacians. Elliptic operators do not enter the story in our approach. Moreover, a crucial simplifying component of our approach (namely, the calculus of [23] for the operator $d$) is not available for other operators such as the Laplacian or $d_t$. It would be interesting to find a more direct connection between the two theories.

The idea of using the stable manifolds of a generic gradient flow to give a cell structure to a manifold goes back to R. Thom [35] (See also [32] and [31] ). F. Laudenbach was the first to consider the stable manifolds as de Rham currents [25]. He studied Morse-Smale flows and computed the boundary operator in the Thom-Smale complex by using Stokes’ Theorem as we do here. The concept of finite volume flows and its use in Morse Theory were introduced in [21]. This article contains an expanded and more leisurely account of the basic ideas presented there. Furthermore, several additional results are included here.

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1. Flows of finite volume

Let $X$ be a compact smooth manifold of dimension $n$, and let $\varphi_t : X \to X$ be the flow generated by a smooth vector field $V$ on $X$. Consider the operator $P_t : \mathcal{E}^*(X) \to \mathcal{E}^*(X)$ on the space of smooth differential forms which is given by pull-back

$$P_t(\alpha) \equiv \varphi_t^*(\alpha).$$

We will exhibit a chain homotopy operator $T_t : \mathcal{E}^k(X) \to \mathcal{E}^{k-1}(X)$ satisfying

$$(A) \quad d \circ T_t + T_t \circ d = I - P_t,$$

and show that under a “finite volume” condition it is possible to take the limit as $t \to \infty$. We thereby obtain operators

$$(B) \quad T = \lim_{t \to \infty} T_t \quad \text{and} \quad P = \lim_{t \to \infty} P_t$$

satisfying:

$$(C) \quad d \circ T + T \circ d = I - P.$$

Now operator equations such as (A) and (C) are difficult to solve directly, but as we shall see in §3, they can be converted into current equations on the product manifold $X \times X$ which are much more tractable. For example, equation (A) becomes the current equation

$$(A) \quad \partial T_t = [\Delta] - P_t \quad \text{on} \quad X \times X$$

where $\Delta \subset X \times X$ is the diagonal and

$$P_t = [\text{graph}(\varphi_t)] = \{(\varphi_t(x), x) : x \in X\}$$

is the (reverse) graph of the diffeomorphism $\varphi_t$. The remaining conditions are that

$$(B) \quad T = \lim_{t \to \infty} T_t \quad \text{and} \quad P = \lim_{t \to \infty} P_t$$

exist and satisfy

$$(C) \quad \partial T = [\Delta] - P \quad \text{on} \quad X \times X.$$ 

Here $T_t$, $T$, and $P$ are currents on $X \times X$ yet to be determined. Details of the above correspondence are discussed in §3. The remainder of this section is devoted to solving the second set of equations (A), (B), (C).
Equation (A) is particularly easy to solve. Consider the family of compact manifolds with boundary:

\[(1.1) \quad \mathcal{T}_t \equiv \{(s, \varphi_s(x), x) : 0 \leq s \leq t \text{ and } x \in X\}\]

contained in \(\mathbb{R} \times X \times X\). Obviously, \(\mathcal{T}_t\) has the two boundary components \(\{0\} \times \Delta\) and \(\{t\} \times P_t\). Assume \(X\) is oriented (this condition will be dropped later) and orient \(\mathcal{T}_t\) so that

\[(1.2) \quad \partial \mathcal{T}_t = \{0\} \times \Delta - \{t\} \times P_t.\]

Let \(\text{pr} : \mathbb{R} \times X \times X \to X \times X\) denote projection and set

\[(1.3) \quad T_t \equiv (\text{pr})_\ast(\mathcal{T}_t).\]

Since \(\partial\) commutes with \((\text{pr})_\ast\), the push-forward of (1.2) by \(\text{pr}_\ast\) gives equation (A).

The current \(\mathcal{T}_t\) can be equivalently defined by

\[(1.3') \quad T_t = \Phi_\ast([0,t] \times X)\]

where \(\Phi : \mathbb{R} \times X \to X \times X\) is the smooth mapping given by \(\Phi(s,x) = (\varphi_s(x), x)\). This mapping is an immersion exactly on the subset \(\mathbb{R} \times (X - Z(V))\) where \(Z(V) = \{x \in X : V(x) = 0\}\). Thus if we fix a riemannian metric \(g\) on \(X\), then \(\Phi_\ast(g \times g)\) is a symmetric positive semi-definite tensor whose associated volume is \(> 0\) exactly on the subset \(\mathbb{R} \times (X - Z(V))\).

This brings us to one of the central concepts of the paper.

**Definition 1.1.** A flow \(\varphi_s\) on \(X\) is called a **finite volume flow** if \(\mathbb{R}^+ \times (X - Z(V))\) has finite volume with respect to the metric induced by the immersion \(\Phi\). (This concept is independent of the choice of riemannian metric on \(X\).)

**Theorem 1.2.** Let \(\varphi_t\) be a finite volume flow on a compact manifold \(X\). Then both the limits

\[(B) \quad P \equiv \lim_{t \to \infty} [\text{graph} \varphi_t] \quad \text{and} \quad T \equiv \lim_{t \to \infty} T_t\]

exist as currents, and by taking the boundary of \(T\) we obtain the equation of currents

\[(C) \quad \partial T = [\Delta] - P \quad \text{on} \quad X \times X.\]

relating \(P\) to the diagonal \(\Delta\) in \(X \times X\).
Proof. Since \( \varphi_t \) is a finite-volume flow, the current \( T \equiv \Phi_\ast((0, \infty) \times X) \) is the limit in the mass norm of the currents \( T_t = \Phi_\ast((0, t) \times X) \) as \( t \to \infty \). The continuity of the boundary operator and equation (A) imply the existence of \( \lim_{t \to \infty} P_t \) and also establish equation (C). q.e.d.

Remark 1.3. Since \( (\varphi_t(x), x) = (y, \varphi_{-t}(y)) \) if \( y = \varphi_t(x) \), it follows that
\[
T^\ast = \Phi_\ast((0, \infty) \times X)
\]
is also a well-defined current for a finite-volume flow. It corresponds to the push-forward of \( T \) under the flip \((y, x) \mapsto (x, y)\) on \( X \times X \).

Remark 1.4. The immersion \( \Phi : \mathbb{R} \times (X - Z(V)) \to X \times X \) is an embedding outside the subset \( \mathbb{R} \times \text{Per}(V) \) where
\[
\text{Per}(V) = \{x \in X : \varphi_t(x) = x \text{ for some } t > 0\}
\]
are the non-trivial periodic points of the flow. Thus, if \( \text{Per}(V) \) has measure zero, then \( T_t \) is given by integration over the embedded finite-volume submanifold \( \Phi(R_t) \), where \( R_t = (0, t) \times (X - Z(V) \cup \text{Per}(V)) \).

If furthermore the flow has finite volume, then \( T \) is given by integration over the embedded, finite-volume submanifold \( \Phi(R_\infty) \).

There is evidence that any flow with periodic points cannot have finite volume. Now a gradient flow never has periodic points, and many such flows are of finite volume (§14.). However, finite-volume flows are more general than gradient flows. For a first example, note that any flow with fixed points on \( S^1 \) has finite volume.

Remark 1.5. If we define a relation on \( X \times X \) by setting \( x \preceq y \) if \( y = \varphi_t(x) \) for some \( 0 \leq t < \infty \), then \( T \) is just the (reversed) graph of this relation. This relation is always transitive and reflexive, and it is antisymmetric if and only if \( \varphi_t \) has no periodic orbits (i.e., \( \preceq \) is a partial ordering precisely when \( \varphi_t \) has no periodic orbits).

Remark 1.6. A standard method for showing that a given flow is finite volume can be outlined as follows. Pick a coordinate change \( t \mapsto \rho \) which sends \( +\infty \) to 0 and \([t_0, \infty]\) to \([0, \rho_0]\). Then show that
\[
T \equiv \{(\rho, \varphi_t(\rho)(x), x) : 0 < \rho < \rho_0\}
\]
has finite volume in \( \mathbb{R} \times X \times X \).

Pushing forward to \( X \times X \) then yields the current \( T \) with finite mass.

Perhaps the most natural such coordinate change is \( r = 1/t \). Another natural choice (if the flow is considered multiplicatively) is \( s = e^{-t} \). Of
course finite volume in the \( r \) coordinate insures finite volume in the \( s \) coordinate since \( r \mapsto s = e^{-1/r} \) is a \( C^\infty \)-map.

Many interesting flows can be seen to be finite volume as follows.

**Proposition 1.7.** If \( X \) is analytic and \( T \subset \mathbb{R} \times X \times X \) is contained in a real analytic subvariety of dimension \( n+1 \), then \( \varphi_t \) is a finite volume flow.

**Proof.** The manifold points of a real analytic subvariety have (locally) finite volume. q.e.d.

A flow need not be a gradient flow to be a finite volume flow.

**Example 1.8.** (The standard degenerate flow on \( S^n \)) Consider the translational flow \( \varphi_t(y) = y + tu \) on \( \mathbb{R}^n \) where \( u \in \mathbb{R}^n \) is a unit vector. We can identify \( \mathbb{R}^n \) with \( S^n - \{\infty\} \) so that \( \varphi_t \) extends to \( S^n \) as a finite volume flow. To do this choose coordinates \( x = y/|y|^2 \) on \( \mathbb{R}^n \cong S^n - \{0\} \). Then

\[
(1.5) \quad \varphi_t(x) = \frac{|x|^2}{|x + t|x|^2u|^2}(x + t|x|^2u)
\]

(The vector field \( V = \frac{\partial\varphi_t}{\partial t}|_{t=0} \) is given by \( V(y) = u \) on \( \mathbb{R}^n = S^n - \{\infty\} \), and by \( V(x) = |x|^2u - 2(x, u)x \) on \( \mathbb{R}^n = S^n - \{0\} \).)

The flow \( \varphi_t \) is finite volume flow on \( S^n \). To see this let \( r = 1/t \) and note that

\[
T = \{(r, z, x) : z = \varphi_{1/r}(x), 0 < r < \infty \text{ and } x \in \mathbb{R}^n = S^n - \{0\}\}
\]

is defined by

\[
z|rx + |x|^2u|^2 = |x|^2r(rx + |x|^2u)
\]

so that Proposition 1.7 is applicable. Note that \( \infty \) (\( x = 0 \)) is the only zero of \( V \). Although \( V \) is not a gradient vector field, it is the limit of gradient vector fields.

Our next problem is to explicitly compute the current \( P \) and its associated operator \( P \) under additional assumptions on the flow. We shall show that when \( V \) is a "good" gradient vector field for a Morse function, the operator \( P \) is projection onto the finite complex of currents spanned by the stable manifolds of the flow. Furthermore, for any given Morse function the "good" gradients are generic.
2. Morse-Stokes flows

Let $f \in C^\infty(X)$ be a Morse function on a compact $n$-manifold $X$, and let $\text{Cr}(f)$ denote the (finite) set of critical points of $f$. Recall that $f$ is a **Morse function** if its Hessian at each critical point is non-degenerate. The standard Morse Lemma asserts that in a neighborhood of each $p \in \text{Cr}(f)$ of index $\lambda$, there exist **canonical local coordinates** $(u_1, \ldots, u_\lambda, v_1, \ldots, v_{n-\lambda})$ for $|u| < r$, $|v| < r$ with $(u(p), v(p)) = (0,0)$ such that

\begin{equation}
  f(u, v) = f(p) - |u|^2 + |v|^2. 
\end{equation}

Choose a Riemannian metric on $X$ and let $\varphi_t$ denote the flow associated to $\nabla f$. Suppose that this metric has the form $|du|^2 + |dv|^2$ in some canonical coordinate system $(u, v)$ about each $p \in \text{Cr}(f)$. Then in these coordinates the gradient flow is given by

$$
\varphi_t(u, v) = (e^{-t}u, e^tv)
$$

Metrics with this property will be called **canonically flat near** $\text{Cr}(f)$ and the flow will be called $f$-**tame**.

Now to each $p \in \text{Cr}(f)$ are associated the **stable** and **unstable manifolds** of the flow, defined respectively by

\begin{equation}
  S_p = \{ x \in X : \lim_{t \to \infty} \varphi_t(x) = p \} \quad \text{and} \quad U_p = \{ x \in X : \lim_{t \to -\infty} \varphi_t(x) = p \}.
\end{equation}

For coordinates $(u, v)$ at $p$, chosen as above, we consider the disks

$$
S_p(\epsilon) = \{(u,0) : |u| < \epsilon\} \quad \text{and} \quad U_p(\epsilon) = \{(0,v) : |v| < \epsilon\}
$$

and observe that

\begin{equation}
  S_p = \bigcup_{-\infty < t < 0} \varphi_t(S_p(\epsilon)) \quad \text{and} \quad U_p = \bigcup_{0 < t < +\infty} \varphi_t(U_p(\epsilon)).
\end{equation}

Hence, $S_p$ and $U_p$ are submanifolds (but not closed subsets) of $X$ with

\begin{equation}
  \dim S_p = \lambda_p \quad \text{and} \quad \dim U_p = n - \lambda_p
\end{equation}

where $\lambda_p$ is the index of the critical point $p$. For each $p$ we choose an orientation on $U_p$. This gives an orientation on the normal bundle of $S_p$ via the splitting $T_pX = T_pU_p \oplus T_pS_p$. We thereby obtain a kernel $[U_p] \times [S_p]$ on $X \times X$ (See A.9.).

The flow $\varphi_t$ induces a partial ordering on $X$ by setting $x \prec y$ if there is a continuous path consisting of a finite number of forward-time orbits,
which begins with $x$ and ends with $y$. We shall see in the proof of Lemma 2.4 that this is the closure of the partial ordering of Remark 1.5.

**Definition 2.1.** The gradient flow of a Morse function $f$ on a riemannian manifold $X$ is called **Morse-Stokes** if it is $f$-tame and:

(i) It is a finite-volume flow.

(ii) Each of the stable and unstable manifolds $S_p$ and $U_p$ for $p \in \text{Cr}(f)$ has finite volume.

(iii) If $p \prec q$ and $p \neq q$ then $\lambda_p < \lambda_q$, for all $p, q \in \text{Cr}(f)$.

**Remark 2.2.** In Section 14 we shall prove that if the gradient flow of $f$ is Morse-Smale, then it is Morse-Stokes. Furthermore, for any Morse function $f$ on a compact manifold $X$ there exist Riemanninan metrics on $X$ for which the gradient flow of $f$ is Morse-Stokes. In fact these metrics are dense in the set of all metrics which are canonically flat near $\text{Cr}(f)$.

**Theorem 2.3.** Let $f \in C^\infty(X)$ be a Morse function on a compact riemannian manifold whose gradient flow is Morse-Stokes. Then there is an equation of integral currents

\begin{equation}
\partial T = [\Delta] - P
\end{equation}

on $X \times X$, where $T$ is an embedded submanifold of finite volume, $\Delta \subset X \times X$ is the diagonal, and where

\begin{equation}
P = \sum_{p \in \text{Cr}(f)} [U_p] \times [S_p]
\end{equation}

**Proof.** For each critical point $p \in \text{Cr}(f)$ we define

$$\tilde{U}_p \overset{\text{def}}{=} \bigcup_{p \prec q} U_q = \{x \in X : p \prec x\}.$$

**Lemma 2.4.** Let $f \in C^\infty(X)$ be any Morse function whose gradient flow is of finite volume, and let $\text{spt } P \subset X \times X$ denote the support of the current $P$ defined in Theorem 1.2. Then

$$\text{spt } P \subset \bigcup_{p \in \text{Cr}(f)} \tilde{U}_p \times S_p.$$
Proof. Since \( P = \lim_{t \to \infty} P_t \) and \( P_t = \{(\varphi_t(x), x) : x \in X\} \), it is clear that \((y, x) \in \text{spt} \ P\) only if there exist sequences \( x_i \to x \) in \( X \) and \( s_i \to \infty \) in \( \mathbb{R} \) such that \( y_i \equiv \varphi_{s_i}(x_i) \to y \). Let \( L(x_i, y_i) \) denote the oriented flow line from \( x_i \) to \( y_i \). Since the lengths of these lines are bounded, an elementary compactness argument shows that a subsequence converges to a piecewise flow line \( L(x, y) \) from \( x \) to \( y \). By the continuity of the boundary operator on currents, \( \partial L(x, y) = [y] - [x] \). Finally, since \( s_i \to \infty \) there must be at least one critical point on \( L(x, y) \), and we define \( p = \lim_{s \to \infty} \varphi_s(x) \). q.e.d.

Consider now the subset

\[
\Sigma \equiv \bigcup_{p \neq q} U_q \times S_p \subset X \times X.
\]

and set \( \Sigma' = \Sigma \cup \{(p, p) : p \in \text{Cr}(f)\} \). Note that from (2.4) and Axiom (iv) in Definition 2.1 that

\[
(2.7) \quad \Sigma' \text{ is a disjoint union of submanifolds of dimension } \leq n - 1.
\]

Lemma 2.5. Let \( f \in C^\infty(X) \) be a Morse function and \( \varphi_t \) an \( f \)-tame gradient flow. Consider the embedded submanifold

\[
T = \{(y, x) : x \notin \text{Cr}(f), \text{ and } y = \varphi_t(x) \text{ for some } 0 < t < \infty\}.
\]

of \( X \times X - \Sigma' \). Then the closure \( \overline{T} \) of \( T \) is a proper \( C^\infty \)-submanifold with boundary

\[
\partial \overline{T} = \Delta - \sum_{p \in \text{Cr}(f)} U_p \times S_p
\]

in \( X \times X - \Sigma' \).

Proof. We first show that it will suffice to prove the assertion in a neighborhood of \((p, p) \in X \times X \) for \( p \in \text{Cr}(f) \). Consider \((\bar{y}, \bar{x}) \in \overline{T} - T\). If \((\bar{y}, \bar{x}) \notin \Sigma'\), then the proof of Lemma 2.4 shows that either \((\bar{y}, \bar{x}) \in \Delta \) or \((\bar{y}, \bar{x}) \in U_p \times S_p \) for some \( p \in \text{Cr}(f) \). Near points \((\bar{x}, \bar{x}) \in \Delta, \bar{x} \notin \text{Cr}(f)\), one easily checks that \( \overline{T} \) is a submanifold with boundary \( \Delta \). If \((\bar{y}, \bar{x}) \in U_p \times S_p \), then for sufficiently large \( s > 0 \), the diffeomorphism \( \psi_s(y, x) \equiv (\varphi_{-s}(y), \varphi_s(x)) \) will map \((\bar{y}, \bar{x})\) into any given neighborhood of \((p, p)\). Note that \( \psi_s \) leaves the subset \( U_p \times S_p \) invariant, and that \( \psi_s^{-1} \)
maps \( T \) into \( T \). Hence, if \( \partial T = \Delta - U_p \times S_p \), in a neighborhood of \((p, p)\), then \( \partial T = -U_p \times S_p \) near \((y, \bar{y})\).

Now in a neighborhood \( \mathcal{O} \) of \((p, p)\) we may choose coordinates as in (2.1) so that \( T \) consists of points \((y, x) = (\bar{u}, \bar{v}, u, v)\) with \( \bar{u} = e^{-t}u \) and \( \bar{v} = e^{t}v \) for some \( 0 < t < \infty \). Consequently, in \( \mathcal{O} \) the set \( \bar{T} \) is given by the equations

\[
\bar{u} = su \quad \text{and} \quad \bar{v} = s\bar{v} \quad \text{for some} \quad 0 \leq s \leq 1.
\]

This obviously defines a submanifold in \( \mathcal{O} - \{(p, p)\} \) with boundary consisting of \( \Delta \) and the set \( \{\bar{u} = 0, \ \bar{v} = 0\} \cong (U_p \times S_p) \cap \mathcal{O} \). q.e.d.

Lemma 2.5 has the following immediate consequence

\[
(2.8) \quad \text{spt} \left\{ P - \sum_{p \in \text{Cr}(f)} U_p \times S_p \right\} \subset \Sigma'
\]

We now apply the following important result of Federer.

**Proposition 2.6.** ([13, 4.1.20]) *Let \( S \) be a flat current of dimension \( k \) in \( \mathbb{R}^n \). If the Hausdorff \( k \)-measure of the support of \( S \) is zero, then \( S = 0 \).

Recall that if \( S \) is a current defined by integration over an oriented submanifold of locally finite volume, then both \( S \) and \( dS \) are flat. (In fact for such currents having the further property that \( dS \) is supported in a submanifold \( N \) with \( \dim(N) < \dim(dS) \), Proposition 2.6 has an elementary proof [13, 4.1.15].) Combining Proposition 2.6 with (2.7) and (2.8) proves (2.6) and completes the proof of Theorem 2.3. q.e.d.

Related to Proposition 2.6 is the following result of Federer ([13, 4.1.15], [13, 4.2.16(2)]).

**Proposition 2.7.** *Let \( S \) be a flat current of dimension \( k \) with \( dS = 0 \) defined in a convex open subset \( U \) of \( \mathbb{R}^n \). If \( \text{spt}(S) \subset U \cap \mathbb{R}^k \), then \( S = c[U \cap \mathbb{R}^k] \) for some \( c \in \mathbb{R} \). Moreover, if \( S = dT \) where \( T \) is locally rectifiable, then \( c \) is an integer.*

Propositions 2.6 and 2.7 are philosophically central to our paper.

**Remark 2.8.** Using the flow given in Example 1.8 and the methods above, one constructs an \((n + 1)\)-current \( T \) on \( S^n \times S^n \) with the property that

\[
\partial T = S^n \times \{\ast\} + \{\ast\} \times S^n.
\]

This is a singular analogue of the form used by Bott and Taubes to study knot invariants [7].
3. From current equations to operator equations

We now explain how to pass from the current equations (A), (B), (C) to the operator equations (A), (B), (C) discussed in §1. This kernel calculus was introduced in [23]. There is a brief appendix on currents with definitions and notation at the end of the paper. The discussion here includes the non-orientable case.

Let \( X \) and \( Y \) be compact manifolds, and let \( \pi_Y \) and \( \pi_X \) denote projection of \( Y \times X \) onto \( Y \) and \( X \) respectively. Then each partially twisted current (or kernel) \( K \in \mathcal{D}'(Y \times \bar{X}) \), determines an operator \( \mathbf{K} : \mathcal{E}^*(Y) \to \mathcal{D}'^*(X) \) by the formula

\[
\mathbf{K}(\alpha) = (\pi_X)_*(K \wedge \pi_Y^*\alpha).
\]

The formula (3.1) can be rewritten as

\[
\mathbf{K}(\alpha)(\beta) = K(\pi_Y^*\alpha \wedge \pi_X^*\beta)
\]

where \( \beta \in \widetilde{\mathcal{E}}^*(X) \) is a twisted form on \( X \). This definition is motivated by the following example.

**Example 3.1.** Suppose \( \varphi : X \to Y \) is a smooth map, and let \( \mathbf{P}_\varphi(\alpha) \equiv \varphi^*(\alpha) \) be the pull-back operator on \( \alpha \) on differential forms. Now a differential form \( \varphi^*\alpha \) defines a current by setting

\[
(\varphi^*\alpha)(\beta) \equiv \int_X (\varphi^*\alpha) \wedge \beta
\]

for all twisted forms \( \beta \in \widetilde{\mathcal{E}}^*(X) \). Consider the graph of \( \varphi \) given by graph \( \varphi = \{ (\varphi(x), x) : x \in X \} \subset Y \times X \). Integration over the graph of \( \varphi \) determines a kernel or (partially twisted) current on \( Y \times X \), by this same formula (3.2). Namely,

\[
[\text{graph } \varphi](\pi_Y^*\alpha \wedge \pi_X^*\beta) \equiv \int_X \varphi^*\alpha \wedge \beta.
\]

The left hand side equals

\[
([\text{graph } \varphi] \wedge \pi_Y^*\alpha)(\pi_X^*\beta) = ((\pi_X)_*[\text{graph } \varphi] \wedge \pi_Y^*\alpha)(\beta).
\]

Therefore,

\[
\mathbf{P}_\varphi(\alpha) = (\pi_X)_*[\text{graph } \varphi] \wedge \pi_Y^*\alpha).
\]

To complete the transfer of the operator equations (A) and (C) to current equations on \( X \times X \), we need the following result.
Lemma 3.2. Suppose the operator $K : \mathcal{E}^*(Y) \to \mathcal{D}'^*(X)$ has kernel $K \in \mathcal{D}'^*(Y \times \tilde{X})$. Suppose that $K$ lowers degree by one, or equivalently, that $\deg(K) = \dim Y - 1$. Then

\begin{equation}
(3.5) \quad \text{The operator } \partial \circ K + K \circ \partial \text{ has kernel } \partial K.
\end{equation}

Proof. The boundary operator $\partial$ is the dual of exterior differentiation. That is $\partial K$ is defined by $(\partial K)(\pi_Y^* \alpha \wedge \pi_X^* \beta) = K(d(\pi_Y^* \alpha \wedge \pi_X^* \beta))$. Also, by definition, $(K(d\alpha), \beta) \equiv K(\pi_Y^*(d\alpha) \wedge \pi_X^* \beta)$, and

\[ (d(K(\alpha)), \beta) \equiv (-1)^{\deg \alpha} K(\alpha)(d\beta) = (-1)^{\deg \alpha} K(\pi_Y^*(\alpha) \wedge \pi_X^* d\beta), \]

since $K(\alpha)$ has degree equal to $\deg \alpha - 1$. q.e.d.

The results that we need are summarized in the following table.

<table>
<thead>
<tr>
<th>Operators</th>
<th>Kernels</th>
</tr>
</thead>
<tbody>
<tr>
<td>$I$</td>
<td>$[\Delta]$</td>
</tr>
<tr>
<td>$P_t \equiv \varphi_t^*$</td>
<td>$P_t \equiv [\text{graph } \varphi_t]$</td>
</tr>
<tr>
<td>$K$</td>
<td>$K$</td>
</tr>
<tr>
<td>$\partial \circ K + K \circ \partial$</td>
<td>$\partial K$</td>
</tr>
</tbody>
</table>

Table 3.6

This completes the transfer of the operator equations (A), (B), (C) to the current equations (A), (B), (C). From Theorems 1.2 and 2.3 we immediately deduce the following.

Theorem 3.3. Let $f \in C^\infty(X)$ be a Morse function on a compact Riemannian manifold $X$ whose gradient flow $\varphi_t$ is Morse-Stokes. Then for every differential form $\alpha \in \mathcal{E}^k(X)$, $0 \leq k \leq n$, one has

\[ P(\alpha) = \lim_{t \to \infty} \varphi_t^* \alpha = \sum_{p \in \text{Cr}(f)} r_p(\alpha)[S_p] \]

where the “residue” $r_p(\alpha)$ of $\alpha$ at $p$ is defined by

\[ r_p(\alpha) = \int_{U_p} \alpha \]

if $k = n - \lambda$ and 0 otherwise. Furthermore, there is an operator $T$ of degree -1 on $\mathcal{E}^*(X)$ with values in flat currents, such that

\begin{equation}
(3.7) \quad d \circ T + T \circ d = I - P
\end{equation}
From Theorem 3.3, we see that \( P : \mathcal{E}^*(X) \to \mathcal{D}'^*(X) \) maps onto the finite-dimensional subspace of currents

\[
S_f \overset{\text{def}}{=} \text{span}_R \{ [S_p] \}_{p \in \text{Cr}(f)}
\]

and that

\[
P \circ d = d \circ P.
\]

This together with (3.7) leads to the following.

**Corollary 3.4.** The subspace \( S_f \) is \( d \)-invariant and is therefore a subcomplex of \( \mathcal{D}'^*(X) \). The surjective linear map of cochain complexes

\[
\hat{P} : \mathcal{E}^*(X) \to S_f
\]

defined by \( P \) induces an isomorphism

\[
\hat{P} : H^*_{deR}(X) \overset{\simeq}{\to} H^*(S_f).
\]

**Proof.** It follows immediately from Theorem 3.3 that

\[
P_* = I_* : H(\mathcal{E}^*(X)) \to H(\mathcal{D}'^*(X)),
\]

and by [11], \( I_* \) is an isomorphism. Since \( i_* \circ \hat{P}_* = P_* \), where \( i : S^*_f \to \mathcal{D}'^*(X) \) denotes the inclusion, we see that \( \hat{P}_* \) is injective.

However, it does not follow formally that \( \hat{P}_* \) is surjective (as the example below shows). We must prove that every \( S \in S^*_f \) with \( dS = 0 \) is of the form \( S = P(\gamma) \) where \( d\gamma = 0 \).

To do this we note the following consequence of 2.1(iii). For all \( p, q \in \text{Cr}(f) \) of the same index, one has that \( \overline{S}_p \cap \partial U_q = \emptyset \), \( \overline{S}_p \cap \overline{U}_q = \emptyset \) if \( p \neq q \), and \( \overline{S}_p \cap \overline{U}_q = \{ p \} \). Now let \( S = \sum n_p S_p \) be a \( k \)-cycle in \( S_f \). Then by the above there is an open neighborhood \( N \) of \( \text{spt}(S) \) such that \( N \cap \partial U_q = \emptyset \) for all \( q \) of index \( k \). Since by [11] cohomology with compact supports can be computed by either smooth forms or all currents, there exists a current \( \sigma \) with compact support in \( N \) such that \( d\sigma = \gamma - S \) where \( \gamma \) is a smooth form. Now for each \( q \) of index \( k \), \( U_q \) is a closed submanifold of \( N \), and we can choose a family \( U_s \) of smooth closed forms in \( N \) such that \( \lim_{s \to 0} U_s = U_q \) in \( \mathcal{D}'(N) \) and \( \lim_{s \to 0} (S_p, U_s) = (S_p, U_q) = \delta_{pq}[p] \) for all \( p \in \text{Cr}(f) \) of index \( k \). This is accomplished via standard Thom form
constructions for the normal bundle using canonical coordinates at \( q \) (e.g. [17]). It follows that \( (\gamma - S, U_q) = \lim_{\epsilon \to 0}(\gamma - S, U_\epsilon) = \lim_{\epsilon \to 0}(d\sigma, U_\epsilon) = \lim_{\epsilon \to 0}(\sigma, dU_\epsilon) = 0 \). We conclude that \( \int_{U_q} \gamma = (S, U_q) = n_q \) for all \( q \) and so \( P(\gamma) = S \) as claimed.

Alternatively, one can choose an \( \epsilon > 0 \) such that \((\text{spt} \, S)_\epsilon \cap \partial U_q = \emptyset\) for all \( q \) of index \( k \), where \((\text{spt} \, S)_\epsilon\) denotes an \( \epsilon \)-neighborhood of \( \text{spt} \, S \). Applying the Federer smoothing homotopy [13, 4.1.18] gives a current \( H_\epsilon(S) \) with \( \text{spt} \, H_\epsilon(S) \subset (\text{spt} \, S)_\epsilon\) and \( dH_\epsilon(S) = \gamma - z \) where \( \gamma \) is a smooth closed form. Since \( (\gamma - S, U_q) = (dH_\epsilon(S), U_q) = (H_\epsilon(S), \partial U_q) = 0 \) we conclude as above that \( \int_{U_q} \gamma = (S, U_q) = n_q \) for all \( q \) and therefore \( P(\gamma) = S \). q.e.d.

**Example.** Consider the short exact sequence of complexes

\[
0 \longrightarrow K = \mathbb{R}\{a\} \longrightarrow \mathcal{E} = \mathbb{R}\{a, b\} \xrightarrow{\hat{P}} S = \mathbb{R}\{b'\} \longrightarrow 0
\]

where \( a = db, \, db' = 0 \) and \( \hat{P}(b) = b' \). Define \( \mathcal{D} = \mathbb{R}\{a, b, b', c\} \) with \( b' = dc \) and let \( i : S \to \mathcal{D} \) denote the inclusion. Define \( T : \mathcal{E} \to \mathcal{D} \) by \( T(a) = b \) and \( T(b) = -c \), and \( I : \mathcal{E} \to \mathcal{D} \) by \( I(a) = a, I(b) = b \), and \( P : \mathcal{E} \to \mathcal{D} \) by \( P = i \circ \hat{P} \). Then \( dt + td = I - P \), but \( \hat{P}_* \) is not surjective on homology.

4. \( \mathbb{Z} \)-complexes, \( \mathbb{Z}/p\mathbb{Z} \)-complexes

We now observe that the complex \((S_f, d)\) is actually defined over the integers. Consider the lattice

\[
S^\mathbb{Z}_f \overset{\text{def}}{=} \text{span}_\mathbb{Z}\{[S_p]\}_{p \in Cr(f)}
\]

and note that \( S^\mathbb{Z}_f \) forms a subgroup of the integral currents \( \mathcal{I}(X) \) on \( X \).

**Theorem 4.1.** The lattice \( S^\mathbb{Z}_f \) is preserved by exterior differentiation \( d \), that is, \((S^\mathbb{Z}_f, d)\) is a subcomplex of \((S_f, d)\). Furthermore, the inclusion of complexes \((S^\mathbb{Z}_f, d) \subset (\mathcal{I}(X), d) \) induces an isomorphism

\[
H(S^\mathbb{Z}_f) \cong H_*(X; \mathbb{Z})
\]

**Proof.** Corollary 3.4 implies that for any \( p \in Cr(f) \) we have

\[
d[S_p] = \sum_{\lambda_q = \lambda_p - 1} n_{p,q} \, [S_q]
\]
for real numbers \( n_{p,q} \). Furthermore, since \([S_p]\) is rectifiable, we have \( n_{p,q} \in \mathbb{Z} \) for all \( p, q \) by Proposition 2.7, and the first assertion is proved.

Now the domain of the operator \( P \) extends to include any \( C^1 \) chain \( c \) which is transversal to the submanifolds \( U_p, \ p \in Cr_k(f) \), while the domain of \( T \) extends to any \( C^1 \) chain \( c \) for which \( c \times X \) is transversal to \( T \). Standard transversality arguments show that such chain groups (over \( \mathbb{Z} \)) compute \( H_\ast(X; \mathbb{Z}) \). The result then follows from (3.7). q.e.d.

**Corollary 4.2.** Let \( G \) be a finitely generated abelian group. Then there are natural isomorphisms

\[
H(S^Z_f \otimes Z G) \cong H_\ast(X; G).
\]

Note that the proof of Theorem 4.1 can be used to give an alternate proof of Corollary 3.4.

Part one of Theorem 4.1 has an elementary proof when the flow is **Morse-Smale**, which means by definition that \( S_p \) is transversal to \( U_q \) for all \( p, q \in Cr(f) \). Suppose the flow is Morse-Smale and that \( p, q \in Cr(f) \) are critical points with \( \lambda_q = \lambda_p - 1 \). Then \( U_q \cap S_p \) is the union of a finite set of flow lines from \( q \) to \( p \) which we denote \( \Gamma_{p,q} \). To each \( \gamma \in \Gamma_{p,q} \) we assign an index \( n_\gamma \) as follows. Let \( B_\varepsilon \subset S_p \) be a small ball centered at \( p \) in a canonical coordinate system (cf. (2.1)), and let \( y \) be the point where \( \gamma \) meets \( \partial B_\varepsilon \). The orientation of \( S_p \) induces an orientation on \( T_y(\partial B_\varepsilon) \), which is identified by flowing backward along \( \gamma \) with \( T_q(S_q) \). If this identification preserves orientations we set \( n_\gamma = 1 \), and if not, \( n_\gamma = -1 \). As in [25] Stokes’ Theorem gives us the following (cf. [36]).

**Proposition 4.3.** When the gradient flow of \( f \) is Morse-Smale, the coefficients in (4.1) are given by

\[
n_{p,q} = (-1)^{\lambda_p} \sum_{\gamma \in \Gamma_{p,q}} n_\gamma
\]

**Proof.** Given a form \( \alpha \) of degree \( \lambda_p - 1 \), we have

\[
(-1)^{\lambda_p} d[S_p](\alpha) = \int_{S_p} d\alpha = \lim_{r \to \infty} \int_{dS_p(r)} \alpha
\]

where \( S_p(r) = \varphi_{-r}(S_p(\varepsilon)) \) as in §3. It suffices to consider forms \( \alpha \) with support near \( q \) where \( \lambda_q = \lambda_p - 1 \). Near such \( q \), the set \( S_p(r) \), for large \( r \), consists of a finite number of manifolds with boundary, transversal to \( U_q \). There is one for each \( \gamma \in \Gamma_{p,q} \). As \( r \to \infty \) along one such \( \gamma \), \( dS_p(r) \)
converges to \( \pm S_q \) where the sign is determined by the agreement (or not) of the orientation of \( dS_p(r) \) with the chosen orientation of \( S_q \). q.e.d.

**Remark 4.4.** The integers \( n_{p,q} \) have a simple definition in terms of currents. Set \( S_p(r) = \varphi_{-r}(S_p(\epsilon)) \) and \( U_q(r) = \varphi_r(U_q(\epsilon)) \) (cf. (2.3)). Then for all \( r \) sufficiently large

\[
(4.2) \quad n_{p,q} = (-1)^{hp} \int_X [U_q(r)] \wedge d[S_p(r)]
\]

where the integral denotes evaluation on the fundamental class.

5. Duality

There is a simple proof of Poincaré duality in this context. Suppose that \( X \) is compact and oriented. Given two oriented submanifolds \( A \) and \( B \) of complementary dimensions in \( X \) which meet transversally in a finite number of points, we define \( A \cdot B = \int_X [A] \wedge [B] \) to be the algebraic number of intersections points (counting a point \( \pm 1 \) depending on orientations as usual). Let \( Cr_k(f) = \{ p \in Cr(f) : \lambda_p = k \} \). Then for any \( k \) we have

\[
(5.1) \quad U_q \cdot S_p = \delta_{pq} \quad \text{for all} \quad p, q \in Cr_k(f).
\]

This gives a formal identification

\[
(5.2) \quad \mathcal{U}_f^Z \overset{\text{def}}{=} \mathbb{Z} \cdot \{ [U_p] \}_{p \in Cr(f)} \cong \text{Hom}\left(S^Z_f, \mathbb{Z}\right).
\]

Therefore, taking the adjoint of \( d \) gives a differential \( \delta \) on \( \mathcal{U}_f^Z \) with the property that \( H_{n-*}(\mathcal{U}_f^Z, \delta) \cong H^*(X; \mathbb{Z}) \). On the other hand the arguments of \( \S\S 1-4 \) (with \( f \) replaced by \( -f \)) show that \( \mathcal{U}_f^Z \) is \( d \)-invariant with \( H_*(\mathcal{U}_f^Z, d) \cong H_*(X; \mathbb{Z}) \). However, these two differentials on \( \mathcal{U}_f^Z \) agree up to sign as we see in the next lemma.

**Lemma 5.1.** One has

\[
(5.3) \quad (dU_q) \cdot S_p = (-1)^{n-k} U_q \cdot (dS_p)
\]

for all \( p \in Cr_k(f) \) and \( q \in Cr_{k-1}(f) \), and for any \( k \).

**Proof.** One can see directly from the definition that the integers \( n_{p,q} \) are invariant (up to a global sign) under time-reversal in the flow. However, for a simple current-theoretic proof consider the 1-dimensional
current \([U_q(r)] \wedge [S_p(r)]\) consisting of a finite sum of oriented line-segments in the flow lines of \(\Gamma_{p,q}\) (cf. Remark 4.4). Note that

\[
d ([U_q(r)] \wedge [S_p(r)]) = (d[U_q(r)]) \wedge [S_p(r)] + (-1)^{n-k+1} [U_q(r)] \wedge (d[S_p(r)])
\]

and apply (4.2). q.e.d.

**Corollary 5.2.** (Poincaré Duality)

\[H^{n-k}(X; \mathbb{Z}) \cong H_k(X; \mathbb{Z}) \quad \text{for all } k.\]

**Note 5.3.** In our operator picture the Poincaré duality isomorphism can be realized in a nice way. Let

\[T_{tot} = T^* + T = \{(y, x) : y = \varphi_t(x) \text{ for some } t \in \mathbb{R}\}.
\]

Then we obtain the operator equation

\[d \circ T_{tot} + T_{tot} \circ d = P - \tilde{P}
\]

where

\[P = \sum_{p \in Cr(f)} [U_p] \times [S_p] \quad \text{and} \quad \tilde{P} = \sum_{p \in Cr(f)} [S_p] \times [U_p].\]

This chain homotopy induces an isomorphism \(H_*(U_1^2) \cong H_*(C_1^2)\), which after identifying \(U_1^2\) with the cochain complex via (5.1) and (5.3), gives the duality isomorphism 5.2. When \(X\) is not oriented, a parallel analysis yields Poincaré duality with mod 2 coefficients.

6. Critical submanifolds of higher dimension

The methods introduced above apply in much greater generality. As seen in §1, one only needs the flow \(\varphi_t\) to be of finite volume to guarantee the existence of an operator \(P(\alpha) = \lim_{t \to \infty} \varphi_t^*(\alpha)\) which is chain homotopic to the identity. In this and the following sections we shall examine some important examples.

Let \(f : X \to \mathbb{R}\) be a smooth function whose critical set (i.e., the set where \(df = 0\)) is a finite disjoint union

\[Cr(f) = \prod_{j=1}^\nu F_j\]
of compact submanifolds $F_j$ in $X$. We assume that $\text{Hess}(f)$ is non-degenerate on the normal spaces to $Cr(f)$. Then for any $f$-tame gradient flow (cf. [24]) there are stable and unstable manifolds

$$S_j = \{ x \in X : \lim_{t \to \infty} \varphi_t(x) \in F_j \} \text{ and } U_j = \{ x \in X : \lim_{t \to -\infty} \varphi_t(x) \in F_j \}$$

with projections

(6.1)\[ S_j \xrightarrow{\tau_j} F_j \xleftarrow{\sigma_j} U_j.\]

where

$$\tau_j(x) = \lim_{t \to +\infty} \varphi_t(x) \text{ and } \sigma_j(x) = \lim_{t \to -\infty} \varphi_t(x).$$

For each $j$, let $n_j = \dim(F_j)$ and set $\lambda_j = \dim(S_j) - n_j$. Then $\dim(U_j) = n - \lambda_j$. For $p \in F_j$ we define $\lambda_p \equiv \lambda_j$ and $n_p \equiv n_j$.

**Definition 6.1.** The gradient flow $\varphi_t$ of a smooth function $f \in C^\infty(X)$ on a riemannian manifold $X$ is called a **generalized Morse-Stokes flow** if it is $f$-tame and:

(i) The critical set of $f$ consists of a finite number of submanifolds $F_1, \ldots, F_\nu$ on the normals of which $\text{Hess}(f)$ is non-degenerate.

(ii) The manifolds $T$, and $T^*$, and the stable and unstable manifolds $S_j, U_j$ for $1 \leq j \leq \nu$ are submanifolds of finite volume. Furthermore, for each $j$, the fibres of the projections $\tau_j$ and $\sigma_j$ are of uniformly bounded volume.

(iii) $p < q \Rightarrow \lambda_p + n_p < \lambda_q \quad \forall p, q \in Cr(f)$.

These axioms are easily verified in a number of important cases in the algebraic and analytic category. The first main result concerning such flows is the following.

**Theorem 6.2.** Suppose $\varphi_t$ is a gradient flow satisfying the generalized Morse-Stokes conditions 6.1 on a compact oriented manifold $X$. Then there is an equation of currents

$$\partial T = [\Delta] - P$$

on $X \times X$, where $T, \Delta, \text{ and } P$ are as in Theorem 1.2, and

(6.2)\[ P = \sum_{j=1}^\nu [U_j \times_{F_j} S_j].\]
where \( U_j \times_{F_j} S_j \equiv \{(y, x) \in U_j \times S_j \subset X \times X : \sigma_j(y) = \tau_j(x)\} \) denotes the fibre product of the projections (6.1)

**Proof.** The argument follows closely the proof of Theorem 2.3. Details are omitted. q.e.d.

Janko Latschev has found a Smale-type condition which yields this result in many cases where the hypothesis of 6.1 (iii) does not hold. In particular, Latschev’s condition implies only that: \( p < q \Rightarrow \lambda_p < \lambda_q \). Details appear in [24].

As in §3, this result can be translated into operator form.

**Theorem 6.3.** Let \( \varphi_t \) be a gradient flow satisfying the generalized Morse-Stokes Conditions on a manifold \( X \) as above. Then for all smooth forms \( \alpha \) on \( X \), the limit

\[
P(\alpha) = \lim_{t \to \infty} \varphi_t^*(\alpha)
\]

exists and defines a continuous linear operator \( P : \mathcal{E}^*(X) \to \mathcal{D}'^*(X) \) with values in flat currents on \( X \). This operator fits into a chain homotopy

\[
d \circ T + T \circ d = I - P.
\]

Furthermore, \( P \) is given by the formula

\[
P(\alpha) = \sum_{j=1}^{\nu} \text{Res}_j(\alpha) [S_j]
\]

where

\[
\text{Res}_j(\alpha) \equiv \tau_j^* \{ (\sigma_j)_* \left( \alpha|_{U_j} \right) \}.
\]

**Proof.** This is a direct consequence of Theorem 6.2 except for the formulae (6.4)-(6.5). To see this consider the pull-back square

\[
\begin{array}{ccc}
U_j \times_{F_j} S_j & \xrightarrow{t_j} & U_j \\
\downarrow s_j & & \downarrow \sigma_j \\
S_j & \xrightarrow{\tau_j} & F_j
\end{array}
\]

where \( t_j \) and \( s_j \) are the obvious projections. One sees from the definitions (cf §3) that

\[
P(\alpha) = \sum_{j=1}^{\nu} (s_j)_* \{ (t_j)_* \left( \alpha|_{U_j} \right) \}.
\]
The commutativity of the diagram (6.6) allows us to rewrite these terms as in (6.5). q.e.d.

**Corollary 6.4.** Suppose that \( \lambda_p + n_p + 1 < \lambda_q \) for all critical points \( p < q \). Then the homology of \( X \) is spanned by the images of the groups \( H_{\lambda_j + \ell}(\overline{S_j}) \) for \( j = 1, \ldots, \nu \) and \( \ell \geq 0 \).

**Proof.** Under this hypothesis \( \partial(U_j \times F_j, S_j) = 0 \) for all \( j \), and so (6.2) yields a decomposition of \( P \) into operators that commute with \( d \). q.e.d.

We can make this corollary more precise. Note that \( \tau_j : S_j \to F_j \) can be given the structure of a vector bundle of rank \( \lambda_j \). The closure \( \overline{S_j} \subset X \) is a compactification of this bundle with a complicated structure at infinity. (See [10] for example.) There is nevertheless a homomorphism \( \Theta_j : H_*(F_j) \to H_{\lambda_j + \ell}(\overline{S_j}) \) which after pushing forward to the one-point compactification of \( S_j \), is the Thom isomorphism. This leads to the following (cf. [2]).

**Theorem 6.5.** Suppose that \( \lambda_p + n_p + 1 < \lambda_q \) for all critical points \( p < q \) and that \( X \) and all \( F_j \) and \( S_j \) are oriented. Then there is an isomorphism

\[
H_*(X) \cong \bigoplus_j H_{* - \lambda_j}(F_j)
\]

This result holds without the orientation assumptions if one takes homology with appropriately twisted coefficients. Much stronger versions of Theorems 6.3 and 6.5, are found in [24]. They include an extension to integral homology groups. Latschev also derives a spectral sequence associated to any Bott-Smale function satisfying a natural Smale-type transversality hypothesis. One virtue of this sequence is that the differentials are explicitly computable. Assuming for simplicity that everything is oriented, the \( E^1 \)-term is given by

\[
E^1_{p,q} = \bigoplus_{\lambda_j = p} H_q(F_j; \mathbb{Z})
\]

and \( E^k_{p,q} \Rightarrow H_*(X; \mathbb{Z}) \)

---

7. The relative case

In standard Morse Theory one often studies the change in the topology as one passes from \( \{ x : f(x) \leq a \} \) to \( \{ x : f(x) \leq b \} \). Our approach is easily adapted to this case.
Let $f : X \to \mathbb{R}$ be a proper Morse function, where $X$ is not necessarily compact, and suppose that $X$ carries a metric as in 14.3. Let $a < b$ be regular values of $f$ and consider the compact manifold with boundary

$$Z \equiv f^{-1}([a,b]).$$

On $Z$ we define a vector field $V = (\psi \circ f) \nabla f$ where $\psi : [a, b] \to [0, 1]$ is a smooth function satisfying: (i) $\psi^{-1}(0) = \{a, b\}$, (ii) $\psi$ is linear on $[a, a+\epsilon]$ and $[b-\epsilon, b]$, (iii) $\psi \equiv 1$ on $[a+2\epsilon, b-2\epsilon]$, (iv) $f(Cr(f)) \cap Z \subset (a+2\epsilon, b-2\epsilon)$ for some small $\epsilon > 0$.

Let $\varphi_t : Z \to Z$ be the flow of $V$. Note that $\varphi_t$ is complete and fixes the boundary $\partial Z$. By 14.3, the stable and unstable manifolds of each $p \in Cr(f)$ have finite volume in $Z$, and so also does $T \equiv \{(y, x) : y = \varphi_t(x)\}$ for some $t$, $0 < t < \infty \subset Z \times Z$.

We decompose the boundary

$$\partial Z \equiv f^{-1}(b) - f^{-1}(a) \overset{\text{def}}{=} \partial_b - \partial_a.$$ 

In analogy with the fibre products appearing in §6 we have the following submanifolds of $Z \times Z$:

$$S(\partial_b) = \{(y, x) \in Z \times Z : y \in \partial_b \text{ and } \lim_{t \to \infty} \varphi_t(x) = y\} \quad \text{and}$$

$$U(\partial_a) = \{(y, x) \in Z \times Z : x \in \partial_a \text{ and } \lim_{t \to -\infty} \varphi_t(y) = y\}.$$ 

**Theorem 7.1.** On $Z \times Z$ there is an equation of integral currents

$$\partial T = [\Delta] - \sum_{p \in Cr(f) \cap Z} [U_p] \times [S_p] - [U(\partial_a)] - [S(\partial_b)].$$

**Proof.** Consider $T_t \subset \mathbb{R} \times X \times X$ defined as in (1.1) and note that

$$\partial T_t = \{0\} \times [\Delta_t] - \{t\} \times [\text{graph } \varphi_t] - [0, t] \times [\Delta_{\partial Z}] + [\Delta_{\partial Z}] - [\text{graph } \varphi_t].$$

Set $T_t = \text{pr}_* T_t$ and observe that since $\text{pr}_*([0, t] \times [\Delta_{\partial Z}]) = 0$,

$$\partial T_t = [\Delta] - [\text{graph } \varphi_t].$$

By hypothesis $T = \lim_{t \to \infty} T_t$ has finite volume, and a direct application of the arguments of §2 establishes (7.1). q.e.d.

Equation (7.1) can be translated to an operator equation. However, here we want the operator to act on the relative forms:

$$\mathcal{E}^*(Z, \partial_b) \equiv \left\{ \alpha \in \mathcal{E}^*(Z) : \alpha|_{\partial_b} = 0 \right\}.$$
We begin with the case where \( f > a \) and so \( \partial_a = \emptyset \).

**Theorem 7.2.** Suppose \( f : X \to \mathbb{R}^+ \) is a proper Morse function. Let \( Z = f^{-1}(-\infty, b] \) where \( b \) is a regular value of \( f \), and consider the operator
\[
P : \mathcal{E}^*(Z, \partial Z) \to \mathcal{D}'^*(Z)
\]
defined by
\[
(7.3) \quad P(\alpha) = \lim_{t \to \infty} \varphi_t^*(\alpha)
\]
where \( \varphi_t \) is the truncated gradient flow defined above. This operator is well defined and continuous. In fact, there exists a continuous operator \( T : \mathcal{E}^*(Z, \partial Z) \to \mathcal{D}'^*(Z) \) of degree -1 with values in flat currents, such that
\[
(7.4) \quad d \circ T + T \circ d = I - P
\]
Furthermore, \( P \) is given by the formula
\[
(7.5) \quad P(\alpha) = \sum_{p \in Cr(f) \cap Z} r_p(\alpha)[S_p]
\]
where \( r_p(\alpha) = \int_{U_p} \alpha \). In particular, \( P \) is a continuous chain mapping onto the finite dimensional complex
\[
S_{f,Z} \overset{\text{def}}{=} \text{span}_{\mathbb{R}} \{ [S_p] \}_{p \in Cr(f) \cap Z},
\]
with differential given as in (4.1), and \( P \) induces an isomorphism
\[
H^*_{deR}(Z, \partial Z) \cong H(S_{f,Z}).
\]

**Proof.** This is deduced exactly as are Theorems 3.3, 4.1. We need only note that the operator given by \( [S(\partial_b)] \) is zero on \( \mathcal{E}^*(Z, \partial Z) \). This follows directly from the definition 3.1 and the fact that \( \pi_1(S(\partial_b)) = \partial_b = \partial Z \). q.e.d.

In the more general case where \( \partial_a \neq \emptyset \) we compose our operators with the projection map \( \pi : \mathcal{E}^*(Z)' \to \mathcal{E}^*(Z, \partial Z)' \), which is adjoint to the inclusion \( \mathcal{E}^*(Z, \partial Z) \subset \mathcal{E}^*(Z) \). In this case the operator corresponding to \([U(\partial_a)]\) is zero. Specifically, letting \( \pi_k : X \times X \to X \) denote projection onto the \( k \)th factor, we have that
\[
(U(\partial_a)(\alpha), \beta) = ((\pi_1)_* \{ \pi_2^* \alpha \wedge [U(\partial_a)] \}, \beta) = 0
\]
since \( \pi_1(U(\partial_a)) = \partial_a \) and \( \beta|_{\partial_a} = 0 \). We conclude the following.

**Theorem 7.3.** The operators

\[
T, P : \mathcal{E}^*(Z, \partial_b Z) \longrightarrow \mathcal{D}^*(Z, \partial_a Z)
\]

corresponding to the currents \( T, P \) from Theorem 7.2 satisfy the equation

\[
d \circ T + T \circ d = I - P
\]

where

\[
P = \sum_{p \in \mathcal{C}(f) \cap Z} r_p [S_p]
\]

and \( r_p(\alpha) = \int_{\alpha} \alpha \). Thus, \( P \) gives a continuous chain mapping of the relative deRham complex \( \mathcal{E}^*(Z, \partial_b) \) onto the finite dimensional complex

\[
\mathcal{S}_{f,Z} \overset{\text{def}}{=} \text{span}_k \{ [S_p] \}_{p \in \mathcal{C}(f) \cap Z}
\]

with differential given as in 3.5. This induces an isomorphism

\[
H^*_\text{deR}(Z, \partial_b Z) \cong H(\mathcal{S}_{f,Z}).
\]

**Remark 7.4.** Taking \( \partial_b Z = \emptyset \) and \( \partial_a Z \neq \emptyset \) in Theorem 7.3 (and interchanging the roles of \( a \) and \( b \)) gives the version of Theorem 7.2 corresponding to going backwards in time. That is, one considers

\[
P(\alpha) \overset{\text{def}}{=} \lim_{t \to -\infty} \varphi_t^* \alpha
\]

and obtains a projection operator

\[
P : \mathcal{E}^*(Z) \longrightarrow \mathcal{S}_{f,Z} \subset \mathcal{D}^*(Z, \partial_b)
\]

where \( \mathcal{S}_{f,Z} \) is a finite complex defined over \( \mathbb{Z} \).

**Remark 7.5. (Duality)** Arguing exactly as in §5 one can retrieve the duality theorem

\[
H^k(Z, \partial_b Z; \mathbb{Z}) \cong H_{n-k}(Z, \partial_a Z : \mathbb{Z})
\]

which gives, in the special case where either \( \partial_a Z = 0 \) or \( \partial_b Z = 0 \), the Lefschetz Duality Theorem.
8. Holomorphic flows and the Carrell-Lieberman-Sommese theorem

The ideas in this paper have interesting consequences in the holomorphic case. Given a $\mathbb{C}^*$-action $\varphi_t$ on a compact Kähler manifold $X$, there is a complex graph

$$\mathcal{T} \overset{\text{def}}{=} \{ (t, \varphi_t(x), x) \in \mathbb{C}^* \times X \times X : t \in \mathbb{C}^* \text{ and } x \in X \} \subset \mathbb{P}^1(\mathbb{C}) \times X \times X$$

similar to the graphs considered above. It is a basic result of Sommese [34] that if $\varphi_t$ has fixed-points, then $\mathcal{T}$ has finite volume and its closure $\overline{\mathcal{T}}$ in $\mathbb{P}^1(\mathbb{C}) \times X \times X$ is an analytic subvariety.

$\mathbb{C}^*$-actions with fixed-points on Kähler manifolds are intimately related to Morse-Theory. The complex action $\varphi_t$ can be decomposed into an “angular” $S^1$-action and a radial flow. Choosing an $S^1$-invariant Kähler metric and applying an argument of Frankel [13] gives a function $f : X \to \mathbb{R}$ of Bott-Morse type whose gradient generates the radial action. The methods of this paper can now be applied. In particular we find that $\overline{\mathcal{T}}$ defines a rational equivalence in $X \times X$ between the diagonal $\Delta$ and an analytic cycle $P$ whose components are fibre products of stable and unstable manifolds over components of the fixed-point set.

When the fixed-points are all isolated, $P$ becomes a sum of analytic Künneth components $P = \sum \overline{S}_p \times \overline{U}_p$. This immediately implies that the cohomology of $X$ is freely generated by the stable subvarieties $\{ \overline{S}_p \}_{p \in \text{Zero}(\varphi)}$. Furthermore, it follows that $X$ is algebraic and that all cohomology theories on $X$ (e.g. algebraic cycles modulo rational equivalence, algebraic cycles modulo algebraic equivalence, singular cohomology) are naturally isomorphic. (cf. [5], [12], [14]).

When the fixed-point set has positive dimension, this method yields results of Carrell-Lieberman-Sommese for $\mathbb{C}^*$-actions ([8], [9]), which assert among other things that if $\dim(X^{\mathbb{C}^*}) = k$, then $H^{p,q}(X) = 0$ for $|p - q| > k$.

9. Singularities and characteristic classes

The ideas in this paper also have an interesting application to the study of curvature and singularities. Suppose

$$\alpha : E \longrightarrow F$$

is a map between smooth vector bundles with connection over a manifold $X$. Let $G = G_k(E \oplus F) \to X$ denote the Grassmann bundle of $k$-planes in
$E \oplus F$ where $k = \text{rank}(E) \leq \text{rank}(F)$. There is a flow $\varphi_t$ on $G$ induced by the flow $\psi_t : E \oplus F \to E \oplus F$ where $\psi_t(e, f) = (te, f)$. This is a very simple generalized Morse-Stokes flow on $G$ (written multiplicatively rather than additively). On the “affine chart” $\text{Hom}(E, F) \subset G$, one has that $\varphi_t(A) = \frac{t}{t}A$. One considers the graph $T$ of the flow in the fibre product of $G$ with itself, and one obtains the equation $\partial T = \Delta - P$ where $\Delta$ is the fibre diagonal and $P$ is a sum of fibre products of stable and unstable manifolds. In the affine chart $\text{Hom}(E, F)$, the stable manifolds are exactly the universal singularity sets $\Sigma_\ell$ consisting of linear maps $A : E \to F$ of rank $k - \ell$.

Passing to the associated operators as in §3 and applying the resulting chain homotopy to Chern-Weil characteristic forms of the tautological bundle $U$ over $G$ leads to a “universal McPherson Formula” on $\text{Hom}(E, F)$. To pull this formula back to $X$ we introduce the following concept.

**Definition 9.1.** The section $\alpha$ is said to be geometrically atomic if the submanifold

$$T(\alpha) \defeq \{ \frac{t}{t} \alpha(x) \in G : 0 < t \leq 1 \text{ and } x \in X \}$$

has locally finite volume in $G$.

This hypothesis is sufficient to guarantee the existence of $\lim_{t \to 0} \alpha_t^* \phi$ where $\alpha_t \equiv \frac{t}{t} \alpha$ and where $\phi$ is any differential form on $G$. Choosing $\phi = \Phi(\Omega_U)$ where $\Phi$ is an $\text{Ad}$-invariant polynomial on $\mathfrak{gl}_k(\mathbb{R})$ and $\Omega_U$ is the curvature of the tautological $k$-plane bundle over $G$, one obtains the following formula for the $\Phi$ characteristic form of $E$:

$$\Phi(\Omega_E) = \sum_{\ell} \text{Res}_{\ell, \Phi} [\Sigma_{\ell}(\alpha)] + dT$$

where $\Sigma_{\ell}(\alpha)$ is a current associated to the locus where $\alpha$ drops rank by $\ell$, $\text{Res}_{\ell, \Phi}$ is an explicit residue form defined along $\Sigma_{\ell}(\alpha)$, and $T$ is an $L^1_{\text{loc}}$-form on $X$.

For bundle maps which are normal, i.e., transversal to the universal singularity sets in $\text{Hom}(E, F)$, this gives a local version of a basic formula of MacPherson [27], [28]. However, many important classes of bundle mappings, such as direct sum and tensor product mappings, are not normal but are generically geometrically atomic. In these cases the explicit formulas given by (9.1) are new even at the global (cohomological) level.

The critical idea is to study the operator from forms on $G$ to currents on $X$ whose “kernel” is given by $T(\alpha)$. The method is analogous to that of §6. Details appear in [19], [20].
When the residues in (9.1) are integers, the form $T$ represents a Cheeger-Simons differential character canonically associated to $\alpha$ and the connections on $E$ and $F$ (cf. [22]).

10. Equivariant Morse theory

The ideas developed here carry over virtually intact to the setting of equivariant cohomology. The reason the method works directly is the simple but important fact that a closed, invariant submanifold is equivariantly closed (See Corollary 10.2 below). In this section we derive some consequences of the method which usefully apply to Morse functions arising in algebra and geometry (e.g., from moment map constructions). Deeper results have been obtained by J. Latschev [24]. We shall adopt the exposition of Cartan’s equivariant de Rham theory found in [6].

Let $G$ be a compact Lie group with Lie algebra $\mathfrak{g}$ acting on a compact $n$-manifold $X$. An equivariant differential form on $X$ is a $G$-equivariant polynomial map $\alpha : \mathfrak{g} \rightarrow \mathcal{E}^*(X)$. The set of such forms is denoted by

$$\mathcal{E}^*_G(X) = \{ S^*(\mathfrak{g}^*) \otimes \mathcal{E}^*(X) \}^G$$

and is graded by defining elements of $S^p(\mathfrak{g}^*) \otimes \mathcal{E}^q(X)$ to have total degree $2p + q$. The equivariant differential $d_G : \mathcal{E}^*_G(X) \rightarrow \mathcal{E}^{*+1}_G(X)$ is defined by setting

$$(d_G\alpha)(V) = d\alpha(V) - i_V\alpha(V)$$

for $V \in \mathfrak{g}$ where the vector field $\tilde{V}$ is the image of $V$ under the natural linear map $\mathfrak{g} \rightarrow \Gamma(TX)$, and where $i_V$ denotes contraction with $\tilde{V}$.

The complex $\mathcal{D}'_G(X)$ of equivariant currents is defined analogously by passing from smooth forms to generalized forms, i.e., forms with distribution coefficients.

Suppose now that $f \in C^\infty(X)$ is a $G$-invariant function and $X$ is provided with a $G$-invariant riemannian metric. Then $g_*\nabla f = \nabla f$ for all $g \in G$ and so the gradient flow of $f$ commutes with the action of $G$. Suppose this flow has finite volume and let

$$(10.1) \quad \partial T = \Delta - P$$

denote the equation discussed in §1. Let $G$ act on $X \times X$ by the diagonal action $g \cdot (x, y) = (gx, gy)$.

**Lemma 10.1.** The currents $T$ and $P$ are $G$-invariant and have the property that $i_{\tilde{V}} T = i_{\tilde{V}} P = 0$ for all $V \in \mathfrak{g}$. 
Proof. The current $T$ corresponds to integration over the finite volume submanifold \( \{(x, y) \in X \times X - \Delta : \exists t \in (0, \infty) \text{ s.t. } y = \varphi_t(x)\} \). Since $g\varphi_t(x) = \varphi_t(gx)$, the invariance of $T$ is clear. The invariance of $P$ then follows from (10.1). For the second assertion note that since $V$ is tangent to $T$, \( (i_V T)(\omega) = \int_T i_V \omega = 0 \) for any $n$-form $\omega$ on $X \times X$. From the equation $d \circ i_V + i_V \circ d = \mathcal{L}_V$ (Lie derivative) and the fact that $\mathcal{L}_V T = i_V \Delta = 0$, we conclude that $i_V P = 0$. q.e.d.

Corollary 10.2. Consider $T \equiv 1 \otimes T \in 1 \otimes \mathcal{D}^n(X \times X)^G$ as an equivariant current of total degree $(n - 1)$ on $X \times X$. Consider $\Delta$ and $P$ similarly as equivariant currents of degree $n$. Then

\begin{equation}
\partial_G T = \Delta - P.
\end{equation}

in the complex of equivariant currents on $X \times X$.

The dictionary given between operators and kernels in §1 carries over directly to this context. Currents in $\mathcal{D}^{n-\ell}_G(X \times X)$ correspond to $G$-equivariant operators $\mathcal{E}^*(X) \rightarrow \mathcal{D}^{\ast+\ell}_G(X)$, and therefore give operators $\mathcal{E}^*_G(X) \rightarrow \mathcal{D}^{\ast+\ell}_G(X)$. Equation (10.2) corresponds to the operator equation

\begin{equation}
d_G \circ \mathbf{T} + \mathbf{T} \circ d_G = I - \mathbf{P},
\end{equation}

and the discussion of §3 proves the following.

Proposition 10.3. Let $X$ be a compact $G$-manifold and $\varphi_t$ an invariant flow of finite volume on $X$. Then for all $\alpha \in \mathcal{E}_G^*(X)$ the limit

\begin{equation}
P(\alpha) = \lim_{t \to \infty} \varphi_t^* \alpha
\end{equation}

exists and defines a continuous linear operator $P : \mathcal{E}_G^*(X) \rightarrow \mathcal{D}^\circ_G(X)$ of degree 0, which is equivariantly chain homotopic to the identity on $\mathcal{E}_G^*(X)$.

Applying the methods of §§2–3 and the fact that $S^*(g^*)^G \cong H^*(BG)$ gives the following result.

Theorem 10.4. Let $X$ be a compact riemannian $G$-manifold and $f \in C^\infty(X)$ an invariant Morse function whose gradient flow $\varphi_t$ is Morse-Stokes. Then the continuous linear operator (10.4) defines a map of equivariant complexes

\[ P : \mathcal{E}_G^*(X) \rightarrow S^*(g^*)^G \otimes S_f \]
where $S_f = \text{span}\{[S_p]\}_{p \in C_r(f)}$ as in (3.8) and the differential on $S^*(\mathfrak{g}^*)^G \otimes S_f$ is $1 \otimes \partial$. The map $P$ induces an isomorphism

$$H_G^*(X) \xrightarrow{\cong} H^*(BG) \otimes H^*(X)$$

For an example of this phenomenon consider the torus acting on $\mathbb{P}_C^n$ via the standard action on homogeneous coordinates $[z_0, ..., z_n]$, and set $f([z]) = \sum k|z_k|^2/\|z\|^2$. One sees immediately the well-known fact that $H_C^*(\mathbb{P}_C^n)$ is a free $H^*(BG)$-module with one generator in each dimension $2k$ for $k = 0, ..., n$. This extends to generalized flag manifolds and to products.

It has been pointed out by Janko Latschev that there exists an invariant Morse function for which no choice of invariant metric gives a Morse-Stokes flow.

On the other hand the method applies to much more general functions and yields results as in §§5-9. Suppose for example that $f$ is an invariant function whose critical set consists of a finite number of non-degenerate critical orbits $O_i = G/H_i$, $i = 1, ..., N$. Latschev (cf. [24], [1]) has established a spectral sequence $E^k_{*,*} \Rightarrow H_G^*(X)$ with computable differentials and (assuming for simplicity that everything is oriented)

$$E^1_{p,*} = \bigoplus_{\lambda_i = p} H_G^*(O_i) = \bigoplus_{\lambda_i = p} H^*(BH_i).$$

11. Flat bundles and local coefficients

The constructions in this paper can be generalized to forms with coefficients in a flat bundle $E \to X$. The kernels of §2 become currents on $X \times X$ with coefficients in $\text{Hom}(\pi_1^*E, \pi_2^*E)$ where $\pi_1$ and $\pi_2$ are the obvious projections. More specifically suppose that $\varphi_t$ is a Morse-Stokes flow on $X$ with kernel $T$ constructed exactly as in §2. Then given a flat bundle $E$ we define the kernel $T_E$ with coefficients in $\text{Hom}(\pi_1^*E, \pi_2^*E)$ by $T_E = h \otimes T$ where and $h : E_{\varphi_t(x)} \to E_x$ is parallel translation along the flow line. It is straightforward to compute that

$$(11.1) \quad \partial T_E = \Delta_E - P_E$$

where $\Delta_E = \text{Id} \otimes \Delta$ and $P_E = \sum_p h_p \otimes ([U_p] \times [S_p])$ with $h_p : E_y \to E_x$ given by parallel translation along the broken flow line from $y$ to $x$. Note that under the canonical trivializations $E|_{U_p} \cong U_p \times E_p$ and $E|_{S_p} \cong$
$S_p \times E_p$, the map $h_p$ becomes the identity $\text{Id} : E_p \to E_p$. Corresponding to (11.1) we have the operator equation

\[(11.2) \quad d \circ T_E + T_E \circ d = I - P_E\]

where $P_E$ maps onto the finite vector space

$$S_E \overset{\text{def}}{=} \bigoplus_{p \in Cr(f)} E_p \otimes [S_p]$$

by integration of forms over the unstable manifolds. By (11.2) this space is $d$-invariant. In fact in the Morse-Smale case the restriction of $d$ to $S_E$ is given as in 4.3 by

$$d(e \otimes [S_p]) = \sum h_{p,q}(e)[S_q]$$

where $h_{p,q} = (-1)^{h_p} \sum_{\gamma} h_{\gamma}$ and $h_{\gamma} : E_p \to E_q$ is parallel translation along $\gamma \in \Gamma_{p,q}$. By (11.2) the complex $(S_E, d)$ computes $H^*(X; E)$. Reversing time in the flow shows that the complex $U_E = \bigoplus E_p' \otimes [U_p]$ with differential defined as above computes $H^*(X; E^*)$. As in §5 the obvious dual pairing of these complexes establishes the generalized Poincaré duality. Furthermore, one can extend all this to integral currents twisted by representations of $\pi_1(X)$ in $\text{GL}_n(\mathbb{Z})$ or $\text{GL}_n(\mathbb{Z}/p\mathbb{Z})$ and obtain duality with local coefficient systems.

**12. Products**

Our method has a number of interesting extensions. For example, consider the triple diagonal $\Delta_3 \subset X \times X \times X$ as the kernel of the wedge-product operator

$$\wedge : \mathcal{E}^*(X) \otimes \mathcal{E}^*(X) \to \mathcal{E}^*(X).$$

Let $f$ and $f'$ be functions with Morse-Stokes flows $\varphi_t$ and $\varphi'_t$ respectively. Assume that for all $(p, p') \in Cr(f) \times Cr(f')$ the stable manifolds $S_p$ and $S'_p$ intersect transversely in a manifold of finite volume, and similarly for the unstable manifolds $U_p$ and $U'_p$. Degenerating $\Delta_3$ gives a kernel

$$T \equiv \{(\varphi_t(x), \varphi'_t(x), x) \in X \times X \times X : x \in X \text{ and } 0 \leq t < \infty\}$$

and a corresponding operator $T : \mathcal{E}^*(X) \otimes \mathcal{E}^*(X) \to \mathcal{D}'^*(X)$ of degree -1. One calculates that $\partial T = \Delta_3 - M$ where

$$M = \sum_{(p, p') \in Cr(f) \times Cr(f')} \beta_p \times \beta_p \times [S_p \cap S'_p].$$
The corresponding operator $\mathbf{M} : \mathcal{E}^*(X) \otimes \mathcal{E}^*(X) \to \mathcal{D}'^*(X)$ is given by

$$
(12.1) \quad \mathbf{M}(\alpha, \beta) = \sum_{(p, p') \in C_R(f) \times C_R(f')} \left( \int_{U_p} \alpha \right) \left( \int_{U_{p'}} \beta \right) [S_p \cap S'_{p'}].
$$

The arguments of §§1-3 adapt to prove the following.

**Theorem 12.1.** There is an equation of operators $\wedge - \mathbf{M} = d \circ \mathbf{T} + \mathbf{T} \circ d$ from $\mathcal{E}^*(X \times X)$ to $\mathcal{D}'^*(X)$ (where $\wedge$ denotes restriction to the diagonal). In particular for $\alpha, \beta \in \mathcal{E}^*(X)$ we have the chain homotopy

$$
(12.2) \quad \alpha \wedge \beta - \mathbf{M}(\alpha, \beta) = d\mathbf{T}(\alpha, \beta) + \mathbf{T}(d\alpha, \beta) + (-1)^{deg_{\alpha}} \mathbf{T}(\alpha, d\beta)
$$

between the wedge product and the operator (12.1).

Note that the operator $\mathbf{M}$ has range in the finite dimensional vector space

$$
\mathcal{M} \overset{\text{def}}{=} \text{span}_R \{ [S_p \cap S'_{p'}] \}_{(p, p') \in C_R(f) \times C_R(f')}.
$$

It converts a pair of smooth forms $\alpha, \beta$ into a linear combination of the pairwise intersections of the stable manifolds $[S_p]$ and $[S'_p]$. If $d\alpha = d\beta = 0$, then

$$
(12.3) \quad \mathbf{M}(\alpha, \beta) = \alpha \wedge \beta - d\mathbf{T}(\alpha, \beta),
$$

and so $\mathbf{M}(\alpha, \beta)$ is a cycle homologous to the wedge product $\alpha \wedge \beta$. This operator also has the following properties.

**Theorem 12.2.** The operator $\mathbf{M}$ maps onto the subspace $\mathcal{M}$. Furthermore, for forms $\alpha, \beta \in \mathcal{E}^*(X)$, it satisfies the equation

$$
(12.4) \quad d\mathbf{M}(\alpha, \beta) = \mathbf{M}(d\alpha, \beta) + (-1)^{deg_{\alpha}} \mathbf{M}(\alpha, d\beta)
$$

**Proof.** To see that $\mathbf{M}$ is onto (as a linear map from $\mathcal{E}^*(X \times X)$) it suffices to see that for each non-empty intersection $S_p \cap S'_{p'}$ the current $[S_p \cap S'_{p'}]$ is in the range. However, by transversality we see that if $S_p \cap S'_{p'} \neq \emptyset$, then $\lambda_p + \lambda_{p'} \geq n$, and so $n \geq (n - \lambda_p) + (n - \lambda_{p'})$. Therefore, by transversality we have $\dim(U_q \cap U'_{q'}) \leq 0$ for all $q, q'$. It follows that we can find differential forms $\alpha$ and $\beta$ such that $\int_{U_p} \alpha = \int_{U'_{p'}} \beta = 1$ and $\int_{U_q} \alpha = \int_{U'_{q'}} \beta = 0$ for all $q \neq p$ and $q' \neq p'$. Then by (12.1), $\mathbf{M}(\alpha, \beta) = [S_p \cap S'_{p'}]$ and the assertion is proved.
Equation (12.4) follows from the fact that $dM = 0$, which implies that $d \circ M + M \circ d = 0$, together with the standard formula for $d(\alpha \wedge \beta)$. q.e.d.

It follows immediately that $d(M) \subset M$. In fact one can see from the transversality assumptions that for $(p, p') \in C\tau(f) \times C\tau(f')$ one has

$$
d[S_p \cap S'_{p'}] = \sum_{q \in C\tau(f)} n_{pq}[S_q \cap U'_{p'}] \\
+ (-1)^{n-\lambda_p} \sum_{q' \in C\tau(f')} n_{p'q'}[S_p \cap U'_{q'}]
$$

(12.5)

where the $n_{pq}$ are defined as in §4. Thus we retrieve the cup product over the integers in the Morse complex.

**Example 12.3.** A fundamental example of a pair satisfying our hypotheses is given by $f, -f$ where the gradient flow is Morse-Smale. In this case $U'_p = S_p$ and $S'_p = U_p$ for all $p \in C\tau(f) = C\tau(-f)$. Thus formula (12.1) becomes

$$
M(\alpha, \beta) = \sum_{p, p' \in C\tau(f)} \left( \int_{U_p} \alpha \right) \left( \int_{S'_{p'}} \beta \right) [S_p \cap U'_{p'}].
$$

In particular we have the following.

**Proposition 12.4.** Suppose the gradient flow of $f$ is Morse-Smale. Then for any cycle $Y$ in $X$ which is transversal to all the $S_p \cap U'_{p'}$, $p, p' \in C\tau(f)$, we have the formula

$$
\int_Y \alpha \wedge \beta = \sum_{p, p' \in C\tau(f)} \left( \int_{U_p} \alpha \right) \left( \int_{S'_{p'}} \beta \right) [S_p \cap U'_{p'} \cap Y],
$$

(12.6)

whenever $d\alpha = d\beta = 0$.

**Example 12.5.** Suppose $\deg \alpha = n - \deg \beta = k$. Then (cf. [25, Prop. 12])

$$
\int_X \alpha \wedge \beta = \sum_{p \in C\tau_k(f)} \left( \int_{U_p} \alpha \right) \left( \int_{S'_{p'}} \beta \right).
$$

13. **A Lefschetz theorem for the Thom-Smale complex**

Let $X$ be a compact oriented riemannian manifold, and let $U_p, S_p, p \in C\tau(f)$ be the unstable and stable manifolds of a Morse-Stokes flow.
on $X$, oriented as in §2. Recall the Lefschetz number of a smooth mapping $F : X \to X$ defined by

$$\text{Lef}(F) = \sum_i (-1)^i \text{trace} \{ F_* : H_i(X; \mathbb{R}) \to H_i(X; \mathbb{R}) \}$$

Theorem 13.1. Suppose $F : X \to X$ is a smooth mapping such that $F$ maps $S_p$ transversally to $U_q$ for all $q > p$ (i.e., $F|_{S_p}$ is transversal to $U_p$ and $F(S_p) \cap U_q = \emptyset$ for all $q > p$ and $q \neq p$). Let $C_p = \{ x \in S_p : F(x) \in U_p \}$. Then

$$\text{Lef}(F) = \sum_{p \in C_r(f)} (-1)^p \sum_{x \in C_p} \sigma_x(F)$$

where

$$\sigma_x(F) \overset{\text{def}}{=} \begin{cases} 1 & \text{if } F_*T_x(S_p) \text{ agrees in orientation with} \\ & \text{the normal space to } U_p \text{ at } F(x) \\ -1 & \text{otherwise.} \end{cases}$$

Proof. Our transversality assumption implies that the graph $\Gamma_F = \{(F(x), x) : x \in X\}$ in $X \times X$ meets the cycle $P$ only in its regular points $\bigcup_p U_p \times S_p$ and it is transversal there. We recall that $\text{Lef}(F) = [\Delta] \bullet [\Gamma_F]$ in $X \times X$. By (2.5) and the fact that $\Gamma_F$ and $P$ meet nicely, we conclude that $\text{Lef}(F) = [P] \bullet [\Gamma_F]$ which is easily computed as claimed. q.e.d.

Note that when $F = \text{Id}$, the hypotheses are satisfied and we get the standard computation of the Euler characteristic from the Morse complex.

14. The genericity theorem

Let $f \in C^\infty(X)$ be a Morse function on a compact manifold $X$. In this section we shall prove that there exists a riemannian metric on $X$ for which the gradient flow satisfies the Morse-Stokes conditions of §2. Some of the material in this section could be reduced by appealing to a paper of Laudenbach [25]. For completeness we have included all the details. To begin we recall the following.

Definition 14.1. The gradient flow of $f$ for a riemannian metric on $X$ is called Morse-Smale if the stable and unstable manifolds $S_p$ and $U_q$ intersect transversely for all $p, q \in C^r(f)$. 

To simplify arguments we shall demand a little more. Recall that at each \( p \in C\mathcal{r}(f) \) there exist **canonical local coordinate systems** \( (u, v) : \mathcal{O}_p \stackrel{\sim}{\longrightarrow} \mathcal{V}_p \) where

\[
\mathcal{V}_p = \left\{ (u, v) \in \mathbb{R}^{\lambda_p} \times \mathbb{R}^{n-\lambda_p} : |u|^2 \leq r_p \text{ and } |v|^2 \leq r_p \right\}
\]

such that \( u(p) = v(p) = 0 \) and \( f(u, v) = f(p) - |u|^2 + |v|^2 \).

**Definition 14.2.** A riemannian metric \( ds^2 \) is said to be **canonically flat near** \( C\mathcal{r}(f) \) if \( ds^2 = |du|^2 + |dv|^2 \) in some canonical linear coordinate system about each \( p \in C\mathcal{r}(f) \).

We shall prove the following.

**Theorem 14.3.** Let \( f \in C^\infty(X) \) be a Morse function on a compact manifold \( X \). Suppose \( X \) is given a riemannian metric which is canonically flat near \( C\mathcal{r}(f) \) and for which the gradient flow \( \varphi_t \) is Morse-Smale. Then \( \varphi_t \) satisfies the Morse-Stokes conditions 2.1.

**Theorem 14.4.** If \( f \in C^\infty(X) \) is a Morse function and \( ds^2 \) is any riemannian metric on \( X \), then \( ds^2 \) can be modified outside some neighborhood of \( C\mathcal{r}(f) \) so that \( \varphi_t \) becomes Morse-Smale. In fact this modification can be made arbitrarily small in the \( C^\infty \)-topology.

Taken together these theorems prove the following.

**Theorem 14.5.** Given any Morse function \( f \) on a compact manifold \( X \), there exists a riemannian metric on \( X \) for which the gradient flow is Morse-Stokes.

Furthermore, this metric can be chosen to be canonically flat near \( C\mathcal{r}(f) \).

**Proof of Theorem 14.3.** We first observe that if the flow of \( f \) is Morse-Smale, then

\[
(14.2) \quad p \prec q \quad \Rightarrow \quad \lambda_p < \lambda_q
\]

for all \( p, q \in C\mathcal{r}(f) \). To see this suppose \( p \) and \( q \) are joined by an (unbroken) flow line \( \ell \). Then \( U_p \cap S_q \supset \ell \) and so by the transversality condition, \( \dim(U_p \cap S_q) = (n - \lambda_p) + \lambda_q - n \geq 1 \).

Now let \( a_1 < \cdots < a_m \) be the critical values of \( f \). For each \( a_k \) let \( C\mathcal{r}(f, a_k) \subset C\mathcal{r}(f) \) be the set of critical points of \( f \) with critical value \( a_k \).

Each \( p \in C\mathcal{r}(f, a_k) \) has a canonical local coordinate system as in (14.1) where the metric is flat. We may assume that the radius \( r_p \) is the same for all \( p \in C\mathcal{r}(f, a_k) \). Call this radius \( r_k \). By shrinking the neighborhoods \( O_p \) we may assume that these canonical coordinate systems are pairwise
disjoint and that \( a_{k+1} - r_{k+1} > a_k + r_k \) for all \( k \). Furthermore, by multiplying \( f \) by some scalar \( \alpha \gg 1 \) and further shrinking the \( \mathcal{O}_p \) we can assume that \( r_p = 2 \) for all \( p \in Cr(f) \).

Now our manifold decomposes into “blocks”:

\[
X = P_0 \cup Q_0 \cup P_1 \cup Q_1 \cup P_2 \cup Q_2 \cup \ldots P_m
\]

where

\[
P_k = f^{-1}[a_k - 1, a_k + 1] \quad \text{and} \quad Q_k = f^{-1}[a_k + 1, a_{k+1} - 1].
\]

Note that \( P_k \) and \( Q_k \) are compact manifolds with boundary. The manifolds \( P_k \) can be further decomposed. Let \( \mathcal{O}'_p \subset \mathcal{O}_p \) be the subset defined by the equations \(|u||v| \leq 1 \) and \(-1 \leq |v|^2 - |u|^2 \leq 1 \). Then

\[
P_k = R_k \cup \bigcup_{p \in Cr(f,a_k)} \mathcal{O}'_p
\]

where \( R_k \) is the closure of \( P_k - \bigcup_p \mathcal{O}'_p \).

Let \( \psi_s \) be the (incomplete) flow on \( X - Cr(f) \) generated by \( W \equiv \text{grad} f/\|	ext{grad} f\|^2 \), so that

\[
f(\psi_s(x)) = f(x) + s
\]

whenever \( \psi_s(x) \) is defined. Using this vector field in the obvious way (cf. [29]) we obtain smooth product structures

\[
Q_k \cong (\partial^- Q_k) \times [0,1]
\]

\[
R_k \cong (\partial^- R_k) \times [0,1]
\]

where \( \partial^- Q_k = Q_k \cap f^{-1}(a_k + 1) \) and \( \partial^- R_k = R_k \cap f^{-1}(a_k - 1) \). Note that \( \partial^- R_k \) is a compact manifold with non-empty boundary.

Consider now the unstable manifold \( U_p \) for some \( p \in Cr(f,a_k) \) and some \( k \). We shall show that \( \text{vol}(U_p) < \infty \). To begin note that \( U_p \cap \mathcal{O}'_p \cong \{ (0,v) \in \mathcal{N}_p : |v| \leq 1 \} \) is a smoothly embedded closed disk of dimension \( \ell \equiv n - \lambda_p \) and clearly has finite \( \ell \)-volume. Its boundary \( U_p \cap (\partial^- Q_k) \) is a smoothly embedded sphere, and via (14.4) we have \( U_p \cap Q_k \cong (U_p \cap \partial^- Q_k) \times [0,1] \) which also has finite \( \ell \)-volume.

We now show that \( U_p \cap P_{k+1} \) has finite \( \ell \)-volume. To begin note that via (14.5) we have a smooth product \( U_p \cap R_{k+1} \cong (U_p \cap \partial^- R_{k+1}) \times [0,1] \) (which extends beyond the boundary of \( R_{k+1} \)) so we needn’t worry about
how $U_p$ meets this boundary). Since $U_p \cap \partial^- R_{k+1}$ is a subset of a compact $(\ell - 1)$-manifold, we see that $U_p \cap R_{k+1}$ has finite $\ell$-volume.

It remains to show that $U_p \cap \mathcal{O}_q'$ has finite volume for $q \in \mathcal{C}r(f, a_k)$. This is equivalent to showing that $U_p \cap \mathcal{O}_q''$ has finite volume, where $\mathcal{O}_q''$ is defined by $|u| \leq 1$ and $|v| \leq 1$. (To see this push inward along the flow.) For simplicity, from here on we shall denote $\mathcal{O}_q''$ by $\mathcal{O}_q$ and $\mathcal{V}_q''$ by $\mathcal{V}_q$.

Since $q \triangleright p$ we know from (14.2) that
\[ \dim U_p > \dim U_q. \]

In our local coordinate box $\mathcal{V}_q = \{(u, v) \in \mathbb{R}^{\lambda q} \times \mathbb{R}^{n-\lambda q} : |u| \leq 1, |v| \leq 1\}$ the flow is generated by
\[ \varphi_t(u, v) = (e^{-t}u, e^t v) \] (14.6)

We decompose $\partial \mathcal{V}_q$ into two pieces:
\[ A = \{(u, v) : |u| = 1, |v| \leq 1\} \quad \text{and} \quad B = \{(u, v) : |u| \leq 1, |v| = 1\}. \]

There are subsets
\[ A_0 = A \cap S_q = \{(u, 0) : |u| = 1\} \cong S^{\lambda q - 1}, \]
\[ B_0 = B \cap U_q = \{(0, v) : |v| = 1\} \cong S^{n-\lambda q - 1}. \]

The flow determines a diffeomorphism
\[ \Phi : A - A_0 \xrightarrow{\cong} B - B_0 \]
given by
\[ \Phi(u, v) = \left( |v|u, \frac{1}{|v|}v \right) \]

Note that $\Phi(u, v)$ is the unique point in $B$ which lies on the flow line through $(u, v)$.

Let $\tilde{A} \xrightarrow{\pi_A} A$ be the "oriented blow-up" of $A$ along $A_0$ where $A_0$ is replaced by the oriented normal lines to $A_0$. Let $\tilde{B} \xrightarrow{\pi_B} B$ be defined similarly. $\tilde{A}$ has coordinates $(\tilde{u}, \tilde{v}, t)$ where $|\tilde{u}| = 1$, $|\tilde{v}| = 1$ and $0 \leq t \leq 1$ and $\pi_A(\tilde{u}, \tilde{v}, t) = (\tilde{u}, t\tilde{v})$. $\tilde{B}$ has the same coordinates with $\pi_B(\tilde{u}, \tilde{v}, t) = (t\tilde{u}, \tilde{v})$.

$\Phi$ lifts to a map $\tilde{\Phi} : \tilde{A} \rightarrow \tilde{B}$ which in these coordinates is the identity map (and so, in particular, a diffeomorphism).

Now since $U_p$ is transversal to $S_q$ we know that:
\[ (U_p \cap S_q) \cap \mathcal{V}_q \cong C(U_p \cap A_0) \] (14.7)
where $U_p \cap A_0$ is a compact submanifold of codimension $\lambda_p$ in $A_0$, and where for any subset $Y \subset A_0$, $C(Y)$ is the \textbf{cone} on $Y$ defined by

$$C(Y) = \{(tu, 0) : u \in Y \text{ and } 0 \leq t \leq 1\}$$

Now transversality also tells us that in a neighborhood of

$$Y \equiv U_p \cap A_0$$

the set $U_p \cap A$ is of the form $Y \times \mathbb{R}^{n-\lambda_q}$. Furthermore, $U_p \cap A$ has a "smooth proper transform" to $\tilde{A}$, i.e., the lift of $U_p \cap (A - A_0)$ to $\tilde{A}$ has closure which is a smooth manifold with boundary diffeomorphic to $Y \times S^{n-\lambda_q-1}$. Denote this closure by $\overline{U_p \cap A}$.

We can now describe the structure of $\overline{U_p}$ in our coordinate box. To begin we observe that

$$\overline{U_p \cap B} = \pi_B \tilde{\Phi}(\overline{U_p \cap A})$$

and recall that $\tilde{\Phi}$ is a diffeomorphism. It follows that $\overline{U_p \cap B}$ is a $C^\infty$ stratified set with two strata. The top stratum is $U_p \cap B$. The singular stratum is exactly $B_0 \cong S^{n-\lambda_q-1}$. In a neighborhood of this singular stratum, $\overline{U_p \cap B}$ is diffeomorphic to $C(Y) \times S^{n-\lambda_q-1}$ where $Y = U_p \cap A_0$.

Since $\overline{U_p \cap B}$ is the image of a manifold of finite $(\ell - 1)$-volume (namely $\overline{U_p \cap A}$) under the smooth proper map $\pi_B \circ \tilde{\Phi}$, it follows that $\overline{U_p \cap B}$ has finite $(\ell - 1)$-volume.

**Conclusion 14.6** The closure of $U_p \cap \partial^{-Q_{k+1}}$ is a compact $C^\infty$-stratified set of finite $(\ell - 1)$-volume, whose top stratum is $U_p \cap \partial^{-Q_{k+1}}$.
and whose singular strata are exactly the spheres $U_q \cap \partial^- Q_{k+1}$ for $q \in Cr(f, a_{k+1})$.

From the above analysis we can also conclude that $U_p$ has finite volume in $\mathcal{V}_q$. Set

$$\tilde{\mathcal{V}}_q = S^{\lambda_q-1} \times S^{n-\lambda_q-1} \times [0,1] \times [0,1]$$

and consider the map $\Pi : \tilde{\mathcal{V}}_q \to \mathcal{V}_q$ given by

$$\Pi(\hat{u}, \hat{v}, s, t) = (s\hat{u}, t\hat{v})$$

where $|\hat{u}| = |\hat{v}| = 1$. We identify $\tilde{A}$ with the subset where $s = 1$ (and $\tilde{B}$ with $t = 1$). Then $\Pi$ restricts to be the projections $\pi_A$ and $\pi_B$.

Consider the mapping

$$\Psi : \tilde{\mathcal{V}}_q \to \tilde{A}$$

given by

$$\Psi(\hat{u}, \hat{v}, s, t) = (\hat{u}, \hat{v}, 1, st).$$

Then $\Psi$ has the following two important properties. Let $M \subset \tilde{A}$ be a closed submanifold with $\partial M \subset \partial \tilde{A}$ which is transversal to $\partial_0 \tilde{A} = S^{\lambda_q-1} \times S^{n-\lambda_q-1} \times \{1\} \times \{0\}$. Then

$$\Psi$$ is strongly transversal to $M$ (See below),

(else where)
\[ \Pi (\Psi^{-1}(M)) = \bigcup_{t \geq 0} \varphi_t (\pi_AM) \]

By **strong transversality** we mean that if we extend \( M \) beyond \( \partial_0 \tilde{A} \) by adding a collar, and if we extend \( \Pi \) to \( S^{n-\lambda_{q+1}} × S^{n-\lambda_{q+1}} × (-\epsilon, 1] × (-\epsilon, 1] \) using the same algebraic formula, then the extended \( \Pi \) is transversal to the extended \( M \). Hence, \( (\Pi^{-1}(M), \partial \Pi^{-1}(M)) \) is a smooth submanifold with corners neatly embedded into \( (\tilde{V}_q, \partial \tilde{V}_q) \).

In particular, if \( \dim(M) = \ell - 1 \), then \( \Psi^{-1}(M) \) has finite \( \ell \)-volume and so does \( \Pi(\Psi^{-1}(M)) \).

**Remark 14.7.** Note that the above comments also apply if \( M \) is a compact \( C^\infty \) stratified set in \( \tilde{A} \) which in a collar neighborhood \( \partial_0 \tilde{A} × [0, \epsilon) \) of \( \partial_0 \tilde{A} \) is of the form \( M_0 × [0, \epsilon) \).

We have now passed the first critical level beyond \( a_k \) and the closure of \( U_p \) has exited as a compact \( C^\infty \) stratified set, whose singularities are the submanifolds \( U_q \) for \( q \succ p \) and \( q \in Cr(f, a_{k+1}) \).

We now compound the process. The product structure (14.4) shows that \( U_p ∩ Q_{k+1} \) has finite \( \ell \)-volume (since it is a product of a smooth stratified set of finite \( (\ell - 1) \)-volume with \([0, 1]\)). For similar reasons, \( U_p ∩ R_{k+2} \) has finite \( \ell \)-volume, and it remains to examine what happens as we pass through the canonical coordinate boxes of critical points \( q \) at level \( k + 2 \).

At points of \( U_p ∩ S_q \) for \( q \in Cr(f, a_{k+2}) \), the above analysis can be applied locally. However, to prove finite volume one must also consider points \( x \in \overline{U}_p ∩ S_q \) where \( \overline{U}_p \) is singular. At such points \( x \) the singular set of \( \overline{U}_p ∩ S_q \) consists of all points of \( U_{q'} \) in a neighborhood of \( x \), for some \( q' \prec q \). Now \( U_{q'} \) is transversal to \( S_q \), and \( \overline{U}_p \) is locally of the form \( C(Y) × U_{q'} \) for some manifold \( Y \). Consequently \( \overline{U}_p ∩ S_q \) is locally of the
form $C(Y) \times \mathbb{R}^i$ and $\overline{U}_p$ is locally of the form $C(Y) \times \mathbb{R}^i \times \mathbb{R}^{n-\lambda_q}$ for some $i > 0$. In particular, $\overline{U}_p \cap A$ has a smooth proper transform to $\tilde{A}$. This proper transform has a neat collar structure at the boundary as discussed in 14.7.

Applying the analysis above one concludes that $U_p \cap \partial^- Q_{k+2}$ is a compact $C^\infty$ stratified set of finite $\ell$-volume whose singular strata consist precisely of the sets $U_q \cap \partial^- Q_{k+2}$ for critical points $q \succ p$ of level $\leq k+2$. The same analysis also shows (using Remark 14.7) that $U_q$ has finite $\ell$-volume in a neighborhood of each critical point of level $k+2$.

One can now proceed inductively through the critical levels to prove that $U_p$ has finite $\ell$-volume.

Since $S_p$ is the unstable manifold for $-\text{grad}(f) = \text{grad}(-f)$, we have also proved that each $S_p$ has finite volume.

It remains to prove that the graph $T$ has finite volume. For this we first observe that the arguments above apply directly to prove the following result. We say that the gradient flow of a smooth function $F$ with non-degenerate critical manifolds is tame in a neighborhood of each critical point there are coordinates $(x, u, v)$ such that $\nabla F = (0, -2u, 2v)$.

**Proposition 14.8.** Let $\Phi_t$ be a tame gradient flow of a proper function $F : X \to \mathbb{R}$ bounded from below with non-degenerate critical manifolds. Let $c$ be a non-critical value of $F$ and suppose that $\Sigma \subset \{F \leq c\}$ is defined as the backward time image of a compact manifold $\Sigma_0 \subset \{F = c\}$. Suppose that $\Sigma$ is transversal to all the unstable manifolds of the flow. Then $\Sigma$ has finite volume.

We now consider the gradient flow

$$\Phi_t(s, x, y) = (e^t s, \varphi_{-t}(y), x)$$

of the function

$$F(s, x, y) = \frac{1}{2}s^2 - f(y)$$

on $\mathbb{R} \times X \times X$ (with metric $ds^2$ on $\mathbb{R}$). The critical set of $F$ consists of the non-degenerate critical manifolds

$$P_p = \{0\} \times \{p\} \times X$$

for $p \in Cr(f)$. The stable and unstable manifolds at $P_p$ are given by

$$S_p = \{0\} \times U_p \times X \quad \text{and} \quad U_p = \mathbb{R} \times S_p \times X.$$
and the subdomain
\[ \mathcal{T} \equiv \{(e^{-s}, \varphi_s(x), x) : 0 \leq s < \infty \text{ and } x \in X\}. \]

Note that \( \tilde{T} \) is merely the union of orbits passing through \( \Delta = \{(1, x, x) : x \in X\} \) and
\[ \mathcal{T} = \bigcup_{s \leq 0} \Phi_s(\Delta) \]
is the union of the backward time orbits of \( \Phi \) which begin at \( \Delta \). Recall (cf. Remark 1.6) that \( \text{vol}(\mathcal{T}) < \infty \Rightarrow \text{vol}(T) < \infty \). Thus to complete the proof we shall prove \( \text{vol}(\mathcal{T}) < \infty \) by applying Proposition 14.8.

To begin, a straightforward check verifies that

\[(14.8) \quad \tilde{T} \text{ is transversal to } S_p \text{ and to } U_p \text{ for all } p. \]

Now the intersection
\[ \tilde{T}(c) \overset{\text{def}}{=} \tilde{T} \cap \{F = c\}, \]
is always a smooth submanifold since \( \tilde{T} \) is \( \Phi_t \)-invariant, i.e., \( \text{grad}(F|_{\tilde{T}}) = \text{grad}(F)|_{\tilde{T}} \neq 0 \) on \( \tilde{T} \). Furthermore, if \( c > \max|f| \), then \( \tilde{T}(c) \) is compact. To see this note that \( \tilde{T}(c) \) is not compact iff there exists a sequence \((s_j, x_j) \in \mathbb{R} \times X\) with
\[ F(e^{s_j}, x_j, \varphi_{s_j}(x_j)) = \frac{1}{2}(e^{2s_j} - f(\varphi_{-s_j}(x)) = c \]
for all \( j \) and for which there is no convergent subsequence. Clear for such a sequence we have \( s_j \to -\infty \) and so \( e^{2s_j} \to 0 \) implying \( c \leq \max|f| \) as claimed. It therefore follows from Proposition 14.8 that for any \( c > \max|f| \), the submanifold \( \tilde{T}_{\leq c} \equiv \tilde{T} \cap \{F \leq c\} \) has finite volume in \( \mathbb{R} \times X \times X \).

Since \( \max\frac{1}{2} + \max(f) \), we have \( \mathcal{T} \subset \tilde{T}_{\leq c} \) for all \( c > \max|f| + \frac{1}{2} \).
Thus \( \mathcal{T} \) has finite volume, and the proof is complete. \( \text{q.e.d.} \)

Proof of Theorem 14.4. The following proof is inspired by arguments of Milnor given for a similar result [30, §4]. Consider the block decomposition (14.3) and the product structure 14.4 given by the flow. Proceeding in order from \( k = 1 \) we shall modify the metric on each subset
\[ \partial^{-}Q_k \times (1/3, 2/3) \subset \partial^{-}Q_k \times [0, 1] \]
so that under the new gradient flow (which agrees with the old one outside \( \partial^{-}Q_k \times (1/3, 2/3) \)), the unstable manifolds entering \( \partial^{-}Q_k \times \{0\} \)
become transversal to the stable manifolds at $\partial^- Q_k \times \{1\}$. By invariance under the flow this implies that each unstable manifold which meets $Q_k$ is transversal everywhere on $X$ to each stable manifold which meets $Q_k$. Modifying the metric at level $k$ does not change the unstable manifolds below $\partial^- Q_k$. It also does not change the stable manifolds which originate below level $k$. From this one sees that after successively modifying the metric at level $k$ for $k = 1, \ldots, m - 1$, we have established the result.

We now show how to modify the metric. Fix a level $k$ and consider the submanifolds

$$M_p = U_p \cap \partial^- Q_k \quad \text{and} \quad N_q = S_q \cap \partial^- Q_k$$

for $p, q \in C\tau(f)$. We want to change the metric over $\partial^- Q_k \times (\frac{1}{3}, \frac{2}{3})$ so that after pushing each $M_p \times \{0\}$ forward by the new gradient flow, it becomes transversal to $N_q \times \{1\}$ for all $q$. We shall do this as follows. We shall construct a family of deformations of the metric, smoothly parameterized by an open subset $U \subset \mathbb{R}^N$ for some $N$. This family will induce a smooth mapping

$$U \times (\partial^- Q_k \times \{0\}) \xrightarrow{\Theta} \partial^- Q_k \times \{1\}$$

such that each $\Theta_u(\cdot) \equiv \Theta(u, \cdot)$ is the diffeomorphism induced by the new gradient flow (in the product structure of the old gradient flow).

By Sard's Theorem for Families it will suffice to prove that $\Theta|_{U \times M_p}$ is transversal to $N_q$ for all $p, q$ (since then for almost all choices of $u \in U$, we have that $\Theta_u|_{M_p}$ is transversal to $N_q$ for each $p, q$). This condition will follow automatically if we show that

$$\frac{\partial \Theta}{\partial u} \text{ is surjective at all points of } U \times \partial^- Q_k$$

In fact it will suffice to show that there exists $u_0 \in U$ such that

$$\frac{\partial \Theta}{\partial u} \text{ is surjective at all points of } \{u_0\} \times \partial^- Q_k$$

for then, by the compactness of $\partial^- Q_k$, condition (14.11) will hold with $U$ replaced by a small neighborhood of $u_0$ in $U$.

We first construct such a map locally on $\partial^- Q_k$. Let $x = (x_1, \ldots, x_{n-1}) : \mathcal{O} \rightarrow \mathbb{R}^{n-1}$ be a local coordinate chart on $Q_k$ (which maps onto $\mathbb{R}^{n-1}$). We then have coordinates $(x, t) \in \mathbb{R}^{n-1} \times [0, 1]$ for $\partial^- Q_k \times [0, 1]$ where $f(x, t) = t$. In these coordinates the given riemannian metric has the form

$$\langle \cdot, \cdot \rangle_{(x,t)} = \langle \cdot, \cdot \rangle_{(x,t)} + dt^2$$
where $(\cdot, \cdot)$ is a family of inner products on $\mathbb{R}^{n-1}$.

Let $\mathfrak{M}$ denote the space of symmetric $n \times n$-matrices. Fix a non-trivial smooth function $\psi : [0, 1] \to [0, 1]$ with support in $(\frac{1}{3}, \frac{2}{3})$. For each $A \in \mathfrak{M}$ with eigenvalues of absolute value < 1, we define a new metric $(\cdot, \cdot)_A$ by

$$
(14.11) \quad (\cdot, \cdot)_A = (\cdot, \cdot) + \psi(A(\cdot), \cdot).
$$

Let $V = V(A)$ be the gradient of $f$ in this new metric. Write $V = V' + V_0 \partial/\partial t$ where $V'$ is tangent to $\mathbb{R}^{n-1}$. Then for any vector field $W = W' + W_0 \partial/\partial t$ we have that

$$
W \cdot f = \langle V, W \rangle_A = \langle \partial/\partial t, W \rangle = \langle (I + \psi(t)A)V, W \rangle,
$$

which implies that

$$
\frac{\partial}{\partial t} = e_n = (I + \psi(t)A)V.
$$

Our map $\Theta$ is given by taking the $\mathbb{R}^{n-1}$-component of the integral of the vector field $V = (I + \psi(t)A)^{-1}e_n$. We write the integral of $V$ as $(\Theta_A(x, s), \tau_A(x, s))$ with respect to the decomposition $\mathbb{R}^{n-1} \times [0, 1] \subset \mathbb{R}^{n-1} \times \mathbb{R}$. Since $V$ is translation invariant in the $x$-variables, we have

$$
\tau_A(x, s) = \tau_A(s) \quad \text{and} \quad \Theta_A(x, s) = \Theta_A(s) + x
$$

where $\Theta_A(s) = \Theta_A(0, s)$. Note that

$$
\frac{d}{ds}\tau_A(s) = \text{n-component of } (I + \psi(\tau_A(s))A)^{-1} \cdot e_n
$$

$$
= (n, n)\text{-component of } \sum_{k=0}^{\infty} \psi(\tau_A(s))^k A^k.
$$

Similarly

$$
\frac{d}{ds}\Theta_A(s) = \text{pr } \{(I + \psi(\tau_A(s))A)^{-1} \cdot e_n\}
$$

where $\text{pr} : \mathbb{R}^n \to \mathbb{R}^{n-1}$ is the linear projection. Hence for all $A$ sufficiently small,

$$
\Theta_A(1) = \text{pr } \int_0^1 (I + \psi(\tau_A(s))A)^{-1} \cdot e_n \, ds
$$

$$
= \text{pr } \int_0^1 \sum_{k=0}^{\infty} \psi(\tau_A(s))^k A^k \cdot e_n \, ds.
$$
Therefore, for each \( i, j \) with \( 1 \leq i, j \leq n \) we have

\[
\frac{\partial \Theta_A}{\partial A_{i,j}} \bigg|_{A=0} = \text{pr} \int_0^1 \sum_{k=0}^{\infty} \frac{\partial}{\partial A_{i,j}} \psi(\tau_A(s))^k A^k \cdot e_n \, ds \bigg|_{A=0}
\]

\[
= \text{pr} \int_0^1 \{ -\psi(\tau_0(s))E_{i,j} \} \cdot e_n \, ds
\]

\[
= - \int_0^1 \psi(s) \, ds \begin{cases} E_{in} & \text{if } i > j = n \\ 0 & \text{otherwise.} \end{cases}
\]

where \( E_{ij} \) is the elementary \((i, j)\)-matrix. This proves the surjectivity of \( \partial \Theta / \partial A \) in this coordinate system.

We now modify this family by replacing \( A \) with \( \xi(x)A \) where \( \xi \in C_0^\infty(\mathbb{R}^{n-1}) \) satisfies \( \xi(x) = 1 \) for \( |x| \leq 2 \). This family of deformations now extends trivially to all of \( \partial^-Q_k \) and agrees with the one above in a neighborhood of \( B_1 = \{|x| \leq 1\} \).

We now choose a finite family of such local coordinate systems \( x^k : \mathcal{O}_k \to \mathbb{R}^{n-1}, k = 1, \ldots, \nu \) such that the open sets \( (x^k)^{-1}(B_1) \) cover \( \partial^-Q_k \). Let \( \alpha_k = \xi_k A_k \), for \( A_k \in \mathcal{M} \), be the global section of \( \text{End}(\mathcal{T}(\partial^-Q_k)) \) defined above, and consider the deformations of the metric given by

\[
\langle \cdot, \cdot \rangle_{A_1, \ldots, A_\nu} = \langle \cdot, \cdot \rangle + \psi(t) \sum_{j=1}^{\nu} \langle \xi_j A_j(\cdot), \cdot \rangle
\]

for \( \vec{A} = (A_1, \ldots, A_\nu) \in \mathcal{M}^\nu \). Then our calculation above shows that

\[
\frac{\partial \Theta_{\vec{A}}}{\partial \vec{A}} \bigg|_{\vec{A}=0}
\]

is surjective

as desired. \( \text{q.e.d.} \)

**Appendix: Currents and the kernel calculus**

Let \( Z \) be a compact smooth \( n \)-dimensional manifold which is not necessarily orientable. In addition to the space \( \mathcal{E}^k(Z) \), of smooth differential forms of degree \( k \), one may consider the space \( \tilde{\mathcal{E}}^k(Z) \), of *twisted* smooth forms on \( Z \) of degree \( k \). These are sections of the bundle \( \Lambda^k T^*Z \otimes_\mathbb{R} \mathcal{O}_Z \) where \( \mathcal{O}_Z \) is the orientation line bundle for \( Z \). Since the transition functions for \( \mathcal{O}_Z \) are \( \mathbb{Z}_2 = \{-1, +1\} \subset \mathbb{R} \) valued, exterior differentiation \( d \) is naturally defined on any twisted form \( \tilde{\alpha} \in \tilde{\mathcal{E}}^k(Z) \). The resulting cohomology groups are the de Rham groups \( H^k(Z; \mathcal{O}_Z) \) of \( Z \) with coefficients in the flat line bundle \( \mathcal{O}_Z \).
A basic fact is that for any twisted n-form $\tilde{\alpha} \in \tilde{E}^n(Z)$ the integral $\int_Z \tilde{\alpha}$ is well defined. (This generalizes the usual definition since, if $Z$ is oriented, then $\tilde{E}^k(Z) \cong E^k(Z)$ are identified.) Following de Rham and Schwartz [33] we have the following.

**Definition A.1.** The space of currents of degree $k$ on $Z$ is the topological dual space

$$D'^k(Z) \overset{\text{def}}{=} \tilde{E}^{n-k}(Z)'$$

of the space of twisted $(n-k)$-forms on $Z$.

Currents of degree $k$ are a generalization of differential forms of degree $k$. In fact there is an embedding

$$\mathcal{E}^k(Z) \hookrightarrow D'^k(Z) \quad \text{(A.1)}$$

which associates to $\alpha \in \mathcal{E}^k(Z)$, the current defined by

$$\alpha(\tilde{\beta}) \equiv \int_Z \alpha \wedge \tilde{\beta}, \quad \text{for all } \tilde{\beta} \in \tilde{E}^{n-k}(Z). \quad \text{(A.2)}$$

Since $\int_Z d\alpha \wedge \tilde{\beta} = \int_Z d(\alpha \wedge \tilde{\beta}) - (-1)^k \int_Z \alpha \wedge d\tilde{\beta} = (-1)^{k-1} \int_Z \alpha \wedge d\tilde{\beta}$, it is natural to define the exterior derivative of a current $T \in D'^*(Z)$ by:

$$(dT)(\tilde{\beta}) = (-1)^{k-1}T(d\tilde{\beta}), \quad \text{for all } \tilde{\beta} \in \tilde{E}^{n-k}(Z). \quad \text{(A.3)}$$

Thus the de Rham complex of smooth forms $(\mathcal{E}^*(Z), d)$ is a subcomplex of the de Rham complex of currents $(D'^*(Z), d)$. (In fact $D'^*(Z)$ are exactly the distributional sections of $\Lambda^*T^*Z$, and $d$ the natural extension of exterior differentiation to these sections.)

**Example A.2.** Let $S$ be a codimension-$k$ submanifold of $Z$ which has finite volume and oriented normal bundle. The identification $\mathcal{O}_Z | S = \mathcal{O}_S$ enables us to pull back twisted forms via the immersion $i : S \to Z$, and so $S$ determines a current $[S] \in D'^*(Z)$ by integration:

$$[S](\tilde{\beta}) = \int_S i^*(\tilde{\beta}), \quad \text{for all } \tilde{\beta} \in \tilde{E}^*(Z). \quad \text{(A.4)}$$

It is sometimes also useful to consider the boundary operator $\partial$ which is defined to be the dual of $d$ on $\tilde{E}^*(Z)$, i.e.

$$\partial = (-1)^{k-1}d \quad \text{on } D'^k(Z).$$
**Remark A.3.** Note that in general an oriented compact submanifold does not define a current, but does define a **twisted current**, i.e., a linear functional on (untwisted) differential forms.

If $T \in \mathcal{D}'^p(Z)$ and $\alpha \in \mathcal{E}^q(Z)$ then the wedge product

\begin{equation}
T \wedge \alpha \in \mathcal{D}'^p + q(Z) \text{ is defined by } (T \wedge \alpha)(\tilde{\beta}) = T(\alpha \wedge \tilde{\beta}).
\end{equation}

More generally, for any flat bundle $E \to Z$ we have the spaces $\mathcal{E}^*(Z; E)$ of differential forms on $Z$ with coefficients in $E$, and their extensions

\begin{equation}
\mathcal{D}'^*(Z; E) \overset{\text{def}}{=} \mathcal{E}^{n-*}(Z; E^* \otimes \mathcal{O}_Z)',
\end{equation}

to currents with coefficients in $E$.

Next we wish to represent operators on differential forms by currents on a product space. Let $Y$ and $X$ be manifolds with

\[
\dim(Y) = n \quad \text{and} \quad \dim(X) = m
\]

and note that $\mathcal{O}_{Y \times X} = \pi_Y^* \mathcal{O}_Y \otimes \pi_X^* \mathcal{O}_X$ where $\pi_Y$ and $\pi_X$ denote the projections to $Y$ and $X$. Consider the space of differential forms $\mathcal{E}^*(Y \times \tilde{X}) \overset{\text{def}}{=} \mathcal{E}^*(Y \times X; \pi_X^* \mathcal{O}_X)$ on $Y \times X$ twisted by the orientation line bundle $\pi_X^* \mathcal{O}_X$. For example $(\pi_Y^* \alpha) \wedge (\pi_X^* \tilde{\beta}) \in \mathcal{E}^*(Y \times \tilde{X})$, if $\alpha \in \mathcal{E}^*(Y)$, $\tilde{\beta} \in \tilde{\mathcal{E}}^*(X)$. The topological dual spaces

\begin{equation}
\mathcal{D}'^*(\tilde{Y} \times X) \equiv \mathcal{D}'^*(Y \times X; \pi_Y^* \mathcal{O}_Y) \equiv \mathcal{E}^{n+m-*}(Y \times \tilde{X})',
\end{equation}

is called the space of **kernels** for operators from $\mathcal{E}^*(Y)$ to $\mathcal{D}'^*(X)$. Each kernel $K \in \mathcal{D}'^n - r(\tilde{Y} \times X)$ determines an operator $K : \mathcal{E}^*(Y) \to \mathcal{D}'^* - r(X)$ by setting

\begin{equation}
K(\alpha)(\tilde{\beta}) = K(\pi_Y^* \alpha \wedge \pi_X^* \tilde{\beta}).
\end{equation}

Since $\pi_X^* : \tilde{\mathcal{E}}^*(X) \to \mathcal{E}^*(Y \times \tilde{X})$ the dual map $(\pi_X)_*: \mathcal{D}'^*(\tilde{Y} \times X) \to \mathcal{D}'^*(X)$ pushes forward kernels on $Y \times X$ to currents on $X$. Now the right hand side of (A.7) can be rewritten as $((\pi_X)_*(K \wedge \pi_Y^* \alpha))(\tilde{\beta})$, so that

\begin{equation}
K(\alpha) = (\pi_X)_*(K \wedge \pi_Y^* \alpha)
\end{equation}

provides an alternate "pull-push" definition of $K$. 

Proposition A.4. Suppose $K \in \mathcal{D}^m - r(\tilde{Y} \times X)$ is a kernel whose operator $K$ lowers degree by $r$. Then the kernel $\partial K \in \mathcal{D}^m - r + 1(\tilde{Y} \times X)$, determines the operator

$$K \circ d + (-1)^{r-1} d \circ K.$$

Proof. By definition $\partial K(\pi_Y^* \alpha \wedge \pi_X^* \tilde{\beta}) = K(d(\pi_Y^* \alpha \wedge \pi_X^* \tilde{\beta}))$ which equals $K(\pi_Y^* d\alpha \wedge \pi_X^* \tilde{\beta}) + (-1)^{\deg \alpha} K(\pi_Y^* \alpha \wedge \pi_X^* d\tilde{\beta})$. But $(K(d\alpha))(\tilde{\beta}) = K(\pi_Y^* d\alpha \wedge \pi_X^* \tilde{\beta})$, and

$$(d(K(\alpha)))(\tilde{\beta}) = (-1)^{\deg \alpha - r - 1}(K(\alpha))(d\tilde{\beta})$$

$$= (-1)^{\deg \alpha - r - 1} K(\pi_Y^* \alpha \wedge \pi_X^* d\tilde{\beta}).$$

q.e.d.

Now we list some examples of kernels and their corresponding operators.

Example A.5. Let $\Sigma \subset Y \times X$ be a finite volume submanifold of codimension-$q$ with a given isomorphism $\pi_X^* \mathcal{O}_X|_\Sigma \cong \mathcal{O}_\Sigma$. Then integration of forms over $\Sigma$ defines a current $[\Sigma] \in \mathcal{D}^q(\tilde{Y} \times X)$.

Example A.6. (The Identity) The identity operator $I : \mathcal{E}^*(X) \rightarrow \mathcal{E}^*(X)$ on forms is represented by the kernel $I = [\Delta]$, corresponding to integration over the diagonal $\Delta \subset X \times X$, since $\alpha(\tilde{\beta}) = \int_\Delta \pi_Y^* \alpha \wedge \pi_X^* \tilde{\beta} = [\Delta](\pi_Y^* \alpha \wedge \pi_X^* \tilde{\beta})$.

Example A.7. (The Pull Back) Suppose $\varphi : X \rightarrow Y$. Then the operator $P_{\varphi} \alpha \equiv \varphi^* \alpha$ is represented by the kernel $P_{\varphi} = [\text{graph } \varphi]$; that is

$$P_{\varphi} = (\pi_X)_*([\text{graph } \varphi] \wedge \pi_Y^* \alpha).$$

Example A.8. (Projection onto $\psi$ along $\tilde{\psi}$). Suppose $\psi \in \mathcal{E}^*(X)$ and $\tilde{\psi} \in \tilde{\mathcal{E}}^*(Y)$. Then $K = \pi_Y^* \tilde{\psi} \wedge \pi_X^* \psi \in \mathcal{D}^*(\tilde{Y} \times X)$ is a kernel inducing the operator

$$K(\alpha) = \pm \left( \int_Y \tilde{\psi} \wedge \alpha \right) \psi,$$

where $\pm$ equals $(-1)^{\deg \psi}(\deg \alpha)$. Note

$$K(\pi_Y^* \alpha \wedge \pi_X^* \tilde{\beta}) = \int_{Y \times X} \pi_Y^* \tilde{\psi} \wedge \pi_X^* \psi \wedge \pi_Y^* \alpha \wedge \pi_X^* \tilde{\beta}.$$
Example A.9. (Projection onto $[S]$ along $[U]$). Suppose $S$ is a submanifold with oriented normal bundle in $X$ and $[U]$ is an oriented submanifold of $Y$. Let $[S]$ denote the current in $X$ and $[U]$ the twisted current in $Y$ determined by integration. Then $K = [U] \times [S] \in \mathcal{D}^* (\bar{Y} \times X)$ is a kernel and the corresponding operator is $K(\alpha) = \pm \left( \int_U \alpha \right) [S]$, where $\pm$ equals $(-1)^{(\deg S)(\deg \alpha)} = (-1)^{(\dim Y - \dim S)(\dim U)}$.

References


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