LOCAL ERROR OF A SPLITTING SCHEME FOR A NONLINEAR SCHRÖDINGER-TYPE EQUATION WITH RANDOM DISPERSION[*]

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Abstract. We study a Lie splitting scheme for a nonlinear Schrödinger-type equation with random dispersion. The main result is an approximation of the local error. Then we can deduce sharp order estimates, for instance in the case of a white noise dispersion.

Keywords. Splitting schemes; nonlinear Schrödinger-type equations; stochastic partial differential equations.

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1. Introduction

We consider the nonlinear Schrödinger equation with white noise dispersion. It can be written as

$$u(t,x) = u_0(x) + i \int_0^t \frac{\partial^2 u}{\partial x^2}(\theta,x) \circ dW(\theta) + \int_0^t g(u(\theta,x)) d\theta, \quad (t,x) \in [0,1] \times \mathbb{R}, \qquad (1.1)$$

where $u_0 \in L^2(\mathbb{R},\mathbb{C})$, W is a Brownian motion and g is a complex nonlinear function. The existence and the uniqueness of the solution are established for instance for a Lipschitz nonlinearity in [15], for a cubic nonlinearity in [7], and for a quintic nonlinearity in [8]. Regarding its numerical analysis, several schemes have been studied (for example in [3, 5, 6, 10, 15]). In particular, a Lie splitting scheme is analyzed in [15]. Among other results, it is proven that the order of the scheme is at least $1/2$ and numerical experiments show that this order is 1 (also shown in [5] and [3]). In addition, order estimates have been established when the Brownian motion W in (1.1) is replaced by another process. For instance, if W is an α-Hölder function ($\alpha \in (0,1)$) then the order is α (see [15]), or if W is a fractional Brownian motion with Hurst index $H \in (0,1)$ then the order is H (see [9]). As in many other works dealing with splitting schemes for other deterministic or random equations (see for instance [1, 2, 4, 9, 15, 17]), the study of the order crucially involves estimates of the local error.

In this paper we consider a Lie splitting scheme for a nonlinear Schrödinger-type equation with random dispersion. This equation has the same form as (1.1) but W is a random process (or eventually a continuous function) and $i\partial^2/\partial x^2$ is replaced by a more general operator.

Under assumptions on the moments of the random dispersion term, we establish an expansion of the local error, which gives us more information than the usual estimates. As a corollary, if the dispersion term is defined from a process with independent increments and mean zero, we deduce a sharp order estimate. In the particular case of a white noise dispersion, we show that the order of convergence of the scheme is 1. This has been theoretically or numerically observed for splitting or other schemes (for instance [3, 5, 15]) for Equation (1.1).

The paper is organized as follows. We present the framework in Section 2. The main result about the approximation of the local error is given in Section 3. Section 4

is devoted to the proofs. In Section 5 we discuss an application to order estimates. In Section 6 we study another splitting scheme. Numerical results are presented in Section 7.

Throughout the paper we denote by L^2 the space $L^2(\mathbb{R},\mathbb{C})$, by $\|\cdot\|_{L^2}$ its norm and by $\langle\cdot,\cdot\rangle_{L^2}$ its inner product. For every $\sigma\in\mathbb{N}$, we denote by H^σ the Sobolev space of functions $f\in L^2$ such that $\xi\mapsto(1+|\xi|^2)^{\sigma/2}\mathcal{F}(f)(\xi)\in L^2$ where $\mathcal{F}$ is the Fourier transform. The norm is denoted by $\|\cdot\|_{H^\sigma}$ and the inner product by $\langle\cdot,\cdot\rangle_{H^\sigma}$.

In this paper we consider a probability space $(\Omega,\mathcal{T},\mathbb{P})$. The expectation is $\mathbb{E}$ and if $q\geq1$ and M is a random variable taking its values in a normed space $F=(F,\|\cdot\|_F)$, we denote $\sqrt[q]{\mathbb{E}[\|M\|_F^q]}$ by $\|M\|_{L_\Omega^q(F)}$ when it is well defined.

2. Framework

2.1. Nonlinear Schrödinger-type equation with random dispersion. Let u_0 be a function in L^2, g be a function from $\mathbb{C}$ to $\mathbb{C}$, a be a function from $\mathbb{R}$ to $\mathbb{R}$ and W be a continuous stochastic process. We assume that there exist $C_a>0$ and $\sigma\in\mathbb{N}$ such that for all $\xi\in\mathbb{R}$,

$$|a(\xi)|\leq C_a(1+|\xi|^2)^{\sigma/2}. \tag{2.1}$$

We consider the following nonlinear Schrödinger-type equation

$$u(t,x)=u_0(x)+\int_0^t Au(\theta,x)\circ dW(\theta)+\int_0^t g(u(\theta,x))d\theta,\ (t,x)\in[0,1]\times\mathbb{R} \tag{2.2}$$

where $\circ dW$ stands for a Stratonovich-type differentiation we explain below and A is the operator on H^σ such that for all $f\in H^\sigma$,

$$Af=\mathcal{F}^{-1}(\xi\to ia(\xi)\mathcal{F}(f)(\xi)) \tag{2.3}$$

where $\mathcal{F}$ is the Fourier transform with respect to x.

We define

$$\Delta=\{(s,t)\in[0,1]^2\,|\,s\leq t\}. \tag{2.4}$$

Equation (2.2) is rewritten as

$$u(t,x)=X(0,t)u_0(x)+\int_0^t X(\theta,t)g(u(\theta,x))\,d\theta,\ (t,x)\in[0,1]\times\mathbb{R} \tag{2.5}$$

where the family of operators $\{X(t_0,t)\}_{(t_0,t)\in\Delta}$ is defined such that for every $v\in L^2$ and every $(t_0,t)\in\Delta$,

$$X(t_0,t)v=\mathcal{F}^{-1}(\exp(ia(\cdot)(W(t)-W(t_0)))\mathcal{F}(v)). \tag{2.6}$$

Notice that for all $p\in\mathbb{N}$, $\|X(t_0,t)v\|_{H^p}=\|v\|_{H^p}$ because a and W are real.

REMARK 2.1.   This framework includes deterministic or stochastic nonlinear Schrödinger-type equations which have many applications to physics. If $W(t)=t$ for all $t\in[0,1]$ and $a(\xi)=|\xi|^p$ for all $\xi\in\mathbb{R}$ with $p>0$, then (2.2) is a deterministic non-linear Schrödinger-type equation such as a fractional Schrödinger equation (see for instance [13, 14]) or a high-order Schrödinger equation (see for instance [11, 12]). If W is a Brownian motion and $a(\xi)=\xi^2$ for all $\xi\in\mathbb{R}$, then (2.2) is a nonlinear Schrödinger equation with white noise dispersion.

Throughout the paper, when $g:(\Re z,\Im z)\mapsto g(z)$ is considered as a function of two real variables, we assume that for all $k\in\mathbb{N}^*$ its partial derivatives of order k exist and are bounded. This implies that g and all its derivatives are Lipschitz functions. Therefore, for every $k\in\mathbb{N}^*$ its differential of order k denoted by $\nabla^k g$ is bounded. Moreover, we assume that $g(0)=0$ and $(\nabla g)(0)=(0,0)$.

REMARK 2.2. Let M be a positive constant and $f:\mathbb{R}_+\to\mathbb{R}_+$ be a smooth and increasing function satisfying $f(x)=x$ if $x\leq 2M$ and $f(x)=3M$ if $x\geq 4M$. If we define g as $g(z)=izf(|z|^2)$, then g satisfies the assumptions above. With such a function g, if M is large enough then Equation (2.2) has locally the same solution as in the case of a cubic nonlinearity, which is more usual in applications to physics.

Under these assumptions, we can prove (as in [15] for instance) that there exists a unique solution to (2.5) denoted by u and almost surely in $\mathcal{C}([0,1],L^2)$. We denote by $S=\{S(t_0,t)\}_{(t_0,t)\in\Delta}$ the family of operators on L^2 satisfying $S(t_0,t_2)=S(t_1,t_2)S(t_0,t_1)$ if $t_0\leq t_1\leq t_2$ and such that the solution u is given by $u(t,x)=S(0,t)u_0(x)$. Moreover, we denote by $Y=\{Y(t)\}_{t\in[0,1]}$ the family of operators such that for every u_0 the function $w:(t,x)\mapsto w(t,x)=Y(t)u_0$ is solution of

$$w(t,x)=u_0(x)+\int_0^t g(w(\theta,x))\,d\theta,\ (t,x)\in[0,1]\times\mathbb{R}. \tag{2.7}$$

2.2. Lie splitting scheme. We define

$$\delta:=\{(n,h)\in\mathbb{N}\times(0,1]\,|\,nh\leq 1\}.$$

For all $t_0\in[0,1]$ we denote by u_{t_0} the (random) function $u(t_0,\cdot):x\mapsto u(t_0,x)$. In order to approximate u_{nh} for all $(n,h)\in\delta$, we define the (Lie) splitting scheme as

$$u_n^h:=Z_n^h\cdots Z_1^h u_0 \tag{2.8}$$

where $Z_k^h:=Z((k-1)h,kh)$ for all $k\in\{1,\cdots,n\}$ and $Z(t_0,t):=Y(t-t_0)X(t_0,t)$ for all $(t_0,t)\in\Delta$. We also define $S_k^h:=S((k-1)h,kh)$ for all $k\in\{1,\cdots,n\}$ such that

$$u_{nh}:=S_n^h\cdots S_1^h u_0.$$

We fix two real numbers $\beta\geq 1$ and $\alpha>0$. We assume that W is a stochastic process with continuous sample paths and finite moments of order β, and such that there exists $C>0$ such that for all (s,t),

$$\mathbb{E}[|W(t)-W(s)|^\beta]\leq C|t-s|^{\beta\alpha}. \tag{2.9}$$

REMARK 2.3. For instance, a fractional Brownian motion (see [16]) with Hurst index $\alpha\in(0,1)$ satisfies (2.9) with $\beta=2$.

The following theorem generalizes error estimates proven in [15].

THEOREM 2.1. Let $m\in\mathbb{N}$ and $u_0\in H^{m+\sigma}$. If β, α and W satisfy (2.9) then there exists a constant $C>0$ such that for all $(n,h)\in\delta$,

$$\|u_{nh}-u_n^h\|_{L_\Omega^\beta(H^m)}\leq Ch^\alpha. \tag{2.10}$$

Proof. The proof is a consequence of Lemmas 2.1 and 2.2, and similar to the proof of Theorem 4.1 in [15]. □

The following lemma gives the uniform boundedness of the Lie splitting scheme defined by (2.8).

LEMMA 2.1.   *Let $k \in \mathbb{N}$ and $u_0 \in H^k$. There exists a (deterministic) positive constant C_k, which depends only on g, k and $\|u_0\|_{H^k}$, and such that almost surely and for all $(n, h) \in \delta$,*

$$\|Z_n^h Z_{n-1}^h \cdots Z_1^h u_0\|_{H^k} = \|u_n^h\|_{H^k} \leq C_k.$$

Proof.   The proof is similar to the proof of Lemma 4.4 in [15] and uses (4.13).   □

The following lemma establishes an upper bound for the local error of the scheme.

LEMMA 2.2.   *Let $m \in \mathbb{N}$ and $u_0 \in H^{m+\sigma}$. If β, α and W satisfy (2.9) then there exists a constant C such that for every $(t_0, t) \in \Delta$,*

$$\|S(t_0, t)u_{t_0} - Z(t_0, t)u_{t_0}\|_{L_\Omega^\beta(H^m)} \leq C(t - t_0)^{1+\alpha}.$$

Proof.   We have

$$\begin{aligned} S(t_0, t)u_{t_0} - Z(t_0, t)u_{t_0} &= \int_{t_0}^t X(\theta, t)\{g(S(t_0, \theta)u_{t_0}) - g(Z(t_0, \theta)u_{t_0})\}d\theta \\ &+ \int_{t_0}^t X(\theta, t)g(Z(t_0, \theta)u_{t_0}) - g(Z(t_0, \theta)u_{t_0})d\theta \\ &+ \int_{t_0}^t \left(g(Z(t_0, \theta)u_{t_0}) - g(Y(\theta - t_0)X(t_0, t)u_{t_0})\right)d\theta. \end{aligned}$$

By the Cauchy-Schwarz inequality, (2.9), Lemmas 4.9, 4.6 and 4.10, we get

$$\begin{aligned} \|S(t_0, t)u_{t_0} - Z(t_0, t)u_{t_0}\|_{L_\Omega^\beta(H^m)}^\beta &\leq C(t - t_0)^{\beta-1} \int_{t_0}^t \|S(t_0, \theta)u_{t_0} - Z(t_0, \theta)u_{t_0}\|_{L_\Omega^\beta(H^m)}^\beta d\theta \\ &+ C(t - t_0)^{\beta(1+\alpha)}. \end{aligned}$$

The proof is completed with the Gronwall lemma.   □

3. Local error

The local error estimate given in Lemma 2.2 is a crucial step of the proof of Theorem 2.1. In this section we establish an expansion of the local error. As a consequence, in Section 5 we improve the error estimate of Theorem 2.1 if W has independent increments and mean zero.

Throughout the paper we use the notation

$$\langle (\nabla g) \circ \phi_0 \,|\, \phi_1 \rangle = \left(\frac{\partial g}{\partial \Re z} \circ \phi_0\right)\Re\phi_1 + \left(\frac{\partial g}{\partial \Im z} \circ \phi_0\right)\Im\phi_1$$

for all ϕ_0 and $\phi_1 \in L^2$, where $\dfrac{\partial g}{\partial \Re z}$ and $\dfrac{\partial g}{\partial \Im z}$ are the first partial derivatives of g. Notice that $\langle (\nabla g) \circ \phi_0 \,|\, \phi_1 \rangle$ is then in L^2.

For every $v \in H^\sigma$ we define

$$\mathcal{G}v = A(g \circ v) - \langle (\nabla g) \circ v \,|\, Av \rangle. \tag{3.1}$$

We fix two real numbers $\beta \geq 1$ and $\alpha \in (0,1]$. In this section we assume that W is a stochastic process with continuous sample paths and finite moments of order 2β, and such that there exists $C > 0$ such that for all (s,t),

$$\mathbb{E}[|W(t) - W(s)|^{2\beta}] \leq C|t-s|^{2\beta\alpha}. \tag{3.2}$$

As a consequence, by the Cauchy-Schwarz inequality we also have

$$\mathbb{E}[|W(t) - W(s)|^{\beta}] \leq \sqrt{C}|t-s|^{\beta\alpha} \text{ and } \mathbb{E}[(W(t) - W(s))^2] \leq \sqrt[\beta]{C}|t-s|^{2\alpha}. \tag{3.3}$$

For all $(t_0, t) \in \Delta$ we define

$$I(t_0, t) = \int_{t_0}^{t} (W(t) - W(\theta)) d\theta. \tag{3.4}$$

The following theorem establishes an expansion of the local error.

THEOREM 3.1.   *Let $m \in \mathbb{N}$ and $u_0 \in H^{m+2\sigma}$. If β, α and W satisfy (3.2) then there exists a constant $C > 0$ such that for every $(t_0, t) \in \Delta$,*

$$\|S(t_0,t)u_{t_0} - Z(t_0,t)u_{t_0} - I(t_0,t)\mathcal{G}u_{t_0}\|_{L_{\Omega}^{\beta}(H^m)} \leq C(t-t_0)^{2\alpha+1}. \tag{3.5}$$

Hence, the local error $S_n^h u_{(n-1)h} - Z_n^h u_{(n-1)h}$ can be approximated by $I_n^h \mathcal{G} u_{(n-1)h}$ where $I_n^h = I((n-1)h, nh)$. Notice that in the case of a white noise dispersion (if W is a Brownian motion), we have

$$\mathbb{E}[I_n^h \mathcal{G} u_{(n-1)h}] = 0 \tag{3.6}$$

because the Brownian motion has independent increments with mean zero. This is important in Section 5 in order to improve the order estimate of the scheme.

4. Proof of Theorem 3.1

In Subsection 4.1 we present the main steps of the proof of Theorem 3.1. Technical Lemmas are postponed to Subsection 4.2.

4.1. Main steps of the proof of Theorem 3.1.   For all ϕ_1 and ϕ_2 in L^2, we define

$$R(\phi_1, \phi_2) = g \circ \phi_2 - g \circ \phi_1 - \langle (\nabla g) \circ \phi_1 | \phi_2 - \phi_1 \rangle. \tag{4.1}$$

Hence, for every $v \in L^2$ and every $(t_0, t) \in \Delta$,

$$\begin{aligned}
S(t_0,t)v - Z(t_0,t)v = &\int_{t_0}^{t} (X(\theta,t) - \text{Id})(g \circ v) d\theta \\
&+ \int_{t_0}^{t} \langle (\nabla g) \circ v | S(t_0,\theta)v - Y(\theta - t_0)X(t_0,t)v \rangle d\theta \\
&+ \int_{t_0}^{t} (X(\theta,t) - \text{Id}) \langle (\nabla g) \circ v | S(t_0,\theta)v - v \rangle d\theta \\
&+ \int_{t_0}^{t} (X(\theta,t)R(v, S(t_0,\theta)v) - R(v, Y(\theta - t_0)X(t_0,t)v)) d\theta.
\end{aligned} \tag{4.2}$$

The proof of Theorem 3.1 is based on lemmas dealing with the terms of (4.2).

We fix $m \in \mathbb{N}$ and $u_0 \in H^{m+2\sigma}$. For simplicity, in this subsection the function u_{t_0} is denoted by v, and the letter C stands for a (deterministic) positive constant which is independent of (t_0, t) and may change from line to line. We recall that we assume that β, α and W satisfy (3.2).

LEMMA 4.1.   *There exists a constant C such that for every $(t_0, t) \in \Delta$,*

$$\left\| \int_{t_0}^t (X(\theta, t) - \mathrm{Id})(g \circ v) d\theta - I(t_0, t) A(g \circ v) \right\|_{L_\Omega^\beta(H^m)} \leq C(t - t_0)^{1+2\alpha}.$$

Proof.   Using the Cauchy-Schwarz inequality and Lemma 4.6, we get

$$\left\| \int_{t_0}^t (X(\theta, t) - \mathrm{Id})(g \circ v) d\theta - I(t_0, t) A(g \circ v) \right\|_{H^m}$$

$$\leq \int_{t_0}^t \left\| (X(\theta, t) - \mathrm{Id})(g \circ v) - (W(t) - W(\theta)) A(g \circ v) \right\|_{H^m} d\theta$$

$$\leq \left\| A^2(g \circ v) \right\|_{H^m} \int_{t_0}^t |W(t) - W(\theta)|^2 d\theta \leq C \int_{t_0}^t |W(t) - W(\theta)|^2 d\theta.$$

Then Lemma 4.10 and (3.3) complete the proof.   □

LEMMA 4.2.   *There exists a constant C such that for every $(t_0, t) \in \Delta$,*

$$\left\| \int_{t_0}^t \langle (\nabla g) \circ v \,|\, S(t_0, \theta) v - Y(\theta - t_0) X(t_0, t) v \rangle d\theta + I(t_0, t) \langle (\nabla g) \circ v \,|\, Av \rangle \right\|_{L_\Omega^\beta(H^m)}^\beta$$

$$\leq C \left((t - t_0)^{\beta(1+2\alpha)} + (t - t_0)^{\beta - 1} \int_{t_0}^t \| S(t_0, \theta) v - Z(t_0, \theta) v \|_{L_\Omega^\beta(H^m)}^\beta d\theta \right).$$

Proof.   We have

$$\int_{t_0}^t \langle (\nabla g) \circ v \,|\, S(t_0, \theta) v - Y(\theta - t_0) X(t_0, t) v \rangle d\theta + I(t_0, t) \langle (\nabla g) \circ v \,|\, Av \rangle$$

$$= \int_{t_0}^t \langle (\nabla g) \circ v \,|\, X(t_0, \theta) v - X(t_0, t) v \rangle d\theta + I(t_0, t) \langle (\nabla g) \circ v \,|\, Av \rangle$$

$$\quad + \int_{t_0}^t \langle (\nabla g) \circ v \,|\, (Y(\theta - t_0) - \mathrm{Id}) X(t_0, \theta) v - (Y(\theta - t_0) - \mathrm{Id}) X(t_0, t) v \rangle d\theta$$

$$\quad + \int_{t_0}^t \langle (\nabla g) \circ v \,|\, S(t_0, \theta) v - Z(t_0, \theta) v \rangle d\theta. \tag{4.3}$$

We then study the terms of the right-hand side of (4.3). By (4.12) and Lemma 4.6, we have

$$\left\| \int_{t_0}^t \langle (\nabla g) \circ v \,|\, X(t_0, \theta) v - X(t_0, t) v \rangle d\theta + \langle (\nabla g) \circ v \,|\, Av \rangle I(t_0, t) \right\|_{H^m}$$

$$\leq \int_{t_0}^t \left\| \langle (\nabla g) \circ v \,|\, X(t_0, \theta) v - X(t_0, t) v + (W(t) - W(\theta)) Av \rangle \right\|_{H^m} d\theta$$

$$\leq C \| (\nabla g) \circ v \|_{H^{m+1}} \int_{t_0}^t \| X(t_0, \theta) v - X(t_0, t) v + (W(t) - W(\theta)) Av \|_{H^m} d\theta$$

$$\leq C\|A^2 v\|_{H^m} \int_{t_0}^t |W(t)-W(\theta)|\sqrt{|W(t)-W(\theta)|^2+|W(\theta)-W(t_0)|^2}d\theta.$$

Then by Lemma 4.10 and (3.2) we get

$$\left\|\int_{t_0}^t \langle(\nabla g)\circ v\,|\,X(t_0,\theta)v-X(t_0,t)v\rangle d\theta + \langle(\nabla g)\circ v\,|\,Av\rangle I(t_0,t)\right\|_{L^\beta_\Omega(H^m)} \leq C(t-t_0)^{1+2\alpha}.$$

$$(4.4)$$

By (4.12) and Lemma 4.10, we also have

$$\left\|\int_{t_0}^t \langle(\nabla g)\circ v\,|\,(Y(\theta-t_0)-\mathrm{Id})X(t_0,\theta)v-(Y(\theta-t_0)-\mathrm{Id})X(t_0,t)v\rangle d\theta\right\|_{L^\beta_\Omega(H^m)}$$

$$\leq C\int_{t_0}^t \|(Y(\theta-t_0)-\mathrm{Id})X(t_0,\theta)v-(Y(\theta-t_0)-\mathrm{Id})X(t_0,t)v\|_{L^\beta_\Omega(H^m)}d\theta$$

$$\leq C\int_{t_0}^t \|\int_{t_0}^\theta (g(Y(\sigma-t_0)X(t_0,\theta)v)-g(Y(\sigma-t_0)X(t_0,t)v))d\sigma\|_{L^\beta_\Omega(H^m)}d\theta$$

$$\leq C(t-t_0)\int_{t_0}^t \|X(t_0,\theta)v-X(t_0,t)v\|_{L^\beta_\Omega(H^m)}d\theta$$

$$\leq C(t-t_0)^{(2+\alpha)} \leq C(t-t_0)^{(1+2\alpha)},$$

$$(4.5)$$

and

$$\left\|\int_{t_0}^t \langle(\nabla g)\circ v\,|\,S(t_0,\theta)v-Z(t_0,\theta)v\rangle d\theta\right\|^\beta_{L^\beta_\Omega(H^m)}$$

$$\leq C(t-t_0)^{\beta-1}\int_{t_0}^t \|S(t_0,\theta)v-Z(t_0,\theta)v\|^\beta_{L^\beta_\Omega(H^m)}d\theta.$$

$$(4.6)$$

By (4.3), (4.4), (4.5) and (4.6), we prove the lemma.   □

LEMMA 4.3.   *There exists a constant C such that for every $(t_0,t)\in\Delta$,*

$$\left\|\int_{t_0}^t (X(\theta,t)-\mathrm{Id})\langle(\nabla g)\circ v\,|\,S(t_0,\theta)v-v\rangle d\theta\right\|_{L^\beta_\Omega(H^m)} \leq C(t-t_0)^{1+2\alpha}.$$

Proof.   By Lemma 4.6, (4.12) and Lemma 4.10, we have

$$\left\|\int_{t_0}^t (X(\theta,t)-\mathrm{Id})\langle(\nabla g)\circ v\,|\,S(t_0,\theta)v-v\rangle d\theta\right\|_{H^m}$$

$$\leq \int_{t_0}^t |W(t)-W(\theta)|\|\langle(\nabla g)\circ v\,|\,S(t_0,\theta)v-v\rangle\|_{H^{m+\sigma}}d\theta$$

$$\leq C\|(\nabla g)\circ v\|_{H^{m+\sigma+1}}\int_{t_0}^t |W(t)-W(\theta)|\|S(t_0,\theta)v-v\|_{H^{m+\sigma}}d\theta$$

$$\leq C(t-t_0)^{\beta-1}\int_{t_0}^t |W(t)-W(\theta)|^\beta\|S(t_0,\theta)v-v\|^\beta_{H^{m+\sigma}}d\theta.$$

$$(4.7)$$

From Lemmas 4.11 and 4.10 and (3.2), we deduce

$$\left\|\int_{t_0}^t (X(\theta,t)-\mathrm{Id})\langle(\nabla g)\circ v\,|\,S(t_0,\theta)v-v\rangle d\theta\right\|^\beta_{L^\beta_\Omega(H^m)}$$

$$\leq C(t-t_0)^{\beta-1}\int_{t_0}^{t}\mathbb{E}\bigg[(W(t)-W(\theta))^{\beta}\Big((W(\theta)-W(t_0))^2+(\theta-t_0)^2\Big)^{\beta/2}\bigg]d\theta$$
$$\leq C(t-t_0)^{\beta\min\{1+2\alpha;2+\alpha\}}\leq C(t-t_0)^{\beta(1+2\alpha)},$$

which completes the proof. $\qquad\square$

LEMMA 4.4. *There exists a constant C such that for every $(t_0,t)\in\Delta$,*

$$\left\|\int_{t_0}^{t}X(\theta,t)R(v,S(t_0,\theta)v)d\theta\right\|_{L_{\Omega}^{\beta}(H^m)}\leq C(t-t_0)^{1+2\alpha}$$

where R is defined by (4.1).

   Proof. We have

$$\left\|\int_{t_0}^{t}X(\theta,t)R(v,S(t_0,\theta)v)d\theta\right\|_{H^m}\leq C\int_{t_0}^{t}\left\||S(t_0,\theta)v-v|^2\right\|_{H^m}d\theta$$
$$\leq C\int_{t_0}^{t}\|S(t_0,\theta)v-v\|_{H^{m+1}}\|S(t_0,\theta)v-v\|_{H^m}d\theta.$$

By Lemma 4.11, we have

$$\|S(t_0,\theta)v-v\|_{H^{m+1}}\|S(t_0,\theta)v-v\|_{H^m}\leq C\big(|W(\theta)-W(t_0)|^2+|\theta-t_0|^2\big)$$

and by (3.2) we prove the lemma. $\qquad\square$

LEMMA 4.5. *There exists a constant C such that for every $(t_0,t)\in\Delta$,*

$$\left\|\int_{t_0}^{t}R(v,Y(\theta-t_0)X(t_0,t)v)d\theta\right\|_{L_{\Omega}^{\beta}(H^m)}\leq C(t-t_0)^{1+2\alpha}$$

where R is defined by (4.1).

   Proof. We have

$$\left\|\int_{t_0}^{t}R(v,Y(\theta-t_0)X(t_0,t)v)d\theta\right\|_{H^m}\leq C\int_{t_0}^{t}\left\|(Y(\theta-t_0)X(t_0,t)v-v)^2\right\|_{H^m}d\theta.$$

Then the proof is similar to the proof of Lemma 4.4. $\qquad\square$

   Finally, we give the proof of Theorem 3.1.

   Proof. **(Proof of Theorem 3.1.)** By (4.2) and Lemmas 4.1, 4.2, 4.3, 4.4 and 4.5, there exists a constant C such that for every $(t_0,t)\in\Delta$,

$$\|S(t_0,t)v-Z(t_0,t)v-I(t_0,t)\mathcal{G}v\|_{L_{\Omega}^{\beta}(H^m)}^{\beta}$$
$$\leq C\bigg((t-t_0)^{\beta(1+2\alpha)}+(t-t_0)^{\beta-1}\int_{t_0}^{t}\|S(t_0,\theta)v-Z(t_0,\theta)v\|_{L_{\Omega}^{\beta}(H^m)}^{\beta}d\theta\bigg). \qquad(4.8)$$

Moreover, because of Lemma 2.2, we have

$$\|S(t_0,t)v-Z(t_0,t)v\|_{L_{\Omega}^{\beta}(H^m)}^{\beta}\leq C(t-t_0)^{\beta(1+\alpha)}$$

and then, with (4.8),

$$\mathbb{E}[\|S(t_0,t)v-Z(t_0,t)v-I(t_0,t)\mathcal{G}v\|_{H^m}^{\beta}]^{1/\beta}\leq C(t-t_0)^{1+2\alpha},$$

which completes the proof. $\qquad\square$

4.2. Technical lemmas. Throughout this subsection, m is a positive integer and, unless otherwise mentioned, W is a general real continuous function.

In the following lemma we establish properties of X.

LEMMA 4.6. *If $v \in H^{m+\sigma}$ then for every $(t_1, t_2) \in \Delta$,*

$$\|(X(t_1, t_2) - \mathrm{Id})v\|_{H^m} \le |W(t_2) - W(t_1)| \|v\|_{H^{m+\sigma}}. \qquad (4.9)$$

If $v \in H^{m+2\sigma}$ then for all t_0, t_1 and t_2 such that $t_0 \le t_1 \le t_2$, we have

$$\|(X(t_0, t_2) - X(t_0, t_1))v - (W(t_2) - W(t_1))Av\|_{H^m}^2$$
$$\le |W(t_2) - W(t_1)|^2 \big(|W(t_2) - W(t_1)|^2 + |W(t_1) - W(t_0)|^2 \big) \|v\|_{H^{m+2\sigma}}^2. \qquad (4.10)$$

In particular, if $t_0 = t_1$ then

$$\|(X(t_1, t_2) - \mathrm{Id})v - (W(t_2) - W(t_1))Av\|_{H^m} \le |W(t_2) - W(t_1)|^2 \|v\|_{H^{m+2\sigma}}. \qquad (4.11)$$

Proof. We assume that $v \in H^{m+2\sigma}$. If we define $r : z \mapsto e^{iz} - 1 - iz$ then we can write

$$(X(t_1, t_2) - \mathrm{Id})v - (W(t_2) - W(t_1))Av = \mathcal{F}^{-1}(\xi \mapsto r(a(\xi)(W(t_2) - W(t_1)))\mathcal{F}(v)(\xi)).$$

Because of (2.1), we get

$$\|(X(t_1, t_2) - \mathrm{Id})v - (W(t_2) - W(t_1))Av\|_{H^m}^2 \le |W(t_2) - W(t_1)|^4 \|v\|_{H^{m+2\sigma}}^2,$$

which gives (4.11). The proof of (4.9) is similar to the proof of (4.11). We have

$$\|(X(t_0, t_2) - X(t_0, t_1))v - (W(t_2) - W(t_1))Av\|_{H^m}^2$$
$$\le C|W(t_2) - W(t_1))|^2 \|(X(t_0, t_1) - \mathrm{Id})Av\|_{H^m}^2$$
$$+ C\|(X(t_0, t_2) - X(t_0, t_1))v - (W(t_2) - W(t_1))AX(t_0, t_1)v\|_{H^m}^2.$$

By (4.9) and (4.11) we get (4.10). $\qquad \square$

The Sobolev inequality $\|\phi_1\|_{L^\infty} \le c\|\phi\|_{H^1}$ (for all $\phi \in H^1$) implies the following lemma.

LEMMA 4.7. *For every $m \in \mathbb{N}$, there exists c_m such that for all $\phi_1 \in H^{m+1}$ and $\phi_2 \in H^m$,*

$$\|\phi_1 \phi_2\|_{H^m} \le c_m \|\phi_1\|_{H^{m+1}} \|\phi_2\|_{H^m}. \qquad (4.12)$$

The following lemma deals with Sobolev norms of a composition of functions.

LEMMA 4.8. *Let $p \in \mathbb{N}^*$, $v \in H^p$, and $f : \mathbb{R}^2 \to \mathbb{R}$ be a p times differentiable function such that $f(0) = 0$ and $\nabla^k f$ is bounded for all $k \in \{1, \cdots, p\}$. Then there exists a constant $C_{p-1} > 0$, which depends only on f, p and $\|v\|_{H^{p-1}}$, and such that*

$$\|f \circ v\|_{H^p} \le C_{p-1} \|v\|_{H^p}. \qquad (4.13)$$

Proof. Since $f(0) = 0$, we have $\|f \circ v\|_{L^2} \le \|\nabla f\|_\infty \|v\|_{L^2}$. Let $p \ge 1$. By differentiating p times, we get

$$\|\partial_x^p(f \circ v)\|_{L^2} \le C\|\nabla f\|_\infty \|\partial_x^p v\|_{L^2} + C\sum_{k=2}^p \|\nabla^k f\|_\infty \sum_{(l_1, \cdots, l_k) \in \pi(k,p)} \left\| \prod_{r=1}^k \partial_x^{l_r} v \right\|_{L^2}$$

where

$$\pi(k,p)=\{(l_1,\cdots,l_k)|1\le l_1\le\cdots\le l_k\le p-1,l_1+\cdots+l_k=p\}$$

and C is a constant which is independent of f and v, and may change from line to line. By (4.12), we get

$$\|\partial_x^p(f\circ v)\|_{L^2}\le C\|\nabla f\|_\infty\|\partial_x^p v\|_{L^2}+C\sum_{k=2}^p\|\nabla^k f\|_\infty\sum_{(l_1,\cdots,l_k)\in\pi(k,p)}\|v\|_{H^{l_1}}\prod_{r=2}^k\|v\|_{H^{l_r+1}}$$

$$\le C\left(\|\nabla f\|_\infty+\sum_{k=2}^p\|\nabla^k f\|_\infty\sum_{(l_1,\cdots,l_k)\in\pi(k,p)}\|v\|_{H^{l_1}}\prod_{r=2}^{k-1}\|v\|_{H^{l_r+1}}\right)\|v\|_{H^p}$$

$$\le C\left(\|\nabla f\|_\infty+\sum_{k=2}^p\|\nabla^k f\|_\infty\|v\|_{H^{p-1}}^{k-1}\right)\|v\|_{H^p}$$

where $\prod_{r=2}^1\cdots=1$. This completes the proof.   □

The following lemma deals with Lipschitz continuity with Sobolev norms.

LEMMA 4.9.   *Let $p\in\mathbb{N}^*$, $v_1,v_2\in H^p$, and $f:\mathbb{R}^2\to\mathbb{R}$ be a p times differentiable function such that $f(0)=0$ and $\nabla^k f$ is bounded for all $k\in\{1,\cdots,p+1\}$. Then there exists a constant $C_p>0$, which depends only on f, p, $\|v_1\|_{H^p}$ and $\|v_2\|_{H^p}$, and such that*

$$\|f\circ v_1-f\circ v_2\|_{H^p}\le C_p\|v_1-v_2\|_{H^p}. \tag{4.14}$$

Proof.   We use the same notation as in the proof of Lemma 4.8. Moreover, we denote the vector $(\partial_x^{l_1}v,\cdots,\partial_x^{l_k}v)$ by $(\partial_x^l v)_k$ for $v=v_1$ or $v=v_2$. Differentiating p times, we get

$$\|\partial_x^p(f\circ v_1-f\circ v_2)\|_{L^2}\le\|(\nabla f)(v_1)(\partial_x^p v_1)-(\nabla f)(v_2)(\partial_x^p v_2)\|_{L^2}$$

$$+\sum_{k=2}^p\sum_{(l_1,\cdots,l_k)\in\pi(k,p)}\left\|(\nabla^k f)(v_1)(\partial_x^l v_1)_k-(\nabla^k f)(v_2)(\partial_x^l v_2)_k\right\|_{L^2}.$$

Using (4.12), we get

$$\|(\nabla f)(v_1)(\partial_x^p v_1)-(\nabla f)(v_2)(\partial_x^p v_2)\|_{L^2}$$
$$\le\|(\nabla f)(v_1)(\partial_x^p v_1)-(\nabla f)(v_2)(\partial_x^p v_1)\|_{L^2}+\|(\nabla f)(v_2)(\partial_x^p v_1)-(\nabla f)(v_2)(\partial_x^p v_2)\|_{L^2}$$
$$\le\|\nabla^2 f\|_\infty\|v_1-v_2\|_{H^1}\|v_1\|_{H^p}$$
$$+\|\nabla f\|_\infty\|v_1-v_2\|_{H^p}$$
$$\le(\|\nabla^2 f\|_\infty\|v_1\|_{H^p}+\|\nabla f\|_\infty)\|v_1-v_2\|_{H^p}.$$

For all $k\ge2$,

$$\|(\nabla^k f)(v_1)(\partial_x^l v_1)_k-(\nabla^k f)(v_2)(\partial_x^l v_2)_k\|_{L^2}$$
$$\le\|(\nabla^k f)(v_1)(\partial_x^l v_1)_k-(\nabla^k f)(v_2)(\partial_x^l v_1)_k\|_{L^2}$$
$$+\|(\nabla^k f)(v_2)(\partial_x^l v_1)_k-(\nabla^k f)(v_2)(\partial_x^l v_2)_k\|_{L^2}.$$

By (4.12), we have

$$\|(\nabla^k f)(v_1)(\partial_x^{l.} v_1)_k - (\nabla^k f)(v_2)(\partial_x^{l.} v_1)_k\|_{L^2}$$

$$\leq \|\nabla^{k+1} f\|_\infty \|v_1 - v_2\|_{H^1} \prod_{r=1}^k \|v_1\|_{H^{l_r+1}} \leq \|\nabla^{k+1} f\|_\infty \|v_1 - v_2\|_{H^p} \|v_1\|_{H^p}^k.$$

Moreover,

$$\|(\nabla^k f)(v_2)(\partial_x^{l.} v_1)_k - (\nabla^k f)(v_2)(\partial_x^{l.} v_2)_k\|_{L^2}$$

$$\leq \|\nabla^k f\|_\infty \sum_{j=1}^k \|\partial_x^{l_j}(v_1 - v_2)\|_{L^2} \prod_{r=1}^{j-1} \|\partial_x^{l_r} v_1\|_\infty \prod_{r=j+1}^k \|\partial_x^{l_r} v_2\|_\infty$$

$$\leq \|\nabla^k f\|_\infty \|v_1 - v_2\|_{H^p} \sum_{j=1}^k \|v_1\|_{H^p}^{j-1} \|v_2\|_{H^p}^{k-j}.$$

This completes the proof. □

The next lemma gives an estimate for the solution u of Equation (2.5).

LEMMA 4.10. *Let $m \in \mathbb{N}$ and $u_0 \in H^m$. There exists a positive constant C, which does not depend on W, and such that the solution u of Equation (2.5) satisfies for all $t \in [0,1]$,*

$$\|u_t\|_{H^m} + \|g(u_t)\|_{H^m} + \|(\nabla g)(u_t)\|_{H^m} \leq C.$$

Proof. In this proof, C is a constant which does not depend on W and t, and may change from line to line. We define the sequence $\{v_k\}_{k \in \mathbb{N}}$ such that $v_0 = u_0$ and for all $k \in \mathbb{N}$,

$$v_{k+1}(t,x) = X(0,t)u_0(x) + \int_0^t X(\theta,t)g(v_k(\theta,x)) d\theta, \qquad (t,x) \in [0,1] \times \mathbb{R}. \qquad (4.15)$$

We recall that $v_k \to u$ in $\mathcal{C}([0,1],L^2)$ as $k \to \infty$ (see [15]). Similarly to the proof of Lemma 3.3 of [15] and by using Lemma 4.8, we prove that there exists a constant C such that for all k and t, $\|v_k(t,\cdot)\|_{H^m} \leq C$. As in the proof of Lemma 3.6 of [15], we deduce that for all t, $\|u(t,\cdot)\|_{H^m} \leq C$. We then prove that for all t, $\|g(u(t,\cdot))\|_{H^m} \leq C$ and $\|(\nabla g)(u(t,\cdot))\|_{H^m} \leq C$ by using the assumptions on g and Lemma 4.8. □

The next lemma establishes properties of Y, Z, and S.

LEMMA 4.11. *Let $m \in \mathbb{N}$. If $u_0 \in H^m$, then there exists a constant C, which does not depend on W, and such that for all $(t_1,t_2) \in \Delta$,*

$$\|Y(t_2 - t_1)u_{t_1} - u_{t_1}\|_{H^m} \leq C(t_2 - t_1). \qquad (4.16)$$

If $v \in H^{m+\sigma}$, then there exists a constant C, which does not depend on W, and such that for every $(t_1,t_2) \in \Delta$,

$$\|Z(t_1,t_2)u_{t_1} - u_{t_1}\|_{H^m}^2 \leq C\big(|W(t_2) - W(t_1)|^2 + |t_2 - t_1|^2\big) \qquad (4.17)$$

and

$$\|S(t_1,t_2)u_{t_1} - u_{t_1}\|_{H^m}^2 \leq C\big(|W(t_2) - W(t_1)|^2 + |t_2 - t_1|^2\big). \qquad (4.18)$$

Proof. The proof of (4.16) is a consequence of Lemma 4.8. We get (4.17) and (4.18) by (4.16) and Lemma 4.6. □

5. Order estimate

In this section we assume that W is a random process such that for all $t \geq 0$,

$$W(t) = \int_0^t \phi(\theta) dB_\theta$$

where B is a standard Brownian motion and $\phi : (0, \infty) \to \mathbb{R}$ is a (deterministic) function such that there exist $C_W > 0$ and $b > -1/2$ such that for all $t > 0$,

$$|\phi(t)| \leq C_W t^b.$$

This ensures that $W(t)$ is well defined for all t. We can also deduce that there exists $C > 0$ such that for all $(t, s) \in \mathbb{R}^2$,

$$\mathbb{E}[(W(t) - W(s))^2] \leq C|t - s|^{2\alpha} \tag{5.1}$$

where $\alpha = \frac{1}{2} \min\{2b + 1; 1\}$. Following Theorem 2.1, if $u_0 \in H^{p+\sigma}$ then there exists a constant $C > 0$ such that for all $(n, h) \in \delta$,

$$\|u_{nh} - u_n^h\|_{L^2_\Omega(H^p)} \leq Ch^\alpha. \tag{5.2}$$

Notice that W has independent increments with mean zero. This enables us to improve (5.2) by applying Theorem 3.1. In Theorem 5.1 we establish that the order of the scheme is at least 2α instead of α.

THEOREM 5.1.   *For every $p \in \mathbb{N}$, if $u_0 \in H^{p+2\sigma}$ then there exists a constant $C > 0$ such that for every $(n, h) \in \delta$,*

$$\|u_{nh} - u_n^h\|_{L^2_\Omega(H^p)} \leq Ch^{2\alpha}. \tag{5.3}$$

In this section, the letter C stands for a constant which does not depend on (n, h), unless otherwise mentioned, and may change from line to line. The proof of Theorem 5.1 uses Lemmas 5.1, 5.2 and 5.3 which are established at the end of this section. The proof of Lemma 5.1 uses Theorem 3.1.

Proof.   Let $p \in \mathbb{N}$. For all $(n, h) \in \delta$ we write

$$\|u_{nh} - u_n^h\|_{H^p}^2 = E_1(n, h) + E_2(n, h) + 2\mathcal{R}E_3(n, h)$$

where

$$E_1(n, h) = \|S_n^h u_{(n-1)h} - Z_n^h u_{(n-1)h}\|_{H^p}^2, E_2(n, h) = \|Z_n^h u_{(n-1)h} - Z_n^h u_{n-1}^h\|_{H^p}^2,$$
$$\text{and } E_3(n, h) = \langle S_n^h u_{(n-1)h} - Z_n^h u_{(n-1)h}, Z_n^h u_{(n-1)h} - Z_n^h u_{n-1}^h \rangle_{H^p},$$

and we define

$$\mathcal{E}_n^h := \mathbb{E}[\|u_{nh} - u_n^h\|_{H^p}^2] = \|u_{nh} - u_n^h\|_{L^2_\Omega(H^p)}^2.$$

By Lemma 2.2, there exists C such that for every $(n, h) \in \delta$,

$$\mathbb{E}[E_1(n, h)] \leq Ch^{2+2\alpha}. \tag{5.4}$$

By Lemma 5.2, there exists C such that

$$E_2(n, h) \leq \exp(Ch)\|u_{(n-1)h} - u_{n-1}^h\|_{H^p}^2,$$

and, therefore,

$$\mathbb{E}[E_2(n,h)] \leq \exp(Ch)\mathcal{E}_{n-1}^h. \tag{5.5}$$

From (5.4), (5.5) and Lemma 5.1, we deduce

$$\mathcal{E}_n^h \leq Ch^{2+2\alpha} + \exp(Ch)\mathcal{E}_{n-1}^h + Ch^{1+2\alpha}\sqrt{\mathcal{E}_{n-1}^h}$$

and then, because

$$h^{1+2\alpha}\sqrt{\mathcal{E}_{n-1}^h} \leq Ch^{1+4\alpha} + Ch\mathcal{E}_{n-1}^h,$$

we get

$$\mathcal{E}_n^h \leq Ch^{1+4\alpha} + \exp(Ch)\mathcal{E}_{n-1}^h$$

for all $(n,h) \in \delta$. Then we deduce (5.3). $\qquad\square$

The remaining part of this section is devoted to lemmas we use in the proof of Theorem 5.1.

LEMMA 5.1. *Let $p \in \mathbb{N}$. With the same notation as in the proof of Theorem 5.1, if $u_0 \in H^{p+2\sigma}$ then there exists C such that for all $(n,h) \in \delta$,*

$$|\mathbb{E}[\mathcal{R}E_3(n,h)]| \leq Ch^{1+2\alpha}\sqrt{\mathcal{E}_{n-1}^h}. \tag{5.6}$$

Proof. For all $(n,h) \in \delta$, we define

$$R_1(n,h) = S_n^h u_{(n-1)h} - Z_n^h u_{(n-1)h} - I_n^h \mathcal{G} u_{(n-1)h},$$

and

$$R_2(n,h) = Z_n^h u_{(n-1)h} - Z_n^h u_{n-1}^h - (\mathrm{Id} + W_n^h A)(u_{(n-1)h} - u_{n-1}^h)$$

where $W_n^h = W(nh) - W((n-1)h)$. We write

$$\begin{aligned}
E_3(n,h) = {} & \langle I_n^h \mathcal{G} u_{(n-1)h}, (\mathrm{Id} + W_n^h A)(u_{(n-1)h} - u_{n-1}^h) \rangle_{H^p} \\
& + \langle I_n^h \mathcal{G} u_{(n-1)h}, R_2(n,h) \rangle_{H^p} \\
& + \langle R_1(n,h), Z_n^h u_{(n-1)h} - Z_n^h u_{n-1}^h \rangle_{H^p}.
\end{aligned}$$

From the Cauchy-Schwarz inequality, Theorem 3.1 and Lemma 5.2, there exists C such that

$$|\mathbb{E}[\langle R_1(n,h), Z_n^h u_{(n-1)h} - Z_n^h u_{n-1}^h \rangle_{H^p}]| \leq Ch^{1+2\alpha}\sqrt{\mathcal{E}_{n-1}^h}.$$

By the Cauchy-Schwarz inequality and Lemmas 4.6 and 5.3, there exists C such that

$$|\mathbb{E}[\langle I_n^h \mathcal{G} u_{(n-1)h}, R_2(n,h) \rangle_{H^p}]| \leq Ch^{1+3\alpha}\sqrt{\mathcal{E}_{n-1}^h} \leq Ch^{1+2\alpha}\sqrt{\mathcal{E}_{n-1}^h}.$$

Since Brownian motion has independent increments with mean zero, we obtain

$$|\mathbb{E}[\langle I_n^h \mathcal{G} u_{(n-1)h}, (\mathrm{Id} + W_n^h A)(u_{(n-1)h} - u_{n-1}^h) \rangle_{H^p}]|$$

$$=|\mathbb{E}[I_n^h W_n^h]\mathbb{E}[\langle u_{(n-1)h}, A(u_{(n-1)h} - u_{n-1}^h)\rangle_{H^p}]|$$

$$=|\mathbb{E}[I_n^h W_n^h]\mathbb{E}[\langle -Au_{(n-1)h}, u_{(n-1)h} - u_{n-1}^h\rangle_{H^p}]| \leq Ch^{1+2\alpha}\sqrt{\mathcal{E}_{n-1}^h}.$$

As a consequence, we get (5.6). □

LEMMA 5.2.   *Let $p \in \mathbb{N}$. With the same notation as in the proof of Theorem 5.1, if $u_0 \in H^p$ then there exists C such that almost surely and for all $(n,h) \in \delta$,*

$$\|Z_n^h u_{(n-1)h} - Z_n^h u_{(n-1)}^h\|_{H^p} \leq \exp(Ch)\|u_{(n-1)h} - u_{(n-1)}^h\|_{H^p}.$$

Proof.   It suffices to prove that for all (v_1, v_2) in $H^p \times H^p$ there exists a (deterministic) constant C, which depends only on g, p, $\|v_1\|_{H^p}$ and $\|v_2\|_{H^p}$, and such that almost surely and for every $(t_0, t) \in \Delta$,

$$\|Z(t_0,t)v_1 - Z(t_0,t)v_2\|_{H^p} \leq \exp(C(t-t_0))\|v_1 - v_2\|_{H^p}.$$

We have

$$Z(t_0,t)v_2 - Z(t_0,t)v_1 = X(t_0,t)v_2 - X(t_0,t)v_1$$
$$+ \int_{t_0}^t (g(Y(\theta - t_0)X(t_0,t)v_2) - g(Y(\theta - t_0)X(t_0,t)v_1))d\theta.$$

By Lemma 4.9,

$$\left\|\int_{t_0}^t (g(Y(\theta - t_0)X(t_0,t)v_2) - g(Y(\theta - t_0)X(t_0,t)v_1))d\theta\right\|_{H^p}$$
$$\leq C\int_{t_0}^t \|Y(\theta - t_0)X(t_0,t)v_2 - Y(\theta - t_0)X(t_0,t)v_1\|_{H^p}d\theta$$

and by the Gronwall lemma we get

$$\|Z(t_0,t)v_1 - Z(t_0,t)v_2\|_{H^p} \leq \exp(C(t-t_0))\|X(t_0,t)(v_1 - v_2)\|_{H^p}$$
$$= \exp(C(t-t_0))\|v_1 - v_2\|_{H^p}.$$

This completes the proof. □

LEMMA 5.3.   *Let $p \in \mathbb{N}$. With the same notation as in the proof of Lemma 5.1, if $u_0 \in H^{p+2\sigma}$, then there exists a constant C such that for every $(n,h) \in \delta$,*

$$\|R_2(n,h)\|_{L^2_\Omega(H^p)} \leq Ch^{2\alpha}\|u_{n-1}^h - u_{(n-1)h}\|_{L^2_\Omega(H^p)}.$$

Proof.   We write

$$Z_n^h u_{n-1}^h - Z_n^h u_{(n-1)h}$$
$$= (\mathrm{Id} + W_n^h A)(u_{n-1}^h - u_{(n-1)h}) + (X_n^h - \mathrm{Id} - W_n^h A)(u_{n-1}^h - u_{(n-1)h})$$
$$+ \int_{(n-1)h}^{nh} (g(Y(\theta - (n-1)h)X_n^h u_{n-1}^h) - g(Y(\theta - (n-1)h)X_n^h u_{(n-1)h}))d\theta.$$

The proof is completed by Lemmas 4.6 and 4.9. □

6. Another splitting scheme

6.1. Setting and results. In this section we deal with another splitting scheme for Equation (2.2). Using the same notation as in Section 2.2 we define for all $(n,h) \in \delta$ the (Lie) splitting scheme

$$\overline{u}_n^h := \overline{Z}_n^h \cdots \overline{Z}_1^h u_0$$

where $\overline{Z}_k^h := \overline{Z}((k-1)h, kh)$ for all $k \in \{1, \cdots, n\}$ and $\overline{Z}(t_0, t) := X(t_0, t)Y(t - t_0)$ for all $(t_0, t) \in \Delta$. This is another Lie splitting scheme. Under the same assumptions as in Section 2.2 we establish an order estimate for this scheme. The proof is omitted because it is similar to the proof of Theorem 2.1.

THEOREM 6.1. *Let $m \in \mathbb{N}$ and $u_0 \in H^{m+\sigma}$. If β, α and W satisfy (2.9) then there exists a constant $C > 0$ such that for all $(n,h) \in \delta$,*

$$\|u_{nh} - \overline{u}_n^h\|_{L_\Omega^\beta(H^m)} \leq Ch^\alpha. \tag{6.1}$$

Under the same assumptions as in Section 3 we have the following result that we prove in the next subsection.

THEOREM 6.2. *Let $m \in \mathbb{N}$ and $u_0 \in H^{m+2\sigma}$. If β, α and W satisfy (3.2) then there exists a constant C such that for every $(t_0, t) \in \Delta$,*

$$\|S(t_0,t)u_{t_0} - \overline{Z}(t_0,t)u_{t_0} + J(t_0,t)\mathcal{G}u_{t_0}\|_{L_\Omega^\beta(H^m)} \leq C(t - t_0)^{2\alpha+1}$$

where $J(t_0,t) = \displaystyle\int_{t_0}^t (W(\theta) - W(t_0))d\theta$.

Therefore, the local error $S_n^h u_{(n-1)h} - \overline{Z}_n^h u_{(n-1)h}$ can be approximated by $-J_n^h \mathcal{G} u_{(n-1)h}$ where $J_n^h = J((n-1)h, nh)$.

As a consequence, we have the following result regarding the global error if W is Gaussian and have independent increments and mean zero.

THEOREM 6.3. *Let W be a process as defined in Section 5. For every $p \in \mathbb{N}$, if $u_0 \in H^{p+2\sigma}$ then there exists a constant $C > 0$ such that for every $(n,h) \in \delta$,*

$$\|u_{nh} - \overline{u}_n^h\|_{L_\Omega^2(H^p)} \leq Ch^{2\alpha}. \tag{6.2}$$

We omit the proof of Theorem 6.3 because it is similar to the proof of Theorem 5.1 with $-J_n^h$ instead of I_n^h. Notice also that the results of Lemmas 2.2, 5.1, 5.2 and 5.3 still hold if we replace Z with $\overline{Z}$.

6.2. Proof of Theorem 6.2. We write

$$
\begin{aligned}
S(t_0,t)v - \overline{Z}(t_0,t)v &= \int_{t_0}^t (X(\theta,t) - X(t_0,t))(g \circ v)d\theta \\
&\quad + \int_{t_0}^t X(t_0,t)\langle (\nabla g) \circ v \,|\, S(t_0,\theta)v - Y(\theta - t_0)v \rangle d\theta \\
&\quad + \int_{t_0}^t (X(\theta,t) - X(t_0,t))\langle (\nabla g) \circ v \,|\, S(t_0,\theta)v - v \rangle d\theta \\
&\quad + \int_{t_0}^t (X(\theta,t)R(v, S(t_0,\theta)v) - X(t_0,t)R(v, Y(\theta - t_0)v))\,d\theta \quad (6.3)
\end{aligned}
$$

where $v = u_{t_0}$. By using the same tools as in the proof of Lemma 4.1 we get

$$\left\| \int_{t_0}^t (X(\theta,t) - X(t_0,t))(g \circ v) d\theta + J(t_0,t) A(g \circ v) \right\|_{L_\Omega^\beta(H^m)} \leq C(t-t_0)^{1+2\alpha}.$$

In the same way as for Lemma 4.2 we obtain

$$\left\| \int_{t_0}^t X(t_0,t) \langle (\nabla g) \circ v \,|\, S(t_0,\theta)v - Y(\theta-t_0)v \rangle d\theta - J(t_0,t) \langle (\nabla g) \circ v \,|\, Av \rangle \right\|_{L_\Omega^\beta(H^m)}^\beta$$
$$\leq C \left((t-t_0)^{\beta(1+2\alpha)} + (t-t_0)^{\beta-1} \int_{t_0}^t \| S(t_0,\theta)v - \overline{Z}(t_0,\theta)v \|_{L_\Omega^\beta(H^m)}^\beta d\theta \right).$$

Similarly to Lemma 4.3 we can prove

$$\left\| \int_{t_0}^t (X(\theta,t) - X(t_0,t)) \langle (\nabla g) \circ v \,|\, S(t_0,\theta)v - v \rangle d\theta \right\|_{L_\Omega^\beta(H^m)} \leq C(t-t_0)^{1+2\alpha}.$$

By Lemma 4.4 we have

$$\left\| \int_{t_0}^t X(\theta,t) R(v, S(t_0,\theta)v) d\theta \right\|_{L_\Omega^\beta(H^m)} \leq C(t-t_0)^{1+2\alpha}$$

and as for Lemma 4.5 we get

$$\left\| \int_{t_0}^t X(t_0,t) R(v, Y(\theta-t_0)v) d\theta \right\|_{L_\Omega^\beta(H^m)} \leq C(t-t_0)^{1+2\alpha}.$$

Finally we deduce from above that

$$\left\| S(t_0,t)v - \overline{Z}(t_0,t)v + J(t_0,t)\mathcal{G}v \right\|_{L_\Omega^\beta(H^m)}^\beta$$
$$\leq C \left((t-t_0)^{\beta(1+2\alpha)} + (t-t_0)^{\beta-1} \int_{t_0}^t \| S(t_0,\theta)v - \overline{Z}(t_0,\theta)v \|_{L_\Omega^\beta(H^m)}^\beta d\theta \right)$$

and we complete the proof as for Theorem 3.1 and by using

$$\| S(t_0,t)v - \overline{Z}(t_0,t)v \|_{L_\Omega^\beta(H^m)} \leq C(t-t_0)^{1+\alpha}$$

which is proven as Lemma 2.2.

7. Numerical results

In this section we present numerical simulations. We consider Equation (2.2) with $g(u) = iu|u|^2$. We assume that $a(\xi) = \xi^2$, the initial condition is $u_0(x) = \exp(-x^2/2)$ and W is a fractional Brownian motion with Hurst index $H \in (0,1)$ (see [16]), namely a Gaussian process with mean 0 and such that for all $(s,t) \in [0,1]^2$,

$$\mathbb{E}(W(t)W(s)) = \frac{1}{2}(|t|^{2H} + |s|^{2H} - |t-s|^{2H}). \tag{7.1}$$

For all $t \in [0,1]$ we define $L(t)u_0$ by

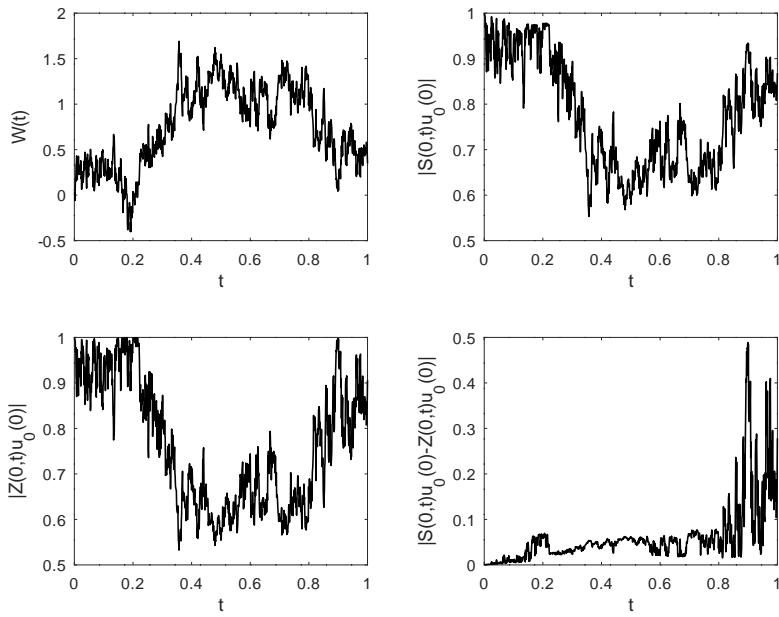$$L(t)u_0 = \| S(0,t)u_0 - Z(0,t)u_0 \|_{L_\Omega^2(L^2)}. \tag{7.2}$$

FIG. 7.1. *Sample paths of* W, $|S(0,\cdot)u_0(0)|$, $|Z(0,\cdot)u_0(0)|$, *and* $|S(0,\cdot)u_0(0) - Z(0,\cdot)u_0(0)|$ *with* $H = 1/3$.
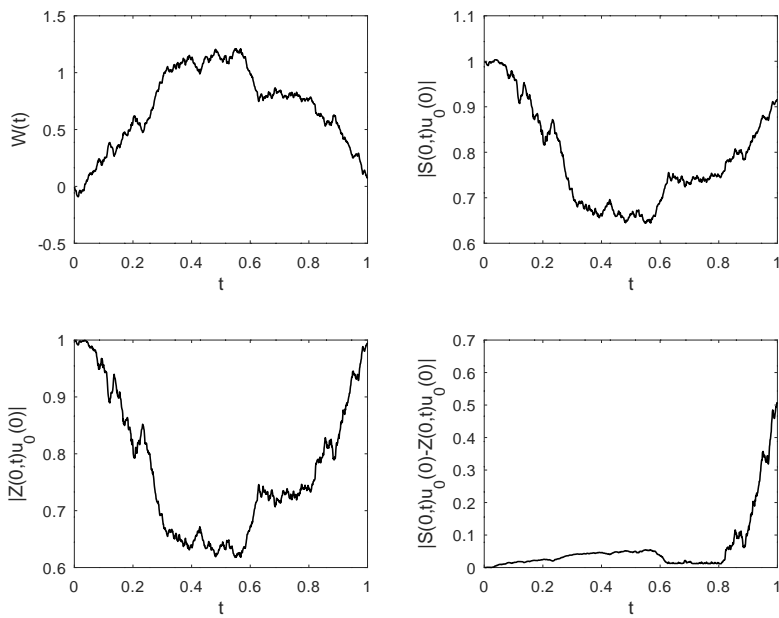

FIG. 7.2. *Sample paths of* W, $|S(0,\cdot)u_0(0)|$, $|Z(0,\cdot)u_0(0)|$, *and* $|S(0,\cdot)u_0(0) - Z(0,\cdot)u_0(0)|$ *with* $H = 2/3$.
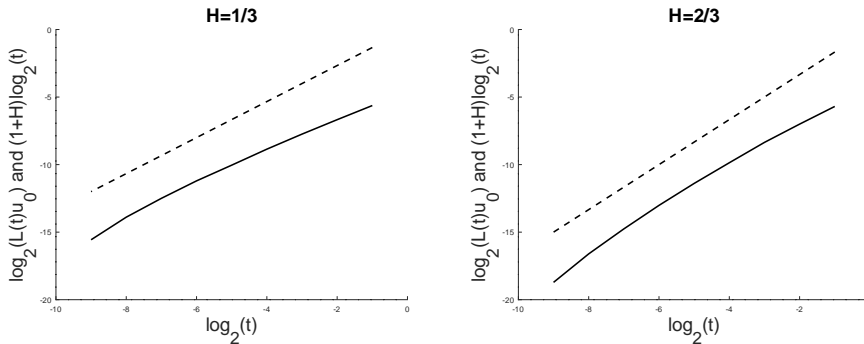
FIG. 7.3. *Log-log plot of* $t \mapsto L(t)u_0$ *with* $H = 1/3$ *and* $H = 2/3$ *(solid line) and line of equation* $y = (1+H)x$ *(dashed line).*

As a consequence of (7.1), for all $(s,t) \in [0,1]^2$,

$$\mathbb{E}((W(t) - W(s))^2) = |t - s|^{2H}, \tag{7.3}$$

which implies that W satisfies (3.2) with $\alpha = H$ and $\beta = 1$. Moreover, by Theorem 3.1 (and Remark 2.2), there exists $C > 0$ such that, as $t \to 0$,

$$L(t)u_0 \sim Ct^{H+1}, \tag{7.4}$$

whereas Lemma 2.2 gives only an upper bound. We illustrate this result with the numerical simulation of $L(t)u_0$. This involves the computations of W, X and Y.

The process W is Gaussian, then its computation is obtained from a square root of its covariance function given by (7.1). The family of operators X is implemented from (2.6) with the fast Fourier transform. The nonlinearity term is $g(u) = iu|u|^2$, then Y is given by $Y(t)v(x) = v(x) \exp(it|v(x)|^2)$ for all $(t,x) \in [0,1] \times \mathbb{R}$ and $v \in L^2$. We use the Lie splitting scheme defined by Equation (2.8) with a very small time step in order to compute the solution $u : (t,x) \mapsto S(0,t)u_0(x)$ of (2.2).

Figures 7.1 and 7.2 show sample paths of W with $H = 1/3$ and $H = 2/3$, and their corresponding $|S(0,\cdot)u_0(0)|$, $|Z(0,\cdot)u_0(0)|$, and $|S(0,\cdot)u_0(0) - Z(0,\cdot)u_0(0)|$. Figure 7.3 shows that $L(t)u_0$ is approximately proportional to t^{H+1} with $H = 1/3$ and $H = 2/3$. This is in good agreement with (7.4). The computational domain for the variable x is $[-2^4\sqrt{2}, 2^4\sqrt{2}]$ with 2^{11} points. The time step is 2^{-10} for the simulation of the solution u. The mathematical expectations are computed with averages over 1000 samples.

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