# Quasi-local mass on unit spheres at spatial infinity 

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#### Abstract

In this note, we compute the limit of the Wang-Yau quasi-local mass on unit spheres at spatial infinity of an asymptotically flat initial data set. Similar to the small sphere limit of the WangYau quasi-local mass, we prove that the leading order term of the quasi-local mass recovers the stress-energy tensor. For a vacuum spacetime, the quasi-local mass decays faster and the leading order term is related to the Bel-Robinson tensor. Several new techniques of evaluating quasilocal mass are developed in this note.


1 Introduction ..... 746
2 eview of the Wang-Yau quasi-local mass and asymptotical flatness ..... 749
3 The Brown-York mass ..... 752
4 Optimal embedding equation and the Jang equation ..... 755
5 Limit of the Wang-Yau mass ..... 757
6 Small sphere limit ..... 770
References ..... 774
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## 1. Introduction

In general relativity, a spacetime is a 4-manifold $N$ with a Lorentzian metric $g_{\alpha \beta}$ satisfying the Einstein equation

$$
R_{\alpha \beta}-\frac{R}{2} g_{\alpha \beta}=8 \pi T_{\alpha \beta}
$$

where $R_{\alpha \beta}$ and $R$ are the Ricci curvature and the scalar curvature of the metric $g_{\alpha \beta}$, respectively. On the right hand side of the Einstein equation, $T_{\alpha \beta}$ is the stress-energy tensor of the matter field, a divergence free and symmetric 2-tensor. For most matter fields, $T_{\alpha \beta}$ satisfies the dominant energy condition. For a vacuum spacetime where $T_{\alpha \beta}=0$ (which implies $R_{\alpha \beta}=0$ ), one way of measuring the gravitational energy is to consider the Bel-Robinson tensor [1]

$$
\begin{equation*}
Q_{\mu \nu \alpha \beta}=W_{\mu}^{\rho}{ }_{\mu}{ }_{\alpha}{ }_{\alpha} W_{\rho \nu \sigma \beta}+W_{\mu}^{\rho}{ }_{\mu}{ }_{\beta} W_{\rho \nu \sigma \alpha}-\frac{1}{2} g_{\mu \nu} W_{\alpha}{ }^{\rho \sigma \tau} W_{\beta \rho \sigma \tau} \tag{1.1}
\end{equation*}
$$

where $W_{\alpha \beta \gamma \delta}$ is the Weyl curvature tensor of the spacetime $N$. For a vacuum spacetime, the Bel-Robinson tensor is a divergence free and totally symmetric 4 -tensor which also satisfies a certain positivity condition [11, Lemma 7.1.1].

We recall that given a spacelike 2 -surface $\Sigma$ in a spacetime $N$, the WangYau quasi-local energy $E\left(\Sigma, \mathcal{X}, T_{0}\right)$ (see (2.1)) is defined in [27, 28] with respect to each pair $\left(\mathcal{X}, T_{0}\right)$ of an isometric embedding $\mathcal{X}$ of $\Sigma$ into the Minkowski space $\mathbb{R}^{3,1}$ and a constant future timelike unit vector $T_{0} \in \mathbb{R}^{3,1}$. If the spacetime satisfies the dominant energy condition and the pair $\left(\mathcal{X}, T_{0}\right)$ is admissible (see [28, Definition 5.1]), it is proved that $E\left(\Sigma, \mathcal{X}, T_{0}\right) \geq 0$. The Wang-Yau quasi-local mass is defined to be the infimum of the quasi-local energy among all admissible pairs $\left(\mathcal{X}, T_{0}\right)$. The Euler-Lagrange equation for the critical points of the quasi-local energy is derived in [28]. The EulerLagrange equation, coupled with the isometric embedding equation, is referred to as the optimal embedding equation, see (2.2). A solution to the equation is referred to as an optimal embedding.

When studying different notions of quasi-local energy, it is natural to evaluate the large sphere and the small sphere limits of the quasi-local energy and compare with the known measures of the gravitational energy in these situations. One expects the following [12, 23]:

1) For a family of surfaces approaching the spatial/null infinity of an isolated system (the large sphere limit), the limit of the quasi-local energy recovers the total energy-momentum of the isolated system.
2) For a family of surfaces approaching a point $p$ (the small sphere limit), the limit of the quasi-local energy recovers the stress-energy tensor for spacetimes with matter fields and the Bel-Robinson tensor for vacuum spacetimes.

There are many works on evaluating the large sphere and the small sphere limits of different notions of quasi-local energy. See for example [3[6, 14, 15, 18, 20, 22, 29-31. The list here is by no means exhaustive. For a more comprehensive review of different notions of quasi-local energy and their limiting behaviors, see [25] and the references therein.

In a series of papers [5, 6, 29], the above expectations for the WangYau quasi-local energy were verified. One of the key observations in [29] (see [29, Theorem 2.1]) is that for a family of surfaces $\Sigma_{r}$ and isometric embeddings $\mathcal{X}_{r}$, the limit of $E\left(\Sigma_{r}, \mathcal{X}_{r}, T_{0}\right)$ is a linear function of $T_{0}$ under the compatibility condition

$$
\begin{equation*}
\lim _{r \rightarrow r_{0}} \frac{\left|H_{0}\right|}{|H|}=1 \tag{1.2}
\end{equation*}
$$

where $H$ and $H_{0}$ are the mean curvature vectors of $\Sigma_{r}$ in $N$ and the image of the isometric embedding $\mathcal{X}_{r}$ in $\mathbb{R}^{3,1}$, respectively. The compatibility condition (1.2) holds naturally in the large sphere limit $\left(r_{0}=\infty\right)$ at both spatial and null infinity and the small sphere limit ( $r_{0}=0$ ) around a point. In particular, [29, Theorem 2.1] is used throughout the sequence of papers [5, 6, 29 .

In addition to the large sphere limit and the small sphere limit, there is another interesting situation where the compatibility condition holds naturally, namely, the limit of the quasi-local mass on unit spheres at infinity of an asymptotically flat spacetime. In a series of papers [9, 10], we evaluated the limit at null infinity to capture the information of gravitational radiation. In particular, this is carried out in [10] for the Vaidya spacetime. In this note, we evaluate the limit for unit spheres at spatial infinity of an asymptotically flat spacetime, namely, at infinity of an asymptotically flat initial data set.

Theorem 1.1. Let $(M, g, k)$ be an asymptotically flat initial data set as in (2.1). Let $\gamma$ be a geodesic on $M$ which is parametrized by arc-length and extends to infinity. Let $p=\gamma(d)$ be a point on $\gamma$ and $\Sigma$ be the unit geodesic
sphere in $M$ that is centered at $p=\gamma(d)$. The quasi-local mass $E\left(\Sigma, \mathcal{X}, T_{0}\right)$ for $T_{0}=\left(a_{0},-a_{1},-a_{2},-a_{3}\right)$ has the following asymptotic behavior as $d \rightarrow \infty$ for each of the following isometric embeddings $\mathcal{X}$ of $\Sigma$.

1) For the isometric embedding $\mathcal{X}: \Sigma \rightarrow \mathbb{R}^{3}$, we have

$$
E\left(\Sigma, \mathcal{X}, T_{0}\right)=\frac{1}{6}\left(a_{0} \mu(p)-a_{i} J^{i}(p)\right)+O\left(d^{-3-2 \alpha}\right)
$$

where $\mu$ and $J^{i}$ are defined in 2.5 and 2.6.
2) Suppose the initial data set $(M, g, k)$ satisfies the vacuum constraint equation (2.7). Let $N$ be the future development of $(M, g, k)$ with Weyl curvature $\bar{W}$. Let $e_{0}, e_{1}, e_{2}, e_{3}$ be an orthonormal basis at $p$ with $e_{0}$ the unit timelike normal of $M$ in $N$. For $\left(\mathcal{X}, T_{0}\right)$ solving the leading order of the optimal embedding equation (2.2), we have

$$
E\left(\Sigma, \mathcal{X}, T_{0}\right)=\frac{1}{90}\left(Q\left(e_{0}, e_{0}, e_{0}, T_{0}\right)+\frac{1}{2 a_{0}} \bar{W}_{0 i 0 j} \bar{W}_{0}{ }_{0}{ }_{0}{ }^{j}\right)+O\left(d^{-4-3 \alpha}\right) .
$$

Here $\bar{W}_{0 i 0 j}=\bar{W}\left(e_{0}, e_{i}, e_{0}, e_{j}\right)(p), Q$ is the Bel-Robinson tensor of $N$ at $p$, and $T_{0}$ is identified with the timelike vector $a_{0} e_{0}+\sum_{i=1}^{3} a_{i} e_{i}$ at $p$.

Our investigation begins with the Brown-York mass. We compute the derivative of the Brown-York mass and use it to rewrite the Brown-York mass as a bulk integral. The integrand consists of the scalar curvature and quadratic terms of the difference of the physical and the reference data, see Lemma 3.1. We use Lemma 3.1 to evaluate the limit in Theorem 3.3, The scalar curvature corresponds to the stress-energy tensor whereas the quadratic terms, which decay faster than the scalar curvature, correspond to the Bel-Robinson tensor.

In the remaining part of this article, we consider the Wang-Yau quasilocal mass for initial data sets which are not necessarily time-symmetric. We start by solving the optimal embedding equation. The structure of the equation is similar to that of [6] for the small sphere limit and of [10] for unit spheres at null infinity of the Vaidya spacetime. After obtaining the optimal embedding, we use it as the Dirichlet boundary value to solve Jang's equation in the bulk. Using the Schoen-Yau identity from [24] and the canonical gauge for the quasi-local mass from [27], we obtain Theorem 4.1] which generalizes Theorem 3.3 for the Wang-Yau quasi-local mass. While the formula is more complicated, it still consists of the integral of the stress-energy tensor and some quadratic terms. In Section 5, we compute the terms appearing in

Theorem 4.1 explicitly and evaluate the limit. Theorem 1.1 is obtained after assembling these results. We observe that the answer is very similar to the small sphere limit obtained in [6]. In Section 6, we demonstrate how the new approach of this article can be applied to recover the result of [6] for the small sphere limit.

## 2. Review of the Wang-Yau quasi-local mass and asymptotical flatness

Let $\Sigma$ be a closed spacelike 2 -surface in a spacetime $N$ with spacelike mean curvature vector $H$. Denote the induced metric and connection one-form of $\Sigma$ by $\sigma$ and

$$
\alpha_{H}(\cdot)=\left\langle\nabla_{(\cdot)}^{N} \frac{J}{|H|}, \frac{H}{|H|}\right\rangle
$$

where $J$ is the reflection of $H$ through the incoming light cone in the normal bundle. Given an isometric embedding $\mathcal{X}: \Sigma \rightarrow \mathbb{R}^{3,1}$ and future timelike unit Killing field $T_{0}$ in $\mathbb{R}^{3,1}$, we consider the projected embedding $\widehat{\mathcal{X}}$ into the orthogonal complement of $T_{0}$, and denote the induced metric and the mean curvature of the image surface $\widehat{\Sigma}$ by $\widehat{\sigma}$ and $\widehat{H}$.

The quasi-local energy with respect to $\left(\mathcal{X}, T_{0}\right)$ is

$$
\begin{align*}
E\left(\Sigma, \mathcal{X}, T_{0}\right) & =\frac{1}{8 \pi} \int_{\widehat{\Sigma}} \widehat{H} d \widehat{\Sigma}  \tag{2.1}\\
& -\frac{1}{8 \pi} \int_{\Sigma}\left(\sqrt{1+|\nabla \tau|^{2}} \cosh \theta|H|-\nabla \tau \cdot \nabla \theta-\alpha_{H}(\nabla \tau)\right) d \Sigma
\end{align*}
$$

where $\nabla$ and $\Delta$ are the gradient and Laplace operator of $\sigma, \tau=-\left\langle\mathcal{X}, T_{0}\right\rangle$ is considered as a function on the 2-surface, and

$$
\theta=\sinh ^{-1}\left(\frac{-\Delta \tau}{|H| \sqrt{1+|\nabla \tau|^{2}}}\right)
$$

Moreover, we say that $\tau$ solves the optimal embedding equation if

$$
\begin{equation*}
\operatorname{div}_{\sigma}\left(\rho \nabla \tau-\nabla\left[\sinh ^{-1}\left(\frac{\rho \Delta \tau}{\left|H_{0}\right||H|}\right)\right]-\alpha_{H_{0}}+\alpha_{H}\right)=0 \tag{2.2}
\end{equation*}
$$

where

$$
\rho=\frac{\sqrt{\left|H_{0}\right|^{2}+\frac{(\Delta \tau)^{2}}{1+|\nabla \tau|^{2}}}-\sqrt{|H|^{2}+\frac{(\Delta \tau)^{2}}{1+|\nabla \tau|^{2}}}}{\sqrt{1+|\nabla \tau|^{2}}}
$$

Next we recall the definition of an asymptotically flat initial data set.

Definition 2.1. $\left(M^{3}, g, k\right)$ is an asymptotically flat initial data set if, outside a compact set, $M^{3}$ is diffeomorphic to $\mathbb{R}^{3} \backslash\left\{|x| \leq r_{0}\right\}$ for some $r_{0}>0$ and under the diffeomorphism, we have

$$
\begin{align*}
g_{i j}-\delta_{i j} & =O\left(|x|^{-\alpha}\right), \quad \partial g_{i j}=O\left(|x|^{-1-\alpha}\right) \\
\partial^{2} g_{i j} & =O\left(|x|^{-2-\alpha}\right), \quad \partial^{3} g_{i j}=O\left(|x|^{-3-\alpha}\right) \tag{2.3}
\end{align*}
$$

and

$$
\begin{equation*}
k_{i j}=O\left(|x|^{-1-\alpha}\right), \partial k_{i j}=O\left(|x|^{-2-\alpha}\right), \partial^{2} k_{i j}=O\left(|x|^{-3-\alpha}\right) \tag{2.4}
\end{equation*}
$$

for some $\alpha>\frac{1}{2}$. Here $\partial$ denotes the partial differentiation on $\mathbb{R}^{3}$. Furthermore, we shall assume that for the constraint equation, we have

$$
\begin{align*}
\frac{1}{2}\left(R(g)+(t r k)^{2}-|k|^{2}\right)=\mu, & \mu=O\left(|x|^{-3-\alpha}\right), \partial \mu=O\left(|x|^{-4-\alpha}\right)  \tag{2.5}\\
D^{i}\left(k_{i j}-(t r k) g_{i j}\right)=J_{j}, & J=O\left(|x|^{-3-\alpha}\right), \partial J=O\left(|x|^{-4-\alpha}\right) \tag{2.6}
\end{align*}
$$

Recall that an initial data set satisfies the dominant energy condition if

$$
\mu \geq|J| .
$$

On the other hand, an initial data set satisfies the vacuum constraint equation if

$$
\begin{equation*}
\mu=0 \text { and } J=0 . \tag{2.7}
\end{equation*}
$$

In this case, there is a unique spacetime $N$ with initial data $\left(M^{3}, g, k\right)$ which solves the vacuum Einstein equation.

Let $\gamma$ be a geodesic on $M$ which is parametrized by arc-length and extends to infinity. We consider $p=\gamma(d)$ for $d \rightarrow \infty$. Consider the normal coordinate $\left(X^{1}, X^{2}, X^{3}\right)$ centered at $p$ and let $\Sigma(s)$ be the sphere of radius $s$ in the normal coordinate. The goal is to evaluate the quasi-local mass of the surface $\Sigma=\Sigma(1)$. In particular, we are interested in the leading order term in $d$.

The set-up of our calculation can be described as the following. On a unit ball $B$ of $\mathbb{R}^{3}$, there is a family of Riemannian metrics $g_{i j}(d)$ and symmetric 2-tensors $k_{i j}(d)$ parametrized by $d$. The metrics $g_{i j}(d)$ (the symmetric 2tensors $k_{i j}(d)$, respectively) are the pull back of the metrics (the symmetric 2 -tensors, respectively) on the unit geodesic ball centered at $\gamma(d), d_{0} \leq d<$ $\infty$, a geodesic on $M$ that extends to spatial infinity. We assume that

1) the standard Cartesian coordinate system $\left(X^{1}, X^{2}, X^{3}\right)$ is a geodesic coordinates system for each $g_{i j}(d)$ such that the origin of the coordinates system corresponds to $\gamma(d)$;
2) with respect to $\left(X^{1}, X^{2}, X^{3}\right)$, the asymptotic flat conditions (2.3) and (2.4) are satisfied with $|x|$ replaced by $d$;
$3)$ the constraint equations $(2.5)$ and $(2.6)$ are satisfied with $|x|$ replaced by $d$.

Namely,

$$
\begin{align*}
g_{i j}(d)-\delta_{i j} & =O\left(d^{-\alpha}\right), \quad \partial g_{i j}(d)=O\left(d^{-1-\alpha}\right)  \tag{2.8}\\
\partial^{2} g_{i j}(d) & =O\left(d^{-2-\alpha}\right), \quad \partial^{3} g_{i j}(d)=O\left(d^{-3-\alpha}\right)
\end{align*}
$$

and

$$
\begin{equation*}
k_{i j}(d)=O\left(d^{-1-\alpha}\right), \partial k_{i j}(d)=O\left(d^{-2-\alpha}\right), \partial^{2} k_{i j}(d)=O\left(d^{-3-\alpha}\right) \tag{2.9}
\end{equation*}
$$

for some $\alpha>\frac{1}{2}$, where $\partial$ now denotes the partial differentiation with respect to $X^{1}, X^{2}, X^{3}$. Moreover,

$$
\begin{align*}
\frac{1}{2}\left(R(g)+(t r k)^{2}-|k|^{2}\right)=\mu, & \mu=O\left(d^{-3-\alpha}\right), \partial \mu=O\left(d^{-4-\alpha}\right)  \tag{2.10}\\
D^{i}\left(k_{i j}-(t r k) g_{i j}\right)=J_{j}, & J=O\left(d^{-3-\alpha}\right), \partial J=O\left(d^{-4-\alpha}\right) \tag{2.11}
\end{align*}
$$

In particular, let $R_{i j}(d)$ denote the Ricci curvature of $g_{i j}(d)$, by the Taylor expansion at a point in $B$ with respect to the geodesic coordinate system $\left(X^{1}, X^{2}, X^{3}\right)$, we have

$$
\begin{align*}
g_{i j}(d)\left(X^{1}, X^{2}, X^{3}\right)= & \delta_{i j}-\frac{1}{3} R_{i k j l}(d)(0,0,0) X^{k} X^{l}+O\left(d^{-3-\alpha}\right)  \tag{2.12}\\
R_{i j}(d)\left(X^{1}, X^{2}, X^{3}\right)= & R_{i j}(d)(0,0,0)+O\left(d^{-3-\alpha}\right)  \tag{2.13}\\
k_{i j}(d)\left(X^{1}, X^{2}, X^{3}\right)= & k_{i j}(d)(0,0,0)+\partial_{m} k_{i j}(d)(0,0,0) X^{m}  \tag{2.14}\\
& +O\left(d^{-3-\alpha}\right)
\end{align*}
$$

These expansions will be abbreviated as

$$
\begin{align*}
g_{i j} & =\delta_{i j}-\frac{1}{3} R_{i k j l}(p) X^{k} X^{l}+O\left(d^{-3-\alpha}\right)  \tag{2.15}\\
R_{i j} & =R_{i j}(p)+O\left(d^{-3-\alpha}\right)  \tag{2.16}\\
k_{i j} & =k_{i j}(p)+\partial_{m} k_{i j}(p) X^{m}+O\left(d^{-3-\alpha}\right) \tag{2.17}
\end{align*}
$$

We will also use the spherical coordinate system $\left(s, u^{1}, u^{2}\right)$ on $B$ such that the coordinate transformation $\left(s, u^{1}, u^{2}\right) \mapsto\left(X^{1}, X^{2}, X^{3}\right)$ is given by $X^{i}=$ $s \tilde{x}^{i}\left(u^{1}, u^{2}\right), i=1,2,3$, where $\tilde{x}^{i}, i=1,2,3$ are the three standard coordinate functions on the standard unit sphere in $\mathbb{R}^{3}$.

Notation: Einstein summation notation will be used throughout the paper, where $i, j, \cdots$ sum from 1 to 3 . Since we are working in normal coordinates, we can freely raise or lower indices for tensors at $p=\gamma(d)$.

## 3. The Brown-York mass

In this section, we consider a time-symmetric initial data set and compute the limit of the Brown-York quasi-local mass. The starting point is the following lemma for the Brown-York quasi-local mass: Given a surface $\Sigma$ in a 3-manifold $(M, g)$, let $R$ be the scalar curvature of $g$. Let $\Omega$ be the region in $M$ bounded by $\Sigma$. Suppose $\Omega$ is foliated by surfaces $\Sigma(s)$ with positive Gauss curvature where $0<s \leq 1, \Sigma(1)=\Sigma$, and $\Sigma(s)$ shrinks to a point as $s$ tends to 0 . Let $\sigma(s)$ be the induced metric on $\Sigma(s)$. The positivity of the Gauss curvature of $\sigma(s)$ guarantees an isometric embedding into $\mathbb{R}^{3}$. Denote the mean curvature of $\Sigma(s)$ in $M$ by $H(s)$ and the mean curvature of the isometric embedding of $\Sigma(s)$ into $\mathbb{R}^{3}$ by $H_{0}(s)$. Let $h(s)$ and $h_{0}(s)$ be the second fundamental form of $\Sigma(s)$ in $M$ and $\mathbb{R}^{3}$, respectively.

Lemma 3.1. The Brown-York quasi-local mass, $m_{B Y}(\Sigma)$, of $\Sigma$ is

$$
m_{B Y}(\Sigma)=\frac{1}{16 \pi} \int_{\Omega}\left(\left|h_{0}(s)-h(s)\right|^{2}-\left(H_{0}(s)-H(s)\right)^{2}+R\right)
$$

where $R$ is the scalar curvature of $g$.
Proof. Assume that $\Sigma(s)$ are given by $F(x, s): \Sigma \times(0,1] \rightarrow M$ with $D F_{(x, s)}\left(\frac{\partial}{\partial s}\right)=f(x, s) \nu(x, s)$ where $\nu(x, s)$ is the unit normal of $\Sigma(s)$. We first show that the derivative of the Brown York quasi-local mass is given by

$$
\begin{equation*}
\frac{\mathrm{d}}{\mathrm{~d} s} E(\Sigma(s))=\int_{\Sigma(s)} \frac{f}{2}\left(\left|h_{0}-h\right|^{2}-\left(H_{0}-H\right)^{2}+R\right) . \tag{3.1}
\end{equation*}
$$

The above formula is known, see [21, Theorem 3.1] for example. For completeness, we include the proof here. We have

$$
\frac{\mathrm{d}}{\mathrm{~d} s} \sigma(s)=2 f h
$$

By Proposition 6.1 of [28],

$$
\begin{equation*}
\frac{\mathrm{d}}{\mathrm{~d} s} \int_{\Sigma(s)} H_{0}(s)=\int_{\Sigma(s)} f\left(H_{0} H-h \cdot h_{0}\right) \tag{3.2}
\end{equation*}
$$

On the other hand, from the second variation formula, we have

$$
\begin{equation*}
\frac{\mathrm{d}}{\mathrm{~d} s} \int_{\Sigma(s)} H(s)=\int_{\Sigma(s)} f\left(H^{2}-\operatorname{Ric}(\nu, \nu)-|h|^{2}\right) \tag{3.3}
\end{equation*}
$$

The Gauss equations of $\Sigma(s)$ in $\mathbb{R}^{3}$ and $M$ imply:

$$
\begin{aligned}
K & =\frac{1}{2}\left(H_{0}^{2}-\left|h_{0}\right|^{2}\right) \\
K & =\frac{R}{2}-\operatorname{Ric}(\nu, \nu)+\frac{1}{2}\left(H^{2}-|h|^{2}\right) .
\end{aligned}
$$

Taking the difference of the two Gauss equations, we obtain

$$
\begin{equation*}
\operatorname{Ric}(\nu, \nu)=\frac{R}{2}+\frac{1}{2}\left(H^{2}-|h|^{2}-H_{0}^{2}+\left|h_{0}\right|^{2}\right) . \tag{3.4}
\end{equation*}
$$

The claim follows from subtracting (3.3) from (3.2) and using (3.4) to replace the Ricci curvature term in the result. The lemma follows from integrating (3.1) along the foliation.

In our setup, $\Sigma(s)$ is the sphere of radius $s$ in the normal coordinates centered at $p=\gamma(d) \in M$. The induced metric and second fundamental form of $\Sigma(s)$ are given by

$$
\begin{aligned}
\sigma_{a b} & =s^{2}\left(\tilde{\sigma}_{a b}-\frac{1}{3} R_{i k j l}(p) \tilde{x}_{a}^{i} \tilde{x}_{b}^{j} \tilde{x}^{k} \tilde{x}^{l}\right)+O\left(d^{-3-\alpha}\right) \\
h(s)_{a b} & =s \tilde{\sigma}_{a b}+O\left(d^{-2-\alpha}\right)
\end{aligned}
$$

where $R_{i k j l}$ is the Riemann curvature tensor of the metric $g$ on $M$ and $\tilde{x}_{a}^{i}$ is a shorthand for $\partial_{a} \tilde{x}^{i}$.

We first compute the difference of the mean curvature and second fundamental form of $\Sigma(s)$ in $M$ and $\mathbb{R}^{3}$.

Lemma 3.2. Consider the surface $\Sigma(s)$. We have

$$
\begin{equation*}
H_{0}(s)-H(s)=-s R_{i j}(p) \tilde{x}^{i} \tilde{x}^{j}+O\left(d^{-3-\alpha}\right) \tag{3.5}
\end{equation*}
$$

and

$$
\begin{equation*}
h_{0}(s)-h(s)=s^{3} R_{i j}(p) \tilde{x}_{a}^{i} \tilde{x}_{b}^{j}+O\left(d^{-3-\alpha}\right) \tag{3.6}
\end{equation*}
$$

Proof. We will use repeatedly an implication of (2.5) that $R=O\left(d^{-3-\alpha}\right)$. Let $\widehat{h}$ and $\widehat{h}_{0}$ denote the traceless second fundamental forms. By the Gauss equations,

$$
\begin{aligned}
2 K & =R-2 \operatorname{Ric}(\nu, \nu)+\frac{1}{2} H^{2}-\frac{1}{2}|\widehat{h}|^{2} \\
& =\frac{1}{2} H_{0}^{2}-\frac{1}{2}\left|\widehat{h_{0}}\right|^{2} .
\end{aligned}
$$

Since the unit normal of $\Sigma(s)$ is $\nu=\tilde{x}^{i} \frac{\partial}{\partial X^{i}}+O\left(d^{-3-\alpha}\right)$ and $\operatorname{Ric}(\nu, \nu)=$ $R_{i j} \tilde{x}^{i} \tilde{x}^{j}+O\left(d^{-3-\alpha}\right)$, we get $H_{0}(s)-H(s)=-s R_{i j} \tilde{x}^{i} \tilde{x}^{j}+O\left(d^{-3-\alpha}\right)$.

Taking the difference of the Codazzi equations for $\Sigma(s)$ in $M$ and $\mathbb{R}^{3}$ implies

$$
\begin{aligned}
\tilde{\nabla}^{a}\left(\widehat{h}_{a b}(s)-\widehat{h}_{0 a b}(s)\right) & =-\frac{1}{2} \partial_{b}\left(H_{0}(s)-H(s)\right)-\operatorname{Ric}\left(\nu, \partial_{b}\right)+O\left(d^{-4-2 \alpha}\right) \\
& =\partial_{b}\left(s R_{i j} \tilde{x}^{i} \tilde{x}^{j}\right)+O\left(d^{-3-\alpha}\right)
\end{aligned}
$$

One readily checks that

$$
\widehat{h}_{a b}(s)-\widehat{h}_{0 a b}(s)=s^{3} R_{i j} \tilde{x}_{a}^{i} \tilde{x}_{b}^{j}+\frac{s^{3}}{2} R_{i j} \tilde{x}^{i} \tilde{x}^{j} \tilde{\sigma}_{a b}
$$

satisfies the above equation. Indeed, we find the unique solution as there is no divergence-free, traceless symmetric 2-tensor on $S^{2}$.

We obtain the following result for the limit of the Brown-York mass:

Theorem 3.3. On $\Sigma=\Sigma(1)$, we have

$$
m_{B Y}(\Sigma)=\frac{1}{6} \mu(p)+O\left(d^{-4-\alpha}\right)
$$

For an initial data set satisfying the vacuum constraint equation, we have

$$
m_{B Y}(\Sigma)=\frac{1}{60} Q\left(e_{0}, e_{0}, e_{0}, e_{0}\right)+O\left(d^{-5-2 \alpha}\right)
$$

where $Q$ is the Bel-Robinson tensor (1.1) at $p$ of the solution to the vacuum Einstein equation with the time-symmetric initial data $(M, g)$.

Proof. On $\Omega, R=R(p)+O\left(d^{-4-\alpha}\right)$ by 2.5. Applying Lemma 3.1, together with

$$
\begin{align*}
\left|h(s)-h_{0}(s)\right| & =O\left(d^{-2-\alpha}\right) \\
H_{0}(s)-H(s) & =O\left(d^{-2-\alpha}\right) \tag{3.7}
\end{align*}
$$

we obtain the first formula.
For a vacuum initial data set, we compute

$$
\begin{aligned}
& \left|h_{0}(s)-h(s)\right|^{2}-\left(H_{0}(s)-H(s)\right)^{2} \\
& \quad=s^{2} R_{i j} R_{l m}\left(\delta^{i l} \delta^{j m}-\delta^{i l} \tilde{x}^{j} \tilde{x}^{m}-\delta^{j m} \tilde{x}^{i} \tilde{x}^{l}\right)+O\left(d^{-5-2 \alpha}\right)
\end{aligned}
$$

Since $R=0$, we have
$m_{B Y}(\Sigma)=\frac{1}{16 \pi} R_{i j} R^{i j} \cdot \frac{4 \pi}{3} \int_{0}^{1} s^{4} d s+O\left(d^{-5-2 \alpha}\right)=\frac{1}{60} R_{i j} R^{i j}+O\left(d^{-5-2 \alpha}\right)$.
Finally, if $N$ is the solution to the Einstein equation with time-symmetric initial data $(M, g)$, its Weyl curvature satisfies

$$
\begin{aligned}
& \bar{W}_{0 i 0 j}=R_{i j}, \\
& \bar{W}_{0 i j k}=0
\end{aligned}
$$

This finishes the proof of the theorem.

## 4. Optimal embedding equation and the Jang equation

In this section, we describe our strategy to handle the second fundamental form $k_{i j}$. We study the optimal embedding equation on $\Sigma$ and the Jang equation on $\Omega$. In particular, we first solve the optimal embedding equation on the boundary. Then we solve the Jang equation on the bulk $\Omega$ using the solution of the optimal embedding equation as the boundary value

Consider the product manifold $\Omega \times \mathbb{R}$ with the product metric $d t^{2}+$ $g_{i j} d X^{i} d X^{j}$. The data $k_{i j}, \mu, J$ are extended parallelly along the $\mathbb{R}$ factor. Jang's equation for $u \in C^{2}(\Omega)$ reads

$$
\begin{equation*}
\left(g^{i j}-\frac{D^{i} u D^{j} u}{1+|D u|^{2}}\right)\left(k_{i j}-\frac{D_{i} D_{j} u}{\sqrt{1+|D u|^{2}}}\right)=0 \tag{4.1}
\end{equation*}
$$

Denote the graph of $u$ in $\Omega \times \mathbb{R}$ by $\tilde{\Omega}$ and $\tilde{\Sigma}=\partial \tilde{\Omega}$. Let $\tilde{e}_{4}$ be the downward normal of $\tilde{\Omega}$ and $Y_{i}=\left(k-\frac{D^{2} u}{\sqrt{1+|D u|^{2}}}\right)\left(\frac{\partial}{\partial X^{i}}, \tilde{e}_{4}\right)$.

Let $\tilde{g}$ be the induced metric of $\tilde{\Omega}$. Let $H_{0}$ be the mean curvature of the isometric embedding of $\tilde{\Sigma}$ into $\mathbb{R}^{3}$. We recall

$$
\begin{aligned}
& E\left(\Sigma, \mathcal{X}, T_{0}\right) \\
& \quad=\frac{1}{8 \pi}\left(\int H_{0} d \tilde{\Sigma}-\int\left[\sqrt{1+|\nabla \tau|^{2}} \cosh |H|+\Delta \tau \theta-\alpha_{H}(\nabla \tau)\right] d \Sigma\right)
\end{aligned}
$$

where $\sinh \theta=\frac{-\Delta \tau}{|H| \sqrt{1+|\nabla \tau|^{2}}}$. By [28, Theorem 4.1],

$$
\begin{aligned}
E\left(\Sigma, \mathcal{X}, T_{0}\right) & =\frac{1}{8 \pi}\left(\int\left[H_{0}-\tilde{H}+\left\langle Y, \tilde{e}_{3}\right\rangle\right] d \tilde{\Sigma}\right. \\
& \left.+\int\left[|H| \sqrt{1+|\nabla \tau|^{2}}\left(\cosh \theta^{\prime}-\cosh \theta\right)+\Delta \tau\left(\theta^{\prime}-\theta\right)\right] d \Sigma\right)
\end{aligned}
$$

where $\theta^{\prime}$ is defined by

$$
\cosh \phi e_{3}-\sinh \phi e_{4}=\cosh \theta^{\prime} e_{3}^{H}-\sinh \theta^{\prime} e_{4}^{H}
$$

with $\sinh \phi=-\frac{u_{3}}{\sqrt{1+|\nabla \tau|^{2}}}$. By the Schoen-Yau identity [24, (2.29)]

$$
2\left(\mu-J\left(\tilde{e}_{4}\right)\right)=\tilde{R}-\left|k_{i j}-\frac{D_{i} D_{j} u}{\sqrt{1+|D u|^{2}}}\right|_{\tilde{g}}^{2}-2|Y|_{\tilde{g}}^{2}+2 \tilde{D}^{i} Y_{i}
$$

Together with Lemma 3.1, we obtain

## Theorem 4.1.

$$
\begin{aligned}
E\left(\Sigma, X, T_{0}\right)= & \frac{1}{8 \pi} \int\left(\mu-J\left(\tilde{e}_{4}\right)\right) d \tilde{\Omega} \\
& +\frac{1}{16 \pi} \int\left[\left|k_{i j}-\frac{D_{i} D_{j} u}{\sqrt{1+|D u|^{2}}}\right|_{\tilde{g}}^{2}+2|Y|_{\tilde{g}}^{2}\right] d \tilde{\Omega} \\
& +\frac{1}{16 \pi} \int\left[\left|h_{0}(s)-h(s)\right|^{2}-\left(H_{0}(s)-H(s)\right)^{2}\right] d \tilde{\Omega} \\
& +\frac{1}{8 \pi} \int\left[|H| \sqrt{1+|\nabla \tau|^{2}}\left(\cosh \theta^{\prime}-\cosh \theta\right)+\Delta \tau\left(\theta^{\prime}-\theta\right)\right] d \Sigma
\end{aligned}
$$

## 5. Limit of the Wang-Yau mass

In this section, we study the optimal embedding equation and the Jang equation with respect to the observer

$$
T_{0}=\left(a_{0},-a_{1},-a_{2},-a_{3}\right)
$$

Before restating our main result, Theorem 1.1, recall that in the vacuum case we view the initial data set $(M, g, k)$ as a spacelike hypersurface in its future development $N$ and denote the Weyl curvature of $N$ by $\bar{W}$. Let $e_{0}, e_{1}, e_{2}, e_{3}$ be an orthonormal basis at $p$ with $e_{0}$ the unit timelike normal of $M$ in $N$ and identify $T_{0}$ with the timelike vector $a_{0} e_{0}+\sum_{i=1}^{3} a_{i} e_{i}$ at $p$.

Theorem 5.1. The quasi-local mass $E\left(\Sigma, \mathcal{X}, T_{0}\right)$ for $T_{0}=\left(a_{0},-a_{1},-a_{2}\right.$, $\left.-a_{3}\right)$ has the following asymptotic behavior as $d \rightarrow \infty$ for each of the following isometric embeddings $\mathcal{X}$ of $\Sigma$.

1) For the isometric embedding $\mathcal{X}: \Sigma \rightarrow \mathbb{R}^{3}$, we have

$$
E\left(\Sigma, \mathcal{X}, T_{0}\right)=\frac{1}{6}\left(a_{0} \mu(p)-a_{i} J^{i}(p)\right)+O\left(d^{-3-2 \alpha}\right)
$$

where $\mu$ and $J^{i}$ are defined in (2.5) and 2.6.
2) Suppose the initial data set $(M, g, k)$ satisfies the vacuum constraint equation (2.7). For $\left(\mathcal{X}, T_{0}\right)$ solving the leading order of the optimal embedding equation (2.2), we have

$$
E\left(\Sigma, \mathcal{X}, T_{0}\right)=\frac{1}{90}\left(Q\left(e_{0}, e_{0}, e_{0}, T_{0}\right)+\frac{1}{2 a_{0}} \bar{W}_{0 i 0 j} \bar{W}_{0}{ }_{0}^{i j}\right)+O\left(d^{-4-3 \alpha}\right)
$$

Here $\bar{W}_{0 i 0 j}=\bar{W}\left(e_{0}, e_{i}, e_{0}, e_{j}\right)(p)$ and $Q$ is the Bel-Robinson tensor of $N$ at $p$.
Remark 5.2. We mostly work at the initial data level and the error term has order $O\left(d^{-5-2 \alpha}\right)$. Only when the result is expressed in terms of the spacetime curvature using the Gauss equation of $N, \bar{W}_{0 i 0 j}=R_{i j}+O\left(d^{-2-2 \alpha}\right)$, does the error become $O\left(d^{-4-3 \alpha}\right)$.

The outline of this section is as follows. We solve the optimal embedding equation and the Dirichlet problem of Jang's equation in the first two subsections and then evaluate each integral in Theorem 4.1 in the subsequent three subsections. Finally, we put everything together to prove Theorem 5.1.

### 5.1. Optimal embedding

Let us begin with the optimal embedding equation.

Lemma 5.3. The following pair $T_{0}=\left(a_{0},-a_{1},-a_{2},-a_{3}\right)$ and

$$
\begin{aligned}
& \mathcal{X}^{0}=\frac{1}{2} k_{i j}(p) \tilde{x}^{i} \tilde{x}^{j}+\frac{1}{6} \partial_{i} k_{j m}(p) \tilde{x}^{i} \tilde{x}^{j} \tilde{x}^{m}+\frac{a_{i} R_{m n}(p) \tilde{x}^{m} \tilde{x}^{n} \tilde{x}^{i}}{6 a_{0}} \\
& \mathcal{X}^{i}=\tilde{x}^{i}-\frac{1}{6} R_{i n}(p) \tilde{x}^{n}-\frac{1}{6} R_{m n}(p) \tilde{x}^{m} \tilde{x}^{n} \tilde{x}^{i}
\end{aligned}
$$

solves the first two order of the optimal embedding equation. In particular, the above solution gives a time function $\tau=-\left\langle\mathcal{X}, T_{0}\right\rangle$ with

$$
\begin{equation*}
\tau=a_{i} \tilde{x}^{i}+a_{0}\left[\frac{1}{2} k_{i j}(p) \tilde{x}^{i} \tilde{x}^{j}+\frac{1}{6} \partial_{i} k_{j m}(p) \tilde{x}^{i} \tilde{x}^{j} \tilde{x}^{m}\right]-\frac{1}{6} a_{i} R_{n}^{i}(p) \tilde{x}^{n} \tag{5.1}
\end{equation*}
$$

Proof. With $T_{0}=\left(a_{0},-a_{1},-a_{2},-a_{3}\right)$, the optimal embedding equation reads

$$
\begin{aligned}
\frac{1}{2} \Delta(\Delta+2) \mathcal{X}^{0}= & \operatorname{div} \alpha_{H}+\frac{a_{i}}{a_{0}}\left[\operatorname{div}\left(\left(H_{0}-|H|\right) \nabla \tilde{x}^{i}\right)+\frac{1}{2} \Delta\left(\left(H_{0}-|H|\right) \tilde{x}^{i}\right)\right] \\
& +O\left(d^{-3-\alpha}\right)
\end{aligned}
$$

See [7, Section 7]. We first compute

$$
\begin{aligned}
\left(\alpha_{H}\right)_{a}= & -k\left(\partial_{a}, \nu\right)+\partial_{a}\left(\frac{\operatorname{tr}_{\Sigma} k}{H}\right)+O\left(d^{-3-3 \alpha}\right) \\
= & -2 k_{i j} \tilde{x}_{a}^{i} \tilde{x}^{j}-2 \partial_{m} k_{i j} \tilde{x}_{a}^{i} \tilde{x}^{j} \tilde{x}^{m}+\frac{1}{2} \partial_{m} k_{i i} \tilde{x}_{a}^{m} \\
& -\frac{1}{2} \partial_{m} k_{i j} \tilde{x}^{i} \tilde{x}^{j} \tilde{x}_{a}^{m}+O\left(d^{-3-\alpha}\right)
\end{aligned}
$$

Using the Codazzi equation, $\partial_{i} k_{i m}=\partial_{m} k_{i i}+O\left(d^{-3-2 \alpha}\right)$, we obtain

$$
\begin{aligned}
\operatorname{div} \alpha_{H}= & -2 k_{i j}\left(\delta^{i j}-3 \tilde{x}^{i} \tilde{x}^{j}\right) \\
& +10 \partial_{m} k_{i j}\left(\tilde{x}^{i} \tilde{x}^{j} \tilde{x}^{m}-\frac{1}{5} \delta^{i j} \tilde{x}^{m}-\frac{1}{5} \delta^{i m} \tilde{x}^{j}-\frac{1}{5} \delta^{j m} \tilde{x}^{i}\right)+O\left(d^{-3-\alpha}\right)
\end{aligned}
$$

Note that $\delta^{i j}-3 \tilde{x}^{i} \tilde{x}^{j}$ and $\tilde{x}^{i} \tilde{x}^{j} \tilde{x}^{m}-\frac{1}{5} \delta^{i j} \tilde{x}^{m}-\frac{1}{5} \delta^{i m} \tilde{x}^{j}-\frac{1}{5} \delta^{j m} \tilde{x}^{i}$ are -6 and -12 eigenfunctions respectively.

On the other hand, by Lemma 3.2 and $|H|=\sqrt{H^{2}-\left(\operatorname{tr}_{\Sigma} k\right)^{2}}$, we have

$$
H_{0}-|H|=-R_{i j} \tilde{x}^{i} \tilde{x}^{j}+O\left(d^{-2-2 \alpha}\right)
$$

and

$$
\begin{aligned}
& \operatorname{div}\left(\left(H_{0}-|H|\right) \nabla \tilde{x}^{i}\right)+\frac{1}{2} \Delta\left(\left(H_{0}-|H|\right) \tilde{x}^{i}\right) \\
& \quad=10 R_{m n} \tilde{x}^{m} \tilde{x}^{n} \tilde{x}^{i}-4 R_{i n} \tilde{x}^{n}+O\left(d^{-2-2 \alpha}\right)
\end{aligned}
$$

It follows that the given $\mathcal{X}^{0}$ satisfies the equation up to error of the order $O\left(d^{-2-2 \alpha}\right)$.

For the $\mathcal{X}^{i}$, we use the well-known formula of Riemann curvature tensor in 3-dimension

$$
\begin{equation*}
R_{i k j l}=g_{i j} R_{k l}-g_{i l} R_{k j}+g_{k l} R_{i j}-g_{k j} R_{i l}-\frac{R}{2}\left(g_{i j} g_{k l}-g_{i l} g_{k j}\right) \tag{5.2}
\end{equation*}
$$

and (2.5) to show that the induced metric is

$$
\sigma_{a b}=\tilde{\sigma}_{a b}-\frac{1}{3} R_{k l} \tilde{x}_{a}^{k} \tilde{x}_{b}^{l}-\frac{1}{3} R_{i j} \tilde{x}^{i} \tilde{x}^{j} \tilde{\sigma}_{a b}+O\left(d^{-2-2 \alpha}\right)
$$

The lemma follows from the linearized isometric embedding equation into $\mathbb{R}^{3}$.

### 5.2. Jang's equation

We work in local coordinates and $\Omega$ is identified with $B_{1} \subset \mathbb{R}^{3}$. We discuss the solution of Dirichlet problem of Jang's equation

$$
\left\{\begin{array}{cl}
\left(g^{i j}-\frac{D^{i} u D^{j} u}{1+|D u|^{2}}\right)\left(k_{i j}-\frac{D_{i} D_{j} u}{\sqrt{1+|D u|^{2}}}\right)=0 & \text { in } B_{1}  \tag{5.3}\\
u=\tau & \text { on } \partial B_{1}
\end{array}\right.
$$

Let $b_{i j}=g_{i j}-\delta_{i j}+\frac{1}{3} R_{i k j l}(p) X^{k} X^{l}$ and $c_{i j}=k_{i j}-k_{i j}(p)-\partial_{m} k_{i j}(p) X^{m}$. By Definition 2.1 and 2.12), we have

$$
\begin{equation*}
\left\|b_{i j}\right\|_{C^{1}\left(B_{1}\right)},\left\|c_{i j}\right\|_{C^{1}\left(B_{1}\right)} \leq C d^{-3-\alpha} \tag{5.4}
\end{equation*}
$$

Lemma 5.4. Let $u$ be the solution of the Dirichlet problem of Jang's equation on $\Omega$ with boundary value $\tau$ given in 5.1). Then $u=a_{i} X^{i}+\frac{1}{6} T_{i} X^{i}+$
$\frac{1}{2} a_{0} k_{i j} X^{i} X^{j}+\frac{1}{6} B_{i j m} X^{i} X^{j} X^{m}-\frac{1}{6} a_{i} R_{i n} X^{n}+v$, where

$$
\begin{aligned}
T_{m}= & -\frac{1}{4+\frac{1}{a_{0}^{2}}} \cdot \frac{2}{a_{0}} a_{i} a_{j} \bar{W}_{0}{ }^{i}{ }_{m}^{j}(p)+\frac{1}{4+\frac{1}{a_{0}^{2}}} \cdot 2 a_{l} R_{m}^{l}(p) \\
& +\frac{1}{\left(4+\frac{1}{a_{0}^{2}}\right)\left(2+\frac{3}{a_{0}^{2}}\right)} \cdot \frac{4 a_{m}}{a_{0}} a_{i} a_{j} R^{i j}(p) \\
B_{i j m}= & \frac{a_{0}}{3}\left(\partial_{i} k_{j m}(p)+\partial_{j} k_{i m}(p)+\partial_{m} k_{i j}(p)\right)-\frac{1}{3}\left(\delta_{i j} T_{m}+\delta_{j m} T_{i}+\delta_{m i} T_{j}\right),
\end{aligned}
$$

and $\|v\|_{C^{2, \beta}} \leq C^{\prime} d^{-3-\alpha}$ for some constant $C^{\prime}$ and $0<\beta<1$ depending only on $C$ in (5.4).

Proof. We write

$$
u=a_{i} X^{i}+b_{i} X^{i}+\frac{1}{2} a_{0} k_{i j} X^{i} X^{j}+\frac{1}{6} B_{i j m} X^{i} X^{j} X^{m}-\frac{1}{6} a_{i} R_{i n} X^{n}+v
$$

for constants $b_{i}, B_{i j m}$ to be determined from the leading order of Jang's equation.

Define a symmetric 3-tensor

$$
T_{i j m}=\frac{a_{0}}{3}\left(\partial_{i} k_{j m}+\partial_{j} k_{m i}+\partial_{m} k_{i j}\right)-B_{i j m}
$$

We need to show that $\tau-u$ is perpendicular to all -2 and -12 eigenfunctions on $\partial B_{1}=S^{2}$ which, by the expression (5.1) of $\tau$, is equivalent to

$$
\begin{aligned}
& \int_{S^{2}}\left(\frac{1}{6} T_{i j m} \tilde{x}^{i} \tilde{x}^{j} \tilde{x}^{m}-b_{i} \tilde{x}^{i}\right) \tilde{x}^{l} d S^{2}=0 \\
& \int_{S^{2}} T_{i j m} \tilde{x}^{i} \tilde{x}^{j} \tilde{x}^{m}\left(\tilde{x}^{l} \tilde{x}^{p} \tilde{x}^{q}-\frac{1}{5} \tilde{x}^{l} \delta^{p q}-\frac{1}{5} \tilde{x}^{p} \delta^{q l}-\frac{1}{5} \tilde{x}^{q} \delta^{l p}\right) d S^{2}=0
\end{aligned}
$$

The second equation contains 7 linear equations with 10 variables. Using [8, Lemma 5.3], we solve $T_{i j m}$ by free variables $T_{111}, T_{222}, T_{333}$ :

$$
T_{i j m}=\frac{1}{3}\left(\delta_{i j} T_{m}+\delta_{j m} T_{i}+\delta_{m i} T_{j}\right), \quad T_{m}:=T_{m m m}
$$

and then solve $b_{i}=\frac{1}{6} T_{i}$.

It remains to solve $T_{m}$ from Jang's equation

$$
\left(g^{i j}-\frac{D^{i} u D^{j} u}{1+|D u|^{2}}\right)\left(k_{i j}-\frac{D_{i} D_{j} u}{\sqrt{1+|D u|^{2}}}\right)=0
$$

By the Codazzi equation, $\partial_{m} k_{i j}-\partial_{i} k_{m j}=-\bar{W}_{0 j m i}+O\left(d^{-3-2 \alpha}\right)$, it follows that

$$
k_{i j}-\frac{u_{i j}}{\sqrt{1+|D u|^{2}}}=S_{i j m} X^{m}+O\left(d^{-3-\alpha}\right)
$$

where

$$
\begin{align*}
S_{i j m}=\frac{1}{3}( & \frac{1}{a_{0}}\left(\delta_{i j} T_{m}+\delta_{j m} T_{i}-\delta_{m i} T_{j}\right)  \tag{5.5}\\
& \left.-\bar{W}_{0 i m j}-\bar{W}_{0 j m i}+\frac{a_{l}}{a_{0}}\left(R_{i l j m}+R_{i m j l}\right)\right) .
\end{align*}
$$

The leading order of Jang's equation thus reduces to 3 linear equations

$$
\sum_{i, j}\left(\delta_{i j}-\frac{a_{i} a_{j}}{a_{0}^{2}}\right) S_{i j m}=0
$$

We have

$$
\begin{aligned}
0= & \sum_{i, j}\left(\delta_{i j}-\frac{a_{i} a_{j}}{a_{0}^{2}}\right)\left(\delta_{i j} T_{m}+\delta_{j m} T_{i}+\delta_{m i} T_{j}\right) \\
& +\frac{a_{i} a_{j}}{a_{0}}\left(\bar{W}_{0}^{i}{ }_{m}{ }^{j}+\bar{W}_{0}{ }^{j}{ }_{m}^{i}\right)-2 a_{l} R_{m}^{l} \\
= & \sum_{i} G_{i m} T_{i}+\frac{a_{i} a_{j}}{a_{0}}\left(\bar{W}_{0}{ }^{i}{ }^{j}{ }^{j}+\bar{W}_{0}{ }^{j}{ }_{m}{ }^{i}\right)-2 a_{l} R_{m}^{l}
\end{aligned}
$$

where $G_{i m}=\left(4+\frac{1}{a_{0}^{2}}\right) \delta_{i m}-2 \frac{a_{i} a_{m}}{a_{0}^{2}}$. We solve for the inverse matrix of $G_{i m}$

$$
\left(G^{-1}\right)_{m l}=\frac{1}{\left(4+\frac{1}{a_{0}^{2}}\right)\left(2+\frac{3}{a_{0}^{2}}\right)}\left[\left(2+\frac{3}{a_{0}^{2}}\right) \delta_{m l}+2 \frac{a_{m} a_{l}}{a_{0}^{2}}\right]
$$

to get

$$
\begin{aligned}
T_{m}= & -\frac{1}{4+\frac{1}{a_{0}^{2}}} \cdot \frac{2 a_{i} a_{j}}{a_{0}} \bar{W}_{0}{ }^{i}{ }_{m}^{j}+\frac{1}{4+\frac{1}{a_{0}^{2}}} \cdot 2 a_{l} R_{m}^{l} \\
& +\frac{1}{\left(4+\frac{1}{a_{0}^{2}}\right)\left(2+\frac{3}{a_{0}^{2}}\right)} \cdot \frac{4 a_{m}}{a_{0}^{2}} R^{i j} a_{i} a_{j}
\end{aligned}
$$

After obtaining the leading order of $u$, we treat Jang's equation as a quasilinear partial differential equation $Q(x, D v) v=0$ in $B_{1}$ and $v=0$ on $\partial B_{1}$. By (5.4), we can choose a constant $C^{\prime}$ that depends only on $C$ such that $\pm C^{\prime} d^{-3-\alpha}\left(|x|^{2}-1\right)$ is a sub/super solution to this equation. This provides the $C^{0}$-estimate and the boundary gradient estimate. By [16, Theorem 15.1] and [16, Theorem 13.7], we get the gradient estimate and Hölder estimate for the gradient. The $C^{2, \beta}$ a priori estimate for $v$ and the solvability of $u$ then follows from the Schauder estimate and [16, Theorem 11.4].
Proof of Theorem 5.1, (1). We first examine the limit for an initial data set with matter fields. We will show below that all terms except $\mu-J\left(\tilde{e}_{4}\right)$ are of the order $O\left(d^{-4-2 \alpha}\right)$. As a result,

$$
E(\Sigma)=\frac{1}{8 \pi} \int\left(\mu-J\left(\tilde{e}_{4}\right)\right) d \tilde{\Omega}+O\left(d^{-4-2 \alpha}\right)
$$

The assertion follows from $d \tilde{\Omega}=a_{0} d x+O\left(d^{-2-\alpha}\right)$ and $\tilde{e}_{4}=\frac{1}{a_{0}}\left(-1, a_{1}, a_{2}, a_{3}\right)$ $+O\left(d^{-1-\alpha}\right)$.

For a vacuum initial data set, Theorem 4.1 becomes

$$
\begin{align*}
& E\left(\Sigma, X, T_{0}\right)=\frac{1}{16 \pi} \int\left[\left|k_{i j}-\frac{D_{i} D_{j} u}{\sqrt{1+|D u|^{2}}}\right|_{\tilde{g}}^{2}+2|Y|_{\tilde{g}}^{2}\right] d \tilde{\Omega}  \tag{5.6}\\
& \quad+\frac{1}{16 \pi} \int\left[\left|h_{0}(s)-h(s)\right|^{2}-\left(H_{0}(s)-H(s)\right)^{2}\right] d \tilde{\Omega}  \tag{5.7}\\
& \quad+\frac{1}{8 \pi} \int\left[|H| \sqrt{1+|\nabla \tau|^{2}}\left(\cosh \theta^{\prime}-\cosh \theta\right)+\Delta \tau\left(\theta^{\prime}-\theta\right)\right] d \Sigma \tag{5.8}
\end{align*}
$$

### 5.3. Evaluation of (5.6)

Lemma 5.5.

$$
\begin{aligned}
\frac{1}{16 \pi} & \int_{B_{1}}\left(\left|k_{i j}-\frac{D_{i} D_{j} u}{\sqrt{1+|D u|^{2}}}\right|_{\bar{g}}^{2}+2|Y|_{\bar{g}}^{2}\right) d \tilde{\Omega} \\
= & -\frac{1}{54 a_{0}} \sum_{m} T_{m}^{2}-\frac{1}{27 a_{0}} T_{m} a_{l} R^{l m}(p)+\frac{1}{90}\left(a_{0}-\frac{1}{a_{0}}\right) R_{i j}(p) R^{i j}(p) \\
& -\frac{1}{54 a_{0}} \sum_{i, j, l} a_{i} a_{j} R^{i l}(p) R_{l}^{j}(p)+\frac{a_{0}}{180} \bar{W}_{0 i m j}(p) \bar{W}_{0}^{i m j}(p) \\
& -\frac{1}{45} a_{m} \bar{W}_{0}^{i m j}(p) \bar{W}_{0 i 0 j}(p)+O\left(d^{-5-2 \alpha}\right)
\end{aligned}
$$

Proof. Recall that we write $k_{i j}-\frac{D_{i} D_{j} u}{\sqrt{1+|D u|^{2}}}=S_{i j m} X^{m}+O\left(d^{-3-\alpha}\right)$ in the proof of Lemma 5.4. Since $\tilde{e}_{4}=\frac{\left(-1, a_{1}, a_{2}, a_{3}\right)}{a_{0}}+O\left(d^{-1-\alpha}\right)$, we have $Y=$ $\sum_{i, m, p} \frac{a_{p}}{a_{0}} S_{i p m} X^{m} \frac{\partial}{\partial X^{i}}+O\left(d^{-3-\alpha}\right)$ and

$$
\begin{aligned}
\frac{1}{16 \pi} & \int_{B_{1}}\left|k_{i j}-\frac{D_{i} D_{j} u}{\sqrt{1+|D u|^{2}}}\right|_{\bar{g}}^{2}+2|Y|_{\bar{g}}^{2} d V_{\bar{g}} \\
= & \frac{a_{0}}{60} \sum_{i, j, m, p, q}\left[\left(\delta_{i j}-\frac{a_{i} a_{j}}{a_{0}^{2}}\right) S_{i p m} S_{j q m}\left(\delta_{p q}-\frac{a_{p} a_{q}}{a_{0}^{2}}\right)\right. \\
& \left.+2\left(\delta_{i j}-\frac{a_{i} a_{j}}{a_{0}^{2}}\right) \frac{a_{p} a_{q}}{a_{0}^{2}} S_{i p m} S_{j q m}\right]+O\left(d^{-5-2 \alpha}\right) \\
= & \frac{a_{0}}{60}\left[\sum_{i, j, m} S_{i j m}^{2}-\sum_{i, j, m, p, q} \frac{a_{i} a_{j} a_{p} a_{q}}{a_{0}^{4}} S_{i p m} S_{j q m}\right]+O\left(d^{-5-2 \alpha}\right) \\
= & \frac{a_{0}}{60}\left[\sum_{i, j, m} S_{i j m}^{2}-\sum_{m}\left(\sum_{i} S_{i i m}\right)^{2}\right]+O\left(d^{-5-2 \alpha}\right)
\end{aligned}
$$

where Jang's equation is used in the last equality. We compute, by 5.5,

$$
\begin{aligned}
\sum_{m}\left(\sum_{i} S_{i i m}\right)^{2} & =\frac{1}{9 a_{0}^{2}} \sum_{m}\left(5 T_{m}+2 a_{l} R_{m}^{l}\right)^{2} \\
& =\frac{1}{9 a_{0}^{2}}\left(25 \sum_{m} T_{m}^{2}+10 a_{l} T_{m} R^{l m}+4 a_{l} a_{n} R^{l m} R_{m}^{n}\right)
\end{aligned}
$$

and

$$
\begin{aligned}
& \sum_{i, j, m} S_{i j m}^{2}=\frac{1}{9}\left[\frac{15}{a_{0}^{2}} \sum_{m} T_{m}^{2}+\sum_{i, j, m}\left(\bar{W}_{0 i m j}+\bar{W}_{0 j m i}\right)^{2}\right. \\
& \quad+\frac{1}{a_{0}^{2}} \sum_{i, j, m}\left(2 a_{m} R_{i j}+2 a_{l} R_{m}^{l} \delta_{i j}-a_{j} R_{i m}-a_{i} R_{j m}-a_{l} R_{j}^{l} \delta_{i m}-a_{l} R_{i}^{l} R_{j m}\right)^{2} \\
& \left.\quad-2 \sum_{i, j, l, m} \frac{a_{l}}{a_{0}}\left(\bar{W}_{0 i m j}+\bar{W}_{0 j m i}\right)\left(R_{i l j m}+R_{i m j l}\right)\right]
\end{aligned}
$$

By the first Bianchi identity, $2 \sum_{i, j, m} \bar{W}_{0 i m j} \bar{W}_{0 j m i}=\sum_{i, j, m} \bar{W}_{0 i m j} \bar{W}_{0 i m j}$ and hence $\sum_{i, j, m}\left(\bar{W}_{0 i m j}+\bar{W}_{0 j m i}\right)^{2}=3 \sum_{i, j, m} \bar{W}_{0 i m j}^{2}$. Direct computation shows that the third term in the bracket is equal to $\frac{1}{a_{0}^{2}}\left(6 \sum_{m} a_{m}^{2} R_{i j}^{2}-6 a_{i} a_{j} R^{i l} R_{l}^{j}\right)$.

Finally, by (5.2), the last term in the bracket is equal to

$$
-12 \sum_{i, j, m} \frac{a_{m}}{a_{0}} \bar{W}_{0 i m j} \bar{W}_{0 i 0 j}
$$

### 5.4. Evaluation of 5.7

## Lemma 5.6.

$$
\begin{gathered}
\frac{1}{16 \pi} \int\left[\left|h_{0}(s)-h(s)\right|^{2}-\left(H_{0}(s)-H(s)\right)^{2}\right] d \tilde{\Omega} \\
\quad=\frac{1}{60 a_{0}} R_{i j}(p) R^{i j}(p)+O\left(d^{-5-2 \alpha}\right)
\end{gathered}
$$

Proof. By Lemma 5.8 below, we have

$$
h_{0}(s)-h(s)=s^{3} \frac{\sqrt{1+\left|a_{i} \tilde{\nabla} \tilde{x}^{i}\right|^{2}}}{a_{0}} R_{i j} \tilde{x}_{a}^{i} \tilde{x}_{b}^{j}+O\left(d^{-3-\alpha}\right)
$$

We compute

$$
\begin{aligned}
& \left|h_{0}(s)-h(s)\right|_{\sigma}^{2}-\left(H_{0}(s)-H(s)\right)^{2} \\
& \quad=\left(\operatorname{det}_{\tilde{\sigma}}(\sigma)\right)^{-1}\left(\left|h_{0}(s)-h(s)\right|_{\tilde{\sigma}}^{2}-\left(\operatorname{tr}_{\tilde{\sigma}} h_{0}(s)-\operatorname{tr}_{\tilde{\sigma}} h(s)\right)^{2}\right) \\
& \quad=\frac{s^{2}}{a_{0}^{2}}\left(R_{i j} R^{i j}-2 R_{i j} R_{l}^{i} \tilde{x}^{j} \tilde{x}^{l}\right)+O\left(d^{-5-2 \alpha}\right) .
\end{aligned}
$$

Finally, we note that the volume form $d \tilde{\Omega}=a_{0} s^{2} d S^{2} d s+O\left(d^{-2-\alpha}\right)$ and hence

$$
\begin{aligned}
& \int\left[\left|h_{0}(s)-h(s)\right|^{2}-\left(H_{0}(s)-H(s)\right)^{2}\right] d \tilde{\Omega} \\
= & \frac{1}{a_{0}} \int_{0}^{1} \int_{S^{2}}\left(R_{i j} R^{i j}-2 R_{i j} R_{l}^{i} \tilde{x}^{i} \tilde{x}^{j}\right) d S^{2} s^{4} d s+O\left(d^{-5-2 \alpha}\right) \\
= & \frac{4}{15 a_{0}} R_{i j} R^{i j}+O\left(d^{-5-2 \alpha}\right) .
\end{aligned}
$$

The rest of this subsection is devoted to computing the difference of second fundamental forms of $\Sigma_{s}$ in $\tilde{\Omega}$ and in $\mathbb{R}^{3}$, Lemma 5.8 . We first solve the isometric embedding of $\Sigma_{s}$ into $\mathbb{R}^{3}$ and then compute the second fundamental
form. Recall the solution of Jang's equation is $u=a_{i} X^{i}+\frac{1}{2} a_{0} k_{i j} X^{i} X^{j}+$ $\frac{1}{6} B_{i j m} X^{i} X^{j} X^{m}-\frac{a_{i}}{6} R_{i n} X^{n}+O\left(d^{-4}\right)$. The induced metric on the graph of Jang's equation is then given by

$$
\begin{aligned}
\bar{g}_{i j}= & \delta_{i j}+a_{i} a_{j}-\frac{1}{3} R_{i k j l} X^{k} X^{l}+a_{0}\left(a_{i} k_{j m}+a_{j} k_{i m}\right) X^{m} \\
& +\frac{1}{2}\left(a_{i} B_{j l m}+a_{j} B_{i l m}\right) X^{l} X^{m}-\frac{1}{6} a_{i} a_{l} R_{l j}-\frac{1}{6} a_{j} a_{l} R_{l i}+O\left(d^{-3-\alpha}\right)
\end{aligned}
$$

In polar coordinates $\left(s, u^{a}\right)$, we have $\bar{g}=\bar{g}_{s s} d s^{2}+2 \bar{g}_{a s} d s d u^{a}+\bar{g}_{a b} d u^{a} d u^{b}$ where

$$
\begin{aligned}
\bar{g}_{s s}= & 1+\left(a_{i} \tilde{x}^{i}\right)^{2} \\
& +a_{i} \tilde{x}^{i}\left(2 s a_{0} k_{j m} \tilde{x}^{j} \tilde{x}^{m}+s^{2} B_{j l m} \tilde{x}^{j} \tilde{x}^{l} \tilde{x}^{m}-\frac{1}{3} a_{l} R_{l j} \tilde{x}^{j}\right)+O\left(d^{-3-\alpha}\right) . \\
\bar{g}_{a s}= & s a_{i} \tilde{x}_{a}^{i} a_{j} \tilde{x}^{j}+s a_{i} \tilde{x}_{a}^{i}\left(s a_{0} k_{j m} \tilde{x}^{j} \tilde{x}^{m}+\frac{1}{2} s^{2} B_{j l m} \tilde{x}^{j} \tilde{x}^{l} \tilde{x}^{m}-\frac{1}{6} a_{l} R_{l j} \tilde{x}^{j}\right) \\
& +s a_{j} \tilde{x}^{j}\left(s a_{0} k_{i m} \tilde{x}_{a}^{i} \tilde{x}^{m}+\frac{1}{2} s^{2} B_{i l m} \tilde{x}_{a}^{i} \tilde{x}^{l} \tilde{x}^{m}-\frac{1}{6} a_{l} R_{l i} \tilde{x}_{a}^{i}\right)+O\left(d^{-3-\alpha}\right) . \\
\bar{g}_{a b}= & s^{2} \tilde{\sigma}_{a b}+s^{2}\left(a_{i} a_{j}-\frac{s^{2}}{3} R_{i k j l} \tilde{x}^{k} \tilde{x}^{l}\right) \tilde{x}_{a}^{i} \tilde{x}_{b}^{j}+s^{3} a_{0}\left(a_{i} k_{j m}+a_{j} k_{i m}\right) \tilde{x}_{a}^{i} \tilde{x}_{b}^{j} \tilde{x}^{m} \\
& +\frac{1}{2} s^{4}\left(a_{i} B_{j l m}+a_{j} B_{i l m}\right) \tilde{x}_{a}^{i} \tilde{x}_{b}^{j} \tilde{x}^{l} \tilde{x}^{m}-\frac{1}{6} s^{2}\left(a_{i} a_{l} R_{j}^{l}+a_{j} a_{l} R_{i}^{l}\right) \tilde{x}_{a}^{i} \tilde{x}_{b}^{j} \\
& +O\left(d^{-3-\alpha}\right) .
\end{aligned}
$$

Let $\sigma(s)$ be the induced metric on $\Sigma_{s}$. We consider the isometric embedding of $\left(\Sigma_{s}, \sigma(s)_{a b}\right)$ into the hyperplane $X^{0}=a_{i} X^{i}$ in $\mathbb{R}^{4}$ with the form $X^{0}=a_{i} s\left(\tilde{x}^{i}+\mathfrak{y}^{i}\right)$ and $X^{i}=s\left(\tilde{x}^{i}+\mathfrak{y}^{i}\right)$ where $\mathfrak{y}^{i}=O\left(d^{-1-\alpha}\right)$ and satisfies the linearized isometric embedding equations

$$
\begin{aligned}
\left(\delta_{i j}+\right. & \left.a_{i} a_{j}\right)\left(\tilde{x}_{a}^{i} \mathfrak{y}_{b}^{j}+\tilde{x}_{b}^{j} \mathfrak{y}_{a}^{i}\right)=-\frac{s^{2}}{3} R_{i k j l} \tilde{x}^{k} \tilde{x}^{l} \tilde{x}_{a}^{i} \tilde{x}_{b}^{j} \\
& +s a_{0}\left(a_{i} k_{j m}+a_{j} k_{i m}\right) \tilde{x}^{m} \tilde{x}_{a}^{i} \tilde{x}_{b}^{j}+\frac{s^{2}}{2}\left(a_{i} B_{j l m}+a_{j} B_{i l m}\right) \tilde{x}^{l} \tilde{x}^{m} \tilde{x}_{a}^{i} \tilde{x}_{b}^{j} \\
& -\frac{1}{6}\left(a_{i} R_{j}^{l}+a_{j} R_{i}^{l}\right) a_{l} \tilde{x}_{a}^{i} \tilde{x}_{b}^{j}+O\left(d^{-3-\alpha}\right) .
\end{aligned}
$$

It's not hard to see that $\mathfrak{y}^{i}=y^{(0) i}+y^{i}$ with

$$
y^{(0) i}=a_{i}\left(\frac{s}{2 a_{0}} k_{l m} \tilde{x}^{l} \tilde{x}^{m}+\frac{s^{2}}{6 a_{0}^{2}} B_{j l m} \tilde{x}^{j} \tilde{x}^{l} \tilde{x}^{m}-\frac{1}{6 a_{0}^{2}} a_{m} R_{n}^{m} \tilde{x}^{n}\right)
$$

and

$$
\begin{equation*}
\left(\delta_{i j}+a_{i} a_{j}\right)\left(\tilde{x}_{a}^{i} y_{b}^{j}+\tilde{x}_{b}^{j} y_{a}^{i}\right)=-\frac{s^{2}}{3} R_{i k j l} \tilde{x}^{k} \tilde{x}^{l} \tilde{x}_{a}^{i} \tilde{x}_{b}^{j} \tag{5.9}
\end{equation*}
$$

Equation (5.9) is a linearized isometric embedding equation on an ellipsoid. Let $\widehat{y}^{i}=\left(\delta_{i j}+a_{i} a_{j}\right) y^{j}$. One readily verifies that

$$
\widehat{y}^{i}=-\frac{s^{2}}{6}\left(R_{j}^{i} \tilde{x}^{j}+R_{j k} \tilde{x}^{j} \tilde{x}^{k} \tilde{x}^{i}\right)
$$

solves 5.9.
The family of isometric embedding of $\Sigma_{s}$ forms a foliation $F:(0,1] \times$ $S^{2} \rightarrow\left\{X^{0}=a_{i} X^{i}\right\} \subset \mathbb{R}^{4}$. From $F_{*}\left(\partial_{s}\right)=\left(\tilde{x}^{i}+\mathfrak{y}^{i}+s \frac{\partial \mathfrak{y}^{i}}{\partial s}\right)\left(a_{i} \frac{\partial}{\partial X^{0}}+\frac{\partial}{\partial X^{i}}\right)$ and $F_{*}\left(\partial_{a}\right)=s\left(\tilde{x}_{a}^{i}+\mathfrak{y}_{a}^{i}\right)\left(a_{i} \frac{\partial}{\partial X^{0}}+\frac{\partial}{\partial X^{i}}\right)$, we could write the flat metric, denoted by $\breve{g}$, in $\left(s, u^{a}\right)$ coordinates. Straightforward computation shows that

$$
\begin{aligned}
& \breve{g}_{s s}=\bar{g}_{s s}+-2 s^{2} R_{i j} \tilde{x}^{i} \tilde{x}^{j}+O\left(d^{-3-\alpha}\right) \\
& \breve{g}_{b s}=\bar{g}_{b s}-s^{3} R_{i j} \tilde{x}_{b}^{i} \tilde{x}^{j}+O\left(d^{-3-\alpha}\right)
\end{aligned}
$$

Remark 5.7. It shouldn't be surprising that $\breve{g}-\bar{g}$ does not depend on $y^{(0)}$; namely, $\bar{g}$ remains flat after the graphical perturbation of $u$. Indeed, if $\bar{g}_{i j}=$ $g_{i j}+u_{i} u_{j}$, then the curvature tensors are related by

$$
\bar{R}_{i j}{ }^{k}{ }_{l}=R_{i j}{ }^{k}{ }_{l}-\frac{1}{1+|\nabla u|^{2}} R_{i j}{ }^{p}{ }_{l} \nabla_{p} u \nabla^{k} u+X_{i j}{ }^{k}{ }_{l},
$$

where $X$ is quadratic in the Hessian of $u$.
We are ready to compute the second fundamental forms.

## Lemma 5.8.

$$
\bar{h}_{a b}-\breve{h}_{a b}=-s^{3} \frac{\sqrt{1+\left|a_{i} \tilde{\nabla} \tilde{x}^{i}\right|^{2}}}{a_{0}} R_{i j}(p) \tilde{x}_{a}^{i} \tilde{x}_{b}^{j}+O\left(d^{-3-\alpha}\right)
$$

Proof. We denote the leading order of $\tau$ by $\bar{\tau}=a_{i} \tilde{x}^{i}$. The second fundamental form of $\Sigma_{s}$ can be computed from the formula

$$
\bar{h}=\frac{\frac{1}{2} \partial_{s} \bar{g}_{a b}-\nabla_{a} \bar{g}_{b s}}{\sqrt{\bar{g}_{s s}-\sigma^{a b} \bar{g}_{a s} \bar{g}_{b s}}}
$$

Here $\sigma$ is the induced metric of $\Sigma_{s}$. We note that $\sigma_{a b}=s^{2}\left(\tilde{\sigma}_{a b}+\bar{\tau}_{a} \bar{\tau}_{b}\right)+$ $O\left(d^{-1-\alpha}\right)$.

We compute

$$
\begin{aligned}
\bar{g}_{s s}-\sigma^{a b} \bar{g}_{a s} \bar{g}_{b s} & =\frac{a_{0}^{2}}{1+|\tilde{\nabla} \bar{\tau}|^{2}}+O\left(d^{-2-\alpha}\right) \\
\frac{1}{2} \partial_{s} \bar{g}_{a b}-\nabla_{a} \bar{g}_{b s} & =s \frac{a_{0}^{2}}{1+|\tilde{\nabla} \bar{\tau}|^{2}} \tilde{\sigma}_{a b}+O\left(d^{-2-\alpha}\right)
\end{aligned}
$$

Hence, the difference of second fundamental forms is given by

$$
\begin{aligned}
\bar{h}-\breve{h}= & \left(\frac{1}{2} \partial_{s} \bar{g}_{a b}-\nabla_{a} \bar{g}_{b s}\right) \cdot \frac{\left(\breve{g}_{s s}-\sigma^{c d} \breve{g}_{c s} \breve{g}_{d s}\right)-\left(\bar{g}_{s s}-\sigma^{c d} \bar{g}_{c s} \bar{g}_{d s}\right)}{2 a_{0}^{3}} \\
& \cdot\left(1+|\tilde{\nabla} \bar{\tau}|^{2}\right)^{\frac{3}{2}}+\frac{\nabla_{a}\left(\breve{g}_{b s}-\bar{g}_{b s}\right)}{a_{0}} \sqrt{1+|\tilde{\nabla} \bar{\tau}|^{2}}+O\left(d^{-4-2 \alpha}\right) \\
= & \frac{\sqrt{1+|\tilde{\nabla} \bar{\tau}|^{2}}}{a_{0}}\left(\frac{1}{2}\left(\breve{g}_{s s}-\bar{g}_{s s}+\sigma^{c d} \bar{g}_{c s} \bar{g}_{d s}-\sigma^{c d} \breve{g}_{c s} \breve{g}_{d s}\right) \cdot s \tilde{\sigma}_{a b}\right. \\
& \left.+\nabla_{a}\left(\breve{g}_{b s}-\bar{g}_{a s}\right)\right)+O\left(d^{-3-\alpha}\right) .
\end{aligned}
$$

We compute

$$
\begin{aligned}
\nabla_{a}\left(\breve{g}_{b s}-\bar{g}_{b s}\right)= & \tilde{\nabla}_{a}\left(\breve{g}_{b s}-\bar{g}_{b s}\right)-\frac{\tilde{\nabla}^{c} \bar{\tau}}{1+|\tilde{\nabla} \bar{\tau}|^{2}} \tilde{\nabla}_{a} \tilde{\nabla}_{b} \bar{\tau}\left(\breve{g}_{c s}-\bar{g}_{c s}\right)+O\left(d^{-3-2 \alpha}\right) \\
= & s^{3} R_{i j} \tilde{x}^{i} \tilde{x}^{j} \tilde{\sigma}_{a b}-s^{3} R_{i j} \tilde{x}_{a}^{i} \tilde{x}_{b}^{j}-\frac{\tilde{\nabla}^{c} \bar{\tau}}{1+|\tilde{\nabla} \bar{\tau}|^{2}} \tilde{\nabla}_{a} \tilde{\nabla}_{b} \bar{\tau}\left(\breve{g}_{c s}-\bar{g}_{c s}\right) \\
& +O\left(d^{-3-\alpha}\right)
\end{aligned}
$$

On the other hand,

$$
\begin{aligned}
& \frac{1}{2}\left(\breve{g}_{s s}-\bar{g}_{s s}+\sigma^{a b}\left(\bar{g}_{a s} \bar{g}_{b s}-\breve{g}_{a s} \breve{g}_{b s}\right)\right) \\
& \quad=-s^{2} R_{i j} \tilde{x}^{i} \tilde{x}^{j}+\frac{1}{2} \sigma^{c d}\left(\bar{g}_{c s}\left(\bar{g}_{d s}-\breve{g}_{d s}\right)+\breve{g}_{d s}\left(\bar{g}_{c s}-\breve{g}_{c s}\right)\right)+O\left(d^{-3-\alpha}\right) \\
& \quad=-s^{2} R_{i j} \tilde{x}^{i} \tilde{x}^{j}+\frac{\tilde{\nabla} \bar{\tau}}{1+|\tilde{\nabla} \bar{\tau}|^{2}} \cdot s^{-1} \bar{\tau}\left(\bar{g}_{c s}-\breve{g}_{c s}\right)+O\left(d^{-3-\alpha}\right)
\end{aligned}
$$

Putting these together, the assertion follows.

### 5.5. Evaluation of 5.8

In this subsection, we evaluate the integral resulted from the difference between the gauge induced by Jang's equation and the canonical gauge.

Recall the solution of optimal isometric embedding equation is $\tau=a_{i} \tilde{x}^{i}+$ $\frac{a_{0}}{2} k_{i j} \tilde{x}^{i} \tilde{x}^{j}+\frac{a_{0}}{6} \partial_{i} k_{j m} \tilde{x}^{i} \tilde{x}^{j} \tilde{x}^{m}-\frac{a_{i}}{6} R_{i n} \tilde{x}^{n}$ and the solution of Jang's equation is $u=a_{i} X^{i}+\frac{1}{6} T_{i} \tilde{x}^{i}+\frac{1}{2} a_{0} k_{i j} X^{i} X^{j}+\frac{1}{6} B_{i j m} X^{i} X^{j} X^{m}-\frac{a_{i}}{6} R_{i n} X^{n}$. We will need the following lemma.

Lemma 5.9. For $\tau=a_{i} \tilde{x}^{i}+v, v=O\left(d^{-1-\alpha}\right)$, we have

$$
\Delta \tau=\tilde{\Delta} \tau+\tilde{\Delta} v-\frac{2}{3} a_{i} R_{i j} \tilde{x}^{j}+\frac{1}{3} a_{i} R_{k l} \tilde{x}^{i} \tilde{x}^{k} \tilde{x}^{l}+O\left(d^{-3-\alpha}\right)
$$

## Lemma 5.10.

$$
\begin{aligned}
& \frac{1}{8 \pi} \int\left[|H| \sqrt{1+|\nabla \tau|^{2}}\left(\cosh \theta^{\prime}-\cosh \theta\right)+\Delta \tau\left(\theta^{\prime}-\theta\right)\right] d \Sigma \\
& \quad=\frac{1}{54 a_{0}}\left(\sum_{m} T_{m}^{2}+2 T_{m} a_{i} R^{i m}(p)+a_{i} a_{j} R^{i l}(p) R_{l}^{j}(p)\right)+O\left(d^{-5-2 \alpha}\right)
\end{aligned}
$$

Proof. For the canonical gauge, we have

$$
\begin{aligned}
\left\langle H, \bar{e}_{4}\right\rangle= & |H| \sinh \theta=\frac{-\Delta \tau}{\sqrt{1+|\nabla \tau|^{2}}} \\
= & \frac{1}{\sqrt{1+|\nabla \tau|^{2}}}\left[2 a_{i} \tilde{x}^{i}+3 a_{0} k_{i j}\left(\tilde{x}^{i} \tilde{x}^{j}-\frac{1}{3} \delta^{i j}\right)\right. \\
& \quad+a_{0} \partial_{i} k_{j m}\left(2 \tilde{x}^{i} \tilde{x}^{j} \tilde{x}^{m}-\frac{1}{3}\left(\tilde{x}^{i} \delta^{j m}+\tilde{x}^{j} \delta^{m i}+\tilde{x}^{m} \delta^{i j}\right)\right) \\
& \left.\quad+\frac{a_{i}}{3} R_{n}^{i} \tilde{x}^{n}-\frac{1}{3} a_{m} R_{i j} \tilde{x}^{i} \tilde{x}^{j} \tilde{x}^{m}\right]+O\left(d^{-3-\alpha}\right)
\end{aligned}
$$

For the gauge $\left\{e_{3}^{\prime}, e_{4}^{\prime}\right\}$ induced by Jang's equation, we have [27, Theorem 4.1] $e_{4}^{\prime}=\sinh \phi e_{3}+\cosh \phi e_{4}$ with

$$
\begin{aligned}
\sinh \phi= & \frac{-u_{3}}{\sqrt{1+|\nabla \tau|^{2}}} \\
= & \frac{-1}{\sqrt{1+|\nabla \tau|^{2}}}\left(a_{i} \tilde{x}^{i}+\frac{1}{6} T_{i} \tilde{x}^{i}+a_{0} k_{i j} \tilde{x}^{i} \tilde{x}^{j}+\frac{1}{2} B_{i j m} \tilde{x}^{i} \tilde{x}^{j} \tilde{x}^{m}-\frac{1}{6} a_{i} R_{n}^{i} \tilde{x}^{n}\right) \\
& +O\left(d^{-3-\alpha}\right)
\end{aligned}
$$

and hence

$$
\begin{aligned}
& \left\langle H, e_{4}^{\prime}\right\rangle=\cosh \phi\left\langle H, e_{4}\right\rangle+\sinh \phi\left\langle H, e_{3}\right\rangle \\
& = \\
& \quad \frac{a_{0}}{\sqrt{1+|\nabla \tau|^{2}}}\left(-k_{i i}+k_{i j} \tilde{x}^{i} \tilde{x}^{j}-\partial_{m} k_{i i} \tilde{x}^{m}+\partial_{m} k_{i j} \tilde{x}^{m} \tilde{x}^{i} \tilde{x}^{j}\right) \\
& \quad+\frac{1}{\sqrt{1+|\nabla \tau|^{2}}}\left(a_{i} \tilde{x}^{i}+\frac{1}{6} T_{i} \tilde{x}^{i}+a_{0} k_{i j} \tilde{x}^{i} \tilde{x}^{j}+\frac{1}{2} B_{i j m} \tilde{x}^{i} \tilde{x}^{j} \tilde{x}^{m}-\frac{1}{6} a_{i} R_{n}^{i} \tilde{x}^{n}\right) \\
& \quad \cdot\left(2-\frac{1}{3} R_{i j} \tilde{x}^{i} \tilde{x}^{j}\right)+O\left(d^{-3-\alpha}\right) .
\end{aligned}
$$

By the constraint equations, we get

$$
|H|\left(\sinh \theta-\sinh \theta^{\prime}\right)=\frac{1}{\sqrt{1+|\nabla \tau|^{2}}} \frac{2}{3}\left(T_{m} \tilde{x}^{m}+a_{i} R_{j}^{i} \tilde{x}^{j}\right)+O\left(d^{-3-\alpha}\right)
$$

Next, using two elementary computations

$$
\cosh \theta^{\prime}-\cosh \theta=\frac{\sinh \theta^{\prime}+\sinh \theta}{\cosh \theta^{\prime}+\cosh \theta}\left(\sinh \theta^{\prime}-\sinh \theta\right)
$$

and (up to error of order $O\left(d^{-6-3 \alpha}\right)$ )

$$
\begin{aligned}
\theta^{\prime}-\theta & =\sinh \left(\theta^{\prime}-\theta\right)=\sinh \theta^{\prime} \cosh \theta-\sinh \theta \cosh \theta^{\prime} \\
& =\cosh \theta\left(\sinh \theta^{\prime}-\sinh \theta\right)-\sinh \theta\left(\cosh \theta^{\prime}-\cosh \theta\right)
\end{aligned}
$$

we get up to a negligible error,

$$
\begin{aligned}
|H| & \sqrt{1+|\nabla \tau|^{2}}\left(\cosh \theta^{\prime}-\cosh \theta\right)+\Delta \tau\left(\theta^{\prime}-\theta\right) \\
= & \left(\sqrt{1+|\nabla \tau|^{2}}|H|-\sinh \theta \Delta \tau\right)\left(\cosh \theta^{\prime}-\cosh \theta\right) \\
& +\Delta \tau \cosh \theta\left(\sinh \theta^{\prime}-\sinh \theta\right) \\
= & \left(\left(\sqrt{1+|\nabla \tau|^{2}}|H|-\sinh \theta \Delta \tau\right) \frac{\sinh \theta+\sinh \theta^{\prime}}{\cosh \theta+\cosh \theta^{\prime}}+\Delta \tau \cosh \theta\right) \\
& \cdot\left(\sinh \theta^{\prime}-\sinh \theta\right) \\
= & \sqrt{1+|\nabla \tau|^{2}}|H|\left(\cosh ^{2} \theta \frac{\sinh \theta+\sinh \theta^{\prime}}{\cosh \theta+\cosh \theta^{\prime}}-\sinh \theta \cosh \theta\right) \\
& \cdot\left(\sinh \theta^{\prime}-\sinh \theta\right) \\
= & \frac{1}{\cosh \theta+\cosh \theta^{\prime}} \sqrt{1+|\nabla \tau|^{2}}|H|\left(\sinh \theta^{\prime}-\sinh \theta\right)^{2}
\end{aligned}
$$

Consequently,

$$
\begin{aligned}
& \frac{1}{8 \pi} \int\left[|H| \sqrt{1+|\nabla \tau|^{2}}\left(\cosh \theta^{\prime}-\cosh \theta\right)+\Delta \tau\left(\theta^{\prime}-\theta\right)\right] d \Sigma \\
& \quad=\frac{1}{8 \pi} \int \frac{1}{2 \cosh \theta} \sqrt{1+|\nabla \tau|^{2}}|H|\left(\sinh \theta^{\prime}-\sinh \theta\right)^{2} d S^{2} \\
& \quad=\frac{1}{8 \pi} \frac{1}{4 a_{0}} \frac{4}{9} \int\left(T_{m} \tilde{x}^{m}+a_{i} R_{j}^{i} \tilde{x}^{j}\right)^{2} d S^{2}+O\left(d^{-5-2 \alpha}\right) \\
& \quad=\frac{1}{54 a_{0}}\left(\sum_{m} T_{m}^{2}+2 T_{m} a_{i} R^{i m}+a_{i} a_{j} R^{i l} R_{l}^{j}\right)+O\left(d^{-5-2 \alpha}\right)
\end{aligned}
$$

Proof of Theorem 5.1, (2). Putting Lemma 5.5,5.6, 5.10 together, we get

$$
\begin{aligned}
E\left(\Sigma, X, T_{0}\right)= & \frac{a_{0}}{90} R_{i j}(p) R^{i j}(p)+\frac{1}{180 a_{0}} R_{i j}(p) R^{i j}(p) \\
& +\frac{a_{0}}{180} \bar{W}_{0 i m j}(p) \bar{W}_{0}^{i m j}(p)-\frac{1}{45} a_{m} \bar{W}_{0}^{i m j}(p) \bar{W}_{0 i 0 j}(p) .
\end{aligned}
$$

Recall [8, page 4]

$$
\begin{aligned}
Q\left(e_{0}, e_{0}, e_{0}, T_{0}\right)= & \frac{a_{0}}{2} \bar{W}_{0 i m j}(p) \bar{W}_{0}{ }^{i m j}(p)+a_{0} \bar{W}_{0 m 0 n}(p) \bar{W}_{0}{ }_{0}^{m}{ }^{n}(p) \\
& -2 a_{m} \bar{W}_{0}{ }^{i m j}(p) \bar{W}_{0 i 0 j}(p)
\end{aligned}
$$

By the Gauss equation, $\bar{W}_{0 i 0 j}=R_{i j}+O\left(d^{-2-2 \alpha}\right)$, we complete the proof.

## 6. Small sphere limit

The careful readers would surely find the similarity between our main result and the small sphere limit [8, Theorem 1.1, 1.2]. In this section, we adapt the previous computations to the small sphere setting. Although the family of small spheres is different from that considered in [8], the limit of quasi-local mass turns out to be the same.

Let $p$ be a point in the spacetime. We recall the setup in [8]. Let $e_{0}, e_{1}, e_{2}, e_{3}$ be an orthonormal basis at $p,\left\langle e_{\alpha}, e_{\beta}\right\rangle=\eta_{\alpha \beta}$. Using $e_{0}$, we normalize each null vector $L$ at $p$ by $\left\langle L, e_{0}\right\rangle=-1$. We consider the null geodesics with initial velocity being the normalized $L . \Sigma_{r}$ is defined as the level sets of the affine parameter $r$. In short, Chen-Wang-Yau considered small spheres approaching $p$ along the light cone.

Theorem 6.1. [8, Theorem 1.1, 1.2]

1) For the isometric embeddings $\mathcal{X}_{r}$ of $\Sigma_{r}$ into $\mathbb{R}^{3}$, the quasi-local energy satisfies

$$
\begin{equation*}
E\left(\Sigma_{r}, \mathcal{X}_{r}, T_{0}\right)=r^{3} \cdot \frac{4 \pi}{3} T\left(e_{0}, T_{0}\right)+O\left(r^{4}\right) \tag{6.1}
\end{equation*}
$$

as $r$ goes to 0.
2) Suppose the stress-energy tensor $T_{\alpha \beta}$ vanish in a neighborhood of $p$. Then, for the pair $\left(\mathcal{X}_{r}\left(T_{0}\right), T_{0}\right)$ solving the leading order term of the optimal embedding equation of $\Sigma_{r}$, we have

$$
\begin{equation*}
E\left(\Sigma_{r}, \mathcal{X}_{r}\left(T_{0}\right), T_{0}\right)=r^{5} \cdot \frac{1}{90}\left[Q\left(e_{0}, e_{0}, e_{0}, T_{0}\right)+\frac{\sum_{m, n} \bar{W}_{0 m 0 n}^{2}(p)}{2 a_{0}}\right]+O\left(r^{6}\right) \tag{6.2}
\end{equation*}
$$

as r goes to 0 .
In the right-hand side of both formula, we identify $T_{0}=\left(a_{0},-a_{1},-a_{2},-a_{3}\right)$ with the timelike vector $a_{0} e_{0}-\sum_{i=1}^{3} a_{i} e_{i}$ at $p$.

To get the same limit using the method of previous sections, we approach $p$ along a spacelike hypersurface. Let $X^{0}, X^{1}, X^{2}, X^{3}$ be a normal coordinate near $p$. The metric has the expansion

$$
\bar{g}_{\alpha \beta}=\eta_{\alpha \beta}-\frac{1}{3} \bar{R}_{\alpha \gamma \beta \delta} X^{\gamma} X^{\delta}+\cdots
$$

Let $M$ be the slice $\left\{X^{0}=0\right\}$. We consider small spheres $\Sigma_{r}=\left\{X^{0}=0\right.$, $\left.\left(X^{1}\right)^{2}+\left(X^{2}\right)^{2}+\left(X^{3}\right)^{2}=r^{2}\right\}$ and balls $B_{r}=\left\{X^{0}=0,\left(X^{1}\right)^{2}+\left(X^{2}\right)^{2}+\right.$ $\left.\left(X^{3}\right)^{2} \leq r^{2}\right\}, 0<r<\epsilon$. The timelike unit normal vector and second fundamental form of $M$ are given by

$$
\vec{n}=\frac{\partial}{\partial X^{0}}+\frac{1}{3} \bar{R}_{0 j i k} X^{j} X^{k} \frac{\partial}{\partial X^{i}}-\frac{1}{6} \bar{R}_{0 j 0 k} X^{j} X^{k} \frac{\partial}{\partial X^{0}}+O\left(|X|^{3}\right)
$$

and

$$
\begin{aligned}
k_{i j} & =\frac{1}{2}\left(\left\langle D_{\partial_{i}} \vec{n}, \partial_{j}+\left\langle D_{\partial_{j}} \vec{n}, \partial_{i}\right\rangle\right)\right. \\
& =\frac{1}{2} \partial_{0} g_{i j}+\frac{1}{6}\left(\bar{R}_{0 i j q}+\bar{R}_{0 j i q}\right) X^{q}+O\left(|X|^{3}\right) \\
& =-\frac{1}{3}\left(\bar{R}_{0 i q j}+\bar{R}_{0 j q i}\right) X^{q}+O\left(|X|^{2}\right) .
\end{aligned}
$$

We compute on $\Sigma_{r}$

$$
\begin{aligned}
\operatorname{tr}_{\Sigma} k & =O\left(r^{2}\right) \\
\alpha_{H} & =-k\left(\partial_{a}, \nu\right)+\partial_{a}\left(\frac{\operatorname{tr}_{\Sigma} k}{|H|}\right)+O\left(r^{4}\right)=-\frac{r^{2}}{6} \bar{R}_{j 0 i q} \tilde{x}_{a}^{i} \tilde{x}^{j} \tilde{x}^{q}+O\left(r^{4}\right), \\
\operatorname{div\alpha _{H}} & =O\left(r^{2}\right)
\end{aligned}
$$

We are ready to use Theorem 4.1 to recover the small sphere limits, Theorem 6.1. Consider the nonvacuum case first. By definition, we have $\mu=8 \pi T\left(e_{0}, e_{0}\right)$ and $J_{i}=8 \pi T\left(e_{0}, e_{i}\right)$. Moreover, integrating over $B_{r}$ provides a factor of $r^{3}$. Therefore we recover (6.1).

For the non-vacuum case, we again solve the optimal embedding equation and Jang's equation first and then evaluate the three integrals on either $B_{r}$ or $\Sigma_{r}$.

Lemma 6.2. The following pair $T_{0}=\left(a_{0},-a_{1},-a_{2},-a_{3}\right)$ and

$$
\begin{aligned}
\mathcal{X}^{0} & =\frac{a_{i}}{6 a_{0}} r^{3} R_{m n}(p) \tilde{x}^{m} \tilde{x}^{n} \tilde{x}^{i}+O\left(r^{4}\right) \\
\mathcal{X}^{i} & =r \tilde{x}^{i}-\frac{r^{3}}{6} R_{n}^{i}(p) \tilde{x}^{n}-\frac{r^{3}}{6} R_{m n}(p) \tilde{x}^{m} \tilde{x}^{n} \tilde{x}^{i}+O\left(r^{4}\right)
\end{aligned}
$$

solves the leading order of the optimal embedding equation on $\Sigma_{r}$. In particular, the above solution gives a time function $\tau=-\mathcal{X} \cdot T_{0}$ with

$$
\tau=r a_{i} \tilde{x}^{i}-\frac{r^{3}}{6} a_{i} R_{n}^{i}(p) \tilde{x}^{n}+O\left(r^{4}\right)
$$

Lemma 6.3. Let $u$ be the solution of the Dirichlet problem of Jang's equation on $B_{r}$ with boundary value $\tau$. Then

$$
u=a_{i} X^{i}+\frac{r^{2}}{6} T_{i} X^{i}+\frac{r^{2}}{6} B_{i j m} X^{i} X^{j} X^{m}-\frac{r^{2}}{6} a_{i} R_{n}^{i} X^{n}
$$

where

$$
B_{i j m}=-\frac{1}{3}\left(\delta_{i j} T_{m}+\delta_{j m} T_{i}+\delta_{m i} T_{j}\right)
$$

The constants $T_{i}$ can be solved from Jang's equation. As before, their contribution to each integral would cancel and we do not bother to solve them explicitly here.

## Lemma 6.4.

$$
\begin{aligned}
& \frac{1}{16 \pi} \int_{B_{r}}\left[\left|k_{i j}-\frac{D_{i} D_{j} u}{\sqrt{1+|D u|^{2}}}\right|_{\bar{g}}^{2}+2|Y|_{\bar{g}}^{2}\right] d \tilde{\Omega} \\
& = \\
& \quad r^{5}\left[-\frac{1}{54 a_{0}} \sum_{m} T_{m}^{2}-\frac{1}{27 a_{0}} T_{m} a_{l} R^{l m}(p)+\frac{1}{90}\left(a_{0}-\frac{1}{a_{0}}\right) R_{i j}(p) R^{i j}(p)\right. \\
& \quad-\frac{1}{54 a_{0}} a_{i} a_{j} R^{i l}(p) R_{l}^{j}(p)+\frac{a_{0}}{180} \bar{W}_{0 i m j}(p) \bar{W}_{0}^{i m j}(p) \\
& \left.\quad-\frac{1}{45} a_{m} \bar{W}_{0}^{i m j}(p) \bar{W}_{0 i 0 j}(p)\right]+O\left(r^{6}\right)
\end{aligned}
$$

Proof. We have

$$
\begin{aligned}
k_{i j}-\frac{D_{i} D_{j} u}{\sqrt{1+|D u|^{2}}=}=\frac{1}{3} & \left(\frac{1}{a_{0}}\left(\delta_{i j} T_{m}+\delta_{j m} T_{i}+\delta_{m i} T_{j}\right)\right. \\
& \left.-\bar{W}_{0 i m j}-\bar{W}_{0 j m i}+\frac{a_{l}}{a_{0}}\left(R_{i l j m}+R_{i m j l}\right)\right) X^{m}+O\left(r^{2}\right)
\end{aligned}
$$

Since we are integrating on a ball with radius $r$ instead of 1 , we get an additional factor $r^{5}$ from

$$
\frac{1}{16 \pi} \int_{B_{r}} X^{m} X^{n} d x=\frac{r^{5}}{60} \delta^{m n}
$$

## Lemma 6.5.

$\frac{1}{16 \pi} \int\left[\left|h_{0}(s)-h(s)\right|^{2}-\left(H_{0}(s)-H(s)\right)^{2}\right] d \tilde{\Omega}=\frac{r^{5}}{60 a_{0}} R_{i j}(p) R^{i j}(p)+O\left(r^{6}\right)$.
Proof. The argument is almost identical as in the proof of Lemma 5.6. We get an additional factor $r^{5}$ in the last step:

$$
\int_{0}^{r} s^{4} d s=\frac{r^{5}}{5}
$$

## Lemma 6.6.

$$
\begin{aligned}
& \frac{1}{8 \pi} \int_{\Sigma_{r}}\left[|H| \sqrt{1+|\nabla \tau|^{2}}\left(\cosh \theta^{\prime}-\cosh \theta\right)+\Delta \tau\left(\theta^{\prime}-\theta\right)\right] d \Sigma \\
& \quad=\frac{r^{5}}{54 a_{0}}\left(\sum_{m} T_{m}^{2}+2 T_{m} a_{i} R^{i m}(p)+a_{i} a_{j} R^{i l}(p) R_{l}^{j}(p)\right)+O\left(r^{6}\right)
\end{aligned}
$$

Proof. A similar computation as in the proof of Lemma 5.10 leads to

$$
|H|\left(\sinh \theta-\sinh \theta^{\prime}\right)=\frac{r}{\sqrt{1+|\nabla \tau|^{2}}} \frac{2}{3}\left(T_{m} \tilde{x}^{m}+a_{i} R_{j}^{i} \tilde{x}^{j}\right)+O\left(r^{2}\right)
$$

Recall the main term in the integrand is $|H|\left(\sinh \theta-\sinh \theta^{\prime}\right)^{2}$. We get a factor $r^{3}$ because $|H|=\frac{2}{r}+O\left(r^{-2}\right)$ and another factor $r^{2}$ from the area form of $\Sigma_{r}$.

Putting the above three lemma together with Theorem 4.1, we recover 6.2).

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