# Complex structures of a twenty dimensional family of Calabi-Yau 3-folds

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In this paper, we classify all isomorphic classes of a family of Calabi-Yau 3-folds with 20 parameters. In addition, we show that the isomorphisms form a finite group. The invariants under the action of this group are calculated by introducing the so-called DS-graph.

### 1. Introduction

A Calabi-Yau manifold is a manifold with trivial canonical bundle. It plays an important role in theoretical physics. In super-string theory, it is conjectured that the extra dimensions of space-time take the form of a compact complex 3-dimensional Calabi-Yau manifold. Non-singular quintic 3-folds are Calabi-Yau manifolds. It is a fundamental important question in both mathematics and theoretical physics to determine when two given quintic 3-folds have the same complex structure. Such a question seems to be out of reach by 19th century invariant theory or modern geometric invariant theory. Candelas, Ossa, Green and Parkers [1] studied the following one dimensional family of Calabi-Yau 3-folds

$$X_t := \{(x_i) \in \mathbb{CP}^4 : x_1^5 + x_2^5 + x_3^5 + x_4^5 + x_5^5 + tx_1x_2x_3x_4x_5 = 0\}$$

in detail by means of the period map. Chen et al. [3, 4] generalize it to the families

$$X_t^{(n)} := \{ (x_i) \in \mathbb{CP}^{n-1} : x_1^n + x_2^n + \dots + x_n^n + tx_1x_2 \cdots x_n = 0 \}$$

with  $n \ge 3$ . The purpose of this paper is to study the complex structures of a distinguished class of 20-dimensional family of Calabi-Yau 3-folds  $\{V(f_t)\}$ 

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with parameter  $\mathbf{t} := (t_{i,j})$  for i, j = 1, 2, 3, 4, 5 and  $i \neq j$ , where

$$f_{\mathbf{t}} := f_{\mathbf{t}}(x) := x_1^5 + x_2^5 + x_2^5 + x_3^5 + x_4^5 + x_5^5 + \sum_{i \neq j} t_{i,j} x_i^4 x_j.$$

Our main goal is to completely distinguish these complex structures and find out the moduli and modular group of this family by introducing a novel simple method.

Let G be a finite group  $G = S_5 \ltimes \mathbb{Z}_5^5$ . The group operation is given by

$$(\tau, b_1, b_2, \dots, b_5) \cdot (\sigma, a_1, a_2, \dots, a_5)$$
  
:=  $(\tau \sigma, b_{\sigma(1)} + a_1, b_{\sigma(2)} + a_2, \dots, b_{\sigma(5)} + a_5)$ 

for  $(\tau, b_1, b_2, \dots, b_5)$ ,  $(\sigma, a_1, a_2, \dots, a_5) \in G$ . We define the group action on variables  $t_{i,j}$  as follows. Fix  $\eta$  a 5-th primary root of 1. Then

$$(\sigma, a_1, a_2, \dots, a_5) \cdot t_{i,j} := \eta^{a_i - a_j} t_{\sigma(i), \sigma(j)}.$$

When restrict the parameter  $\mathbf{t}$  to a specific affine open subset, the main result of this paper states that the Calabi-Yau 3-fold  $V(f_{\mathbf{t}})$  is biholomorphic to  $V(f_{\mathbf{t}'})$  if and only if there exists some element  $g \in G$  such that  $g \cdot t_{i,j} = t'_{i,j}$  for  $i, j = 1, 2, \ldots, 5$  and  $i \neq j$ . Moreover, we construct a basis of  $\mathbb{C}[t_{ij}]^G$  expressed as the polynomials  $\sum_{\text{sym}} M(V, E_d, E_s)$ , where  $(V, E_d, E_s)$  ranges over all DS-graphs. See the precise statement in Section 3.

## 2. Isomorphic class of family $\{V(f_t)\}$

In this section, we investigate the complex structures of the family  $\{V(f_{\mathbf{t}})\}$ . Let  $x = (x_1, x_2, \dots, x_5)$ . The derivative with respect to  $x_i$  will be shortly denoted by  $\partial_i$ . Let  $I_{\mathbf{t}}$  be the ideal of  $\mathbb{C}[x]$  generated by  $\partial_{i,j} f_{\mathbf{t}} : i, j = 1, 2, \dots, 5$ . We introduce the algebra

$$A_{\mathbf{t}} := \mathbb{C}[x]/I_{\mathbf{t}}.$$

Observe that  $A_{\mathbf{t}}$  is an invariant of the  $V(f_{\mathbf{t}})$ . We require the parameters  $t_{i,j}$  verify the main assumption that ideal  $I_{\mathbf{t}}$  is generated by  $x_i^3$  and  $\sum_{k\neq i} t_{i,k} x_i^2 x_k$  for  $i=1,2,\ldots,5$ . We shall emphasize that this assumption holds generically. To see this, we deduce the following lemma.

**Lemma 1.** Let (i, j, k, l, m) be an ordering of  $\{1, 2, 3, 4, 5\}$ . Suppose that the coefficients  $t_{i,j}$  satisfy the following conditions

- 1)  $t_{i,j}t_{j,k}t_{k,i} + t_{j,i}t_{k,j}t_{i,k} \neq 0$ .
- 2)  $t_{l,i}, t_{l,j}, t_{l,k}$  do not vanish simultaneously.
- 3)  $t_{m,i}, t_{m,j}, t_{m,k}$  do not vanish simultaneously.

Then the ideal  $I_{\mathbf{t}}$  is finite generated by  $x_i^3$  and  $\sum_{k\neq i} t_{i,k} x_i^2 x_k$  for  $i=1,2,\ldots,5$ .

*Proof.* By direct computation, the second derivatives  $\partial_{i,j} f_{\mathbf{t}}$  are expressed as

$$\partial_{i,j} f_{\mathbf{t}} = 4t_{i,j} x_i^3 + 4t_{j,i} x_i^3 \text{ for } i \neq j,$$

and

$$\partial_{i,i} f_{\mathbf{t}} = 20x_i^3 + 12\sum_{k \neq i} t_{i,k} x_i^2 x_k.$$

The first condition of this lemma and the expressions of  $\partial_{i,j} f_{\mathbf{t}}$ ,  $\partial_{j,k} f_{\mathbf{t}}$ ,  $\partial_{k,i} f_{\mathbf{t}}$  imply  $x_i^3, x_j^3, x_k^3$  are contained in  $I_{\mathbf{t}}$ . The rest conditions yield that  $x_l^3, x_m^3$  are also contained in  $I_{\mathbf{t}}$ . The proof of our lemma is completed by applying the expressions of  $\partial_{i,i}(f_{\mathbf{t}})$  with  $i=1,2,\ldots,5$ .

Let  $T = \mathbb{C}^5$  be a  $\mathbb{C}$ -vector space spanned by  $x_i$  for i = 1, 2, ..., 5. For  $\xi \in T$ , we denote  $\bar{\xi} \in A_t$ . Define subset of T by  $S_t := \{\xi \in T : \bar{\xi}^3 = 0\}$ . Now we wish to determine the set  $S_t$ .

**Lemma 2.** Assume that the main assumption of  $\mathbf{t}$  holds. Then the set  $S_{\mathbf{t}}$  is independent on the coefficients  $\mathbf{t}$ . Moreover, it is given by coordinate axes. That is  $S_{\mathbf{t}} = \{\lambda x_i : \lambda \in \mathbb{C}, i = 1, 2, ..., 5\}$ .

*Proof.* The fact  $\bar{\xi}^3 = 0$  means that  $\xi^3$  is generated by  $x_i^3$  and  $\sum_{k \neq i} t_{i,k} x_i^2 x_k$ . Write  $\xi = \alpha_1 x_1 + \alpha_2 x_2 + \alpha_3 x_3 + \alpha_4 x_4 + \alpha_5 x_5$ . Then this means

(1) 
$$(\sum_{i=1}^{5} \alpha_i x_i)^3 = \sum_{i=1}^{5} \beta_i x_i^3 + \sum_{i=1}^{5} \gamma_i \sum_{k \neq i} t_{i,k} x_i^2 x_k$$

with some coefficients  $\beta_i$ ,  $\gamma_i$ . By comparing coefficients, we see that at most two  $\alpha_i$ 's are nonzero. Without loss generality, we assume that  $\alpha_1$  and  $\alpha_2$  are

nonzero. Thus, Equation (1) becomes

$$(\alpha_1 x_1 + \alpha_2 x_2)^3 = \beta_1 x_1^3 + \beta_2 x_2^3 + \gamma_1 (t_{1,2} x_1^2 x_2 + t_{1,3} x_1^2 x_3 + t_{1,4} x_1^2 x_4 + t_{1,5} x_1^2 x_5) + \gamma_2 (t_{2,1} x_2^2 x_1 + t_{2,3} x_2^2 x_3 + t_{2,4} x_2^2 x_4 + t_{2,5} x_2^2 x_5).$$

This implies  $t_{1,k} = t_{2,k} = 0$  for k = 3, 4, 5. The fact  $x_i^3 \in I_t$  implies  $t_{1,2} = t_{2,1} = 0$ . Hence, we obtain  $(\alpha_1 x_1 + \alpha_2 x_2)^3 = \beta_1 x_1^3 + \beta_2 x_2^3$ . Therefore, we have  $\alpha_1 = 0$  or  $\alpha_2 = 0$ . In conclusion, we find that  $\xi = \lambda x_i$  for some constant  $\lambda$ .

**Theorem 3.** Assume that  $\mathbf{t}$  and  $\mathbf{t}'$  satisfy the main assumption. Then the linear isomorphism from  $V(f'_{\mathbf{t}})$  to  $V(f_{\mathbf{t}})$  is generated by permutations on the subscripts of  $t_{i,j}$  and the scaling  $x_i \mapsto x_i \eta_i$  such that  $\eta_i^5 = 1$  and  $t'_{i,j} = t_{i,j} \eta_i \eta_i^{-1}$ .

Proof. Suppose that  $V(f_{\mathbf{t}})$  is isomorphic to  $V(f'_{\mathbf{t}})$ . So we have  $A_{\mathbf{t}} \cong A_{\mathbf{t}'}$ . Hence,  $S_{\mathbf{t}}$  maps isomorphically to  $S_{\mathbf{t}'}$ . Denote by  $\phi$  the isomorphism from  $V(f'_{\mathbf{t}})$  to  $V(f_{\mathbf{t}})$ . From Lemma 2, we can assume that  $\phi(x_i) := \lambda_i x_i$  for some constant  $\lambda_i$  with  $i = 1, 2, \ldots, 5$ . By assumption, we have  $f_{\mathbf{t}'}(\phi(x)) = \lambda_0^5 f_{\mathbf{t}}(x)$  for some complex number  $\lambda_0$ . Then

$$f_{\mathbf{t}'}(\phi(x)) = \sum_{i=1}^{5} \phi(x_i)^5 + \sum_{i \neq j} t'_{i,j} \phi(x_i)^4 \phi(x_j)$$

$$= \sum_{i=1}^{5} \lambda_i^5 x_i^5 + \sum_{i \neq j} t'_{i,j} \lambda_i^4 \lambda_j x_i^4 x_j$$

$$= \sum_{i=1}^{5} \lambda_0^5 x_i^5 + \lambda_0^5 \sum_{i \neq j} t_{i,j} x_i^4 x_j.$$

This implies  $\lambda_i^5 = \lambda_0^5$  and  $\lambda_i^4 \lambda_j t'_{i,j} = \lambda_0^5 t_{i,j}$ . Put  $\eta_i := \lambda_i / \lambda_0$ . Then  $t'_{i,j} = \eta_i \eta_j^{-1} t_{i,j}$ . Conversely, it is easy to verify that permutation on the subscripts and scaling defined above map isomorphically from  $V(f_{\mathbf{t}'})$  to  $V(f_{\mathbf{t}})$ .

Let G be a finite group  $G = S_5 \ltimes \mathbb{Z}_5^5$ . Fix  $\eta$  a 5-th primary root of 1. According to previous theorem, it is natural to define the group action on

variables  $t_{i,j}$  as

$$g \cdot t_{i,j} := \eta^{a_i - a_j} t_{\sigma(i), \sigma(j)}$$

for  $g = (\sigma, a_1, a_2, \dots, a_5) \in G$ . Applying the previous theorem, we obtain the following corollary.

**Corollary 4.** Assume that **t** and **t'** satisfy the main assumption. Then  $V(f_{\mathbf{t}})$  and  $V(f_{\mathbf{t'}})$  are isomorphic if and only if there exists some element  $g \in G$ , such that  $g \cdot t_{i,j} = t'_{i,j}$  for i, j = 1, 2, ..., 5 and  $i \neq j$ .

## 3. Directed graph

In this section, we establish a relationship between invariants of  $V(f_{\mathbf{t}})$  and some directed graphs. The canonical directed graph consists of the set of vertices V and the set of directed edges E. In order to investigate the invariances of the family  $\{V(f_{\mathbf{t}})\}$ , we introduce the new kind of directed graphs which shall be called DS-graph. It consists of the set of vertices V and the set of dashed edges  $E_d$  and the set of (multiple) solid edges  $E_s$  such that

- 1) the couple  $(V, E_s)$  is the union of distinct loops;
- 2) the couple  $(V, E_d)$  is a directed graph containing no loops.

Now we fix V to be a set of five vertices. Let  $(V, E_d, E_s)$  be a DS-graph. Associate it with a monomial  $M(V, E_d, E_s)$  in 20 variables, write  $t_{i,j}$  with i, j = 1, 2, ..., 5 and  $i \neq j$ . That is

$$M(V, E_d, E_s) := \prod_{(i,j) \in E_d} t_{i,j}^5 \prod_{(i,j) \in E_s} t_{i,j}.$$

As usual, two DS-graphs will be viewed isomorphically if they differ exactly by a permutation on the vertices. Denote by DS(5) the set of all isomorphism class of DS-graphs associated to the set of vertices V. For a monomial m in 20 variables  $t_{i,j}$ , we denote  $\sum_{\text{sym}} m$  the symmetric sum of m, namely,

$$\sum_{\text{sym}} m := \sum_{\sigma \in S_5} \sigma(m).$$

We are in the position to describe a basis of the quotient  $\mathbb{C}[t_{i,j}]^G$ .

**Theorem 5.** The quotient  $\mathbb{C}[t_{ij}]^G$  is generated by the polynomials  $\sum_{\text{sym}} M(V, E_d, E_s)$  with  $(V, E_d, E_s) \in DS(5)$ .

*Proof.* Let P be a polynomial in  $\mathbb{C}[t_{ij}]^G$ . Since P is invariant under symmetric group, one may write

$$P = \sum_{\text{sym}} P_1 + \ldots + \sum_{\text{sym}} P_k,$$

where all  $P_s$ 's are monomials. By assumption,  $P_i$  is invariant under action of subgroup  $\{id\} \times \mathbb{Z}_5^5$ . We see that  $P_s$  can be split into three parts

(2) 
$$P_s = \prod_{i=1}^5 (t_{i,j}^5)^{e_{i,j}} \cdot \prod_{\{i_j\}} (t_{i_1,i_2} t_{i_2,i_3} \cdots t_{i_{n-1},i_n} t_{i_n,i_1}) \cdot R.$$

Geometrically, the second part is represented by loops. Hence, we may assume that  $R = \lambda t_{i_1,j_1} t_{i_2,j_2} \dots t_{i_m,j_m}$  contains no loops. That means

$$i_1 \notin \{j_1, j_2, j_3, \dots, j_m\}.$$

However, R is not invariant under  $\{id\} \times \mathbb{Z}_5^5$  if  $m \ge 1$ . Thus, we have  $R = \lambda$ . Suppose that all power  $e_{i,j}$ 's in the expression of  $P_s$  equal 1 and the second part consists of distinct loops. Then clearly the polynomial  $P_s$  is given by some DS-graph  $(V, E_d, E_s)$ . That is  $P_s = M(V, E_d, E_s)$ . To complete the proof, it suffices to reduce the powers in (2). Define invariant polynomials

$$S_1 := \sum_{\text{sym}} (t_{i,j}^5)^2 - \left(\sum_{\text{sym}} t_{i,j}^5\right)^2,$$

and

$$S_2 := \sum_{\text{sym}} (t_{i_1,i_2} t_{i_2,i_3} \cdots t_{i_{n-1},i_n} t_{i_n,i_1})^2 - \left( \sum_{\text{sym}} t_{i_1,i_2} t_{i_2,i_3} \cdots t_{i_{n-1},i_n} t_{i_n,i_1} \right)^2.$$

We find that both  $S_1$  and  $S_2$  satisfy the previous condition. Hence they are generated by polynomials represented by DS-graphs. It yields that  $\sum_{\text{sym}} (t_{i,j}^5)^2$  and  $\sum_{\text{sym}} (t_{i,i_2} t_{i_2,i_3} \cdots t_{i_{n-1},i_n} t_{i_n,i_1})^2$  are also represented by DS-graphs. This completes the proof.

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