

DIRAC STRUCTURES ON THE SPACE OF CONNECTIONS*

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Abstract. We shall investigate the Dirac structures on the space of connections over three-manifolds and over four-manifolds. We show that the space of irreducible connections on the trivial $SU(n)$ -bundle over a three-manifold is canonically endowed with a Dirac structure twisted by a 3-form. We also give a family of Dirac structures twisted by the 3-form on the space of irreducible connections on the trivial $SU(n)$ -bundle over a four-manifold. These twisted Dirac structures induce (non-twisted) Dirac structures on the space of flat connections. The Dirac structure on the space of flat connections over the three-manifold is obtained as the boundary restriction of the corresponding Dirac structure over the four-manifold. We also discuss the action of the group of gauge transformations over these Dirac structures.

Key words. Dirac structures, Symplectic structures, Space of connections.

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1. Introduction. Let X be a four-manifold with the boundary three-manifold M . Let \mathcal{A}_X and \mathcal{A}_M be the spaces of irreducible connections on the principal bundles $X \times SU(n)$ and $M \times SU(n)$ respectively. In physics language these are phase spaces of gauge fields. As a mathematical counterpart of Bohr-Sommerfeld theory we have geometric quantization theory where we deal with symplectic structures on the space of connections and the corresponding Hamiltonian theory. The Lagrangian subspaces correspond to the Dirac structure on this bundle. We shall investigate twisted Dirac structures on the spaces \mathcal{A}_X and \mathcal{A}_M . These twisted Dirac structures are affected by the presence of closed 3-forms. Twisted Poisson structures arose from the study of topological sigma models and play an important role in string theory [6, 11]. P. Ševera and A. Weinstein, [13], investigated how Poisson geometry on a manifold is affected by the presence of a closed 3-form, and they found that the notions of Courant algebroids and Dirac structures provide a framework where one can carry out computations in Poisson geometry in the presence of background 3-forms. On the other hand the geometric quantization of the moduli space of flat connections on a two-manifold was studied extensively in the last decade of 20th century, [1], [5]. The geometric prequantization problem of the moduli space of flat connections on a four-manifold was investigated in [8]. In [10], [8] one of the authors of the present article proved that there is a presymplectic structure on \mathcal{A}_X that is induced from the canonical symplectic structure on the cotangent bundle $T^*\mathcal{A}_X$ by a generating function $CS : \mathcal{A}_X \longrightarrow T^*\mathcal{A}_X$ which is given by the Chern-Simons form:

$$CS(A) = \frac{1}{24\pi^3} \left(AF_A + F_A A - \frac{1}{2} A^3 \right). \quad (1.1)$$

The presymplectic form is given by the formula:

$$\Omega_A(a, b) = \frac{1}{8\pi^3} \int_X \text{tr} [(ab - ba) F_A] - \frac{1}{24\pi^3} \int_M \text{tr} [(ab - ba) A].$$

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for $a, b \in T_A \mathcal{A}_X$.

Let ω be the boundary reduction of this presymplectic form to \mathcal{A}_M . ω is no longer presymplectic but twisted by the Cartan 3-form on \mathcal{A}_M . Associated to the 2-form ω , we have the correspondence:

$$\omega_A : T_A \mathcal{A}_M \ni a \mapsto \omega_A(a, \cdot) \in T_A^* \mathcal{A}_M,$$

at each $A \in \mathcal{A}_M$. Then we have the subbundle

$$\mathcal{D}_M = \{ a \oplus \omega_A(a) \in T\mathcal{A}_X \oplus T^*\mathcal{A}_X \mid a \in T_A \mathcal{A}_M, A \in \mathcal{A}_M \}.$$

\mathcal{D}_M gives a twisted Dirac structure of the standard Courant algebroid $E_0(M) = T\mathcal{A}_M \oplus T^*\mathcal{A}_M$.

The exterior derivative of the 2-form ω is the Cartan 3-form $\kappa = \tilde{d}\omega$ on \mathcal{A}_M :

$$\kappa_A(a, b, c) = \frac{1}{8\pi^3} \int_M \text{tr} [abc - bac], \quad a, b, c \in T_A \mathcal{A}_M, A \in \mathcal{A}_M,$$

where $abc = a \wedge b \wedge c$ etc., and it describes the twist of the Dirac structure \mathcal{D}_M .

On the space of connections \mathcal{A}_X over a four-manifold X we consider the correspondence

$$\phi_A : T_A \mathcal{A}_X \ni a \mapsto F_A a + a F_A \in T_A^* \mathcal{A}_X, \quad A \in \mathcal{A}_X,$$

where F_A is the curvature of A . Then we have the following subbundle of the standard Courant algebroid $E_0(X) = T\mathcal{A}_X \oplus T^*\mathcal{A}_X$:

$$\mathcal{D}_X^\phi = \{ a \oplus \phi_A(a) \in E_0(X) \mid a \in T_A \mathcal{A}_X, A \in \mathcal{A}_X \}.$$

\mathcal{D}_X^ϕ gives a twisted Dirac subbundle of $E_0(X)$. The twist in this case is given by the following 3-form κ on \mathcal{A}_X :

$$\kappa_A(a, b, c) = \kappa_A(\bar{a}, \bar{b}, \bar{c}), \quad a, b, c \in T_A \mathcal{A}_X, A \in \mathcal{A}_X,$$

where \bar{a}, \bar{b} and \bar{c} indicate the restriction of a, b and c respectively to the boundary M , and the right-hand side is the 3-form κ on \mathcal{A}_M described above.

Moreover if we deal with the correspondence from $T_A \mathcal{A}_X$ to $T_A^* \mathcal{A}_X$ given by

$$\gamma_A^t(a) = (F_A + t A^2) a + a (F_A + t A^2), \quad t \in \mathbb{R},$$

then we have the κ -twisted Dirac structure

$$\mathcal{D}_X^t = \{ a \oplus \gamma_A^t(a) \in E_0(X) \mid a \in T_A \mathcal{A}_X, A \in \mathcal{A}_X \}.$$

As for the presymplectic structure on the space of connections \mathcal{A}_X we have a family of closed 2-forms on \mathcal{A}_X given by

$$\Omega_A^t(a, b) = \frac{1}{24\pi^3} \int_X \text{tr} [(ab - ba) \{ 3F_A - (t - 1) A^2 \}] - \frac{1}{24\pi^3} \int_M \text{tr} [(ab - ba) A].$$

for $a, b \in T_A \mathcal{A}_X$. Ω^1 is the presymplectic form discussed in [10], [8].

If we restrict ourselves to the spaces of flat connections we will have (non-twisted) Dirac structures. In fact we have the following Dirac structures

$$\mathcal{D}_M^\flat = \{ a \oplus \omega_A(a) \in E_0(M) \mid a \in T_A \mathcal{A}_M^\flat, A \in \mathcal{A}_M^\flat \},$$

$$\mathcal{D}_X^\flat = \{ a \oplus \gamma_A^1(a) \in E_0(X) \mid a \in T_A \mathcal{A}_X^\flat, A \in \mathcal{A}_X^\flat \},$$

where \mathcal{A}_M^\flat and \mathcal{A}_X^\flat are flat connections in \mathcal{A}_M and \mathcal{A}_X respectively. By the boundary restriction from X to M we have the correspondence $r : \mathcal{A}_X^\flat \longrightarrow \mathcal{A}_M^\flat$ and we proved in [10] that the image of r consists of those flat connections $A \in \mathcal{A}_M^\flat$ with degree 0. Here, the degree of a connection $A \in \mathcal{A}_M$ is defined by using the 3-dimensional Chern-Simons form

$$\deg A = -\frac{1}{8\pi^2} \int_M \text{tr}[AF_A - \frac{1}{3}A^3].$$

If A is a flat connection, $\deg A = \frac{1}{24\pi^2} \int_M \text{tr}[A^3] = 0$. Then we see that $\mathcal{D}_M^{\flat, \deg 0} = \{a \oplus \omega_A(a) \in \mathcal{D}_M^\flat \mid \deg A = 0\}$ is a Dirac substructure of \mathcal{D}_M^\flat and there is an isomorphism of Dirac structures between \mathcal{D}_X^\flat and $\mathcal{D}_M^{\flat, \deg 0}$ induced by the boundary restriction map.

2. Preliminaries.

2.1. Differential calculus on the space of connections. Let M be a compact, connected and oriented m -dimensional Riemannian manifold possibly with boundary ∂M . Let G be a compact Lie group with Lie algebra \mathfrak{g} . We shall denote by $\Gamma(M, E)$ the space of smooth sections of a smooth vector bundle $E \rightarrow M$. Especially, if $E = TM$ we write $\text{Vect}(M)$ for $\Gamma(M, TM)$ if $E = \wedge^k T^*M$ we write $\Omega^k(M)$ for $\Gamma(M, \wedge^k T^*M)$. $\Omega^k(M, E)$ denotes the space $\Gamma(M, \wedge^k T^*M \otimes E)$ of E -valued k -forms on M .

Let P be a principal G -bundle on M . A connection 1-form on P is a \mathfrak{g} -valued 1-form on P that is invariant under G , acting by a combination of the action on P and the adjoint action on \mathfrak{g} . Let \mathcal{A}_M be the space of irreducible connections on P . The space \mathcal{A}_M is an affine space modeled on the vector space $\Omega^1(M, \text{ad } P)$; the space of 1-forms with values in the adjoint bundle $\text{ad } P$ over M . For the trivial principal bundle $P = M \times G$ it is merely the space of \mathfrak{g} -valued differential 1-forms on M . So the tangent space at $A \in \mathcal{A}_M$ is

$$T_A \mathcal{A}_M = \Omega^1(M, \mathfrak{g}).$$

The cotangent space at $A \in \mathcal{A}_M$ is

$$T_A^* \mathcal{A}_M = \Omega^{m-1}(M, \mathfrak{g}).$$

The dual pairing of $T_A \mathcal{A}_M = \Omega^1(M, \mathfrak{g})$ and $T_A^* \mathcal{A}_M = \Omega^{m-1}(M, \mathfrak{g})$ is given by

$$\langle \alpha, a \rangle_A = \int_M \text{tr}(\alpha \wedge a), \quad a \in T_A \mathcal{A}_M, \alpha \in T_A^* \mathcal{A}_M.$$

For a function $H = H(A)$ on \mathcal{A}_M with values in a vector space V , the directional derivative $(\partial_a H)(A)$ at $A \in \mathcal{A}_M$ to the direction $a \in T_A \mathcal{A}_M$ is defined by

$$(\partial_a H)(A) := \lim_{t \rightarrow 0} \frac{1}{t} \{H(A + ta) - H(A)\}.$$

For example, the directional derivative of the identity map $\text{Id} : A \mapsto A$ on \mathcal{A}_M is $(\partial_a \text{Id})(A) = a$. The curvature 2-form of $A \in \mathcal{A}_M$; $F_A = dA + \frac{1}{2}[A \wedge A] = dA + A \wedge A$ is viewed as a function F over \mathcal{A}_M with values in $\Omega^2(M, \mathfrak{g})$. Since $F_{A+ta} - F_A = t(da + a \wedge A + A \wedge a) + t^2a \wedge a$ we have $(\partial_a F)(A) = da + a \wedge A + A \wedge a$.

Let \mathbf{V} be a vector field over \mathcal{A}_M . The directional derivative $\partial_a \mathbf{V}$ of \mathbf{V} to the direction a at $A \in \mathcal{A}_M$ is defined by taking the directional derivative of the coefficients of \mathbf{V} . Namely, if \mathbf{V} is written locally as $\mathbf{V} = \sum_i \xi_i \partial_i$ with coefficients ξ_i , the directional derivative $\partial_a \mathbf{V}$ to the direction $a \in T_A \mathcal{A}_M$ is given by

$$(\partial_a \mathbf{V})(A) := \sum_i (\partial_a \xi_i)(A) \partial_i.$$

Then the Lie bracket of vector fields \mathbf{V} and \mathbf{W} on \mathcal{A}_M is given by

$$[\mathbf{V}, \mathbf{W}](A) = (\partial_{\mathbf{V}(A)} \mathbf{W})(A) - (\partial_{\mathbf{W}(A)} \mathbf{V})(A), \quad A \in \mathcal{A}_M. \quad (2.1)$$

Let θ be a k -form ($k \geq 1$) on the connection space \mathcal{A}_M and \mathbf{W} a vector field on \mathcal{A}_M . The directional derivative $\partial_{\mathbf{W}} \theta$ of θ to the direction of \mathbf{W} is a k -form that is obtained by the directional derivative of the component functions of θ to the direction $\mathbf{W}(A)$ at each $A \in \mathcal{A}_M$. That is, if θ is written locally in the form $\theta = \sum_i f_i \varepsilon_i$ with component functions f_i and local frames $\{\varepsilon_i\}$ of cotangent bundle $T^* \mathcal{A}_M$, $\partial_{\mathbf{W}} \theta$ is given by

$$(\partial_{\mathbf{W}} \theta)_A := \sum_i (\partial_{\mathbf{W}(A)} f_i)(A) \varepsilon_i.$$

Let $\langle \theta \mid \mathbf{V} \rangle$ denote the evaluation of a 1-form θ and a vector field \mathbf{V} . Then it holds that

$$\partial_{\mathbf{W}} \langle \theta \mid \mathbf{V} \rangle = \langle \partial_{\mathbf{W}} \theta \mid \mathbf{V} \rangle + \langle \theta \mid \partial_{\mathbf{W}} \mathbf{V} \rangle. \quad (2.2)$$

The exterior derivative of a k -form θ on \mathcal{A}_M is the $(k+1)$ -form $\tilde{d}\theta$ that is given by

$$\begin{aligned} & (\tilde{d}\theta)_A (\mathbf{V}_1(A), \dots, \mathbf{V}_{k+1}(A)) \\ &:= \sum_{i=1}^{k+1} (-1)^{i+1} (\partial_{\mathbf{V}_i} \theta (\mathbf{V}_1, \dots, \hat{\mathbf{V}}_i, \dots, \mathbf{V}_{k+1}))(A) \\ &+ \sum_{i < j} (-1)^{i+j} \theta_A ([\mathbf{V}_i, \mathbf{V}_j](A), \mathbf{V}_1(A), \dots, \widehat{\mathbf{V}_i(A)}, \dots, \widehat{\mathbf{V}_j(A)}, \dots, \mathbf{V}_{k+1}(A)), \end{aligned}$$

for any vector fields $\mathbf{V}_1, \dots, \mathbf{V}_{k+1}$ on \mathcal{A}_M . It can be shown that $\tilde{d} \circ \tilde{d} = 0$. In particular the exterior derivative of a 1-form θ becomes

$$(\tilde{d}\theta)(\mathbf{V}_1, \mathbf{V}_2) = \langle \partial_{\mathbf{V}_1} \theta \mid \mathbf{V}_2 \rangle - \langle \partial_{\mathbf{V}_2} \theta \mid \mathbf{V}_1 \rangle \quad (2.3)$$

by (2.1) and (2.2). And also, the exterior derivative $\tilde{d}\varphi$ of a 2-form φ is given by

$$(\tilde{d}\varphi)_A (\mathbf{V}_1, \mathbf{V}_2, \mathbf{V}_3) = (\partial_{\mathbf{V}_1} \varphi)(\mathbf{V}_2, \mathbf{V}_3) + (\partial_{\mathbf{V}_2} \varphi)(\mathbf{V}_3, \mathbf{V}_1) + (\partial_{\mathbf{V}_3} \varphi)(\mathbf{V}_1, \mathbf{V}_2). \quad (2.4)$$

The Lie derivative is also defined by the same manner as in the case of finite dimensional smooth manifolds. Let θ be a k -form and \mathbf{W} be a vector field on \mathcal{A}_M , The Lie derivative $\mathcal{L}_{\mathbf{W}} \theta$ of θ by \mathbf{W} is defined to be a k -form on \mathcal{A}_M by

$$\begin{aligned} & (\mathcal{L}_{\mathbf{W}} \theta)_A (\mathbf{V}_1(A), \dots, \mathbf{V}_k(A)) := (\partial_{\mathbf{W}} \theta(\mathbf{V}_1, \dots, \mathbf{V}_k))(A) \\ & - \sum_i \theta ([\mathbf{W}, \mathbf{V}_i](A), \mathbf{V}_1(A), \dots, \widehat{\mathbf{V}_i(A)}, \dots, \mathbf{V}_k(A)). \end{aligned}$$

at each $A \in \mathcal{A}_M$. Especially, for $k = 1$, we have

$$(\mathcal{L}_{\mathbf{W}}\theta)(\mathbf{V}) = \partial_{\mathbf{W}}\langle\theta | \mathbf{V}\rangle - \langle\theta | [\mathbf{W}, \mathbf{V}]\rangle. \quad (2.5)$$

For further details of differential calculus on Banach space we refer the readers to [2, 4, 14].

2.2. Courant algebroids and Dirac structures. The notions of Courant algebroid and Dirac structure are developed in many forms since T. Courant's work in 1990 [3]. P. Ševera and A. Weinstein showed that Courant algebroid and Dirac structure provide a framework to carry out computations in Poisson geometry in the presence of a background 3-form. Poisson structures on a manifold M may be identified with certain Dirac structures in the standard Courant algebroid $E_0 = TM \oplus T^*M$, and a closed 3-form ϕ on M may be used to modify the bracket on E_0 , yielding a new Courant algebroid E_ϕ . Here we shall give a explanatory introduction of these subjects after [12, 13].

DEFINITION 2.1. *A Courant algebroid over a manifold M is a vector bundle $E \rightarrow M$ equipped with a field of nondegenerate symmetric bilinear forms (\cdot, \cdot) on the fibers, an \mathbb{R} -bilinear bracket $[\cdot, \cdot] : \Gamma(M, E) \times \Gamma(M, E) \rightarrow \Gamma(M, E)$ on the space of sections on E , and a bundle map $\rho : E \rightarrow TM$; the anchor, such that the following properties are satisfied:*

- (1) *for any $e_1, e_2, e_3 \in \Gamma(M, E)$, $[e_1, [e_2, e_3]] = [[e_1, e_2], e_3] + [e_2, [e_1, e_3]]$;*
 - (2) *for any $e_1, e_2 \in \Gamma(M, E)$, $\rho([e_1, e_2]) = [\rho(e_1), \rho(e_2)]$;*
 - (3) *for any $e_1, e_2 \in \Gamma(M, E)$ and $f \in C^\infty(M)$, $[e_1, fe_2] = f[e_1, e_2] + (\rho(e_1)f)e_2$;*
 - (4) *for any $e, h_1, h_2 \in \Gamma(M, E)$, $\rho(e)(h_1, h_2) = ([e, h_1], h_2) + (h_1, [e, h_2])$;*
 - (5) *for any $e \in \Gamma(M, E)$, $[e, e] = \mathbb{D}(e, e)$,*
- where $\mathbb{D} = \frac{1}{2}\beta^{-1}\rho^*\text{d}$ and β is the isomorphism between E and E^* given by the bilinear form: $(\beta x)(y) = (x, y)$. That is, $(\mathbb{D}f, e) = \frac{1}{2}\rho(e)f$.

The assertion 5 says that there is a linear map $Z : \Gamma(E) \ni e \rightarrow Z_e \in \text{Vect}(E)$ such that Z_e is a lift of $\rho(e) \in \text{Vect}(M)$, and the first four axioms say that the flow of Z_e preserves the structure of E . The bracket $[e_1, e_2]$ is the Lie derivative of e_2 by Z_{e_1} .

DEFINITION 2.2. *A Dirac structure in E is a maximal isotropic subbundle \mathcal{D} of E whose sections are closed under the bracket, i.e., which is preserved by the flow of Z_e for every $e \in \Gamma(\mathcal{D})$.*

The restriction of the bracket and anchor to any Dirac structure \mathcal{D} forms a Lie algebroid structure on \mathcal{D} .

On any manifold we have the standard Courant algebroid $E_0 = TM \oplus T^*M$ with bilinear form $(X_1 \oplus \xi_1, X_2 \oplus \xi_2) = \frac{1}{2}\{\xi_1(X_2) + \xi_2(X_1)\}$, the anchor $\rho(X \oplus \xi) = X$ and the bracket

$$[X_1 \oplus \xi_1, X_2 \oplus \xi_2] = [X_1, X_2] \oplus (\mathcal{L}_{X_1}\xi_2 - i_{X_2}\text{d}\xi_1). \quad (2.6)$$

Now let ϕ be a 3-form on M . We define a new bracket on E_0 by adding the term $\phi(X_1, X_2, \cdot)$ to the right-hand side of (2.6):

$$[X_1 \oplus \xi_1, X_2 \oplus \xi_2]_\phi = [X_1, X_2] \oplus (\mathcal{L}_{X_1}\xi_2 - i_{X_2}\text{d}\xi_1 - i_{X_1 \wedge X_2}\phi). \quad (2.7)$$

A simple computation shows that the new bracket together with the original bilinear form and anchor constitute a Courant algebroid structure on $E_0 = TM \oplus T^*M$ if and only if $d\phi = 0$. We denote this modified Courant algebroid by E_ϕ . A maximal isotropic subbundle \mathcal{D} of E_ϕ whose sections are closed under the bracket $[\cdot, \cdot]_\phi$ is called a *ϕ -twisted Dirac structure*.

We endow the following canonical skew symmetric form on the standard Courant algebroid $E_0 = TM \oplus T^*M$:

$$\Lambda(X_1 \oplus \xi_1 \mid X_2 \oplus \xi_2) := \frac{1}{2} \{ \langle \xi_1 \mid X_2 \rangle - \langle \xi_2 \mid X_1 \rangle \}, \quad (2.8)$$

for $X_1 \oplus \xi_1, X_2 \oplus \xi_2 \in E_0$.

3. Dirac structures on the space of connections. We shall introduce several Dirac structures on the space of connections over the manifolds of dimension 3 and 4. First we give an explanation about the related presymplectic structures.

3.1. Presymplectic structures on the space of connections. Let X be a four-manifold with the boundary three-manifold M . Let \mathcal{A}_X and \mathcal{A}_M be the spaces of irreducible connections on the principal bundles $X \times \mathrm{SU}(n)$ and $M \times \mathrm{SU}(n)$ respectively. The symplectic structure on the space of connections over a Riemann surface was introduced in 1983 by M. Atiyah and L. Bott in their study of the geometry and topology of moduli spaces of gauge fields (see [1]). In [10], we introduced a presymplectic structure on the space \mathcal{A}_X of irreducible connections over a four-manifold X . That was given by the 2-form:

$$\Omega_A(a, b) = \frac{1}{8\pi^3} \int_X \mathrm{tr}[(ab - ba)F_A] - \frac{1}{24\pi^3} \int_M \mathrm{tr}[(ab - ba)A] \quad (3.1)$$

for $a, b \in T_A \mathcal{A}_X \simeq \Omega^1(X, \mathfrak{g})$. We often abbreviate the exterior product of differential forms $a \wedge b$ to ab . Let θ be the canonical 1-form on the cotangent bundle $T^* \mathcal{A}_X$, and let $\sigma = \tilde{d}\theta$ be the canonical 2-form. A 1-form φ on \mathcal{A}_X gives a tautological section of the cotangent bundle $T^* \mathcal{A}_X$ so that the pullback θ^φ of θ by φ becomes φ itself: $\theta^\varphi = \varphi$, this is the characteristic property of the canonical 1-form θ . The pullback σ^φ of the canonical 2-form σ by φ is a closed 2-form on \mathcal{A}_X . In particular if we take the 1-form on \mathcal{A}_X given by

$$CS(A) = q \left(AF_A + F_A A - \frac{1}{2} A^3 \right), \quad q = \frac{1}{24\pi^3}, \quad (3.2)$$

then we see that the pullback $\Omega = \sigma^{CS}$ is given by the equation (3.1) (the notation CS comes from the Chern-Simons function). Thus, for a four-manifold X there is a presymplectic form on \mathcal{A}_X that is induced from the canonical symplectic form on the cotangent bundle $T^* \mathcal{A}_X$ by the generating function $CS : \mathcal{A}_X \rightarrow T^* \mathcal{A}_X$.

The quantity $\frac{1}{24\pi^2} \int_M \mathrm{tr}[A^3]$ for a connection $A \in \mathcal{A}_X$ plays an analogous role of winding number. In fact, when A is a pure gauge; $A = f^{-1} \tilde{d}f$ for a $f \in C^\infty(X, G)$, it is equal to the degree of f around M . We shall change the ratio of counting this number and look for the family of presymplectic structures affected by it.

Put

$$\Theta_A^t(a) = q \int_X \mathrm{tr} \left[\left(AF_A + F_A A - \frac{t}{2} A^3 \right) a \right], \quad (t \in \mathbb{R}).$$

By the same observation as above the pullback of the canonical 2-form σ on the cotangent space $T^*\mathcal{A}_X$ by the generating function Θ^t provides a presymplectic structure Ω^t on \mathcal{A}_X . It holds that

$$\begin{aligned}\Omega_A^t(a, b) &= (\tilde{d}\Theta^t)_A(a, b) = \langle (\partial_a\Theta^t)_A \mid b \rangle - \langle (\partial_b\Theta^t)_A \mid a \rangle \\ &= q \int_X \text{tr} \left[2(ab - ba) F_A - t(ab - ba) A^2 \right. \\ &\quad \left. - (d_A a \wedge b - a \wedge d_A b - d_A b \wedge a + b \wedge d_A a) \wedge A \right] \\ &= q \int_X \text{tr} [3(ab - ba) F_A - (t - 1)(ab - ba) A^2] - q \int_M \text{tr} [(ab - ba) A],\end{aligned}$$

because

$$\begin{aligned}&\text{tr} \left[-(d_A a \wedge b - a \wedge d_A b - d_A b \wedge a + b \wedge d_A a) \wedge A \right] \\ &= \text{tr} \left[(ab - ba) F_A + (ab - ba) A^2 \right] - d \text{tr} \left[(ab - ba) A \right].\end{aligned}$$

THEOREM 3.1. *We have a family of presymplectic structures on the space \mathcal{A}_X parametrized by $t \in \mathbb{R}$:*

$$\Omega_A^t(a, b) = \Omega_A(a, b) - (t - 1)\gamma'_A(a, b),$$

with $\gamma'_A(a, b) = q \int_X \text{tr} [(ab - ba) A^2]$.

The case for $t = 1$ was discussed in [10].

It is a well known fact that given a principal G -bundle P over a 3-manifold M there exists an oriented 4-manifold X with boundary $\partial X = M$ and a principal G -bundle \mathbf{P} over X that extends P . And any connection A on P has an extension to a connection \mathbf{A} on \mathbf{P} . These are essentially consequences of Tietze's extension theorem for continuous functions on a closed subset [7]. So we can detect a 2-form on \mathcal{A}_M that is the boundary restriction of the presymplectic structure Ω on \mathcal{A}_X . The boundary 2-form ω is given by

$$\omega_A(a, b) := \frac{1}{24\pi^3} \int_M \text{tr} [(ab - ba) A], \quad A \in \mathcal{A}_M, a, b \in T_A \mathcal{A}_M. \quad (3.3)$$

But it is not a closed form and does not give a presymplectic structure on \mathcal{A}_M . Instead it gives the following 3-form on \mathcal{A}_M that is called the *Cartan 3-form*. Let κ be the 3-form on \mathcal{A}_M defined by

$$\kappa_A(a, b, c) = \frac{1}{8\pi^3} \int_M \text{tr} [(ab - ba) c] \quad (3.4)$$

for any $a, b, c \in T_A \mathcal{A}_M$. It holds that $\kappa_A(a, b, c) = \kappa_A(b, c, a) = \kappa_A(c, a, b)$. We have then

$$\tilde{d}\omega = \kappa. \quad (3.5)$$

In fact, (2.4) yields

$$\begin{aligned}
& (\tilde{d}\omega)_A(a, b, c) \\
&= (\partial_a \omega)_A(b, c) + (\partial_b \omega)_A(c, a) + (\partial_c \omega)_A(a, b) \\
&= \frac{1}{24\pi^3} \int_M \text{tr}[(b \wedge c - c \wedge b) \wedge a] + \frac{1}{24\pi^3} \int_M \text{tr}[(c \wedge a - a \wedge c) \wedge b] \\
&\quad + \frac{1}{24\pi^3} \int_M \text{tr}[(a \wedge b - b \wedge a) \wedge c] \\
&= \frac{1}{8\pi^3} \int_M \text{tr}[(a \wedge b - b \wedge a) \wedge c].
\end{aligned}$$

The 2-form (3.3) gives a presymplectic structure twisted by the Cartan 3-form κ .

In the next section we shall describe twisted Dirac structures that are associated to the twisted presymplectic structures discussed above.

3.2. Twisted Dirac structure on the space of connections on a 3-manifold M . In this section M is a compact connected oriented Riemannian 3-manifold and $G = \text{SU}(n)$ with $n \geq 2$. We shall write $\mathfrak{g} = \mathfrak{su}(n)$. Let P be a G -principal bundle. Any principal bundle over a 3-manifold has a trivialization so that we may assume $P = M \times G$. Let $\Omega_{s-1}^r(M, \mathfrak{g})$ be the Sobolev space of L_s^2 -sections of \mathfrak{g} -valued r -forms on M , where we assume $s \geq \frac{5}{2}$. It is the completion of $\{\phi \otimes X \mid \phi \in \Omega_s^r(M), X \in \mathfrak{g}\}$ by the L_s^2 -norms. $\Omega_{s-1}^1(M, \mathfrak{g})$ is a Hilbert space by the inner product

$$(\xi \mid \eta) := \int_M \langle \xi, \eta \rangle \text{vol}_M \quad (3.6)$$

for any $\xi, \eta \in \Omega_{s-1}^1(M, \mathfrak{g})$. Here, vol_M stands for a volume form on M , and $\langle \cdot, \cdot \rangle$ is the inner product induced from the Riemannian metric on M and the Killing form on \mathfrak{g} .

We write \mathcal{A}_M the space of irreducible connections over P . We note that $d_A : \Omega^0(M, \mathfrak{g}) \rightarrow \Omega^1(M, \mathfrak{g})$ is injective for an irreducible connection A . \mathcal{A}_M is an affine space modeled by the vector space $\Omega_{s-1}^1(M, \mathfrak{g})$. So the tangent space at $A \in \mathcal{A}_M$ is

$$T_A \mathcal{A}_M = \Omega_{s-1}^1(M, \mathfrak{g}),$$

that is, the space of differential 1-forms with values in $\mathfrak{su}(n)$ whose component functions are of class L_{s-1}^2 . The dual pairing of a 2-form $\alpha \in \Omega_{s-1}^2(M, \mathfrak{g})$ and a 1-form $a \in \Omega_{s-1}^1(M, \mathfrak{g})$ is given by

$$\langle \alpha \mid a \rangle_M := q \int_M \text{tr}(\alpha \wedge a), \quad q = \frac{1}{24\pi^3},$$

which yields the identification of the cotangent space $T_A^* \mathcal{A}_M$ and $\Omega_{s-1}^2(M, \mathfrak{g})$.

Let $E_0(M) = \mathbb{T}\mathcal{A}_M := T\mathcal{A}_M \oplus T^*\mathcal{A}_M$ be the standard Courant algebroid with the bilinear form

$$\langle \mathbf{a} \oplus \alpha, \mathbf{b} \oplus \beta \rangle_+ := \frac{1}{2} \{ \langle \alpha \mid \mathbf{b} \rangle_M + \langle \beta \mid \mathbf{a} \rangle_M \}, \quad (3.7)$$

the anchor $\rho(\mathbf{a} \oplus \alpha) = \mathbf{a}$, and the bracket $[\![\cdot, \cdot]\!]$ for sections that is defined by

$$[\![\mathbf{a} \oplus \alpha, \mathbf{b} \oplus \beta]\!] := [\mathbf{a}, \mathbf{b}] \oplus (\mathcal{L}_{\mathbf{a}}\beta - i_{\mathbf{b}}\tilde{d}\alpha). \quad (3.8)$$

We take the Cartan 3-form κ on \mathcal{A}_M of (3.4). Since $\kappa = \tilde{d}\omega$ is a closed 2-form we have the Courant algebroid $E_\kappa(M)$ modified by the bracket

$$[\![\mathbf{a} \oplus \alpha, \mathbf{b} \oplus \beta]\!]_\kappa := [\mathbf{a}, \mathbf{b}] \oplus (\mathcal{L}_{\mathbf{a}}\beta - i_{\mathbf{b}}\tilde{d}\alpha - i_{\mathbf{a}\wedge\mathbf{b}}\kappa). \quad (3.9)$$

Note that the bilinear form and the anchor of $E_\kappa(M)$ are the same ones as for the standard Courant algebroid $E_0(M)$.

We define a vector subbundle \mathcal{D}_M of $E_\kappa(M)$ by

$$\mathcal{D}_M := \coprod_{A \in \mathcal{A}_M} \left\{ a \oplus (A \wedge a - a \wedge A) \mid a \in T_A \mathcal{A}_M \right\}. \quad (3.10)$$

Let $\omega : T\mathcal{A}_M \longrightarrow T^*\mathcal{A}_M$ be a bundle homomorphism given by

$$\omega_A(a) := A \wedge a - a \wedge A, \quad a \in T_A \mathcal{A}_M, A \in \mathcal{A}_M. \quad (3.11)$$

Any vector field $\mathbf{a} : \mathcal{A}_M \rightarrow T\mathcal{A}_M$ gives rise to a section $\tilde{\mathbf{a}}$ of \mathcal{D}_M by $\tilde{\mathbf{a}} = \mathbf{a} \oplus \omega(\mathbf{a})$, where $\omega(\mathbf{a})$ denotes the section of $T^*\mathcal{A}_M$: $\omega(\mathbf{a})(A) = \omega_A(\mathbf{a}(A))$.

LEMMA 3.2. $\langle \tilde{\mathbf{a}}, \tilde{\mathbf{b}} \rangle_+ = 0$ for any section $\tilde{\mathbf{a}}, \tilde{\mathbf{b}}$ of \mathcal{D}_M .

In fact, for $a = \mathbf{a}(A)$, $b = \mathbf{b}(A)$, we have

$$\begin{aligned} & \langle \mathbf{a} \oplus \omega(\mathbf{a}), \mathbf{b} \oplus \omega(\mathbf{b}) \rangle_+(A) \\ &= \frac{1}{2} \left\{ \langle \omega_A(a) \mid b \rangle_M + \langle \omega_A(b) \mid a \rangle_M \right\} \\ &= \frac{q}{2} \int_M \text{tr} [(A \wedge a - a \wedge A) \wedge b] + \frac{q}{2} \int_M \text{tr} [(A \wedge b - b \wedge A) \wedge a] \\ &= 0. \end{aligned}$$

As mentioned in Section 1, the 3-form κ which describes the twist on $E_0(M)$ is defined by

$$\kappa_A(a, b, c) = \frac{1}{8\pi^3} \int_M \text{tr} [abc - bac], \quad a, b, c \in T_A \mathcal{A}_M, A \in \mathcal{A}_M,$$

where $abc = a \wedge b \wedge c$ etc..

LEMMA 3.3. *The space of sections $\Gamma(\mathcal{A}_M, \mathcal{D}_M)$ of \mathcal{D}_M is closed under the bracket (3.9):*

$$[\![\Gamma(\mathcal{A}_M, \mathcal{D}_M), \Gamma(\mathcal{A}_M, \mathcal{D}_M)]!]_\kappa \subset \Gamma(\mathcal{A}_M, \mathcal{D}_M).$$

Proof. It suffices to show that

$$\mathcal{L}_{\mathbf{a}}\omega(\mathbf{b}) - i_{\mathbf{b}}\tilde{d}\omega(\mathbf{a}) - i_{\mathbf{a}\wedge\mathbf{b}}\kappa = \omega([\mathbf{a}, \mathbf{b}])$$

for any vector field \mathbf{a}, \mathbf{b} on \mathcal{A}_M . Let \mathbf{a}, \mathbf{b} and \mathbf{c} be vector fields on \mathcal{A}_M and put $a = \mathbf{a}(A)$, $b = \mathbf{b}(A)$ and $c = \mathbf{c}(A)$. From (2.5) and (2.2)

$$\begin{aligned} & (\mathcal{L}_{\mathbf{a}}\omega(\mathbf{b}))_A(c(A)) = \mathcal{L}_{\mathbf{a}}(A \wedge b - b \wedge A)(c) \\ &= \partial_a \langle A \wedge b - b \wedge A \mid c \rangle_M(A) - \langle A \wedge b - b \wedge A \mid [\mathbf{a}, \mathbf{c}](A) \rangle_M \\ &= \langle a \wedge b + A \wedge (\partial_a b) - (\partial_a b) \wedge A - b \wedge a \mid c \rangle_M + \langle A \wedge b - b \wedge A \mid \partial_c a \rangle_M. \end{aligned} \quad (3.12)$$

On the other hand, we see from the formula (2.3) that $i_b \tilde{d}\omega(\mathbf{a})(\mathbf{c})$ is equal to

$$\begin{aligned} \tilde{d}(\omega(\mathbf{a}))_A(b, c) &= \langle \partial_b \omega_A(a) | c \rangle_M - \langle \partial_c \omega_A(a) | b \rangle_M \\ &= \langle b \wedge a + A \wedge (\partial_b a) - (\partial_b a) \wedge A - a \wedge b | c \rangle_M \\ &\quad - \langle c \wedge a + A \wedge (\partial_c a) - (\partial_c a) \wedge A - a \wedge c | b \rangle_M \\ &= \langle b \wedge a + A \wedge (\partial_b a) - (\partial_b a) \wedge A - a \wedge b | c \rangle_M \\ &\quad - \langle a \wedge b - b \wedge a | c \rangle_M - \langle b \wedge A - A \wedge b | \partial_c a \rangle_M. \end{aligned} \quad (3.13)$$

By Eqs.(3.12) and (3.13),

$$\begin{aligned} &\mathcal{L}_{\mathbf{a}}(\omega(\mathbf{b}))_A(c) - \tilde{d}(\omega(\mathbf{a}))_A(b, c) \\ &= \langle A \wedge (\partial_a b) - (\partial_b a) \wedge A - A \wedge (\partial_b a) + (\partial_b a) \wedge A | c \rangle_M + 3 \langle a \wedge b - b \wedge a | c \rangle_M \\ &= \langle A \wedge [a, b] - [a, b] \wedge A | c \rangle_M + 3 \langle a \wedge b - b \wedge a | c \rangle_M \\ &= \langle \omega([a, b]) | c \rangle_A + (i_{a \wedge b} \kappa)_A(c), \end{aligned}$$

which proves the lemma. \square

The definition of twisted Dirac structure in (2.7) together with Lemmas 3.2 and 3.3 yield the following theorem.

THEOREM 3.4. \mathcal{D}_M is a κ -twisted Dirac structure on \mathcal{A}_M .

If a, b, c are $\mathfrak{su}(2)$ -valued 1-forms on M , it holds that $\text{tr}(ab - ba)c = 0$ (see Lemma 1.3 in [9]). Accordingly, \mathcal{D}_M is a non-twisted Dirac structure when $G = \text{SU}(2)$.

3.3. Dirac structures on the space of connections on a 4-manifold X .

3.3.1. The twisted Dirac structure induced from the curvature form.

Let X be a four-manifold with the boundary $\partial X = M$ which may be empty. We denote by \mathcal{A}_X the irreducible connection space for the trivial bundle $X \times G$ over X with $G = \text{SU}(n)$. We denote $\mathfrak{g} = \mathfrak{su}(n)$ for $n \geq 2$. The tangent space $T_A \mathcal{A}_X$ at $A \in \mathcal{A}_X$ is identified with the space $\Omega_{s-\frac{1}{2}}^1(X, \mathfrak{g})$ of \mathfrak{g} -valued 1-forms, and the cotangent space $T_A^* \mathcal{A}_X$ is identified with $\Omega_{s-\frac{1}{2}}^3(X, \mathfrak{g})$. The pairing of $T_A \mathcal{A}_X$ and $T_A^* \mathcal{A}_X$ is given by

$$\langle \alpha | a \rangle_X := \frac{1}{8\pi^3} \int_X \text{tr}(\alpha \wedge a), \quad \text{for } \alpha \in T_A^* \mathcal{A}_X, a \in T_A \mathcal{A}_X.$$

Let $E_0(X) = \mathbb{T}\mathcal{A}_X$ be the standard Courant algebroid over \mathcal{A}_X . We define a twist κ on the Courant algebroid $E_0(X)$ by the following 3-form:

$$\kappa_A(a, b, c) = \kappa_A(\bar{a}, \bar{b}, \bar{c}), \quad \text{for } a, b, c \in T_A \mathcal{A}_X, A \in \mathcal{A}_X, \quad (3.14)$$

where \bar{a}, \bar{b} and \bar{c} indicate the restriction of a, b and c respectively to the boundary M , and the right-hand side is the 3-form κ on \mathcal{A}_M described in the subsection 3.2.

LEMMA 3.5. κ can be represented in the form

$$\begin{aligned} \kappa_A(a, b, c) &= \langle d_A a \wedge b + b \wedge d_A a | c \rangle_X + \langle d_A b \wedge c + c \wedge d_A b | a \rangle_X \\ &\quad + \langle d_A c \wedge a + a \wedge d_A c | b \rangle_X, \end{aligned}$$

for $a, b, c \in T_A \mathcal{A}_X$.

Proof. By the Stokes theorem

$$\kappa_A(a, b, c) = \frac{1}{8\pi^3} \int_M \text{tr} [(ab - ba) \wedge c] = \frac{1}{8\pi^3} \int_X d \text{tr} [(ab - ba) \wedge c].$$

Since

$$\begin{aligned} & d \text{tr} [(ab - ba)c] \\ &= \text{tr} [(d_A a \wedge b - a \wedge d_A b - d_A b \wedge a + b \wedge d_A a) \wedge c + (a \wedge b - b \wedge a) \wedge d_A c] \\ &= \text{tr} [(d_A a \wedge b + b \wedge d_A a) \wedge c] - \text{tr} [(a \wedge d_A b + d_A b \wedge a) \wedge c] \\ &\quad + \text{tr} [(a \wedge b - b \wedge a) \wedge d_A c], \end{aligned} \tag{3.15}$$

the lemma is proved. \square

Let $\phi : T\mathcal{A}_X \rightarrow T^*\mathcal{A}_X$ be a bundle homomorphism defined by

$$\phi_A(a) := F_A \wedge a + a \wedge F_A, \quad \text{for } a \in T_A \mathcal{A}_X, A \in \mathcal{A}_X, \tag{3.16}$$

where F_A is the curvature form of $A \in \mathcal{A}_X$. Let \mathcal{D}_X^ϕ be the vector subbundle of $E_0(X)$ defined by

$$\mathcal{D}_X^\phi := \coprod_{A \in \mathcal{A}_X} \left\{ a \oplus \phi_A(a) \mid a \in T_A \mathcal{A}_X \right\}. \tag{3.17}$$

We shall show that \mathcal{D}_X^ϕ gives a κ -twisted Dirac structure on \mathcal{A}_X .

First, for vector fields \mathbf{a} and \mathbf{b} on \mathcal{A}_X , we have

$$\begin{aligned} \langle \phi(\mathbf{a}) \mid \mathbf{b} \rangle_X(A) &= \frac{1}{8\pi^3} \int_X \text{tr} (\phi_A(a) \wedge b) = \frac{1}{8\pi^3} \int_X \text{tr} (F_A \wedge a \wedge b + a \wedge F_A \wedge b) \\ &= \frac{1}{8\pi^3} \int_X \text{tr} [(a \wedge b - b \wedge a) \wedge F_A], \end{aligned}$$

where $a = \mathbf{a}(A)$ and $b = \mathbf{b}(A)$. Then we have the following:

PROPOSITION 3.6. *It holds that*

$$\langle \phi(\mathbf{a}) \mid \mathbf{b} \rangle_X + \langle \phi(\mathbf{b}) \mid \mathbf{a} \rangle_X = 0 \tag{3.18}$$

for any vector fields \mathbf{a}, \mathbf{b} on \mathcal{A}_X .

Next, we shall show that the sections of \mathcal{D}_X^ϕ is closed under the bracket $[\cdot, \cdot]_\kappa$.

LEMMA 3.7. *Let \mathbf{a}, \mathbf{b} and \mathbf{c} be vector fields on \mathcal{A}_X and put $a = \mathbf{a}(A), b = \mathbf{b}(A), c = \mathbf{c}(A)$ for $A \in \mathcal{A}_X$. We have the following formulas:*

$$\begin{aligned} (\mathcal{L}_{\mathbf{a}} \phi(\mathbf{b}))_A(c) &= \langle \phi_A(\partial_a \mathbf{b}) \mid c \rangle_X + \langle d_A a \wedge b + b \wedge d_A a \mid c \rangle_X \\ &\quad + \langle \phi_A(b) \mid (\partial_c \mathbf{a})(A) \rangle_X, \end{aligned} \tag{3.19}$$

and

$$\begin{aligned} (i_{\mathbf{b}} \tilde{d}\phi(\mathbf{a}))_A(c) &= \langle \phi_A(\partial_b \mathbf{a}) \mid c \rangle_X + \langle \phi_A(b) \mid (\partial_c \mathbf{a})(A) \rangle_X \\ &\quad - \langle d_A b \wedge c + c \wedge d_A b \mid a \rangle_X - \langle a \wedge d_A c + d_A c \wedge a \mid b \rangle_X. \end{aligned} \tag{3.20}$$

Proof. Since $\partial_a F_A = d_A a$ for the curvature F_A of A . We have from (2.2) and (2.5),

$$\begin{aligned}
& (\mathcal{L}_a \phi(\mathbf{b}))_A(c) \\
&= \mathcal{L}_a(F_A \wedge b + b \wedge F_A)(c) \\
&= \partial_a \langle F_A \wedge b + b \wedge F_A \mid c \rangle_X - \langle F_A \wedge b + b \wedge F_A \mid [\mathbf{a}, \mathbf{c}](A) \rangle_X \\
&= \langle d_A a \wedge b + F_A \wedge \partial_a b + \partial_a b \wedge F_A + b \wedge d_A a \mid c \rangle_X + \langle F_A \wedge b + b \wedge F_A \mid \partial_a c \rangle_X \\
&\quad - \langle F_A \wedge b + b \wedge F_A \mid \partial_a c - \partial_c a \rangle_X \\
&= \langle F_A \wedge \partial_a b + \partial_a b \wedge F_A \mid c \rangle_X + \langle d_A a \wedge b + b \wedge d_A a \mid c \rangle_X + \langle F_A \wedge b + b \wedge F_A \mid \partial_c a \rangle_X,
\end{aligned}$$

which proves the first formula (3.19). Next, we have

$$\begin{aligned}
& (i_{\mathbf{b}} \tilde{d}\phi(\mathbf{a}))_A(c) \tag{3.21} \\
&= (\tilde{d}(F_A \wedge a + a \wedge F_A))_A(b, c) \\
&= \partial_b \langle F_A \wedge a + a \wedge F_A \mid c \rangle_X - \partial_c \langle F_A \wedge a + a \wedge F_A \mid b \rangle_X - \langle a \wedge F_A + F_A \wedge a \mid [b, c] \rangle_X \\
&= \langle F_A \wedge \partial_b a + \partial_b a \wedge F_A + a \wedge d_A b + d_A b \wedge a \mid c \rangle_X + \langle a \wedge F_A + F_A \wedge a \mid \partial_b c \rangle \\
&\quad - \langle F_A \wedge \partial_c a + \partial_c a \wedge F_A + a \wedge d_A c + d_A c \wedge a \mid b \rangle_X - \langle a \wedge F_A + F_A \wedge a \mid \partial_c b \rangle_X \\
&\quad - \langle a \wedge F_A + F_A \wedge a \mid \partial_b c - \partial_c b \rangle_X \\
&= \langle F_A \wedge \partial_b a + \partial_b a \wedge F_A \mid c \rangle_X + \langle F_A \wedge b + b \wedge F_A \mid \partial_c a \rangle_X \\
&\quad - \langle c \wedge d_A b + d_A b \wedge c \mid a \rangle_X - \langle a \wedge d_A c + d_A c \wedge a \mid b \rangle_X,
\end{aligned}$$

where we used $\langle a \wedge d_A b + d_A b \wedge a \mid c \rangle_X = -\langle c \wedge d_A b + d_A b \wedge c \mid a \rangle_X$. The second formula (3.20) is proved. \square

Lemmas 3.5 and 3.7 yield the following:

PROPOSITION 3.8. *For any vector field \mathbf{a}, \mathbf{b} on \mathcal{A}_X ,*

$$\mathcal{L}_{\mathbf{a}} \phi(\mathbf{b}) - i_{\mathbf{b}} \tilde{d}\phi(\mathbf{a}) - i_{\mathbf{a} \wedge \mathbf{b}} \kappa = \phi([\mathbf{a}, \mathbf{b}]).$$

Propositions 3.6 and 3.8 yield the following:

THEOREM 3.9.

$$\mathcal{D}_X^\phi := \coprod_{A \in \mathcal{A}_X} \left\{ a \oplus \phi_A(a) \mid a \in T_A \mathcal{A}_X \right\}$$

is a κ -twisted Dirac structure.

3.3.2. A non-twisted Dirac structure on \mathcal{A}_X . On the subspace of flat connections $\mathcal{A}_X^\flat \subset \mathcal{A}_X$ the subspace $\mathcal{D}_X^\phi \subset E_0(X)$ reduces to the subspace $T\mathcal{A}_X^\flat \oplus T\mathcal{A}_X^\flat$. That implies no knowledge about the Courant algebroid structure on $T\mathcal{A}_X^\flat \oplus T^*\mathcal{A}_X^\flat$. In the sequel we shall introduce a more precise Dirac structure over \mathcal{A}_X that relates to the winding number of flat connections.

We introduce the following bundle homomorphism:

$$\gamma'_A(a) = A^2 \wedge a + a \wedge A^2, \quad A \in \mathcal{A}_X, \tag{3.22}$$

where $A^2 = A \wedge A$.

THEOREM 3.10. *The subbundle of $E_0(X)$ given by*

$$\mathcal{D}'_X := \coprod_{A \in \mathcal{A}_X} \left\{ a \oplus \gamma'_A(a) \mid a \in T_A \mathcal{A}_X \right\}$$

is a Dirac structure.

For the proof we verify the following two conditions:

$$(1) \quad \langle \tilde{\mathbf{a}}, \tilde{\mathbf{b}} \rangle_+ = 0,$$

$$(2) \quad \mathcal{L}_{\mathbf{a}} \gamma'(\mathbf{b}) - i_{\mathbf{b}} \tilde{d}\gamma'(\mathbf{a}) = \gamma'([\mathbf{a}, \mathbf{b}])$$

for $\tilde{\mathbf{a}} = \mathbf{a} \oplus \gamma'(\mathbf{a})$ and $\tilde{\mathbf{b}} = \mathbf{b} \oplus \gamma'(\mathbf{b})$. It is easy to check (1) since

$$\langle \gamma'(a) \mid b \rangle_X = \frac{1}{8\pi^3} \int_X \text{tr}(A^2 \wedge a + a \wedge A^2) \wedge b = \frac{1}{8\pi^3} \int_X \text{tr}[(a \wedge b - b \wedge a) \wedge A^2].$$

As for (2), the Lie derivative $\mathcal{L}_{\mathbf{a}} \gamma'(\mathbf{b})$ is calculated to be

$$\begin{aligned} (\mathcal{L}_{\mathbf{a}} \gamma'(\mathbf{b}))_A(c) &= \mathcal{L}_{\mathbf{a}}(A^2 \wedge b + b \wedge A^2)(c) \\ &= \partial_{\mathbf{a}} \langle A^2 \wedge b + b \wedge A^2 \mid c \rangle_X - \langle A^2 \wedge b + b \wedge A^2 \mid [\mathbf{a}, \mathbf{c}](A) \rangle_X \\ &= \langle (a \wedge A + A \wedge a) \wedge b + b \wedge (a \wedge A + A \wedge a) + A^2 \wedge \partial_a b + \partial_a b \wedge A^2 \mid c \rangle_X \\ &\quad + \langle A^2 \wedge b + b \wedge A^2 \mid \partial_a c \rangle_X - \langle A^2 \wedge b + b \wedge A^2 \mid \partial_a c - \partial_c a \rangle_X \\ &= \langle (a \wedge A + A \wedge a) \wedge b \mid c \rangle_X + \langle b \wedge (a \wedge A + A \wedge a) \mid c \rangle_X \\ &\quad + \langle A^2 \wedge \partial_a b + \partial_a b \wedge A^2 \mid c \rangle_X + \langle A^2 \wedge b + b \wedge A^2 \mid \partial_c a \rangle_X. \end{aligned}$$

On the other hand, we have by (2.3) the following:

$$\begin{aligned} (i_{\mathbf{b}} \tilde{d}\gamma'(\mathbf{a}))_A(c) &= (\tilde{d}(A^2 \wedge a + a \wedge A^2))_A(b, c) \\ &= \langle \partial_b(A^2 \wedge a + a \wedge A^2) \mid c \rangle_X - \langle \partial_c(A^2 \wedge a + a \wedge A^2) \mid b \rangle_X \\ &= \langle (b \wedge A + A \wedge b) \wedge a + A^2 \wedge \partial_b a + \partial_b a \wedge A^2 + a \wedge (b \wedge A + A \wedge b) \mid c \rangle_X \\ &\quad - \langle (c \wedge A + A \wedge c) \wedge a + A^2 \wedge \partial_c a + \partial_c a \wedge A^2 + a \wedge (c \wedge A + A \wedge c) \mid b \rangle_X \\ &= \langle (a \wedge A + A \wedge a) \wedge b \mid c \rangle_X + \langle b \wedge (a \wedge A + A \wedge a) \mid c \rangle_X \\ &\quad + \langle A^2 \wedge \partial_b a + \partial_b a \wedge A^2 \mid c \rangle_X + \langle A^2 \wedge b + b \wedge A^2 \mid \partial_c a \rangle_X. \end{aligned}$$

Therefore,

$$\begin{aligned} (\mathcal{L}_{\mathbf{a}} \gamma'(\mathbf{b}))_A(c) - (i_{\mathbf{b}} \tilde{d}\gamma'(\mathbf{a}))_A(c) &= \langle A^2 \wedge (\partial_a b - \partial_b a) + (\partial_a b - \partial_b a) \wedge A^2 \mid c \rangle_X \\ &= \langle A^2 \wedge [\mathbf{a}, \mathbf{b}](A) + [\mathbf{a}, \mathbf{b}](A) \wedge A^2 \mid c \rangle_X \\ &= \langle \gamma'_A([\mathbf{a}, \mathbf{b}](A)) \mid c \rangle_X, \end{aligned}$$

which proves (2).

3.3.3. A family of κ -twisted Dirac structures on \mathcal{A}_X . Now we discuss the perturbation of the κ -twisted Dirac structure \mathcal{D}_X^ϕ by the (non-twisted) Dirac structure \mathcal{D}'_X . We consider the bundle homomorphism $\gamma^t : T\mathcal{A}_X \rightarrow T^*\mathcal{A}_X$ given by

$$\gamma_A^t(a) := (F_A + t A^2) \wedge a + a \wedge (F_A + t A^2), \quad t \in \mathbb{R}. \quad (3.23)$$

We have $\gamma^t = \phi + t\gamma'$.

The following theorem is a consequence of Theorems 3.9 and 3.10

THEOREM 3.11. *For $t \in \mathbb{R}$, put*

$$\mathcal{D}_X^t := \coprod_{A \in \mathcal{A}_X} \left\{ a \oplus \gamma_A^t(a) \mid a \in T_A \mathcal{A}_X \right\}. \quad (3.24)$$

Then $\{\mathcal{D}_X^t\}_{t \in \mathbb{R}}$ gives a family of κ -twisted Dirac structures.

3.3.4. Dirac structure over the space of flat connections. In this subsection, we shall describe several Dirac structures on flat connections. Let

$$\mathcal{A}_X^\flat = \{ A \in \mathcal{A}_X \mid F_A = 0 \}$$

be the space of flat connections on a $SU(n)$ -bundle over a 4-manifold X with $\partial X = M$. The tangent space to \mathcal{A}_X^\flat at A is given by

$$T_A \mathcal{A}_X^\flat = \{ a \in \Omega_{s-\frac{1}{2}}^1(X, \mathfrak{g}) \mid d_A a = 0 \}.$$

If vector fields \mathbf{a}, \mathbf{b} on \mathcal{A}_X^\flat satisfy $d_A a = d_A b = 0$ with $a = \mathbf{a}(A), b = \mathbf{b}(A)$ at each $A \in \mathcal{A}_X^\flat$, then their Lie bracket $[\mathbf{a}, \mathbf{b}]$ again satisfies $d_A[a, b] = 0$ at A because $d_A[a, b] = [d_A a, b] + [a, d_A b]$. So, $T \mathcal{A}_X^\flat$ is a integrable subspace of $T \mathcal{A}_X$.

Let

$$\mathcal{D}_X^\flat := \coprod_{A \in \mathcal{A}_X} \left\{ a \oplus \gamma_A^1(a) \mid a \in T_A \mathcal{A}_X^\flat \right\}, \quad (3.25)$$

with

$$\gamma_A^1(a) = \gamma'_A(a) := A^2 \wedge a + a \wedge A^2, \quad A \in \mathcal{A}_X^\flat. \quad (3.26)$$

By virtue of Lemma 3.5, we know that the Cartan 3-form κ vanishes on \mathcal{A}_X^\flat . Therefore we have the following:

THEOREM 3.12. *\mathcal{D}_X^\flat is a Dirac structure over $\mathcal{A}_X^\flat \subset \mathcal{A}_X$.*

Now we shall look at the restriction of the Dirac manifold \mathcal{D}_X^\flat to the boundary M of X . Let \mathcal{A}_M^\flat be the space of flat connections over M :

$$\mathcal{A}_M^\flat = \{ A \in \mathcal{A}_M \mid F_A = 0 \}.$$

The tangent space of \mathcal{A}_M^\flat at $A \in \mathcal{A}_M^\flat$ is given by

$$T_A \mathcal{A}_M^\flat = \{ a \in \Omega_{s-1}^1(M, \mathfrak{g}) \mid d_A a = 0 \}.$$

Let X be an oriented 4-manifold whose boundary is M and let \mathbf{P} be the principal G -bundle over X that extends P . As we have remarked in the subsection 3.1, a connection A on P has an extension to a connection \mathbf{A} on \mathbf{P} . Then the boundary restriction map $r : \mathcal{A}_X \rightarrow \mathcal{A}_M$ is well defined and surjective. The tangent map of r at $\mathbf{A} \in \mathcal{A}_X$ is also given by the restriction to the boundary:

$$(\partial r)_{\mathbf{A}} : T_{\mathbf{A}} \mathcal{A}_X = \Omega_{s-\frac{1}{2}}^1(X, \mathfrak{g}) \longrightarrow T_{\mathbf{A}} \mathcal{A}_M = \Omega_{s-1}^1(M, \mathfrak{g}), \quad A = r(\mathbf{A}).$$

In [10], it is proved that the space of flat connections \mathcal{A}_X^\flat is mapped by r onto the space of flat connections over M that are of degree 0:

$$\mathcal{A}_M^{\flat, \deg 0} = \left\{ A \in \mathcal{A}_M^\flat \mid \int_M \text{tr } A^3 = 0 \right\}.$$

Let \mathcal{D}_M^\flat and $\mathcal{D}_M^{\flat, \deg 0}$ be the subbundles of $E^\flat(M)$ that are defined by

$$\mathcal{D}_M^\flat = \left\{ a \oplus \omega_A(a) \mid a \in T_A \mathcal{A}_M^\flat, A \in \mathcal{A}_M^\flat \right\},$$

and

$$\mathcal{D}_M^{\flat, \deg 0} = \left\{ a \oplus \omega_A(a) \mid a \in T_A \mathcal{A}_M^{\flat, \deg 0}, A \in \mathcal{A}_M^{\flat, \deg 0} \right\}.$$

LEMMA 3.13. *For any $a \in T_A \mathcal{A}_X^\flat$ we have*

$$\gamma_A^1(a) = \omega_{r(A)}((\partial r)_A(a)). \quad (3.27)$$

Proof. Let $A \in \mathcal{A}_X^\flat$ and $a, b \in T_A \mathcal{A}_X^\flat$. Put $A' = r(A) \in \mathcal{A}_M^\flat$, $\bar{a} = (\partial r)_A(a) \in T_{A'} \mathcal{A}_M^\flat$ and $\bar{b} = (\partial r)_A(b) \in T_{A'} \mathcal{A}_M^\flat$. We have

$$\langle \omega_{A'}(\bar{a}) \mid \bar{b} \rangle = q \int_M \text{tr}[(\bar{a} \bar{b} - \bar{b} \bar{a}) A'] = q \int_X \text{d} \text{tr}[(ab - ba) A].$$

Since $F_A = 0$ and $\text{d}_A a = \text{d}_A b = 0$ for $a, b \in T_A \mathcal{A}_X^\flat$, by a similar calculation as in (3.15) we find that the last formula is equal to

$$q \int_X \text{tr}[(ab - ba) \text{d}_A A] = q \int_X \text{tr}[(ab - ba) A^2] = \langle \gamma_A^1(a) \mid b \rangle.$$

□

From the discussion hitherto we are convinced to have the following consequences.

THEOREM 3.14.

- (1) \mathcal{D}_M^\flat is a Dirac structure over \mathcal{A}_M^\flat .
- (2) $\mathcal{D}_M^{\flat, \deg 0}$ is a Dirac structure over $\mathcal{A}_M^{\flat, \deg 0}$.
- (3) The boundary restriction map r implies an isomorphism between the Dirac structures \mathcal{D}_X^\flat and $\mathcal{D}_M^{\flat, \deg 0}$.

4. The action of the group of gauge transformations on Dirac spaces.

Let $G = \text{SU}(n)$ and $P \rightarrow N$ be a G -principal bundle over a n -dimensional Riemannian manifold N as in subsection 2.1. Let $\text{Ad } P$ be the fiber bundle $\text{Ad } P = P \times_G G \rightarrow N$. The group of smooth sections of $\text{Ad } P$ under the fiber-wise multiplication is called *the group of gauge transformations*. We denote by \mathcal{G}'_N the group of L_s^2 -gauge transformations, i.e., $\mathcal{G}'_N = \Omega_s^0(N, \text{Ad } P)$. \mathcal{G}'_N acts on \mathcal{A}_N by

$$g \cdot A = g^{-1} \text{d}g + g^{-1} A g = A + g^{-1} \text{d}_A g, \quad g \in \mathcal{G}'_N.$$

\mathcal{G}'_N is a Hilbert Lie Group and its action is a smooth map of Hilbert manifolds. The action of $g \in \mathcal{G}'_N$ on the tangent space $T_A \mathcal{A}_N$ is given by

$$\text{Ad}_{g^{-1}} : T_A \mathcal{A}_N \ni a \mapsto \text{Ad}_{g^{-1} a} = g^{-1} a g \in T_A \mathcal{A}_N.$$

We choose a fixed point $p_0 \in N$ and deal with the group of gauge transformations that are identity at p_0 :

$$\mathcal{G}_N = \{g \in \mathcal{G}'_N \mid g(p_0) = 1\}.$$

\mathcal{G}_N acts freely on \mathcal{A}_N . We have $\text{Lie } \mathcal{G}_N = \Omega_s^0(N, \text{ad } P)$. The action of $\text{Lie } \mathcal{G}_N$ on \mathcal{A}_N is given by the covariant exterior derivative:

$$d_A = d + [A \wedge \cdot] : \text{Lie } \mathcal{G}_N = \Omega_s^0(N, \text{ad } P) \ni \xi \longrightarrow d_A \xi \in \Omega_{s-1}^1(N, \text{ad } P) = T_A \mathcal{A}_N.$$

So, the fundamental vector field on \mathcal{A}_N corresponding to $\xi \in \text{Lie } \mathcal{G}_N$ is given by

$$d_A \xi = \left. \frac{d}{dt} \right|_{t=0} (\exp t\xi) \cdot A.$$

$\ker d_A = 0$ because $A \in \mathcal{A}_N$ is irreducible by our assumption. The tangent space to the orbit at $A \in \mathcal{A}_N$ is

$$T_A(\mathcal{G}_N \cdot A) = \{d_A \xi \mid \xi \in \Omega_s^0(N, \text{ad } P)\}.$$

Moreover, $\{d_A \xi \mid \xi \in \text{Lie } \mathcal{G}_N\}$ is tangent to the space of flat connections \mathcal{A}_N^\flat , because $d_A(d_A \xi) = [F_A, \xi] = 0$ on \mathcal{A}_N^\flat . Evidently, the condition $F_A = 0$ is \mathcal{G}_N -invariant, so \mathcal{A}_N^\flat is also \mathcal{G}_N -invariant manifold,

Now we restrict ourselves to the case treated previously, that is, $N = X$ is a four-manifold or $N = M$ is the boundary three-manifold $M = \partial X$.

4.1. \mathcal{D}_X^ϕ under the action of \mathcal{G}_X . Let $\phi_A : T_A \mathcal{A}_X \longrightarrow T_A^* \mathcal{A}_X$ be the bundle homomorphism $\phi_A(a) = F_A \wedge a + a \wedge F_A$ in (3.16). Since $F_{g \cdot A} = g^{-1} F_A g$, we have

$$\phi_{g \cdot A} = g^{-1} \phi_A g. \quad (4.1)$$

We also see that κ is invariant under \mathcal{G}_X . Therefore we have the following;

PROPOSITION 4.1. *The κ -twisted Dirac manifold \mathcal{D}_X^ϕ is invariant under the action of \mathcal{G}_X .*

4.2. \mathcal{D}_M under the infinitesimal action of \mathcal{G}_M . In [10] we saw that the action of \mathcal{G}_M on the space of flat connections \mathcal{A}_M^\flat is infinitesimally presymplectic, that is, the Lie derivative of the 2-form ω in (3.3) by the fundamental vector field $d_A \xi$ vanishes:

$$\mathcal{L}_{d_A \xi} \omega = 0, \quad A \in \mathcal{A}_M^\flat, \quad (4.2)$$

The counterpart of this assertion for the infinitesimal action of \mathcal{G}_M on the Dirac structure \mathcal{D}_M^\flat holds as well. We shall explain it in the following.

We have the canonical skew symmetric form Λ_0 on $E_0(M) = T \mathcal{A}_M \oplus T^* \mathcal{A}_M$ as defined in (2.8)

$$\Lambda_0(a \oplus \alpha \mid b \oplus \beta) := \frac{1}{2} \{ \langle \alpha \mid b \rangle_M - \langle \beta \mid a \rangle_M \}.$$

We know that the space of connections \mathcal{A}_M admits the Dirac structure

$$\mathcal{D}_M = \coprod_{A \in \mathcal{A}_M} \left\{ a \oplus \omega_A(a) \mid a \in T_A \mathcal{A}_M \right\}, \quad \omega_A(a) = Aa - aA.$$

whose anchor map is $\rho : E_0(M) \longrightarrow T\mathcal{A}_M$ (see (3.10)).

LEMMA 4.2. *Restricted to \mathcal{D}_M the canonical 2-form Λ_0 is the pull back of the presymplectic form ω by ρ : $\Lambda_0|_{\mathcal{D}_M} = \rho^*\omega$.*

Proof. For any section $\mathbf{a} \oplus \omega(\mathbf{a}), \mathbf{b} \oplus \omega(\mathbf{b})$ of \mathcal{D}_M , we have

$$\begin{aligned}\Lambda_0(a \oplus \omega_A(a) \mid b \oplus \omega_A(b)) &= \frac{1}{2} \{ \langle Aa - aA \mid b \rangle - \langle Ab - bA \mid a \rangle \} \\ &= q \int_M \text{tr} [(ab - ba) A] = \omega_A(a, b),\end{aligned}$$

which is equal to $(\rho^*\omega)(a \oplus \omega_A(a), b \oplus \omega_A(b))$. \square

$\text{Lie } \mathcal{G}_M$ acts on $\mathcal{D}_M \subset E_0(M)$ by the fundamental vector field

$$\mathbf{v}_\xi = d_A \xi \oplus \omega_A(d_A \xi), \quad \xi \in \text{Lie } \mathcal{G}_M, \quad A \in \mathcal{A}_M.$$

The derivation of the 2-form Λ_0 along the orbit of $\text{Lie } \mathcal{G}_M$ is given by the Lie derivative $\mathcal{L}_{\mathbf{v}_\xi(A)} \Lambda_0$. Then, we have the following result.

PROPOSITION 4.3. *It holds that $\mathcal{L}_{\mathbf{v}_\xi(A)} \Lambda_0 = 0$ at each $A \in \mathcal{A}_M^\flat$. Hence the action of \mathcal{G}_M on the Dirac manifold \mathcal{D}_M^\flat is infinitesimally symplectic.*

Proof. Since $\rho(\mathbf{v}_\xi(A)) = \rho(d_A \xi \oplus \omega_A(d_A \xi)) = d_A \xi$, Lemma 4.2 and the equation (4.2) imply

$$\mathcal{L}_{\mathbf{v}_\xi(A)} \Lambda_0 = \mathcal{L}_{d_A \xi \oplus \omega_A(d_A \xi)} (\rho^*\omega) = \rho^*(\mathcal{L}_{d_A \xi} \omega) = 0.$$

\square

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