# Stability of $N$ Solitary Waves for the Generalized BBM Equations 

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#### Abstract

We consider the generalized BBM (Benjamin-Bona-Mahony) equations: $$
\begin{equation*} \left(1-\partial_{x}^{2}\right) u_{t}+\left(u+u^{p}\right)_{x}=0 \tag{0.1} \end{equation*}
$$ for $p \geqslant 2$ integer, and the family of solitary wave solutions $\varphi_{c}\left(x-x_{0}-c t\right)$ of this equation. For any $p$, there exists a necessary and sufficient condition on the speed $c>1$ so that a solitary wave solution is nonlinearly stable ( $[\mathbf{2 1}]$, [20]). Following the approach of [14] for the generalized KdV equations, we prove that the sum of $N$ sufficiently decoupled stable solitary wave solutions is also stable in the energy space. The proof combines arguments of [21] to prove the stability of a single solitary wave, and monotonicity results of [6]. We also obtain asymptotic stability results following [6]. Using the same tools, we then prove the existence and uniqueness of a solution behaving asymptotically in large time as the sum of $N$ given solitary waves, following the method of [11].


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## 1. Introduction

We consider in this paper the generalized BBM equations (gBBM henceforth)

$$
\left\{\begin{array}{l}
\left(1-\partial_{x}^{2}\right) u_{t}+\left(u+u^{p}\right)_{x}=0,(t, x) \in \mathbb{R} \times \mathbb{R}  \tag{1.1}\\
u(0, x)=u_{0}(x), x \in \mathbb{R}
\end{array}\right.
$$

where $p \in \mathbb{N}, p \geqslant 2$, as introduced by Peregrine $[\mathbf{1 9}]$ and Benjamin, Bona and Mahony [2]. The Cauchy problem associated to (1.1) is globally well posed in $H^{1}(\mathbb{R})($ see $[\mathbf{2}])$, and $H^{1}$ solutions are such that

$$
\begin{gather*}
E(u(t))=\frac{1}{2} \int u^{2}(t, x) d x+\frac{1}{p+1} \int u^{p+1}(t, x) d x=E\left(u_{0}\right)  \tag{1.2}\\
m(u(t))=\frac{1}{2} \int\left(u^{2}(t, x)+u_{x}^{2}(t, x)\right) d x=m\left(u_{0}\right) \tag{1.3}
\end{gather*}
$$

The quantity $\int u(t)$ is also formally conserved. However, there is no value of $p$ such that the gBBM equation admits more conserved quantities. In particular, the gBBM equation is not completely integrable, for any value of $p$. As a consequence no inverse-scattering theory can be developed for this equation, see [15] and [18]. This situation is in contrast with the generalized Korteweg-de Vries equations (gKdV equations):

$$
\begin{equation*}
u_{t}+\left(u_{x x}+u^{p}\right)_{x}=0 \tag{1.4}
\end{equation*}
$$

which is completely integrable for both $p=2$ and 3 (but not for other values of $p$ ).
As the $g K d V$, the $g B B M$ equation has a two parameter family of solitary wave solutions: for any $c>1$ and $x_{0} \in \mathbb{R}, u(t, x)=\varphi_{c}\left(x-c t-x_{0}\right)$ is a traveling wave solution of (1.1) if $\varphi_{c}$ is solution of

$$
\begin{equation*}
-c \partial_{x}^{2} \varphi_{c}+(c-1) \varphi_{c}-\varphi_{c}^{p}=0 \tag{1.5}
\end{equation*}
$$

The unique even function going to zero at infinity which is solution of (1.5) is given by

$$
\varphi_{c}(x)=(c-1)^{\frac{1}{p-1}} Q\left(\sqrt{\frac{c-1}{c}} x\right)
$$

where

$$
Q(x)=\left(\frac{p+1}{2 \cosh ^{2}\left(\frac{p-1}{2} x\right)}\right)^{\frac{1}{p-1}} \text { satisfies } \quad Q^{\prime \prime}+Q^{p}=Q
$$

The $H^{1}$ nonlinear stability of a solitary wave solution $\varphi_{c}\left(x-c t-x_{0}\right)$ of (1.1) was studied by Weinstein [21] and Souganidis and Strauss [20]. We say that $\varphi_{c}$ is stable if:

For any $\gamma>0$, there exists $\delta>0$ such that $\left\|u_{0}-\varphi_{c}\right\|_{H^{1}}<\delta$ implies that there exists $r(t)$ such that for all $t \in \mathbb{R},\left\|u(t, .-r(t))-\varphi_{c}\right\|_{H^{1}} \leqslant \gamma$.

From [21] and [20], it turns out that $\varphi_{c}\left(x-c t-x_{0}\right)$ is stable if the following condition is satisfied:

$$
\begin{equation*}
\frac{d}{d c} m\left(\varphi_{c}\right)>0 \tag{1.6}
\end{equation*}
$$

and is unstable if $\frac{d}{d c} m\left(\varphi_{c}\right)<0$. Indeed, condition (1.6) was found to be a natural condition under which stability is true, not only for the Schrödinger, gKdV and
gBBM equation ( $[\mathbf{2 1}]$ ) but also for other nonlinear dispersive equations. In the case of the gBBM equation, we have by straightforward calculations

$$
\begin{equation*}
m\left(\varphi_{c}\right)=\frac{(c-1)^{\frac{5-p}{2(p-1)}}}{\sqrt{c}}\left[c\left(\frac{p+1}{p-1}\right)-\frac{1}{2}\right] \int Q_{x}^{2} \tag{1.7}
\end{equation*}
$$

and thus it is easily checked that if we define, for $p \geqslant 6$,

$$
\begin{equation*}
c^{\star}(p)=\frac{(p-1)(2+\sqrt{2(p+3)})}{4(p+1)} \tag{1.8}
\end{equation*}
$$

and $c^{\star}(p)=1$ for $p=2,3,4$ or 5 , then condition (1.6) is satisfied if and only if $c>c^{\star}(p)$. Therefore:

- If $p=2,3,4,5$ and $c>1$, or $p \geqslant 6$ and $c>c^{\star}(p)$, then $\varphi_{c}\left(x-c t-x_{0}\right)$ is stable, see Weinstein [21].
- If $p \geqslant 6$ and $1<c<c^{\star}(p)$ then $\varphi_{c}\left(x-c t-x_{0}\right)$ is unstable, see Souganidis and Strauss [20].

Numerical studies on the asymptotic behavior of solutions of (1.1) were performed by Bona and al. [4].

In this paper, we consider $N$ solitary waves $\varphi_{c_{j}}\left(x-c_{j}^{0} t-x_{j}^{0}\right)$ of (1.1) which are stable. We prove that their sum is also stable, in an appropriate sense, provided that the solitary waves are sufficiently decoupled. Our main result is the following.

ThEOREM 1.1. Let $p \geqslant 2$ be an integer and let $u_{0} \in H^{1}(\mathbb{R})$. Fix $N$ velocities: $1 \leqslant c^{\star}(p)<c_{1}^{0}<\ldots<c_{N}^{0}$. There exist $\gamma_{0}, A_{0}, L_{0}, \alpha_{0}>0$ such that if for some $L>L_{0}, \alpha<\alpha_{0}$, and $x_{1}^{0}<\ldots<x_{N}^{0}$,

$$
\begin{equation*}
\left\|u_{0}-\sum_{j=1}^{N} \varphi_{c_{j}^{0}}\left(\cdot-x_{j}^{0}\right)\right\|_{H^{1}} \leqslant \alpha, \quad \text { with } x_{j}^{0}>x_{j-1}^{0}+L, \text { for all } j=2, \ldots, N, \tag{1.9}
\end{equation*}
$$

then, there exist $x_{1}(t), \ldots, x_{N}(t)$ such that the solution $u(t)$ of (1.1) satisfies:

$$
\begin{equation*}
\text { for any } t \geqslant 0, \quad\left\|u(t)-\sum_{j=1}^{N} \varphi_{c_{j}^{0}}\left(\cdot-x_{j}(t)\right)\right\|_{H^{1}} \leqslant A_{0}\left(\alpha+e^{-\gamma_{0} L}\right) \tag{1.10}
\end{equation*}
$$

Remark 1. A similar result was proved by Martel, Merle and Tsai [14] for the generalized KdV equations. Here, we combine a generalization of the argument of [14] with some tools developed by El Dika [5]-[7] for the gBBM equation. This paper is thus an illustration of the fact that the approach in [14] does not depend on specific calculations for the $g K d V$ equation, but is a general method for proving the stability of the sum of $N$ solitary waves of a nonlinear dispersive equation as a consequence of two basic properties:

- a dynamical proof of the stability of solitary waves solutions, as provided in [21] for several dispersive equations,
- a property of almost monotonicity of a local version of an invariant quantity, see Lemma 2.1.

We expect that these two properties hold not only for the gKdV and the gBBM equations, but also for several other nonlinear dispersive equations, for example : the fifth-order KdV equation, the Benjamin-Ono equation, and the ILW equation (see [21]). Let us give some details for the fifth-order KdV equation:

$$
\left\{\begin{array}{l}
u_{t}+\left(u_{x x}-u_{x x x x}+u^{2}\right)_{x}=0,(t, x) \in \mathbb{R} \times \mathbb{R}  \tag{1.11}\\
u(0, x)=u_{0}(x), x \in \mathbb{R}
\end{array}\right.
$$

For this equation, the monotonicity property is easily checked (as for the gKdV equation, see Corollary 1 in [12]), and a proof of stability of solitary waves is available (using numerical calculations), see Il'ichev and Semenov [9].

Now, we turn to the question of asymptotic stability. Recall that the first result of asymptotic stability of solitary waves for the gBBM equation (for $p=2,3$ ) in the energy space has been proved by the first author ([5], [6]) and independently by Mizumachi $[\mathbf{1 7}]$. Their work is in the same spirit as asymptotic stability results for the generalized KdV equations by Martel and Merle [12] (see also [13] for a simplified proof).

A direct corollary of the asymptotic stability result for one solitary wave and the stability of the sums of $N$ solitary waves (Theorem 1.1) is the following result of asymptotic stability of the sums of $N$ solitary waves in the energy space.

THEOREM 1.2. Let $p=2$ or 3 . There exists a set $E \subset(1,+\infty)$ without accumulation points ( $E$ may be empty) for which : given $N$ velocities $1<c_{1}^{0}<\cdots<$ $c_{N}^{0}$, such that for $j \in\{1, \cdots, N\}, c_{j}^{0} \in(1,+\infty) \backslash E$, there exist $\gamma_{0}, A_{0}, L_{0}, \alpha_{0}>0$ such that if for some $L>L_{0}, \alpha<\alpha_{0}$, and $x_{1}^{0}<\ldots<x_{N}^{0}, u_{0} \in H^{1}(\mathbb{R})$ satisfies

$$
\begin{equation*}
\left\|u_{0}-\sum_{j=1}^{N} \varphi_{c_{j}^{0}}\left(\cdot-x_{j}^{0}\right)\right\|_{H^{1}} \leqslant \alpha, \quad \text { and } x_{j}^{0}>x_{j-1}^{0}+L, \text { for all } j=2, \ldots, N \tag{1.12}
\end{equation*}
$$

then, there exist $1<c_{1}^{+\infty}<\cdots<c_{N}^{+\infty}, x_{1}(t), \ldots, x_{N}(t)$ such that the solution $u(t)$ of (1.1) satisfies:

$$
\begin{equation*}
u(t)-\sum_{j=1}^{N} \varphi_{c_{j}^{+\infty}}\left(\cdot-x_{j}(t)\right) \rightarrow 0 \quad \text { in } H^{1}\left(x>\frac{1+c_{1}^{0}}{2} t\right) \text { as } t \rightarrow+\infty \tag{1.13}
\end{equation*}
$$

Remark 2. Note that the asymptotic stability in $H^{1}(\mathbb{R})(1.13)$ has a local in space sense. As for the gKdV equation, we cannot have in general convergence in $H^{1}(\mathbb{R})$, since almost all solutions have dispersion for $x<t$, see Remark 5 .

Remark 3. The restriction $c_{j}^{0} \notin E$ is probably a technical condition, due to the use of a spectral result by Miller and Weinstein [16], as in the asymptotic stability result of [6]. In fact, the conclusion of Theorem 1.2 would be true in general provided that for any $c_{j}^{0}$, a linear rigidity condition related to $\varphi_{c_{j}^{0}}$ is satisfied (see [6], Theorem 6.1 and section 4.1 of this paper).

Finally, we state another result related to $N$-solitary waves for the gBBM equations. Being given $1 \leqslant c^{\star}(p)<c_{1}^{0}<\cdots<c_{N}^{0}$, and $x_{1}^{0}, \cdots, x_{N}^{0} \in \mathbb{R}$, we prove that there exists a unique solution $U(t)$ of (1.1) such that

$$
\begin{equation*}
\lim _{t \rightarrow+\infty}\left\|U(t)-\sum_{j=1}^{N} \varphi_{c_{j}^{0}}\left(\cdot-x_{j}^{0}-c_{j}^{0} t\right)\right\|_{H^{1}}=0 . \tag{1.14}
\end{equation*}
$$

A similar result was proved by the second author for the generalized KdV equations, see [11].

Theorem 1.3. Let $p \geqslant 2$ be an integer. Let $1 \leqslant c^{\star}(p)<c_{1}^{0}<\ldots<c_{N}^{0}$, and $x_{1}^{0}, \ldots, x_{N}^{0} \in \mathbb{R}$. There exists a unique function $U \in C\left(\mathbb{R}, H^{1}(\mathbb{R})\right)$ which is solution
of (1.1) and satisfies

$$
\begin{equation*}
\left\|U(t)-\sum_{j=1}^{N} \varphi_{c_{j}}\left(.-x_{j}^{0}-c_{j}^{0} t\right)\right\|_{H^{1}} \rightarrow 0 \quad \text { as } t \rightarrow+\infty . \tag{1.15}
\end{equation*}
$$

Moreover, $U(t)$ is such that, for any $s \geqslant 1$, for any $t \geqslant 0$,

$$
\begin{equation*}
\left\|U(t)-\sum_{j=1}^{N} \varphi_{c_{j}}\left(.-x_{j}^{0}-c_{j}^{0} t\right)\right\|_{H^{s}} \leqslant A_{s} e^{-\gamma t} \tag{1.16}
\end{equation*}
$$

where $\gamma>0$, and $A_{s}>0$.
Remark 4. The existence of such $N$-solitary wave solutions is a somewhat surprising phenomenon for a non integrable equation. For the KdV and modified KdV equations (the integrable cases) such $N$-solitary wave solutions are explicitly known, and describe a perfect interaction between several solitary waves. By Theorem 1.1 and the continuity of the flow of the gBBM equation, the family of solutions $U_{\left\{c_{j}^{0}, x_{j}^{0}\right\}}$ constructed in the above Theorem is stable in $H^{1}(\mathbb{R})$ for $t \geqslant 0$.

Recall that the first result of stability of $N$-solitary wave solutions of the KdV equation was proved in $H^{N}(\mathbb{R})$ by Maddocks and Sachs [10].

Remark 5. The uniqueness part implies that the result of asymptotic stability in Theorem 1.2 is in some sense optimal, since convergence in $H^{1}(\mathbb{R})$, that is (1.13), determines uniquely the solution. Note also that in Theorem 1.3, as in Theorem 1.1, there is no restriction on the $c_{j}^{0}$ nor on $p$ : the proof does not use the spectral result of Miller and Weinstein [16].

## 2. Preliminaries

2.1. Modulation. The aim of this section is to prove that if $u$ is a solution of the gBBM equation which remains close to the manifold of the sum of $N$ solitary waves for $t \in\left[0, t_{0}\right]$, then for the same time interval we can decompose $u$ as the sum of $N$ modulated solitary waves plus a function $\varepsilon(t)$ which remains small in $H^{1}(\mathbb{R})$ :

$$
\begin{equation*}
u(t, x)=\sum_{j=1}^{N} \varphi_{c_{j}(t)}\left(x-x_{j}(t)\right)+\varepsilon(t, x) \tag{2.1}
\end{equation*}
$$

with $\varepsilon(t)$ orthogonal to $\left(1-\partial_{x}^{2}\right) \varphi_{c_{j}(t)}\left(\cdot-x_{j}(t)\right)$ and $\left(1-\partial_{x}^{2}\right) \partial_{x} \varphi_{c_{j}(t)}\left(\cdot-x_{j}(t)\right)$ in $L^{2}$, for $t \in\left[0, t_{0}\right]$.

Henceforth we fix an integer $p \geqslant 2$, and $N$ velocities

$$
1 \leqslant c^{\star}(p)<c_{1}^{0}<c_{2}^{0}<\cdots<c_{N}^{0}
$$

where $c^{\star}(p)$ is, as noted in the Introduction, the critical speed for stability. We also fix

$$
\begin{equation*}
\sigma_{0}=\frac{1}{2} \min \left(2, \sqrt{\frac{c_{1}^{0}-1}{c_{1}^{0}}}, c_{1}^{0}-c^{\star}(p), c_{2}^{0}-c_{1}^{0}, \cdots, c_{N}^{0}-c_{N-1}^{0}\right)>0 . \tag{2.2}
\end{equation*}
$$

We denote by $\mathcal{U}(\alpha, L)$ the neighborhood of size $\alpha$ of all the sum of $N$ solitary waves of speed $c_{j}^{0}$ such that the distance between their spatial shifts $x_{j}$ is larger then $L$,
i.e.

$$
\begin{equation*}
\mathcal{U}(\alpha, L)=\left\{u \in H^{1}(\mathbb{R}) ; \inf _{x_{j}>x_{j-1}+L}\left\|u-\sum_{j=1}^{N} \varphi_{c_{j}^{0}}\left(\cdot-x_{j}\right)\right\|_{H^{1}}<\alpha\right\} \tag{2.3}
\end{equation*}
$$

Proposition 2.1. There exists $L_{1}, \alpha_{1}, K_{1}>0$ such that if for some $L>L_{1}$, $0<\alpha<\alpha_{1}, t_{0}>0$,

$$
u(t) \in \mathcal{U}(\alpha, L) \text { for all } t \in\left[0, t_{0}\right]
$$

then there exist unique $C^{1}$ functions

$$
c_{j}:\left[0, t_{0}\right] \rightarrow\left(c^{\star}(p),+\infty\right), \quad x_{j}:\left[0, t_{0}\right] \rightarrow \mathbb{R}
$$

such that if we define $\varepsilon$ by

$$
\varepsilon(t)=u(t)-\sum_{j=1}^{N} R_{j}(t), \text { where } R_{j}(t)=\varphi_{c_{j}(t)}\left(\cdot-x_{j}(t)\right)
$$

then the following properties are satisfied for all $j \in\{1, \cdots, N\}$, for all $t \in\left[0, t_{0}\right]$ :

$$
\begin{equation*}
\left|\dot{c}_{j}(t)\right|+\left|\dot{x}_{j}(t)-c_{j}(t)\right| \leqslant K_{1}\left(\int e^{-\sigma_{0}\left|x-x_{j}(t)\right|} \varepsilon^{2}(t) d x\right)^{\frac{1}{2}}+K_{1} e^{-\frac{\sigma_{0}\left(L+\sigma_{0} t\right)}{4}} \tag{2.6}
\end{equation*}
$$

for some constant $K_{1}>0$.
Proof. First, we prove the decomposition result for general function $u \in$ $\mathcal{U}(\alpha, L)$, i.e., with no time dependency. Let $L>0, X^{0}=\left(x_{j}^{0}\right) \in \mathbb{R}^{N}$ such that $x_{j}^{0}>x_{j-1}^{0}+L$, and set $R_{X^{0}}=\sum_{j=1}^{N} \varphi_{c_{j}^{0}}\left(\cdot-x_{j}^{0}\right)$. We denote by $B\left(R_{X^{0}}, \alpha\right)$ the ball in $H^{1}(\mathbb{R})$ of center $R_{X^{0}}$ and radius $\alpha$, and we define the mapping :

$$
\mathcal{Y}: \prod_{j=1}^{N}\left(c_{j}^{0}-\alpha, c_{j}^{0}+\alpha\right) \times \prod_{j=1}^{N}(-\alpha, \alpha) \times B\left(R_{X^{0}}, \alpha\right) \longrightarrow \mathbb{R}^{N} \times \mathbb{R}^{N}
$$

by $\mathcal{Y}=\left(\mathcal{Y}^{1,1}, \cdots, \mathcal{Y}^{1, N}, \mathcal{Y}^{2,1}, \cdots, \mathcal{Y}^{2, N}\right)$, where

$$
\begin{aligned}
& \mathcal{Y}^{1, j}\left(c_{1}, \cdots, c_{N}, y_{1}, \cdots, y_{N}, u\right) \\
& =\int\left(u(x)-\sum_{k=1}^{N} \varphi_{c_{k}^{0}}\left(x-x_{k}^{0}-y_{k}\right)\right)\left(1-\partial_{x}^{2}\right) \varphi_{c_{j}^{0}}\left(x-x_{j}^{0}-y_{j}\right) d x
\end{aligned}
$$

and

$$
\begin{aligned}
& \mathcal{Y}^{2, j}\left(c_{1}, \cdots, c_{N}, y_{1}, \cdots, y_{N}, u\right) \\
& =\int\left(u(x)-\sum_{k=1}^{N} \varphi_{c_{j}^{0}}\left(x-x_{k}^{0}-y_{k}\right)\right)\left(1-\partial_{x}^{2}\right) \partial_{x} \varphi_{c_{j}^{0}}\left(x-x_{j}^{0}-y_{j}\right) d x
\end{aligned}
$$

By the dominated convergence theorem and the smoothness of $\varphi_{c}$, it can be seen that $\mathcal{Y}$ is a $C^{1}$-mapping. In view of applying the implicit function theorem, let us
compute the partial derivatives of $\mathcal{Y}$ at the point $M_{0}=\left(c_{1}^{0}, \cdots, c_{N}^{0}, 0, \cdots, 0, R_{X^{0}}\right)$, for all $j=1, \cdots, N$ :

$$
\frac{\partial \mathcal{Y}^{1, j}}{\partial c_{j}}\left(M_{0}\right)=-\int \partial_{c} \varphi_{c_{j}^{0}}\left(\cdot-x_{j}^{0}\right)\left(1-\partial_{x}^{2}\right) \varphi_{c_{j}^{0}}\left(\cdot-x_{j}^{0}\right) d x
$$

Using the identity

$$
\begin{equation*}
\partial_{c} \varphi_{c_{0}}(x)=\frac{1}{\left(c_{0}-1\right)(p-1)} \varphi_{c_{0}}(x)+\frac{x}{2 c_{0}\left(c_{0}-1\right)} \partial_{x} \varphi_{c_{0}}(x), \tag{2.7}
\end{equation*}
$$

and integrating by parts, we find that

$$
\frac{\partial \mathcal{Y}^{1, j}}{\partial c_{j}}\left(M_{0}\right)=\frac{-4 c_{j}^{0}-1+p}{4 c_{j}^{0}\left(c_{j}^{0}-1\right)} \int \varphi_{c_{j}^{0}}^{2} d x-\frac{4 c_{j}^{0}+1}{4 c_{j}^{0}\left(c_{j}^{0}-1\right)} \int\left(\partial_{x} \varphi_{c_{j}^{0}}\right)^{2} d x
$$

Remark that $\frac{\partial \mathcal{Y}^{1, j}}{\partial c_{j}}\left(M_{0}\right)=-\left.\frac{d}{d c} m\left(\varphi_{c}\right)\right|_{c=c_{j}^{0}}<0$, since $c^{\star}(p)<c_{j}^{0}$, see the Introduction and $[\mathbf{2 0}],[\mathbf{2 1}]$. Moreover, we deduce from the above identity that $\frac{\partial \mathcal{Y}^{1, j}}{\partial c_{j}}\left(M_{0}\right) \leqslant-C_{1}$, where $C_{1}>0$ depends only on the $\left(c_{j}^{0}\right)$. We also integrate by parts to compute :

$$
\begin{gathered}
\frac{\partial \mathcal{Y}^{1, j}}{\partial y_{j}}\left(M_{0}\right)=\int \partial_{x} \varphi_{c_{j}^{0}}\left(\cdot-x_{j}^{0}\right)\left(1-\partial_{x}^{2}\right) \varphi_{c_{j}^{0}}\left(\cdot-x_{j}^{0}\right) d x=0 \\
\frac{\partial \mathcal{Y}^{2, j}}{\partial c_{j}}\left(M_{0}\right)=-\int \partial_{c} \varphi_{c_{j}^{0}}\left(\cdot-x_{j}^{0}\right)\left(1-\partial_{x}^{2}\right) \partial_{x} \varphi_{c_{j}^{0}}\left(\cdot-x_{j}^{0}\right) d x=0
\end{gathered}
$$

and

$$
\begin{aligned}
\frac{\partial \mathcal{Y}^{2, j}}{\partial y_{j}}\left(M_{0}\right) & =\int \partial_{x} \varphi_{c_{j}^{0}}\left(\cdot-x_{j}^{0}\right)\left(1-\partial_{x}^{2}\right) \partial_{x} \varphi_{c_{j}^{0}}\left(\cdot-x_{j}^{0}\right) d x \\
& =\left\|\partial_{x} \varphi_{c_{j}^{0}}\right\|_{H^{1}}^{2} \geqslant C_{2}
\end{aligned}
$$

where $C_{2}>0$ depends only on the $\left(c_{j}^{0}\right)$. Remark now that there exists $C>0$, such that for all $j=1 \cdots N$,

$$
\left|\varphi_{c_{j}^{0}}(x)\right|+\left|\partial_{x} \varphi_{c_{j}^{0}}(x)\right|+\left|\partial_{x}^{2} \varphi_{c_{j}^{0}}(x)\right| \leqslant C e^{-\sqrt{\frac{c_{j}^{0}-1}{c_{j}^{0}}}|x|} \leqslant C e^{-2 \sigma_{0}|x|}
$$

this allows one to compute, for $j \neq k$

$$
\begin{aligned}
& \left|\frac{\partial \mathcal{Y}^{1, j}}{\partial c_{k}}\left(M_{0}\right)\right|=\left|\int \partial_{c} \varphi_{c_{k}^{0}}\left(\cdot-x_{k}^{0}\right)\left(1-\partial_{x}^{2}\right) \varphi_{c_{j}^{0}}\left(\cdot-x_{j}^{0}\right) d x\right| \\
& \leqslant\left|\int\left(\frac{\varphi_{c_{k}^{0}}^{0}\left(x-x_{k}^{0}\right)}{\left(c_{k}^{0}-1\right)(p-1)}+\frac{\left(x-x_{k}\right) \partial_{x} \varphi_{c_{k}^{0}}\left(x-x_{k}^{0}\right)}{2 c_{k}^{0}\left(c_{k}^{0}-1\right)}\right)\left(1-\partial_{x}^{2}\right) \varphi_{c_{j}^{0}}\left(\cdot-x_{j}^{0}\right) d x\right| \\
& \leqslant C \int e^{-\sigma_{0}\left(\left|x-x_{j}^{0}\right|+\left|x-x_{k}^{0}\right|\right)} d x \leqslant C e^{-\sigma_{0}\left|x_{j}^{0}-x_{k}^{0}\right| / 2} \leqslant C e^{-\sigma_{0} L / 2}
\end{aligned}
$$

In the same way we compute, for $j \neq k$

$$
\begin{aligned}
& \left|\frac{\partial \mathcal{Y}^{1, j}}{\partial y_{k}}\left(M_{0}\right)\right|=\left|\int \partial_{x} \varphi_{c_{k}^{0}}\left(\cdot-x_{k}^{0}\right)\left(1-\partial_{x}^{2}\right) \varphi_{c_{j}^{0}}\left(\cdot-x_{j}^{0}\right) d x\right| \leqslant C e^{-\sigma_{0} L / 2} \\
& \left|\frac{\partial \mathcal{Y}^{2, j}}{\partial c_{k}}\left(M_{0}\right)\right|=\left|\int \partial_{c} \varphi_{c_{k}^{0}}\left(\cdot-x_{k}^{0}\right)\left(1-\partial_{x}^{2}\right) \partial_{x} \varphi_{c_{j}^{0}}\left(\cdot-x_{j}^{0}\right) d x\right| \leqslant C e^{-\sigma_{0} L / 2}
\end{aligned}
$$

and

$$
\left|\frac{\partial \mathcal{Y}^{2, j}}{\partial y_{k}}\left(M_{0}\right)\right|=\left|\int \partial_{x} \varphi_{c_{k}^{0}}\left(\cdot-x_{k}^{0}\right)\left(1-\partial_{x}^{2}\right) \partial_{x} \varphi_{c_{j}^{0}}\left(\cdot-x_{j}^{0}\right) d x\right| \leqslant C e^{-\sigma_{0} L / 2}
$$

We deduce that $\mathcal{D}_{\left(c_{1}, \cdots, c_{N}, y_{1}, \cdots, y_{N}\right)} \mathcal{Y}\left(M_{0}\right)=D+P$, where $D$ is an invertible diagonal matrix with $\|D\| \geqslant C_{3}$, where $C_{3}>0$ depends only on the $\left(c_{j}^{0}\right)$, and $\|P\| \leqslant$ $C e^{-\sigma_{0} L / 2}$. Hence there exists $L_{1}>0$ such that if $L \geqslant L_{1}, \mathcal{D}_{\left(c_{1}, \cdots, c_{N}, y_{1}, \cdots, y_{N}\right)} \mathcal{Y}\left(M_{0}\right)$ is invertible and its norm is larger than $C_{3} / 2$. The implicit function theorem implies the existence of $\alpha_{0}>0$, and $C^{1}$ functions $\left(c_{j}, y_{j}\right)_{j=1}^{N}$ from $B\left(R_{X^{0}}, \alpha_{0}\right)$ in a neighborhood of $\left(c_{1}^{0}, \cdots, c_{N}^{0}, 0, \cdots, 0\right)$ such that $\mathcal{Y}\left(c_{1}(u), \cdots, c_{N}(u), y_{1}(u), \cdots, y_{N}(u), u\right)=$ 0 for all $u \in B\left(R_{X^{0}}, \alpha_{0}\right)$. Moreover there exists $K_{1}>0$ such that if $u \in B\left(R_{X^{0}}, \alpha\right)$, where $0<\alpha \leqslant \alpha_{0}$, then

$$
\begin{equation*}
\sum_{j=1}^{N}\left|c_{j}(u)-c_{j}^{0}\right|+\sum_{j=1}^{N}\left|y_{j}(u)\right| \leqslant K_{1} \alpha . \tag{2.8}
\end{equation*}
$$

It is crucial, for the next step, to note that $\alpha_{0}$ and $K_{1}$ are independent from $X^{0}=\left(x_{j}^{0}\right) \in \mathbb{R}^{N}$ provided that $x_{j}^{0}>x_{j-1}^{0}+L$, with $L \geqslant L_{1}$. For $u \in B\left(R_{X^{0}}, \alpha_{0}\right)$, we set $x_{j}(u)=x_{j}^{0}+y_{j}(u)$, thus $x_{j}$ is a $C^{1}$ function on $B\left(R_{X^{0}}, \alpha_{0}\right)$ such that

$$
\begin{equation*}
x_{j}(u) \geqslant x_{j-1}(u)+L-2 K_{1} \alpha_{0} . \tag{2.9}
\end{equation*}
$$

We are now able to define the modulation of $u \in \mathcal{U}(\alpha, L)$ for $L \geqslant L_{1}$ and $0<\alpha \leqslant \alpha_{1}$, $\alpha_{1}$ to be chosen later. Indeed, for $\alpha \leqslant \alpha_{1}$ one can cover $\mathcal{U}(\alpha, L)$ as follows :

$$
\mathcal{U}(\alpha, L) \subset \bigcup_{X \in \mathbb{R}^{N}, x_{j}>x_{j-1}+L} B\left(R_{X}, \rho_{0}\right)
$$

where $\alpha_{1} \leqslant \rho_{0} \leqslant \alpha_{0}$, and $\rho_{0}$ is chosen such that if $u \in B\left(R_{X}, \rho_{0}\right) \cap B\left(R_{\tilde{X}}, \rho_{0}\right)$, then the modulation of $u$ is uniquely defined thanks to the uniqueness in the implicit function theorem.

Now, we define the modulation of $u$ solution of $(\mathrm{gBBM})$ such that $u(t) \in \mathcal{U}(\alpha, L)$ for all $t \in\left[0, t_{0}\right]$, by setting for $j=1, \cdots, N$ and $t \in\left[0, t_{0}\right]$

$$
\begin{aligned}
& c_{j}(t)=c_{j}(u(t)) \text { and } x_{j}(t)=x_{j}(u(t)) \\
& \varepsilon(t)=u(t)-\sum_{j=1}^{N} \varphi_{c_{j}(t)}\left(\cdot-x_{j}(t)\right)
\end{aligned}
$$

These functions clearly satisfy properties (2.4) and (2.5). To establish estimates (2.6) we argue as in the case of a single solitary wave ([6]). Indeed, substituting $u(t, x)=\sum_{j=1}^{N} \varphi_{c_{j}(t)}\left(x-x_{j}(t)\right)+\varepsilon(t, x)$ in the gBBM equation and using the equation of $\varphi_{c_{j}(t)}$, we find that $\varepsilon(t)$ satisfies for all $t \in\left[0, t_{0}\right]$,

$$
\begin{align*}
\left(1-\partial_{x}^{2}\right) \varepsilon_{t}+\varepsilon_{x}+ & \sum_{j=1}^{N} \dot{c}_{j}\left(1-\partial_{x}^{2}\right) \partial_{c} R_{j}-\sum_{j=1}^{N}\left(\dot{x}_{j}-c_{j}\right)\left(1-\partial_{x}^{2}\right) \partial_{x} R_{j} \\
& +\left(\left(\varepsilon+\sum_{j=1}^{N} R_{j}\right)^{p}-\sum_{j=1}^{N} R_{j}^{p}\right)_{x}=0 \tag{2.10}
\end{align*}
$$

Now remark that thanks to estimate (2.5), one can choose $\alpha_{1}$ sufficiently small such that for all $j$,

$$
\begin{equation*}
\sigma_{0} \leqslant \frac{4}{5} \min \left(\sqrt{\frac{c_{j}(t)-1}{c_{j}(t)}}, c_{1}(t)-c^{\star}(p), c_{2}(t)-c_{1}(t), \cdots, c_{N}(t)-c_{N-1}(t)\right) \tag{2.11}
\end{equation*}
$$

this implies that

$$
\begin{equation*}
\left|R_{j}(t, x)\right| \leqslant C e^{-\sigma_{0}\left|x-x_{j}(t)\right|} . \tag{2.12}
\end{equation*}
$$

Taking the inner product in $L^{2}(\mathbb{R})$ of equation (2.10) with $R_{j}$ and $\partial_{x} R_{j}$, integrating by parts and using the decay of $R_{j}$ and its derivatives, we find

$$
\begin{align*}
\left|\dot{c}_{j}(t)\right|+\left|\dot{x}_{j}(t)-c_{j}(t)\right| \leqslant & C\left(\int e^{-\sigma_{0}\left|x-x_{j}(t)\right|} \varepsilon^{2}(t) d x\right)^{1 / 2} \\
& +C \sum_{k \neq j} e^{-\frac{\sigma_{0}}{2}\left|x_{k}(t)-x_{j}(t)\right|} \tag{2.13}
\end{align*}
$$

Using this inequality, the choice of $\sigma_{0}$, estimates (2.9) and (2.8), one can take $\alpha_{1}$ small enough and $L_{1}$ large enough such that $\left|x_{k}(t)-x_{j}(t)\right| \geqslant L / 2+\sigma_{0} t$; this and estimate (2.13) imply (2.6) and achieve the proof of Proposition 2.1.
2.2. Monotonicity property. We introduce in this section a main tool in the proof of the stability result. It is an adaptation of the monotonicity result in the case of single perturbed solitary wave (Proposition 3.1 in $[\mathbf{6}]$ ) or $H^{1}$-localized solutions of the gBBM equation (Lemma 2.1 in $[7]$ ) to the case of solutions near the sum of $N$ solitary waves.

Before introducing this tool, we recall two fundamental identities (see proofs of Propositions 3.1 and 4.2 in [ $\mathbf{6}]$ and proof of Lemma 2.1 in $[\mathbf{7}]$ ) which are based on the conservation laws: For any solution $u(t)$ of (1.1), and any $C^{1}$ function $g=g(x)$, the following holds:

$$
\begin{align*}
\frac{d}{d t} \int\left(u^{2}(t)+u_{x}^{2}(t)\right) g(x) d x= & -\int u^{2}(t) g^{\prime} d x-\frac{2}{p+1} \int u^{p+1}(t) g^{\prime} d x \\
& +2 \int u h g^{\prime} d x \tag{2.14}
\end{align*}
$$

and

$$
\begin{equation*}
\frac{d}{d t} \int\left(u^{2}(t)+\frac{2}{p+1} u^{p+1}(t)\right) g(x) d x=\int h^{2}(t) g^{\prime} d x-\int h_{x}^{2}(t) g^{\prime} d x \tag{2.15}
\end{equation*}
$$

where $h=\left(1-\partial_{x}^{2}\right)^{-1}\left(u+u^{p}\right)$.
Consider the function $\psi$ :

$$
\psi(x)=\frac{\sigma_{0}}{3 \int Q} \int_{-\infty}^{x} Q\left(\frac{\sigma_{0} y}{3}\right) d y
$$

where $Q$ is defined in the Introduction. Note that $\psi$ is positive, increasing, $\psi(x)$ goes to 1 when $x$ goes to $+\infty$, and $\psi$ and its derivatives satisfy an exponential decay on the left : $\psi(x)+\psi^{\prime}(x)+\left|\psi^{\prime \prime}(x)\right| \leqslant C e^{\frac{\sigma_{0} x}{3}}$ for $x \leqslant 0$. We introduce for all $j \in\{2, \cdots, N\}$ :

$$
\mathcal{I}_{j}(t)=\frac{1}{2} \int\left(u^{2}(t, x)+u_{x}^{2}(t, x)\right) \psi_{j}(t, x) d x
$$

$$
\begin{equation*}
\text { where } \quad \psi_{j}(t, x)=\psi\left(x-y_{j}(t)\right) \quad \text { and } \quad y_{j}(t)=\frac{x_{j-1}(t)+x_{j}(t)}{2} \tag{2.16}
\end{equation*}
$$

Note that $\mathcal{I}_{j}(t)$ is close to $\frac{1}{2}\|u(t)\|_{H^{1}\left(x>y_{j}(t)\right)}^{2}$. The following lemma claims that for a solution $u$ of the gBBM equation such as in Proposition 2.1, the function $\mathcal{I}_{j}$ is almost decreasing with respect to time :

Lemma 2.1. Consider $u$ solution of $g B B M$ in $C\left(\mathbb{R}, H^{1}(\mathbb{R})\right.$ ) as in Proposition 2.1. There exist $\alpha_{2}>0, K_{2}>0$ and $L_{2}>0$, all depending only on $\sigma_{0}$, such that if $0<\alpha<\alpha_{2}$, and for all $j \in\{2, \cdots, N\}, x_{j}(t)-x_{j-1}(t) \geqslant L$, for some $L \geqslant L_{2}$, then

$$
\begin{equation*}
\mathcal{I}_{j}(t)-\mathcal{I}_{j}(0) \leqslant K_{2} e^{-\frac{\sigma_{0} L}{12}}, \text { for all } t \in\left[0, t_{0}\right] \tag{2.17}
\end{equation*}
$$

Proof. Since the proof is very similar to the one of Lemma 2.1 in [7], we only give the main steps. From (2.11), we deduce that for all $j \in\{1, \cdots, N\}$, $\frac{5}{4} \sigma_{0}^{2} \leqslant c_{j}(t)-1$. Thus, using estimate (2.6), one can choose in Proposition 2.1 a value of $\alpha_{1}$ sufficiently small and $L_{1}$ sufficiently large such that

$$
\begin{equation*}
\forall j \in\{1, \cdots, N\}, \quad 1+\sigma_{0}^{2} \leqslant \dot{x}_{j}(t) \text { for all } t \in\left[0, t_{0}\right] \tag{2.18}
\end{equation*}
$$

Using this estimate and following the same steps as in the proof of Lemma 2.1 in [7], we compute :

$$
\begin{aligned}
\mathcal{I}_{j}^{\prime}(t) \leqslant & -\left(1+\frac{\sigma_{0}^{2}}{2}\right) \int u^{2} \psi^{\prime}\left(x-y_{j}(t)\right) d x+\int u \psi^{\prime}\left(x-y_{j}(t)\right)\left(1-\partial_{x}^{2}\right)^{-1} u d x \\
& -\int \frac{u^{p+1}}{p+1} \psi^{\prime}\left(x-y_{j}(t)\right) d x+\int u \psi^{\prime}\left(x-y_{j}(t)\right)\left(1-\partial_{x}^{2}\right)^{-1}\left(u^{p}\right) d x
\end{aligned}
$$

Next we introduce the function $\tilde{h}=\left(1-\partial_{x}^{2}\right)^{-1} u \in H^{2}(\mathbb{R})$, this change of variable and the estimate

$$
\left|\psi^{\prime \prime \prime}(x)\right|=\frac{\sigma_{0}^{2}}{9} \frac{\sigma_{0}}{3 \int Q(y) d y}\left|\partial_{x}^{2} Q\left(\frac{\sigma_{0} x}{3}\right)\right| \leqslant \frac{\sigma_{0}^{2}}{9} \psi^{\prime}(x)
$$

imply

$$
\begin{aligned}
\mathcal{I}_{j}^{\prime}(t) \leqslant & -\frac{\sigma_{0}^{2}}{4} \int u^{2} \psi^{\prime}\left(x-y_{j}(t)\right) d x \\
& -\int \frac{u^{p+1}}{p+1} \psi^{\prime}\left(x-y_{j}(t)\right) d x+\int u \psi^{\prime}\left(x-y_{j}(t)\right)\left(1-\partial_{x}^{2}\right)^{-1}\left(u^{p}\right) d x
\end{aligned}
$$

(see [7]). It remains to deal with the nonlinear terms, the idea is to decompose each of them as the sum of two integrals, one of them being over a region where $u$ is small. To do this, we set $I=\left[x_{j-1}(t)+L / 4, x_{j}(t)-L / 4\right]$ and $I^{C}=\mathbb{R} \backslash I$. Remark that for $x \in I$, taking $L_{2}=L_{2}\left(\sigma_{0}\right)$ sufficiently large, and $a_{0}=a_{0}\left(\sigma_{0}\right)$ sufficiently small, we have by the expression of $\varphi_{c}(x)$,

$$
|u(t, x)|^{p-1}=\left|\sum_{j=1}^{N} R_{j}(t, x)+\varepsilon(t, x)\right|^{p-1} \leqslant C\left(e^{-\frac{\sigma_{0} L}{4}}+\|\varepsilon(t)\|_{H^{1}}^{p-1}\right) \leqslant(p+1) \frac{\sigma_{0}^{2}}{8}
$$

This implies that

$$
\begin{equation*}
\left|\int_{I} \frac{u^{p+1}}{p+1} \psi^{\prime}\left(x-y_{j}(t)\right) d x\right| \leqslant \frac{\sigma_{0}^{2}}{8} \int u^{2} \psi^{\prime}\left(x-y_{j}(t)\right) d x \tag{2.19}
\end{equation*}
$$

Remark that from (2.6) and (2.11), we can choose in Proposition 2.1 the parameter $\alpha_{0}$ sufficiently small so that $\dot{x}_{j}(t)-\dot{x}_{j-1}(t) \geqslant \sigma_{0}$. Thus, for $x \in I^{C}$, we have

$$
\left|x-y_{j}(t)\right| \geqslant\left(x_{j}(t)-x_{j-1}(t)\right) / 2-L / 4 \geqslant \sigma_{0} t / 2+L / 4 .
$$

This estimate and the exponential decay of $\psi^{\prime}$ imply that

$$
\begin{equation*}
\left|\int_{I^{C}} \frac{u^{p+1}}{p+1} \psi^{\prime}\left(x-y_{j}(t)\right) d x\right| \leqslant C e^{-\frac{\sigma_{0}}{6}\left(\sigma_{0} t+L / 2\right)} . \tag{2.20}
\end{equation*}
$$

The second nonlinear term, $\int u \psi^{\prime}\left(x-y_{j}(t)\right)\left(1-\partial_{x}^{2}\right)^{-1}\left(u^{p}\right) d x$, is also decomposed as above, using the same estimates as the ones of the proof of Lemma 2.1 in [7], we get

$$
\begin{align*}
\int u \psi^{\prime}\left(x-y_{j}(t)\right)\left(1-\partial_{x}^{2}\right)^{-1}\left(u^{p}\right) d x \leqslant & \frac{\sigma_{0}^{2}}{8} \int u^{2} \psi^{\prime}\left(x-y_{j}(t)\right) d x \\
& +C e^{-\frac{\sigma_{0}}{6}\left(\sigma_{0} t+L / 2\right)} \tag{2.21}
\end{align*}
$$

Hence, gathering estimates (2.19), (2.20) and (2.21), we obtain

$$
\begin{equation*}
\left.\mathcal{I}_{j}^{\prime}(t) \leqslant C e^{-\frac{\sigma_{0}}{6}\left(\sigma_{0} t+L / 2\right)}\right) \tag{2.22}
\end{equation*}
$$

This implies, after integration between 0 and $t$, that

$$
\mathcal{I}_{j}(t)-\mathcal{I}_{j}(0) \leqslant C e^{-\frac{\sigma_{0} L}{12}}
$$

where $C$ is independent of $t$. Thus, Lemma 2.1 is proved.

### 2.3. Linearization of the energy and coercivity.

Lemma 2.2. There exists $K_{3}>0$ and $L_{3}>0$ such that the decomposition of $u$ given in Proposition 2.1 satisfies the following : if for all $j, x_{j}(t)-x_{j-1}(t) \geqslant L \geqslant$ $L_{3}$, then for all $t \in\left[0, t_{0}\right]$,

$$
\begin{align*}
& \left|\sum_{j=1}^{N}\left[E\left(R_{j}(t)\right)-E\left(R_{j}(0)\right)\right]+\frac{1}{2} \int\left(\varepsilon^{2}(t)+p R^{p-1}(t) \varepsilon^{2}(t)\right) d x\right| \\
& \leqslant K_{3}\left(\|\varepsilon(0)\|_{H^{1}}^{2}+\|\varepsilon(t)\|_{H^{1}}^{3}+e^{-\sigma_{0} L / 2}\right) \tag{2.23}
\end{align*}
$$

where $R(t)=\sum_{j=1}^{N} R_{j}(t)$.
Proof. The proof consists in writing the energy of $u$ as the sum of the energies of the modulated solitary waves and a quadratic form of $\varepsilon$, which is done using the decomposition of $u$ and the orthogonality conditions satisfied by $\varepsilon$. Indeed, using the decomposition of $u$ (2.1), a straightforward calculation gives :

$$
\begin{aligned}
& E(u(t))=\sum_{j=1}^{N} \int\left(\frac{1}{2} R_{j}^{2}(t)+\frac{1}{p+1} R_{j}^{p+1}(t)\right) d x+\frac{1}{2} \int \varepsilon^{2}(t) d x \\
& +\frac{p}{2} \int R^{p-1}(t) \varepsilon^{2}(t) d x+\sum_{j=1}^{N} \int\left(R_{j}+R_{j}^{p}\right)(t) \varepsilon(t) d x+\frac{1}{2} \sum_{j \neq k} \int R_{j}(t) R_{k}(t) d x \\
& +\int\left\{\frac{(R+\varepsilon)^{p+1}(t)}{p+1}-\sum_{j=1}^{N}\left(\frac{R_{j}^{p+1}}{p+1}(t)+R_{j}^{p}(t) \varepsilon(t)\right)-\frac{p}{2} R^{p-1}(t) \varepsilon^{2}(t)\right\} d x
\end{aligned}
$$

First, thanks to the equation of $\varphi_{c}$ (1.5) and the orthogonality condition (2.4) we obtain for all $j$

$$
\int \varepsilon(t)\left(R_{j}+R_{j}^{p}\right)(t) d x=c_{j} \int \varepsilon(t)\left(1-\partial_{x}^{2}\right) R_{j}(t) d x=0
$$

Now, recall that with our choice of $\sigma_{0},\left|R_{j}(t, x)\right| \leqslant C e^{-\sigma_{0}\left|x-x_{j}(t)\right|}$, and on the other hand $\left|x_{j}(t)-x_{k}(t)\right| \geqslant L$ for $j \neq k$. Thus,

$$
\left|\int R_{j} R_{k} d x\right| \leqslant C e^{-\sigma_{0} L / 2}
$$

Finally, for the nonlinear terms : for all $1 \leqslant k \leqslant p-1$,

$$
\left|\int \varepsilon^{k+2} R^{p-1-k}\right| \leqslant C\|\varepsilon\|_{L^{\infty}}^{k} \int \varepsilon^{2} \leqslant K\|\varepsilon(t)\|_{H^{1}}^{3}
$$

since $\|\varepsilon(t)\|_{H^{1}} \leqslant 1$. Hence,

$$
\begin{aligned}
& \left|E(u(t))-\sum_{j=1}^{N} E\left(R_{j}(t)\right)-\frac{1}{2} \int\left(\varepsilon^{2}(t)+p R^{p-1}(t) \varepsilon^{2}(t)\right) d x\right| \\
& \leqslant C\left(e^{-\sigma_{0} L / 2}+\|\varepsilon(t)\|_{H^{1}}^{3}\right)
\end{aligned}
$$

To obtain (2.23), it suffices now to use the energy conservation $E(u(t))=E(u(0))$. Thus Lemma 2.2 is proved.

Finally, we give a generalization of a positivity lemma proved by Weinstein [21], Proposition 5.2. The quadratic form $\mathcal{L}_{N}$ that we consider has a suitable form around each solitary wave, which requires localization arguments.

Lemma 2.3. There exists $L_{4}>0$ and $\lambda_{0}>0$ such that the decomposition of $u$ given in Proposition 2.1 satisfies the following : if for all $j, x_{j}(t)-x_{j-1}(t) \geqslant L$, for some $L \geqslant L_{4}$, then for all $t \in\left[0, t_{0}\right]$,

$$
\begin{equation*}
\left(\mathcal{L}_{N} \varepsilon, \varepsilon\right) \geqslant \lambda_{0}\|\varepsilon(t)\|_{H^{1}}^{2} \tag{2.24}
\end{equation*}
$$

where

$$
\left(\mathcal{L}_{N} \varepsilon, \varepsilon\right)=\int\left(c(t, x) \varepsilon_{x}^{2}(t, x)+(c(t, x)-1) \varepsilon^{2}(t, x)-p R^{p-1}(t, x) \varepsilon^{2}(t, x)\right) d x
$$

$$
\text { and } c(t, x)=c_{1}(t)+\sum_{j=2}^{N}\left(c_{j}(t)-c_{j-1}(t)\right) \psi\left(x-y_{j}(t)\right)
$$

The proof of Lemma 2.3 is given in Appendix A.

## 3. Stability proof

This section is devoted to the proof of the main result i.e. Theorem 1.1. We follow the strategy described in the Introduction. For $A_{0}, L, \alpha>0$, we define

$$
\begin{align*}
& \mathcal{V}_{A_{0}}(\alpha, L)  \tag{3.1}\\
& =\left\{u \in H^{1}(\mathbb{R}) ; \inf _{x_{j}-x_{j-1} \geqslant L}\left\|u-\sum_{j=1}^{N} \varphi_{c_{j}^{0}}\left(.-x_{j}\right)\right\|_{H^{1}} \leqslant A_{0}\left(\alpha+e^{-\frac{\sigma_{0}}{24} L}\right)\right\}
\end{align*}
$$

We claim that there exists $A_{0}>0, L_{0}>0$, and $\alpha_{0}>0$ such that, if for some $L>L_{0}, \alpha<\alpha_{0},\left\|u_{0}-\sum_{j=1}^{N} \varphi_{c_{j}^{0}}\left(.-x_{j}^{0}\right)\right\|_{H^{1}} \leqslant \alpha$, where $x_{j}^{0}>x_{j-1}^{0}+L$, then for all $t \geqslant 0, u(t) \in \mathcal{V}_{A_{0}}(\alpha, L)$, which implies Theorem 1.1. By continuity of $t \mapsto u(t)$ in $H^{1}(\mathbb{R})$, it is a consequence of the following proposition.

Proposition 3.1. There exists $A_{0}>0, L_{0}>0$, and $\alpha_{0}>0$ such that, if

$$
\begin{equation*}
\left\|u_{0}-\sum_{j=1}^{N} \varphi_{c_{j}^{0}}\left(.-x_{j}^{0}\right)\right\|_{H^{1}} \leqslant \alpha \tag{3.2}
\end{equation*}
$$

for some $L>L_{0}, 0<\alpha<\alpha_{0}, x_{j}^{0}>x_{j-1}^{0}+L$, and if for $t^{\star}>0$,

$$
\begin{equation*}
\forall t \in\left[0, t^{\star}\right], \quad u(t) \in \mathcal{V}_{A_{0}}(\alpha, L) \tag{3.3}
\end{equation*}
$$

then

$$
\begin{equation*}
\forall t \in\left[0, t^{\star}\right], \quad u(t) \in \mathcal{V}_{A_{0} / 2}(\alpha, L) \tag{3.4}
\end{equation*}
$$

Proof of Proposition 3.1. Let $A_{0}>0$ to be fixed later. Since by (3.3), $u(t)$ is close in $H^{1}$ to a sum of $N$ sufficiently decoupled solitary waves, we may apply Proposition 2.1 on $\left[0, t^{\star}\right]$. It follows that there exist $c_{j}, x_{j}$ as in the statement of the proposition. Since (3.3) involves the constant $A_{0}$ to be chosen, we obtain estimates on $\varepsilon(t),\left|c_{j}(t)-c_{j}^{0}\right|$, and the quantities in (2.6) all depending on $A_{0}$.

However, for the initial data, i.e., at $t=0$, assumption (3.2) implies directly

$$
\begin{equation*}
\|\varepsilon(0)\|_{H^{1}}+\sum_{j=1}^{N}\left|c_{j}(0)-c_{j}^{0}\right| \leqslant K_{1} \alpha \tag{3.5}
\end{equation*}
$$

with no dependency on $A_{0}$, using the first part the proof of Proposition 2.1. We choose $\alpha_{0}, L_{0}$ such that we can apply Lemmas 2.1-2.3 on [ $\left.0, t^{\star}\right]$, in particular $A_{0} \alpha_{0}$ small enough.

Let us define

$$
\begin{equation*}
d_{j}(t)=\sum_{k=j}^{N} m_{j}(t), \quad \Delta_{0}^{t} d_{j}=d_{j}(t)-d_{j}(0) \tag{3.6}
\end{equation*}
$$

The proof proceeds in two steps ((i) and (ii) in the next lemma) : first, we control the variations of the $c_{j}(t)$. Second, we estimate $\|\varepsilon(t)\|_{H^{1}}$, which gives the stability result.

Lemma 3.1. (i) There exists $K_{5}>0$ such that for all $t \in\left[0, t^{\star}\right]$,

$$
\begin{equation*}
\sum_{j=1}^{N}\left|c_{j}(t)-c_{j}(0)\right| \leqslant K_{5}\left(\|\varepsilon(0)\|_{H^{1}}^{2}+\|\varepsilon(t)\|_{H^{1}}^{2}+e^{-\frac{\sigma_{0}}{12} L}\right) \tag{3.7}
\end{equation*}
$$

(ii) There exists $K_{6}>0$ such that for all $t \in\left[0, t^{\star}\right]$,

$$
\begin{equation*}
\|\varepsilon(t)\|_{H^{1}}^{2} \leqslant K_{6}\left(\|\varepsilon(0)\|_{H^{1}}^{2}+e^{-\frac{\sigma_{0}}{12} L}\right) \tag{3.8}
\end{equation*}
$$

Proof of Lemma 3.1. We recall the three estimates that will be used in the proof: (a) The conclusion of Lemma 2.2:

$$
\begin{align*}
& \left|\sum_{j=1}^{N} \Delta_{0}^{t} E\left(R_{j}\right)+\frac{1}{2} \int\left(\varepsilon^{2}+p R^{p-1} \varepsilon^{2}\right)(t)\right| \\
& \leqslant K\left(\|\varepsilon(0)\|_{H^{1}}^{2}+\|\varepsilon(t)\|_{H^{1}}^{3}+e^{-\frac{\sigma_{0}}{12} L}\right) \tag{3.9}
\end{align*}
$$

(b) From Lemma 2.1 and the orthogonality conditions on $\varepsilon(t)$ :

$$
\begin{equation*}
\Delta_{0}^{t} d_{j}+\frac{1}{2} \int\left(\varepsilon^{2}(t)+\varepsilon_{x}^{2}(t)\right) \psi_{j}(t) \leqslant K\left(\|\varepsilon(0)\|_{H^{1}}^{2}+e^{-\frac{\sigma_{0}}{12} L}\right) \tag{3.10}
\end{equation*}
$$

(c) An estimate

$$
\begin{equation*}
\left|\Delta_{0}^{t} E\left(R_{j}\right)-c_{j}(t) \Delta_{0}^{t} m\left(R_{j}\right)\right| \leqslant K\left|c_{j}(t)-c_{j}(0)\right|^{2} \tag{3.11}
\end{equation*}
$$

which follows from $\frac{d}{d c} E\left(\varphi_{c}\right)=c \frac{d}{d c} m\left(\varphi_{c}\right)$.
We also write an identity that relates $\Delta_{0}^{t} m\left(R_{j}\right)$ to $\Delta_{0}^{t} d_{j}$ :

$$
\begin{align*}
\sum_{j=1}^{N} c_{j}(t) \Delta_{0}^{t} m\left(R_{j}\right) & =\sum_{j=1}^{N-1} c_{j}(t)\left[\Delta_{0}^{t} d_{j}-\Delta_{0}^{t} d_{j+1}\right]+c_{N}(t) \Delta_{0}^{t} d_{N} \\
& =\sum_{j=2}^{N}\left(c_{j}(t)-c_{j-1}(t)\right) \Delta_{0}^{t} d_{j}+c_{1}(t) \Delta_{0}^{t} d_{1} \tag{3.12}
\end{align*}
$$

Proof of (i). We combine (3.9)-(3.11) and the above identity to obtain (i). Let

$$
\mathcal{Q}(t)=\|\varepsilon(0)\|_{H^{1}}^{2}+\|\varepsilon(t)\|_{H^{1}}^{2}+e^{-\frac{\sigma_{0}}{12} L}+\left|c_{j}(t)-c_{j}(0)\right|^{2}
$$

From (3.9), we have

$$
\left|\sum_{j=1}^{N} \Delta_{0}^{t} E\left(R_{j}\right)\right| \leqslant K \mathcal{Q}(t)
$$

and so using (3.11) and (3.12), we obtain

$$
\begin{equation*}
\left|\sum_{j=2}^{N}\left(c_{j}(t)-c_{j-1}(t)\right) \Delta_{0}^{t} d_{j}+c_{1}(t) \Delta_{0}^{t} d_{1}\right| \leqslant K \mathcal{Q}(t) \tag{3.13}
\end{equation*}
$$

Note that directly from (3.10), for all $j \in\{1, \ldots, N\}$, we have

$$
\Delta_{0}^{t} d_{j} \leqslant K\left(\|\varepsilon(0)\|_{H^{1}}^{2}+e^{-\frac{\sigma_{0}}{12} L}\right)
$$

Using this estimate for $j \geqslant 2$ in (3.13), we deduce

$$
c_{1}(t) \Delta_{0}^{t} d_{1} \geqslant-K \mathcal{Q}(t)
$$

Since $c_{1}(t) \geqslant \sigma_{0}$, we obtain $\left|\Delta_{0}^{t} d_{1}\right| \leqslant K \mathcal{Q}(t)$. Similarly, for $j \in\{2, \ldots, N\}$, we have from (3.13),

$$
\left(c_{j}(t)-c_{j-1}(t)\right) \Delta_{0}^{t} d_{j} \geqslant-K \mathcal{Q}(t)
$$

and so, for all $j \in\{1, \ldots, N\}$, we have $\left|\Delta_{0}^{t} d_{j}\right| \leqslant K \mathcal{Q}(t)$. It follows that, for all $j \in\{1, \ldots, N\},\left|\Delta_{0}^{t} m\left(R_{j}\right)\right| \leqslant K \mathcal{Q}(t)$. Since

$$
m\left(R_{j}\right)(t)=f\left(c_{j}(t)\right)
$$

where $f^{\prime}(c)>0$, for $c=c_{j}(t)>c^{*}(p)$ (see (1.7) in the Introduction), we obtain

$$
\sum_{j=1}^{N}\left|c_{j}(t)-c_{j}(0)\right| \leqslant K \mathcal{Q}(t)
$$

Thus (i) is proved.
Proof of (ii). We use again (3.9)-(3.12) together with Lemma 2.3 to obtain (ii). Recall that in Lemma 2.3, we have defined

$$
\left(\mathcal{L}_{N} \varepsilon(t), \varepsilon(t)\right)=\int\left(c(t, x) \varepsilon_{x}^{2}(t, x)+(c(t, x)-1) \varepsilon^{2}(t, x)-p R^{p-1}(t, x) \varepsilon^{2}(t, x)\right) d x
$$

where $c(t, x)=c_{1}(t)+\sum_{j=2}^{N}\left(c_{j}(t)-c_{j-1}(t)\right) \psi_{j}(t, x)$. In the following we set $c_{0} \equiv 0$ and $\psi_{1} \equiv 1$ for the reader convenience. Inserting (3.9) and (3.12) into (3.11), and then using (i), we have

$$
\begin{aligned}
& \left|\frac{1}{2}\left(\mathcal{L}_{N} \varepsilon(t), \varepsilon(t)\right)-\sum_{j=1}^{N}\left(c_{j}(t)-c_{j-1}(t)\right)\left[\Delta_{0}^{t} d_{j}+\frac{1}{2} \int\left(\varepsilon^{2}+\varepsilon_{x}^{2}\right)(t) \psi_{j}(t)\right]\right| \\
& \leqslant K\left(\|\varepsilon(0)\|_{H^{1}}^{2}+\|\varepsilon(t)\|_{H^{1}}^{3}+e^{-\frac{\sigma_{0}}{12} L}+\sum_{j=1}^{N}\left|c_{j}(t)-c_{j}(0)\right|^{2}\right) \\
& \leqslant K\left(\|\varepsilon(0)\|_{H^{1}}^{2}+\|\varepsilon(t)\|_{H^{1}}^{3}+e^{-\frac{\sigma_{0}}{12} L}\right)
\end{aligned}
$$

Thus, by (3.10), and $c_{j}(t)-c_{j-1}(t)>\sigma_{0}$, we obtain

$$
\left(\mathcal{L}_{N} \varepsilon(t), \varepsilon(t)\right) \leqslant K\left(\|\varepsilon(0)\|_{H^{1}}^{2}+\|\varepsilon(t)\|_{H^{1}}^{3}+e^{-\frac{\sigma_{0}}{12} L}\right)
$$

By Lemma 2.3, we have $\left(\mathcal{L}_{N} \varepsilon, \varepsilon\right) \geqslant \lambda_{0}\|\varepsilon(t)\|_{H^{1}}^{2}$, and so we obtain (ii). Thus Lemma 3.1 is proved.

Conclusion of the proof of Proposition 3.1. By (3.5) and Lemma 3.1, we have

$$
\begin{aligned}
\| u(t) & -\sum_{j=1}^{N} \varphi_{c_{j}^{0}}\left(x-x_{j}(t)\right) \|_{H^{1}} \\
& \leqslant\left\|u \varphi(t)-\sum_{j=1}^{N} R_{j}(t)\right\|_{H^{1}}+\left\|\sum_{j=1}^{N} R_{j}(t)-\sum_{j=1}^{N} \varphi_{c_{j}^{0}}\left(x-x_{j}(t)\right)\right\|_{H^{1}} \\
& \leqslant\|\varepsilon(t)\|_{H^{1}}+C \sum_{j=1}^{N}\left|c_{j}(t)-c_{j}^{0}\right| \\
& \leqslant\|\varepsilon(t)\|_{H^{1}}+C \sum_{j=1}^{N}\left|c_{j}(t)-c_{j}(0)\right|+C \sum_{j=1}^{N}\left|c_{j}(0)-c_{j}^{0}\right| \\
& \leqslant\|\varepsilon(t)\|_{H^{1}}+C\left(\|\varepsilon(0)\|_{H^{1}}^{2}+e^{-\frac{\sigma_{0}}{12} L}\right)+C K_{1} \alpha \\
& \leqslant K\left(\alpha+e^{-\frac{\sigma_{0}}{24} L}\right)
\end{aligned}
$$

where $K>0$ is a constant independent of $A_{0}$. Thus the proposition is proved with $A_{0}=2 K$, and $A_{0} \alpha_{0}$ small enough.

## 4. Proof of the asymptotic stability

4.1. Rigidity property. Together with the monotonicity property described in Lemma 2.1, the second main ingredient of the proof of the asymptotic stability of the family of solitary waves in $[\mathbf{6}],[\mathbf{1 7}]$ is the following rigidity property.

ThEOREM $4.1([\mathbf{6}],[\mathbf{1 7}])$. Let $p=2,3$. Let $u_{0} \in H^{1}(\mathbb{R})$. There exists a set $E \subset(1,+\infty)$ without accumulation points ( $E$ may be empty) such that, for any $c_{0} \in(1,+\infty) \backslash E$, there exists $\alpha_{1}>0$ such that if

$$
\begin{equation*}
\left\|u_{0}-\varphi_{c_{0}}\right\|_{H^{1}}<\alpha_{1} \tag{4.1}
\end{equation*}
$$

and if the corresponding solution $u(t)$ of (1.1) satisfies : for all $\delta>0$, there exists $B_{\delta}>0$ such that for all $t \in \mathbb{R}$,

$$
\begin{equation*}
\int_{|x|>B_{\delta}}\left(u^{2}+u_{x}^{2}\right)(t, x+y(t)) d x<\delta \tag{4.2}
\end{equation*}
$$

for some function $y(t)$, then there exists $x_{1} \in \mathbb{R}$, and $c_{1}>1$ such that

$$
u(t, x)=\varphi_{c_{1}}\left(x-x_{1}-c_{1} t\right)
$$

for all $(t, x) \in \mathbb{R} \times \mathbb{R}$.
An analogous result, without the restriction of the set $E$, was proved in [12] for the subcritical gKdV equations. Recall that property (4.2) implies (without assumption (4.1) of closeness to $\varphi_{c_{0}}$ ) complete smoothness and exponential decay of the solution $u(t)$ of the gBBM equation (see Theorem 1.1 in [ $\mathbf{7}]$ ).

Recall also that the proof of Theorem 4.1 is mainly based on a rigidity property of a linear equation:

$$
\begin{equation*}
\left(1-\partial_{x}^{2}\right) w_{t}-\partial_{x}\left(-c \partial_{x}^{2} w+(c-1) w-p \varphi_{c}^{p-1} w\right)=0 \tag{4.3}
\end{equation*}
$$

The proof of this linear property in [6] uses a spectral result due to Miller and Weinstein $[\mathbf{1 6}]$, and for this reason requires the introduction of the set $E$. For the gKdV equation, the proof of the linear rigidity property is obtained in a different way, see [12].

We turn now to the proof of Theorem 1.2. By Theorem 1.1, the solution $u(t)$ is close to the sum of $N$ solitary waves for all time $t \geqslant 0$, and admits a decomposition as in Proposition 2.1. The proof of Theorem 1.2 then proceeds into two steps. First, using Theorem 4.1 and monotonicity properties, we prove the convergence of $\varepsilon(t)$ to 0 around each solitary wave ( $\S 4.2$ ). Second, we prove convergence of $\varepsilon(t)$ in $H^{1}$ in the region $x>\frac{1+c_{1}^{0}}{2} t$ by monotonicity arguments (§4.3).
4.2. Convergence around the solitary waves. We claim the following convergence result.

Proposition 4.1. Under the assumptions of Theorem 1.2, for any $j \in\{1, \ldots, N\}$, there exists $c_{j}^{+\infty} \in(1,+\infty) \backslash E$ such that

$$
\begin{equation*}
\varepsilon\left(t, .+x_{j}(t)\right) \rightarrow 0 \quad \text { in } H_{l o c}^{1}, \quad c_{j}(t) \rightarrow c_{j}^{+\infty}, \quad \dot{x}_{j}(t) \rightarrow c_{j}^{+\infty}, \quad \text { as } t \rightarrow+\infty \tag{4.4}
\end{equation*}
$$

Proof. Proposition 4.1 is a property of the flow of the $g B B M$ equation around the solitary waves, which is a consequence of the rigidity property Theorem 4.1. We sketch the argument, which follows the strategy of section 4 of [6], and we refer to $[\mathbf{6}]$ for more details. Let $j \in\{1, \ldots, N\}$.

First, we prove that $\varepsilon\left(t, .+x_{j}(t)\right) \rightharpoonup 0$ in $H^{1}(\mathbb{R})$. For the sake of contradiction, assume that there exists $\tilde{\varepsilon}_{0} \in H^{1}(\mathbb{R}), \tilde{\varepsilon}_{0} \not \equiv 0$, and $\tilde{c}_{0}>1$, such that for a sequence $t_{n} \rightarrow+\infty$,

$$
\varepsilon\left(t_{n}, .+x_{j}\left(t_{n}\right)\right) \rightharpoonup \tilde{\varepsilon}_{0} \quad \text { in } H^{1}, \quad c_{j}\left(t_{n}\right) \rightarrow \tilde{c}_{0} \quad \text { as } n \rightarrow+\infty
$$

Consider the solution $\tilde{u}(t)$ of the gBBM equation with initial data $\tilde{u}_{0} \equiv \varphi_{\tilde{c}_{0}}+\tilde{\varepsilon}_{0}$. It also admits a decomposition, with parameters $\tilde{c}(t), \tilde{x}(t)$ and $\tilde{\varepsilon}(t)$. By weak convergence and uniqueness of the decomposition of $\tilde{u}_{0}$, we have $\tilde{\varepsilon}(0)=\tilde{\varepsilon}_{0}, \tilde{c}(0)=\tilde{c}_{0}$ and $\tilde{x}(0)=0$.

By the arguments of the proof of Lemma 4.2 of $[\mathbf{6}]$ (see also Lemma 6 in $[\mathbf{1 7}]$ ), we have

$$
\begin{equation*}
u\left(t_{n}+t, .+x\left(t_{n}+t\right)\right) \rightarrow \tilde{u}(t, .+\tilde{x}(t)) \quad \text { in } H_{l o c}^{1} \text { as } n \rightarrow+\infty \tag{4.5}
\end{equation*}
$$

Here, we obtain convergence in $H_{l o c}^{1}$ from a convergence in $H^{1}$ weak, which is a special feature of the gBBM equation, described in the proof of Lemma 4.2 in [6]. The main ingredient is that if $u\left(t_{n}\right)$ converges weakly in $H^{1}$ then by the equation of $u, u_{t}\left(t_{n}\right)$ converges weakly in $H^{2}$.

This convergence result and the monotonicity property (Lemma 2.1) imply that $\tilde{u}$ satisfies the assumptions of Theorem 4.1, and thus is equal to a solitary wave solution. We omit the detail of the proof since it is similar to Proposition 4.1 in $[\mathbf{6}]$. Since $\tilde{u}(0)=\varphi_{\tilde{c}_{0}}+\tilde{\varepsilon}_{0}=\varphi_{c^{*}}\left(.-x^{*}\right)$, for some $c^{*}>1, x^{*} \in \mathbb{R}$, by uniqueness of the decomposition of $\tilde{u}(0)$, we have $c^{*}=\tilde{c}_{0}$ and $\tilde{\varepsilon}_{0} \equiv 0$, which is a contradiction.

Second, from the weak convergence to zero, we obtain as in (4.5) a strong convergence result: $\varepsilon\left(t, .+x_{j}(t)\right) \rightarrow 0$ in $H_{l o c}^{1}(\mathbb{R})$.

Finally, the convergence of $c_{j}(t)$ to some limit value $c_{j}^{+\infty}$ is a consequence of another monotonicity property of the gBBM equation, true on quantities related to the energy conservation:

$$
\mathcal{J}_{j}(t)=\int\left(\frac{1}{2} u^{2}+\frac{1}{p+1} u^{p+1}\right)(t, x) \psi_{j}(t, x) d x
$$

We refer to Proposition 4.2 in [6] for the proof.
4.3. Asymptotic behavior for $x>\frac{1+c_{1}^{0}}{2} t$. Now, we prove the following result, which completes the proof of Theorem 1.2.

Proposition 4.2. Under the assumptions of Theorem 1.2, the following holds

$$
\begin{equation*}
\|\varepsilon(t)\|_{H^{1}\left(x>\frac{1+c_{1}^{0}}{2} t\right)} \rightarrow 0 \quad \text { as } t \rightarrow+\infty \tag{4.6}
\end{equation*}
$$

The proof of this Proposition is based only on Proposition 4.1 and monotonicity properties. It is very similar to the proof of Proposition 3 in [14], but we repeat the proof for the reader's convenience.
Proof. Set $\gamma_{0}=\sigma_{0} / 24$. Let $y_{0}>0$. First, using the arguments of the proof of Lemma 2.1, we have

$$
\begin{aligned}
& \int\left(u^{2}+u_{x}^{2}\right)(t, x) \psi\left(x-y_{0}-x_{N}(t)\right) d x \\
& \leqslant \int\left(u^{2}+u_{x}^{2}\right)(0, x) \psi\left(x-y_{0}-x_{N}(0)-\frac{\sigma_{0}}{2} t\right) d x+C e^{-\gamma_{0} y_{0}}
\end{aligned}
$$

Therefore, by the decay properties of $\varphi_{c}$, we obtain
$\int_{x>x_{N}(t)+y_{0}}\left(\varepsilon^{2}+\varepsilon_{x}^{2}\right)(t) \leqslant 2 \int\left(u^{2}+u_{x}^{2}\right)(0, x) \psi\left(x-y_{0}-x_{N}(0)-\frac{\sigma_{0}}{2} t\right) d x+C e^{-\gamma_{0} y_{0}}$.
Since, for fixed $y_{0}, \int_{x_{N}(t)<x<x_{N}(t)+y_{0}}\left(\varepsilon^{2}+\varepsilon_{x}^{2}\right)(t, x) d x \rightarrow 0$ as $t \rightarrow+\infty$ (by Proposition 4.1), we obtain

$$
\lim _{t \rightarrow+\infty} \int_{x>x_{N}(t)}\left(\varepsilon^{2}+\varepsilon_{x}^{2}\right)(t, x) d x=0
$$

Now, we prove that for all $j, \int_{x>x_{j}(t)}\left(\varepsilon^{2}+\varepsilon_{x}^{2}\right)(t) \rightarrow 0$ as $t \rightarrow+\infty$, by backwards induction on $j$. Assume that for $j_{0} \in\{1, \ldots, N\}$, we have $\int_{x>x_{j_{0}}(t)}\left(\varepsilon^{2}+\varepsilon_{x}^{2}\right)(t) \rightarrow 0$ as $t \rightarrow+\infty$. For $t \geqslant 0$ large enough, there exists $0<t^{\prime}=t^{\prime}(t)<t$, satisfying

$$
x_{j_{0}}\left(t^{\prime}\right)-x_{j_{0}-1}\left(t^{\prime}\right)-\frac{\sigma_{0}}{2}\left(t-t^{\prime}\right)=2 y_{0} .
$$

Indeed, for $t$ large enough, $x_{j_{0}}(t)-x_{j_{0}-1}(t) \geqslant \frac{\sigma_{0}}{2} t \geqslant 2 y_{0}$, and $x_{j_{0}}(0)-x_{j_{0}-1}(0)-$ $\frac{\sigma_{0}}{2} t<0<2 y_{0}$. Then,

$$
\begin{align*}
& \int \psi\left(.-\left(x_{j_{0}-1}(t)+y_{0}\right)\right)\left(u^{2}+u_{x}^{2}\right)(t)  \tag{4.7}\\
& \leqslant \int \psi\left(.-\left(x_{j_{0}-1}\left(t^{\prime}\right)+\frac{\sigma_{0}}{2}\left(t-t^{\prime}\right)+y_{0}\right)\right)\left(u^{2}+u_{x}^{2}\right)\left(t^{\prime}\right)+C e^{-\gamma_{0} y_{0}} \\
& \leqslant \int \psi\left(.-\left(x_{j_{0}}\left(t^{\prime}\right)-y_{0}\right)\right)\left(u^{2}+u_{x}^{2}\right)\left(t^{\prime}\right)+C e^{-\gamma_{0} y_{0}} \tag{4.8}
\end{align*}
$$

Since $t^{\prime}(t) \rightarrow+\infty$ as $t \rightarrow+\infty$, by $H_{l o c}^{1}$ convergence of $\varepsilon\left(t, .+x_{j_{0}}(t)\right)$ and the induction assumption, we have, for fixed $y_{0}$,

$$
\lim _{t \rightarrow+\infty} \int_{x>x_{j_{0}}\left(t^{\prime}\right)-2 y_{0}}\left(\varepsilon^{2}+\varepsilon_{x}^{2}\right)\left(t^{\prime}\right)=0
$$

Therefore, by Proposition 4.1,

$$
\begin{equation*}
\limsup _{t \rightarrow+\infty} \int \psi\left(.-\left(x_{j_{0}}\left(t^{\prime}\right)-y_{0}\right)\right)\left(u^{2}+u_{x}^{2}\right)\left(t^{\prime}\right)-\sum_{k=j_{0}}^{N} m\left(\varphi_{c_{k}^{+\infty}}\right) \leqslant C e^{-\gamma_{0} y_{0}} \tag{4.9}
\end{equation*}
$$

Moreover, by the decomposition of $u(t)$,

$$
\begin{aligned}
& \int \psi\left(.-\left(x_{j_{0}-1}(t)+y_{0}\right)\right)\left(\varepsilon^{2}+\varepsilon_{x}^{2}\right)(t) \\
& \leqslant \int \psi\left(.-\left(x_{j_{0}-1}(t)+y_{0}\right)\right)\left(u^{2}+u_{x}^{2}\right)(t)-\sum_{k=j_{0}}^{N} m\left(\varphi_{c_{k}(t)}\right)+C e^{-\gamma_{0} y_{0}}
\end{aligned}
$$

and since $c_{k}(t) \rightarrow c_{k}^{+\infty}$, we obtain by (4.8):

$$
\lim _{t \rightarrow+\infty} \int_{x>x_{j_{0}-1}(t)+y_{0}}\left(\varepsilon^{2}+\varepsilon_{x}^{2}\right)(t, x) d x=0
$$

and so

$$
\lim _{t \rightarrow+\infty} \int_{x>x_{j_{0}-1}(t)}\left(\varepsilon^{2}+\varepsilon_{x}^{2}\right)(t, x) d x=0
$$

Thus the induction argument yields

$$
\lim _{t \rightarrow+\infty} \int_{x>x_{1}(t)}\left(\varepsilon^{2}+\varepsilon_{x}^{2}\right)(t, x) d x=0
$$

Finally, we prove $\int_{x>\frac{1+c_{1}^{0}}{2} t}\left(\varepsilon^{2}+\varepsilon_{x}^{2}\right)(t) \rightarrow 0$ as $t \rightarrow+\infty$. Indeed, let $0<t^{\prime}=$ $t^{\prime}(t)<t$ such that $x_{1}\left(t^{\prime}\right)-t^{\prime}-\frac{c_{1}^{0}-1}{4}\left(t+t^{\prime}\right)=y_{0}$. Then, for $\sup _{t \geqslant 0}\|\varepsilon(t)\|_{H^{1}}$ small
enough, applying the arguments of Lemma 2.1, we obtain

$$
\begin{aligned}
& \int \psi\left(x-\frac{1+c_{1}^{0}}{2} t\right)\left(u^{2}+u_{x}^{2}\right)(t) \\
& \leqslant \int \psi\left(x-\left(\frac{1+c_{1}^{0}}{2} t^{\prime}+\frac{c_{1}^{0}-1}{4}\left(t-t^{\prime}\right)\right)\right)\left(u^{2}+u_{x}^{2}\right)\left(t^{\prime}\right)+C e^{-\gamma_{0} y_{0}} \\
& \leqslant \int \psi\left(x-\left(x_{1}\left(t^{\prime}\right)-y_{0}\right)\right)\left(u^{2}+u_{x}^{2}\right)\left(t^{\prime}\right)+C e^{-\gamma_{0} y_{0}}
\end{aligned}
$$

The conclusion is obtained as before.

## 5. Existence and uniqueness of $N$ solitary waves

The aim of this section is to prove Theorem 1.3, i.e. the existence and uniqueness of an asymptotic $N$ solitary wave solution. It follows the strategy of [11].

The existence part is done into three steps. First, we consider an increasing sequence $S_{n} \rightarrow+\infty$, and a sequence $\left(u_{n}\right)_{n \in \mathbb{N}}$ of global solutions of (1.1) such that $u_{n}\left(S_{n}\right)$ is equal to the sum of $N$ solitary waves. The desired solution is obtained as the limit of the sequence $\left(u_{n}(t)\right)$, provided we have uniform estimates in $H^{s}$. The second step is devoted to the proof of the $H^{1}$ uniform estimate, which is an adaptation of the stability result (section 3 ). Then, for $s \geqslant 2, H^{s}$-estimates are deduced by computation of the variation in time of norms of $\left(u_{n}\right)_{n \in \mathbb{N}}$.

Finally, the uniqueness part is proved using a refined version of the mass monotonicity.

Let $p \geqslant 2$ be an integer, let $N \in \mathbb{N}, c^{*}(p)<c_{1}^{0}<c_{2}^{0}<\ldots<c_{N}^{0}$, and $x_{1}^{0}, \ldots, x_{N}^{0} \in \mathbb{R}$. Let $\sigma_{0}$ be as in (2.2). We denote by

$$
R(t, x)=\sum_{j=1}^{N} \varphi_{c_{j}^{0}}\left(x-x_{j}^{0}-c_{j}^{0} t\right)
$$

the sum of the $N$ solitary wave solutions of (1.1) associated to $c_{j}^{0}$ and $x_{j}^{0}$.
5.1. Construction of a solution assuming uniform estimates. Let $\left(S_{n}\right)_{n \in \mathbb{N}}$ be an increasing sequence of $\mathbb{R}^{+}$such that $S_{n} \rightarrow+\infty$ as $n \rightarrow+\infty$. For $n>0$ integer, we define $u_{n}(t)$, the solution of

$$
\begin{equation*}
u_{n}\left(S_{n}\right)=R\left(S_{n}\right), \quad\left(1-\partial_{x}^{2}\right)\left(u_{n}\right)_{t}+\left(u_{n}+u_{n}^{p}\right)_{x}=0 \tag{5.1}
\end{equation*}
$$

Note that $u_{n} \in C\left(\mathbb{R}, H^{s}(\mathbb{R})\right)$, for all $s \geqslant 1$. We claim that this sequence satisfies the following uniform estimates :

Proposition 5.1. Consider the sequence $\left(u_{n}\right)_{n \in \mathbb{N}}$ of solutions of (5.1). There exist $\gamma_{1}, T_{1}>0$ such that: for any $s \geqslant 1$ there exists a constant $A_{s}>0$, for which $u_{n}$ satisfies the following estimates for all $n>0$ and for all $t \in\left[T_{1}, S_{n}\right]$ :

$$
\begin{equation*}
\left\|u_{n}(t)-R(t)\right\|_{H^{s}(\mathbb{R})} \leqslant A_{s} e^{-\gamma_{1} t} . \tag{5.2}
\end{equation*}
$$

This result is the main step of the proof of the existence in Theorem 1.3, it is proved in sections $5.2,5.3$. We assume that $S_{n} \geqslant T_{1}$, by possibly taking a subsequence of $\left(S_{n}\right)_{n \in \mathbb{N}}$ satisfying this property. Note that the constants $A_{s}$ do not depend on $n$. Thus, assuming this Proposition we prove that the sequence $\left(u_{n}\left(T_{1}\right)\right)_{n \in \mathbb{N}}$ is $H^{1}$-localized. This allows us to construct the $N$-solitary wave solution as the solution of the gBBM equation emanating from the limit of $\left(u_{n}\left(T_{1}\right)\right)_{n \in \mathbb{N}}$ when $n \rightarrow+\infty$. More precisely,

Lemma 5.1. For all $\delta>0$, there exists $B_{\delta}>0$ such that : for all $n \geqslant 1$,

$$
\begin{equation*}
\int_{|x|>B_{\delta}}\left(u_{n}^{2}+u_{n x}^{2}\right)\left(T_{1}, x\right) d x<\delta . \tag{5.3}
\end{equation*}
$$

Proof. Fix $\delta>0$. From (5.2) and the decay of solitary waves, there exists $B_{1}>0$ and $t_{0}>T_{1}$ such that for all $n \in \mathbb{N}$

$$
\begin{equation*}
\left\|u_{n}\left(t_{0}\right)\right\|_{H^{1}\left(|x|>B_{1}\right)}^{2}<\delta / 2 \tag{5.4}
\end{equation*}
$$

We fix such value of $B_{1}$ and $t_{0}$ and we study the evolution of the $H^{1}(|x|>B)$-norm of $u_{n}(t)$ between $T_{1}$ and $t_{0}$. Let $g: \mathbb{R} \rightarrow[0,1]$, be a $C^{1}$ function, such that $g \equiv 0$ on $[-1,1], g \equiv 1$ on $\mathbb{R} \backslash[-2,2]$, and $\sup _{x \in \mathbb{R}}\left|g^{\prime}(x)\right| \leqslant 2$. We introduce for $B>0$, to be fixed later,

$$
J_{n}(t)=\int\left(u^{2}(t, x)+u_{x}^{2}(t, x)\right) g\left(\frac{x}{B}\right) d x
$$

Differentiating $J_{n}(t)$ with respect to time, using the gBBM equation, and integrating by parts, we find :

$$
\begin{aligned}
J_{n}^{\prime}(t)= & -\frac{1}{B} \int\left(u_{n}^{2}(t)+\frac{2}{p+1} u_{n}^{p+1}(t)\right) g^{\prime}\left(\frac{x}{B}\right) d x \\
& +\frac{2}{B} \int g^{\prime}\left(\frac{x}{B}\right) u_{n}(t)\left(1-\partial_{x}^{2}\right)^{-1}\left(u_{n}(t)+u_{n}^{p}(t)\right) d x
\end{aligned}
$$

Note that $u_{n}(t)$ is bounded in $H^{1}$ uniformly in $t$ and $n$. This implies that for all $n \in \mathbb{N}$ and for all $t \in\left[T_{1}, t_{0}\right],\left|J_{n}^{\prime}(t)\right| \leqslant C_{2} / B$, where $C_{2}$ is independent of $n$. Thus, taking $B=\max \left(1, B_{1}, \frac{C_{2}\left(t_{0}-T_{1}\right)}{\delta}\right)$ implies $\left|J_{n}^{\prime}(t)\right| \leqslant \frac{\delta}{2\left(t_{0}-T_{1}\right)}$, and so

$$
\begin{equation*}
J_{n}\left(T_{1}\right) \leqslant J_{n}\left(t_{0}\right)+\delta / 2 \leqslant\left\|u_{n}\left(t_{0}\right)\right\|_{H^{1}\left(|x|>B_{1}\right)}^{2}+\delta / 2 \leqslant \delta \tag{5.5}
\end{equation*}
$$

To achieve the proof of Lemma 5.1, we note that $\left\|u_{n}\left(T_{1}\right)\right\|_{H^{1}(|x|>2 B)}^{2} \leqslant J_{n}\left(T_{1}\right)$.
We are now able to construct the $N$-solitary wave solution. Indeed, from the uniform $H^{2}$-estimate, (corresponding to the case $s=2$ in (5.2)), and the fact that $R(t)$ in uniformly bounded in $H^{2}(\mathbb{R})$, it follows that $\left(u_{n}\right)_{n \in \mathbb{N}}$ is uniformly bounded in $H^{2}(\mathbb{R})$. Thus there exists $U_{T_{1}} \in H^{2}(\mathbb{R})$, such that $u_{n}\left(T_{1}\right) \rightarrow U_{T_{1}}$ in $H_{l o c}^{1}(\mathbb{R})$. From Lemma 5.1, it follows that $u_{n}\left(T_{1}\right) \rightarrow U_{T_{1}}$ in $H^{1}(\mathbb{R})$.

Note also that by $(5.2),\left(u_{n}\right)_{n \in \mathbb{N}}$ is uniformly bounded in $H^{s}(\mathbb{R})$, for all $s \geqslant 1$. Thus by interpolation between $H^{1}(\mathbb{R})$ and $H^{2 s-2}(\mathbb{R})$ for $s \geqslant 2$, we deduce that $U_{T_{1}} \in H^{s}(\mathbb{R})$, and

$$
\begin{equation*}
u_{n}\left(T_{1}\right) \rightarrow U_{T_{1}} \text { in } H^{s}(\mathbb{R}), \text { for all } s \geqslant 1 \tag{5.6}
\end{equation*}
$$

Now, we define the $N$-solitary waves solution $U$, as the unique solution of

$$
\left\{\begin{array}{l}
\left(1-\partial_{x}^{2}\right) U_{t}+\left(U+U^{p}\right)_{x}=0, \quad(t, x) \in \mathbb{R} \times \mathbb{R}  \tag{5.7}\\
U\left(T_{1}, x\right)=U_{T_{1}}(x), x \in \mathbb{R}
\end{array}\right.
$$

The Cauchy problem of this equation is globally well posed in $H^{s}(\mathbb{R})$ for all $s \in$ $\mathbb{R}$, thus $U \in C\left(\mathbb{R}, H^{s}(\mathbb{R})\right)$. Recall that the Cauchy problem is solved via the contraction principle, which ensures the continuity of the flow of the gBBM equation in $H^{s}(\mathbb{R})$. It follows from (5.6) that for all $t, U_{n}(t) \rightarrow U(t)$ in $H^{s}$, and so passing to the limit as $n \rightarrow+\infty$ in (5.2), we get, for all $s \geqslant 1$, for any $t \geqslant T_{1}$,

$$
\begin{equation*}
\|U(t)-R(t)\|_{H^{s}} \leqslant A_{s} e^{-\gamma_{1} t} \tag{5.8}
\end{equation*}
$$

This estimate also holds for $t \in\left[0, T_{1}\right]$ by possibly taking larger $A_{s}$. Thus, the proof of the existence in Theorem 1.3 is reduced to the proof of Proposition 5.1.
5.2. $H^{1}$ estimate. We claim the following result.

Proposition 5.2. There exists $T_{1}>0, A_{1}>0, \alpha_{1}>0$ with $A_{1} e^{-\sigma_{0}^{2} T_{1} / 24} \leqslant$ $\alpha_{1} / 2$ such that, for all $n \geqslant 0$, if for some $t^{*} \in\left[T_{1}, S_{n}\right]$, for all $t \in\left[t^{*}, S_{n}\right]$,

$$
\begin{equation*}
\left\|u_{n}(t)-R(t)\right\|_{H^{1}} \leqslant \alpha_{1} \tag{5.9}
\end{equation*}
$$

then, for all $t \in\left[t^{*}, S_{n}\right]$,

$$
\begin{equation*}
\left\|u_{n}(t)-R(t)\right\|_{H^{1}} \leqslant A_{1} e^{-\frac{\sigma_{0}^{2}}{24} t} \tag{5.10}
\end{equation*}
$$

This implies (5.2) for $s=1$. Indeed, if we assume Proposition 5.2, since $u_{n}\left(S_{n}\right)=R\left(S_{n}\right)$, by continuity of $u_{n}(t)$ and $R(t)$ in time in $H^{1}(\mathbb{R})$, there exists $\tau_{0}=\tau_{0}(n)>0$ such that (5.9) is true on the interval $\left[S_{n}-\tau_{0}, S_{n}\right]$. Let

$$
t^{*}=t^{*}(n)=\inf \left\{T_{1} \leqslant t \leqslant S_{n},\left\|u_{n}\left(t^{\prime}\right)-R\left(t^{\prime}\right)\right\|_{H^{1}} \leqslant \alpha_{1}, \forall t^{\prime} \in\left[t, S_{n}\right]\right\}
$$

Looking for contradiction, we assume that $t^{*}>T_{1}$, then by Proposition 5.2, we have for all $t \in\left[t^{*}, S_{n}\right],\left\|u_{n}(t)-R(t)\right\|_{H^{1}} \leqslant A_{1} e^{-\sigma_{0}^{2} t / 24} \leqslant A_{1} e^{-\sigma_{0}^{2} T_{1} / 24} \leqslant \alpha_{1} / 2$. Thus, by continuity in $H^{1}(\mathbb{R})$, there exists $\tau_{1}=\tau_{1}(n)>0$ such that $\left\|u_{n}(t)-R(t)\right\|_{H^{1}} \leqslant \frac{3}{4} \alpha_{1}$ for all $t \in\left[t^{*}-\tau_{1}, S_{n}\right]$, which is a contradiction with the definition of $t^{*}$. Therefore, $t^{*}=T_{1}$ and (5.10) holds on $\left[T_{1}, S_{n}\right]$.
Proof of Proposition 5.2. The proof follows the same lines as the proof of the $H^{1}$ stability result (Proposition 3.1). However, we point out two main differences : first, we consider here stability of solution emanating exactly from the sum of $N$ solitary waves $u_{n}\left(S_{n}\right)=R\left(S_{n}\right)$, i.e. $\varepsilon\left(S_{n}\right) \equiv 0$. Second, the $H^{1}$ estimate is proved backwards in time on $\left[t^{*}, S_{n}\right]$. Since the gBBM equation is invariant under the transformation $x \rightarrow-x, t \rightarrow t$, if we simply reverse time, the solitary waves are sorted by decreasing sizes, and we cannot apply directly the proof of Section 3.

In what follows, $u_{n}$ will be denoted by $u$ for the sake of simplicity. We assume that (5.9) holds. Then, assuming $\alpha_{1}$ small enough and $T_{1}$ large enough, we use the results of Section 2 concerning the modulation of the solution. We obtain:

- There exist unique $C^{1}$ functions

$$
c_{j}:\left[t^{*}, S_{n}\right] \rightarrow\left(c^{\star}(p),+\infty\right), \quad x_{j}:\left[t^{*}, S_{n}\right] \rightarrow \mathbb{R}
$$

such that if we define $\varepsilon$ by

$$
\varepsilon(t)=u(t)-\sum_{j=1}^{N} R_{j}(t), \text { where } R_{j}(t)=\varphi_{c_{j}(t)}\left(\cdot-x_{j}(t)\right)
$$

then the following properties are satisfied for all $j \in\{1, \cdots, N\}$, for all $t \in\left[t^{*}, S_{n}\right]$ :

$$
\begin{gather*}
\int \varepsilon(t)\left(1-\partial_{x}^{2}\right) R_{j}(t) d x=\int \varepsilon(t)\left(1-\partial_{x}^{2}\right) \partial_{x} R_{j}(t) d x=0  \tag{5.11}\\
\|\varepsilon(t)\|_{H^{1}}+\sum_{j=1}^{N}\left|c_{j}(t)-c_{j}^{0}\right| \leqslant K \alpha_{1}  \tag{5.12}\\
\left|\dot{c}_{j}(t)\right|+\left|\dot{x}_{j}(t)-c_{j}(t)\right| \leqslant K\left(\int e^{-\sigma_{0}\left|x-x_{j}(t)\right|} \varepsilon^{2}(t) d x\right)^{\frac{1}{2}}+K e^{-\frac{\sigma_{0} t}{4}}, \tag{5.13}
\end{gather*}
$$

for some constant $K>0$.
Following the strategy of section 3 , we first control the variation of the velocities: there exist $C_{1}>0$, such that for all $t \in\left[t^{*}, S_{n}\right]$,

$$
\begin{equation*}
\sum_{j=1}^{N}\left|c_{j}\left(S_{n}\right)-c_{j}(t)\right| \leqslant C_{1}\left(\|\varepsilon(t)\|_{H^{1}}^{2}+e^{-\frac{\sigma_{0}}{12} t}\right) \tag{5.14}
\end{equation*}
$$

To conclude the proof, it remains to estimate $\|\varepsilon(t)\|_{H^{1}}$, this is the main difficulty in the proof of Proposition 5.2. We need to introduce a new monotonicity property.

First, we introduce some notations. For $j=2, \cdots, N$, and $\psi_{j}$ defined as in section 2.2, we set

$$
m_{j}^{R}(t)=\frac{1}{2} \int\left(u^{2}(t, x)+u_{x}^{2}(t, x)\right) \psi_{j}(t, x) d x
$$

and

$$
\begin{equation*}
E_{j}^{R}(t)=\frac{1}{2} \int\left(u^{2}(t, x)+\frac{2}{p+1} u^{p+1}(t, x)\right) \psi_{j}(t, x) d x \tag{5.15}
\end{equation*}
$$

In the same way we introduce for $j=1, \cdots, N-1$

$$
m_{j}^{L}(t)=\frac{1}{2} \int\left(u^{2}(t, x)+u_{x}^{2}(t, x)\right)\left(1-\psi_{j+1}(t, x)\right) d x
$$

and

$$
E_{j}^{L}(t)=\frac{1}{2} \int\left(u^{2}(t, x)+\frac{2}{p+1} u^{p+1}(t, x)\right)\left(1-\psi_{j+1}(t, x)\right) d x
$$

Remark that

$$
\begin{equation*}
m(u(t))=m_{j}^{L}(t)+m_{j+1}^{R}(t), \text { and } E(u(t))=E_{j}^{L}(t)+E_{j+1}^{R}(t) \tag{5.16}
\end{equation*}
$$

In order to write a new monotonicity property, we introduce

$$
\rho(t, x)=\frac{c_{N}^{0}}{c_{N}^{0}-1}+\sum_{j=1}^{N-1}\left(\frac{c_{j}^{0}}{c_{j}^{0}-1}-\frac{c_{j+1}^{0}}{c_{j+1}^{0}-1}\right)\left(1-\psi_{j+1}\right)(t, x)
$$

and we define

$$
\begin{align*}
H(t)= & \frac{1}{2} \int\left\{\rho(t, x)\left(u^{2}(t, x)+u_{x}^{2}(t, x)\right)-(\rho(t, x)-1)\left(u^{2}(t, x)\right.\right. \\
& \left.\left.+\frac{2}{p+1} u^{p+1}(t, x)\right)\right\} d x \tag{5.17}
\end{align*}
$$

Observe that locally around $x_{j}(t), \rho$ is close to $\frac{c_{j}^{0}}{c_{j}^{0}-1}$, and thus $\rho$ is close to $c_{j}^{0}(\rho-1)$.
This is crucial in the definition of $H(t)$. Note also that $\frac{c_{j}^{0}}{c_{j}^{0}-1}$ is decreasing with respect to $j$, and thus $\rho$ is decreasing in $x$.

We can write $H$ in terms of $m_{j}^{L}$ and $E_{j}^{L}$ :

$$
\begin{align*}
H(t) & =\sum_{j=1}^{N}\left[\left(\frac{c_{j}^{0}}{c_{j}^{0}-1}-\frac{c_{j+1}^{0}}{c_{j+1}^{0}-1}\right) m_{j}^{L}(t)-\left(\frac{1}{c_{j}^{0}-1}-\frac{1}{c_{j+1}^{0}-1}\right) E_{j}^{L}(t)\right] \\
8) & =\sum_{j=1}^{N} r_{j}\left(m_{j}^{L}(t)-E_{j}^{L}(t)\right) \tag{5.18}
\end{align*}
$$

where $c_{N+1}=0, r_{j}=\left(\frac{c_{j}^{0}}{c_{j}^{0}-1}-\frac{c_{j+1}^{0}}{c_{j+1}^{0}-1}\right)=\left(\frac{1}{c_{j}^{0}-1}-\frac{1}{c_{j+1}^{0}-1}\right)$, and $m_{N}^{L}(t)=m(u(t))$, $E_{N}^{L}(t)=E(u(t))$. We also introduce

$$
(\tilde{\mathcal{L}} \varepsilon, \varepsilon)=\frac{1}{2} \int\left(\rho(t, x)\left(\varepsilon^{2}+\varepsilon_{x}^{2}\right)(t, x)-(\rho(t, x)-1)\left(\varepsilon^{2}+p R^{p-1} \varepsilon^{2}\right)(t, x)\right) d x
$$

It is easy to check that $\tilde{\mathcal{L}}$ satisfies the same positivity property as $\mathcal{L}_{N}$ under the orthogonality conditions on $\varepsilon(t)$ (see Lemma 2.3), thus there exists $\lambda_{1}>0$ such that

$$
\begin{equation*}
(\tilde{\mathcal{L}} \varepsilon, \varepsilon) \geqslant \lambda_{1}\|\varepsilon(t)\|_{H^{1}}^{2} \tag{5.19}
\end{equation*}
$$

Now we define, for $\gamma>0$ :

$$
H^{\gamma}(t)=H(t)+\frac{\gamma}{2} \int \rho(t, x)\left(u^{2}(t, x)+u_{x}^{2}(t, x)\right) d x
$$

In order to fix $\gamma$, we need to remark that using (5.14), there exists $C_{3}>0$, such that for all $t \in\left[t^{*}, S_{n}\right]$,

$$
\begin{equation*}
\sum_{j=1}^{N} \frac{c_{j}^{0}}{c_{j}^{0}-1} \Delta_{t}^{S_{n}} m\left(R_{j}\right) \leqslant C_{3}\left(\|\varepsilon(t)\|_{H^{1}}^{2}+e^{-\frac{\sigma_{0}}{12} t}\right) \tag{5.20}
\end{equation*}
$$

We now fix $\gamma \leqslant \min \left(1, \frac{\lambda_{1}}{2 C_{3}}\right)$. We claim that
Lemma 5.2. Under the above assumptions, there exists $C_{4}>0$, such that for all $t \in\left[t^{*}, S_{n}\right]$,

$$
\begin{equation*}
\Delta_{t}^{S_{n}} H^{\gamma} \geqslant-C_{4} e^{-\frac{\sigma_{0}}{12} t} \tag{5.21}
\end{equation*}
$$

Let us assume for the moment this lemma and prove the control of the $H^{1}$-norm of $\varepsilon$. Therefore, by calculations similar to the ones in the proof of Lemma 2.2 we obtain from (5.21)

$$
\begin{align*}
& \sum_{j=1}^{N} \frac{1}{c_{j}^{0}-1} \Delta_{t}^{S_{n}}\left(c_{j}^{0} m\left(R_{j}\right)-E\left(R_{j}\right)\right)+\Delta_{t}^{S_{n}}(\tilde{\mathcal{L}} \varepsilon, \varepsilon) \\
& +\frac{\gamma}{2} \Delta_{t}^{S_{n}} \int \rho\left(\varepsilon^{2}+\varepsilon_{x}^{2}\right) d x+\gamma \sum_{j=1}^{N} \frac{c_{j}^{0}}{c_{j}^{0}-1} \Delta_{t}^{S_{n}} m\left(R_{j}\right) \\
& \geqslant-K\left(\|\varepsilon(t)\|_{H^{1}}^{3}+e^{-\sigma_{0}^{2} t / 12}\right) \tag{5.22}
\end{align*}
$$

This implies, thanks to (3.11) and (5.14), that

$$
\begin{align*}
& \Delta_{t}^{S_{n}}(\tilde{\mathcal{L}} \varepsilon, \varepsilon)+\frac{\gamma}{2} \Delta_{t}^{S_{n}} \int \rho\left(\varepsilon^{2}+\varepsilon_{x}^{2}\right) d x+\gamma \sum_{j=1}^{N} \frac{c_{j}^{0}}{c_{j}^{0}-1} \Delta_{t}^{S_{n}} m\left(R_{j}\right) \\
& \geqslant-K\left(\|\varepsilon(t)\|_{H^{1}}^{3}+e^{-\sigma_{0}^{2} t / 12}\right) \tag{5.23}
\end{align*}
$$

Using (5.20), the fact that $\varepsilon\left(S_{n}\right)=0$, and (5.19) we find that
$\lambda_{1}\|\varepsilon(t)\|_{H^{1}}^{2} \leqslant(\tilde{\mathcal{L}} \varepsilon(t), \varepsilon(t)) \leqslant K\left(\|\varepsilon(t)\|_{H^{1}}^{3}+e^{-\sigma_{0}^{2} t / 12}\right)+\gamma C_{3}\left(\|\varepsilon(t)\|_{H^{1}}^{2}+e^{-\frac{\sigma_{0}}{12} t}\right)$.
Now, using our choice of $\gamma$, we deduce that

$$
\begin{equation*}
\|\varepsilon(t)\|_{H^{1}}^{2} \leqslant C e^{-\sigma_{0}^{2} t / 12} \tag{5.24}
\end{equation*}
$$

for $\alpha_{1}>0$ sufficiently small.
Proof of Lemma 5.2. Thanks to identities (5.18), (5.16) and the conservation of mass and energy, we find that

$$
\begin{equation*}
\frac{d}{d t} H^{\gamma}(t)=-\sum_{j=1}^{N-1} r_{j}\left((1+\gamma) \frac{d}{d t} m_{j+1}^{R}(t)-\frac{d}{d t} E_{j+1}^{R}(t)\right) \tag{5.25}
\end{equation*}
$$

Remark that from the monotonicity results related to mass (Lemma 2.1) and energy (Proposition 4.2 in $[\mathbf{6}]$ ), we know that $m_{j}^{R}$ is almost decreasing with respect to time and $-E_{j}^{R}$ is almost increasing with respect to time. This prevents us to conclude directly using $H$.

However, with $\gamma>0$ we can prove that $H^{\gamma}(t)$ is almost increasing. Indeed, using identities (2.14) - (2.15), and setting $h=\left(1-\partial_{x}^{2}\right)^{-1}\left(u+u^{p}\right)$, we find as in the proof of Proposition 4.2 in [6]:

$$
\begin{aligned}
& \frac{d}{d t}\left((1+\gamma) m_{j}^{R}(t)-E_{j}^{R}(t)\right)=-\frac{1+\gamma\left(1+y_{j}^{\prime}\right)}{2} \int u^{2} \psi_{j}^{\prime} d x \\
& -\frac{1-y_{j}^{\prime}-\gamma}{p+1} \int u^{p+1} \psi_{j}^{\prime} d x-(1+\gamma) \frac{y_{j}^{\prime}}{2} \int\left(u_{x}^{2}\right) \psi_{j}^{\prime} d x+\frac{1+2 \gamma}{2} \int h^{2} \psi_{j}^{\prime} d x \\
& +\frac{3+2 \gamma}{2} \int h_{x}^{2} \psi_{j}^{\prime} d x-\frac{1+\gamma}{2} \int h^{2} \psi_{j}^{\prime \prime \prime} d x-(1+\gamma) \int u^{p} h \psi_{j}^{\prime} d x
\end{aligned}
$$

As in Lemma 2.1, we set $I=\left[x_{j-1}(t)+L / 4, x_{j}(t)-L / 4\right]$ and $I^{C}=\mathbb{R} \backslash I$. For $x \in I$, taking $T_{1}$ sufficiently large, and $\alpha_{1}>0$ sufficiently small, we write $|u|=\frac{\left|h-h_{x x}\right|}{\left|1+u^{p-1}\right|}$. This allows us to compare $\int_{I} u^{2} \psi_{j}^{\prime} d x$ with $\int_{I} h^{2} \psi_{j}^{\prime} d x$. Note that the inequality

$$
\frac{1+\gamma\left(1+y_{j}^{\prime}\right)}{2}>\frac{1+2 \gamma}{2}
$$

is crucial to treat these terms. We refer to Proposition 4.2 in [6] for more details on this calculation. This proves Lemma 5.2.

End of the proof of Proposition 5.2. To complete the proof of (5.10), we have to compare $c_{j}(t)$ with $c_{j}^{0}$ and $x_{j}(t)$ with $x_{j}^{0}+c_{j}^{0} t$. First, using (5.13) then (5.24), we find

$$
\begin{equation*}
\left|c_{j}(t)-c_{j}^{0}\right|=\left|\int_{t}^{S_{n}} \dot{c}_{j}(s) d s\right| \leqslant C \int_{t}^{S_{n}} e^{-\sigma_{0}^{2} s / 24} d s \leqslant C e^{-\sigma_{0}^{2} t / 24} \tag{5.26}
\end{equation*}
$$

Similarly, using also (5.13) and (5.24), we find

$$
\begin{equation*}
\left|x_{j}(t)-x_{j}^{0}-c_{j}^{0} t\right| \leqslant C e^{-\sigma_{0}^{2} t / 24} . \tag{5.27}
\end{equation*}
$$

The last two identities imply that

$$
\begin{equation*}
\left\|\sum_{j=1}^{N} R_{j}(t)-R(t)\right\|_{H^{1}} \leqslant C e^{-\sigma_{0}^{2} t / 24} . \tag{5.28}
\end{equation*}
$$

Now remark that (5.24) with (5.28) imply (5.10). This achieves the proof of Proposition 5.2.

A consequence of Proposition 5.2 and its proof, which is also an important tool in the proof of the uniqueness, is the following :

Proposition 5.3. Let $u(t)$ be an $H^{1}$ solution of (1.1) such that

$$
\begin{equation*}
\lim _{t \rightarrow+\infty}\|u(t)-U(t)\|_{H^{1}}=0 \tag{5.29}
\end{equation*}
$$

then there exists $C>0$ such that for all $t>0$,

$$
\begin{equation*}
\|u(t)-U(t)\|_{H^{1}} \leqslant C e^{-\sigma_{0}^{2} t / 24} \tag{5.30}
\end{equation*}
$$

Proof. Let $T>0$ be such that

$$
\|u(t)-U(t)\|_{H^{1}} \leqslant \alpha_{1}, \text { for all } t \in[T,+\infty[
$$

where $\alpha_{1}$ is as in Proposition 5.2. Remark that it suffices to prove estimate (5.30) for $t \in\left[T,+\infty\left[\right.\right.$. Consider a sequence $\left(t_{n}\right)_{n \in \mathbb{N}}$ such that $t_{n} \in[T,+\infty[$ for all $n \in \mathbb{N}$, and $t_{n} \rightarrow+\infty$ when $n \rightarrow+\infty$. Following the proof of Proposition 5.2, we can prove that for all $t \in\left[T, t_{n}\right]$,

$$
\|\varepsilon(t)\|_{H^{1}} \leqslant C e^{-\sigma_{0}^{2} t / 24}+C\left\|u\left(t_{n}\right)-U\left(t_{n}\right)\right\|_{H^{1}}
$$

For $t \geqslant T$, taking the limit as $n \rightarrow+\infty$, we obtain $\|\varepsilon(t)\|_{H^{1}} \leqslant C e^{-\sigma_{0}^{2} t / 24}$. We conclude as before.

### 5.3. Estimates of higher Sobolev norms.

Proposition 5.4. For any $s \geqslant 1$, there exists $A_{s}>0$ such that for all $t \in$ $\left[0, S_{n}\right]$,

$$
\begin{equation*}
\left\|u_{n}(t)-R(t)\right\|_{H^{s}} \leqslant A_{s} e^{-2 \gamma_{1} t} \tag{5.31}
\end{equation*}
$$

where $\gamma_{1}=\sigma_{0}^{2} / 96$.
Proof. We follow the strategy of [11], Proposition 5. We have already established in the previous section:

$$
\begin{equation*}
\left\|u_{n}(t)-R(t)\right\|_{H^{1}} \leqslant A_{1} e^{-4 \gamma_{1} t} \tag{5.32}
\end{equation*}
$$

In what follows, $u_{n}$ will be denoted by $u$. To treat the case $s=2$, we consider

$$
G_{2}(t)=\int\left(u_{x}^{2}(t)+u_{x x}^{2}(t)\right) d x
$$

Differentiating $G_{2}(t)$, using (1.1), and integrating by parts, we find

$$
\begin{aligned}
G_{2}^{\prime}(t) & =2 \int\left(u_{x} u_{x t}+u_{x x} u_{x x t}\right) d x=-2 \int u_{x x}\left(1-\partial_{x}^{2}\right) u_{t} d x \\
& =2 \int u_{x x}\left(u+u^{p}\right)_{x} d x=p \int u^{p-1}\left(u_{x}^{2}\right)_{x} d x=-p(p-1) \int u^{p-2} u_{x}^{3} d x
\end{aligned}
$$

Replacing $u=v+R$ in the above expression of $G_{2}^{\prime}(t)$, we find

$$
G_{2}^{\prime}(t)=-p(p-1) \int(v+R)^{p-2}\left(v_{x}+R_{x}\right)^{3} d x
$$

Now remark that $\int R_{j}^{p-2} R_{j x}^{3} d x=0$, and recall that the $N$ solitary waves $R_{j}$ are sufficiently decoupled, thus we deduce that

$$
\left|\int R^{p-2} R_{x}^{3} d x\right| \leqslant C e^{-8 \gamma_{1} t}
$$

We decompose

$$
\begin{aligned}
\int u^{p-2} u_{x}^{3} d x= & \int\left(\left(v_{x}+R_{x}\right)^{3}-R_{x}^{3}\right)(v+R)^{p-2} d x \\
& +\int R_{x}^{3}\left((v+R)^{p-2}-R^{p-2}\right)+\int R^{p-2} R_{x}^{3} d x
\end{aligned}
$$

Recall that we have

$$
\begin{equation*}
\|v(t)\|_{H^{1}} \leqslant A_{1} e^{-4 \gamma_{1} t} \tag{5.33}
\end{equation*}
$$

Thus, using the Gagliardo-Nirenberg inequality :

$$
\int\left|v_{x}\right|^{3} d x \leqslant C\left(\int v_{x x}^{2} d x\right)^{1 / 4}\left(\int v_{x}^{2}\right)^{5 / 4}
$$

we find that for all $t \in\left[0, S_{n}\right]$,

$$
\left|G_{2}^{\prime}(t)\right| \leqslant C\left(1+G_{2}(t)\right) e^{-4 \gamma_{1} t}
$$

By direct integration, since

$$
\begin{equation*}
G_{2}\left(S_{n}\right)=\int\left(R_{x}^{2}\left(S_{n}\right)+R_{x x}^{2}\left(S_{n}\right)\right) d x \tag{5.34}
\end{equation*}
$$

is uniformly bounded, we find that $G_{2}$ is uniformly bounded on $\left[0, S_{n}\right]$. The function $G_{2}$ being bounded, integrating between $t$ and $S_{n}$, we find, for all $t \in\left[0, S_{n}\right]$,

$$
\begin{equation*}
\left|G_{2}(t)-G_{2}\left(S_{n}\right)\right| \leqslant C e^{-4 \gamma_{1} t} \tag{5.35}
\end{equation*}
$$

On the other hand, replacing $u=v+R$ in the expression of $G_{2}$, then integrating by parts, we find

$$
\begin{aligned}
G_{2}(t)= & \int\left(v_{x}^{2}(t)+v_{x x}^{2}(t)\right) d x+\int\left(R_{x}^{2}(t)+R_{x x}^{2}(t)\right) d x \\
& +2 \int\left(-R_{x x}(t)+R_{x x x x}(t)\right) v(t) d x
\end{aligned}
$$

Using this identity, (5.34) and $v\left(S_{n}\right) \equiv 0$, we compute

$$
\begin{aligned}
\int v_{x x}^{2}(t) d x \leqslant & \left|G_{2}(t)-G_{2}\left(S_{n}\right)\right|+2\|v(t)\|_{L^{\infty}} \int\left|R_{x x}(t)\right|+\left|R_{x x x x}(t)\right| d x \\
& +\left|\int\left(R_{x}^{2}(t)+R_{x x}^{2}(t)\right) d x-\int\left(R_{x}^{2}\left(S_{n}\right)+R_{x x}^{2}\left(S_{n}\right)\right) d x\right|
\end{aligned}
$$

Using estimates (5.33), (5.35), and the exponential decay of the $N$ decoupled solitary waves $R_{j}$, we find that there exists a constant $A_{2}>0$ such that for all $t \in\left[0, S_{n}\right]$,

$$
\begin{equation*}
\|v(t)\|_{H^{2}} \leqslant A_{1} e^{-2 \gamma_{1} t} \tag{5.36}
\end{equation*}
$$

This proves the case $s=2$.
We prove by induction on $s$ that the following holds for all $s \geqslant 3$ :

$$
\begin{equation*}
\forall n \geqslant 0, \forall t \in\left[T_{1}, S_{n}\right], \quad\|v(t)\|_{H^{s}} \leqslant A_{s} e^{-2 \gamma_{1} t} \tag{5.37}
\end{equation*}
$$

We have already proved that (5.37) is true for $s=2$. Now, we assume that it is true for $s-1$, for $s \geqslant 3$, and we prove that it also holds for $s$.

We write the equation of $v=u-R$ :

$$
\left(1-\partial_{x}^{2}\right) v_{t}=-\left(v+(R+v)^{p}-\sum_{j=1}^{N} \tilde{R}_{j}^{p}\right)_{x}
$$

where $\tilde{R}_{j}(t, x)=\varphi_{c_{j}^{0}}\left(x-x_{j}^{0}-c_{j}^{0} t\right)$. We define

$$
F_{s}(t)=\int\left(\partial_{x}^{s-1} v(t)\right)^{2}+\left(\partial_{x}^{s} v(t)\right)^{2}
$$

We compute $F_{s}^{\prime}(t)$ :

$$
\begin{aligned}
F_{s}^{\prime}(t) & =2 \int\left(\partial_{x}^{s-1} v \partial_{x}^{s-1} v_{t}+\partial_{x}^{s} v \partial_{x}^{s} v_{t}\right) d x \\
& =-2 \int \partial_{x}^{s} v\left(1-\partial_{x}^{2}\right) \partial_{x}^{s-2} v_{t} d x \\
& =2 \int \partial_{x}^{s} v \partial_{x}^{s-1}\left(v+(R+v)^{p}-\sum_{j=1}^{N} \tilde{R}_{j}^{p}\right) d x
\end{aligned}
$$

After integrations by parts, we observe that derivatives of $v$ of order $s$ disappear, and that the second-hand term is controlled by $K\left(F_{s-1}(t)+e^{-4 \gamma_{1} t}\right)$, and thus, using the induction assumption, is controlled by $K e^{-4 \gamma_{1} t}$. Integrating between $t$ and $+\infty$, we obtain (5.37) for $s$. Thus, the proof of Proposition 5.4 is complete.
5.4. Uniqueness. We denote by $U(t)$ the solution of (1.1) constructed in Sections 5.1 and 5.2. Recall that it satisfies, for $\gamma_{1}=\sigma_{0}^{2} / 96$, and $A_{s}>0$, for all $s \geqslant 0$, for all $t \geqslant 0$,

$$
\begin{equation*}
\|U(t)-R(t)\|_{H^{s}} \leqslant A_{s} e^{-\gamma_{1} t} \tag{5.38}
\end{equation*}
$$

where $R(t)=\sum_{j=1}^{N} \tilde{R}_{j}(t)$, and $\tilde{R}_{j}(t, x)=\varphi_{c_{j}^{0}}\left(x-x_{j}^{0}-c_{j}^{0} t\right)$. In this section, we prove the following result, which implies the uniqueness part of Theorem 1.3.

Proposition 5.5. Let $u(t)$ be an $H^{1}$ solution of (1.1) on $\mathbb{R}$. Assume that $u(t)$ satisfies

$$
\begin{equation*}
\lim _{t \rightarrow+\infty}\|u(t)-U(t)\|_{H^{1}}=0 \tag{5.39}
\end{equation*}
$$

then $u(t) \equiv U(t)$.
Proof. Assume (5.39). By Proposition 5.3, for all $t>0$,

$$
\|u(t)-U(t)\|_{H^{1}} \leqslant C e^{-\gamma_{1} t}
$$

Let

$$
\begin{equation*}
z(t)=u(t)-U(t) \quad \text { so that for all } t \geqslant T_{0}, \quad\|z(t)\|_{H^{1}} \leqslant C e^{-\gamma_{1} t} \tag{5.40}
\end{equation*}
$$

We write the equation of $z(t)$ :

$$
\begin{equation*}
\left(1-\partial_{x}^{2}\right) z_{t}=-\left((u-U)+u^{p}-U^{p}\right)_{x}=-\left(z+(z+U)^{p}-U^{p}\right)_{x} \tag{5.41}
\end{equation*}
$$

Step 1. Monotonicity property of the energy. The function $\psi$ being defined in section 2.2, just before Lemma 2.1, we set

$$
\tilde{\rho}(t, x)=\frac{c_{N}^{0}}{c_{N}^{0}-1}+\sum_{j=1}^{N-1}\left(\frac{c_{j}^{0}}{c_{j}^{0}-1}-\frac{c_{j+1}^{0}}{c_{j+1}^{0}-1}\right)(1-\psi)\left(x-\tilde{y}_{j}(t)\right)
$$

where

$$
\tilde{y}_{j}(t)=\frac{c_{j}^{0}+c_{j+1}^{0}}{2} t+\frac{x_{j}^{0}+x_{j+1}^{0}}{2} .
$$

Observe that the function $\tilde{\rho}$ takes values close to $\frac{c_{j}^{0}}{c_{j}^{0}-1}$ for $x$ close to $c_{j}^{0} t+x_{j}^{0}$, and has large variations only in regions far away from the solitary waves (for instance we have for all $j$, for all $\left.t \geqslant T_{0},\left\|R_{j}(t) \tilde{\rho}_{x}(t)\right\|_{L^{\infty}} \leqslant C e^{-\gamma_{1} t}\right)$. We also define a quantity related to the energy for $z$ :

$$
\begin{aligned}
& \tilde{H}(t)=\int\left\{\tilde{\rho}(t, x) z_{x}^{2}(t, x)-(\tilde{\rho}(t, x)-1) F(t, z(t, x))+z^{2}(t, x)\right\} d x \\
& F(t, z)=2\left[\frac{(z+U(t))^{p+1}}{p+1}-U^{p}(t) z-\frac{U^{p+1}(t)}{p+1}\right]
\end{aligned}
$$

Note that

$$
\tilde{H}(t)=\int\left\{\tilde{\rho}(t, x)\left(z_{x}^{2}(t, x)+z^{2}(t, x)\right)-(\tilde{\rho}(t, x)-1)\left(F(t, z(t, x))+z^{2}(t, x)\right)\right\} d x
$$

We have the following property.
Lemma 5.3. There exists $K>0$ such that for all $t \geqslant 0$,

$$
\begin{equation*}
\tilde{H}(t) \leqslant K e^{-\gamma_{1} t} \sup _{t^{\prime} \geqslant t}\left\|z\left(t^{\prime}\right)\right\|_{H^{1}}^{2} \tag{5.42}
\end{equation*}
$$

Note that such a result is possible because we estimate the difference of two solutions, and not the difference of a solution with a sum of solitary waves as in Lemma 5.2.

Proof of Lemma 5.3. By direct calculations (we present formal calculations that can be justified by a regularization argument on $u(t)$, using well-posedness and continuous dependence of solutions of (1.1) in the Sobolev spaces $H^{s}, s \geqslant 1$ ),

$$
\begin{aligned}
\frac{d \tilde{H}}{d t}= & \int\left(z_{x}^{2}-F(z)\right) \tilde{\rho}_{t}-2 \int z_{t}\left(z_{x} \tilde{\rho}\right)_{x}-2 \int z_{t}\left((z+U)^{p}-U^{p}\right)(\tilde{\rho}-1) \\
& +2 \int z_{t} z-2 \int U_{t}\left((z+U)^{p}-p U^{p-1} z-U^{p}\right)(\tilde{\rho}-1)
\end{aligned}
$$

where we have used $\frac{d F}{d z}=2\left[(z+U)^{p}-U^{p}\right]$ and for any function $f(x)$ of class $C^{1}$,

$$
\frac{d}{d t} \int z_{x}^{2} f=2 \int z_{t x} z_{x} f=-2 \int z_{t}\left(z_{x} f\right)_{x}
$$

Using the equation of $z$, we obtain the following expression for $d \tilde{H} / d t$ :

$$
\begin{aligned}
\frac{d \tilde{H}}{d t}= & \int\left(z_{x}^{2}-F(z)\right) \tilde{\rho}_{t}+2 \int\left(1-\partial_{x}^{2}\right)^{-1}\left(z+(z+U)^{p}-U^{p}\right)_{x}\left(z_{x} \tilde{\rho}\right)_{x} \\
& +2 \int\left(1-\partial_{x}^{2}\right)^{-1}\left(z+(z+U)^{p}-U^{p}\right)_{x}\left((z+U)^{p}-U^{p}\right)(\tilde{\rho}-1) \\
& -2 \int\left(1-\partial_{x}^{2}\right)^{-1}\left(z+(z+U)^{p}-U^{p}\right)_{x} z \\
& +2 \int U_{x}\left((z+U)^{p}-p U^{p-1} z-U^{p}\right) \tilde{\rho} \\
& -2 \int\left(U_{t}(\tilde{\rho}-1)+U_{x} \tilde{\rho}\right)\left((z+U)^{p}-p U^{p-1} z-U^{p}\right) .
\end{aligned}
$$

Since $\lim _{t \rightarrow+\infty} \tilde{H}(t)=0$, in view of (5.42), our objective is to find a lower bound on $d \tilde{H} / d t$.

- First, we consider the term: $\int\left(z_{x}^{2}-F(z)\right) \tilde{\rho}_{t}$. Note that

$$
\tilde{\rho}_{t}(t, x)=\sum_{j=1}^{N-1}\left(\frac{c_{j}^{0}}{c_{j}^{0}-1}-\frac{c_{j+1}^{0}}{c_{j+1}^{0}-1}\right) \frac{c_{j}^{0}+c_{j+1}^{0}}{2} \psi^{\prime}\left(x-\tilde{y}_{j}(t)\right)
$$

and

$$
\tilde{\rho}_{x}(t, x)=-\sum_{j=1}^{N-1}\left(\frac{c_{j}^{0}}{c_{j}^{0}-1}-\frac{c_{j+1}^{0}}{c_{j+1}^{0}-1}\right) \psi^{\prime}\left(x-\tilde{y}_{j}(t)\right) .
$$

Since $\psi^{\prime}>0$ and $c_{j}^{0}>1+2 \sigma_{0}$, we have

$$
\forall t, x \in \mathbb{R}^{+} \times \mathbb{R}, \quad \tilde{\rho}_{x}(t, x)<0, \quad\left(1+2 \sigma_{0}\right)\left|\tilde{\rho}_{x}(t, x)\right|<\tilde{\rho}_{t}(t, x)<K\left|\tilde{\rho}_{x}(t, x)\right| .
$$

We also note that

$$
\begin{equation*}
|F(z)| \leqslant C|z|^{p+1}+C z^{2}|U|^{p-1} \leqslant C|z|^{p+1}+C z^{2}|U-R|^{p-1}+C z^{2}|R|^{p-1} \tag{5.44}
\end{equation*}
$$

and so $|F(z)| \leqslant C|z|^{2}\left(e^{-\gamma_{1} t}+R\right)$, by (5.38) and (5.40). Moreover, $\left\|R \tilde{\rho}_{x}\right\|_{L^{\infty}} \leqslant$ $C e^{-\gamma_{1} t}$, so that we obtain

$$
\begin{equation*}
\int\left(z_{x}^{2}-F(z)\right) \tilde{\rho}_{t} \geqslant\left(1+2 \sigma_{0}\right) \int z_{x}^{2}\left|\tilde{\rho}_{x}\right|-C e^{-\gamma_{1} t} \int z^{2} \tag{5.45}
\end{equation*}
$$

- Second, we take care of the quadratic terms, i.e. $2 \int\left(1-\partial_{x}^{2}\right)^{-1} z_{x}\left(z_{x} \tilde{\rho}\right)_{x}$ and $-2 \int\left(1-\partial_{x}^{2}\right)^{-1} z_{x} z$. Setting $a=\left(1-\partial_{x}^{2}\right)^{-1} z$, we see immediately that the second term is zero. For the first term, we have

$$
2 \int\left(1-\partial_{x}^{2}\right)^{-1} z_{x}\left(z_{x} \tilde{\rho}\right)_{x}=-2 \int a_{x x}\left(\left(a_{x}-a_{x x x}\right) \tilde{\rho}\right)=\int\left(a_{x}^{2}-a_{x x}^{2}\right) \tilde{\rho}_{x} \geqslant-\int a_{x}^{2}\left|\tilde{\rho}_{x}\right|
$$

Note that

$$
\begin{aligned}
& -\int z_{x}^{2} \tilde{\rho}_{x}=-\int\left(-a_{x x x}+a_{x}\right)^{2} \tilde{\rho}_{x} \\
& =-\int a_{x x x}^{2} \tilde{\rho}_{x}-2 \int a_{x x}^{2} \tilde{\rho}_{x}-\int a_{x}^{2} \tilde{\rho}_{x}+\int a_{x}^{2} \tilde{\rho}_{x x x} \geqslant \int a_{x}^{2}\left|\tilde{\rho}_{x}\right|-\int a_{x}^{2}\left|\tilde{\rho}_{x x x}\right|
\end{aligned}
$$

Since $\left|\tilde{\rho}_{x x x}\right| \leqslant \frac{\sigma_{0}^{2}}{9}\left|\tilde{\rho}_{x}\right|$, by the properties of $\psi$, we obtain $\int a_{x}^{2}\left|\tilde{\rho}_{x}\right| \leqslant \frac{1}{1-\frac{\sigma_{0}^{2}}{9}} \int z_{x}^{2}\left|\tilde{\rho}_{x}\right| \leqslant$ $\left(1+2 \frac{\sigma_{0}^{2}}{9}\right) \int z_{x}^{2}\left|\tilde{\rho}_{x}\right|$, and so

$$
2 \int\left(1-\partial_{x}^{2}\right)^{-1} z_{x}\left(z_{x} \tilde{\rho}\right)_{x} \geqslant-\left(1+2 \frac{\sigma_{0}^{2}}{9}\right) \int z_{x}^{2}\left|\tilde{\rho}_{x}\right| .
$$

This term can then be controlled by (5.45).

- Third, we consider the following terms in the expression of $\frac{d \tilde{H}}{d t}$ :

$$
\begin{aligned}
& 2 \int\left(1-\partial_{x}^{2}\right)^{-1}\left((z+U)^{p}-U^{p}\right)_{x}\left[\left(z_{x} \tilde{\rho}\right)_{x}-z\right] \\
& +2 \int\left[\left(1-\partial_{x}^{2}\right)^{-1} z_{x}\right]\left((z+U)^{p}-U^{p}\right)(\tilde{\rho}-1) \\
& =2 \int\left(1-\partial_{x}^{2}\right)^{-1}\left((z+U)^{p}-U^{p}\right)\left[-\left(z_{x} \tilde{\rho}\right)_{x x}+z_{x} \tilde{\rho}\right] \\
& +2 \int\left\{\left[\left(1-\partial_{x}^{2}\right)^{-1} z_{x}\right](\tilde{\rho}-1)-\left(1-\partial_{x}^{2}\right)^{-1}\left[z_{x}(\tilde{\rho}-1)\right]\right\}\left((z+U)^{p}-U^{p}\right)
\end{aligned}
$$

The first term becomes:

$$
\begin{equation*}
2 \int\left((z+U)^{p}-U^{p}\right) z_{x} \tilde{\rho} \tag{5.46}
\end{equation*}
$$

it will be combined with some other term later on. The second term can be controlled completely. Indeed, we have $-a_{x x}+a=z$ and so $-\left(a_{x}(\tilde{\rho}-1)\right)_{x x}+a_{x}(\tilde{\rho}-1)=$ $z_{x}(\tilde{\rho}-1)-2 a_{x x} \tilde{\rho}_{x}-a_{x} \tilde{\rho}_{x x}$. Thus

$$
\left[\left(1-\partial_{x}^{2}\right)^{-1} z_{x}\right](\tilde{\rho}-1)-\left(1-\partial_{x}^{2}\right)^{-1}\left[z_{x}(\tilde{\rho}-1)\right]=-\left(1-\partial_{x}^{2}\right)^{-1}\left(2 a_{x x} \tilde{\rho}_{x}+a_{x} \tilde{\rho}_{x x}\right)
$$

Therefore, this second term is $-2 \int\left(1-\partial_{x}^{2}\right)^{-1}\left(2 a_{x x} \tilde{\rho}_{x}+a_{x} \tilde{\rho}_{x x}\right)\left((z+U)^{p}-U^{p}\right)$. It is known that $f \leqslant g$ implies $\left(1-\partial_{x}^{2}\right)^{-1} f \leqslant\left(1-\partial_{x}^{2}\right)^{-1} g$; moreover, for $K>2$, $\left(1-\partial_{x}^{2}\right)^{-1} e^{-\frac{\left|x-x_{0}\right|}{K}} \leqslant 2 e^{-\frac{\left|x-x_{0}\right|}{K}}$. Since $\left|\tilde{\rho}_{x x}(t, x)\right|+\left|\tilde{\rho}_{x}(t, x)\right| \leqslant C \sum_{j=1}^{N} e^{-\frac{\sigma_{0}}{3}\left|x-\tilde{y}_{j}(t)\right|}$, we obtain

$$
\left|\left(1-\partial_{x}^{2}\right)^{-1}\left(2 a_{x x} \tilde{\rho}_{x}+a_{x} \tilde{\rho}_{x x}\right)\right| \leqslant C\left(\left\|a_{x x}\right\|_{L^{\infty}}+\left\|a_{x}\right\|_{L^{\infty}}\right) \sum_{j=1}^{N} e^{-\frac{\sigma_{0}}{3}\left|x-\tilde{y}_{j}(t)\right|}
$$

Moreover, $\left\|a_{x x}\right\|_{L^{\infty}}+\left\|a_{x}\right\|_{L^{\infty}} \leqslant C\|z\|_{H^{1}}$, and $\left|(z+U)^{p}-U^{p}\right| \leqslant C|z||U|+C|z|^{p}$, so that

$$
\begin{aligned}
& \left|2 \int\left(1-\partial_{x}^{2}\right)^{-1}\left(2 a_{x x} \tilde{\rho}_{x}+a_{x} \tilde{\rho}_{x x}\right)\left((z+U)^{p}-U^{p}\right)\right| \\
& \leqslant C\|z\|_{H^{1}}^{2} \int \sum_{j=1}^{N} e^{-\frac{\sigma_{0}}{3}\left|x-\tilde{y}_{j}(t)\right|}|U(t, x)| d x+C\|z\|_{H^{1}}^{p+1} \leqslant C e^{-\gamma_{1} t}\|z\|_{H^{1}}^{2} .
\end{aligned}
$$

- Fourth, we consider the term $-2 \int\left(U_{t}(\tilde{\rho}-1)+U_{x} \tilde{\rho}\right)\left((z+U)^{p}-p U^{p-1} z-U^{p}\right)$. We have

$$
\begin{aligned}
& \left\|U_{t}(\tilde{\rho}-1)+U_{x} \tilde{\rho}\right\|_{L^{\infty}} \leqslant\left\|\left(1-\partial_{x}^{2}\right)^{-1}\left[\left(U+U^{p}\right)-\left(R+R^{p}\right)\right]_{x}(\tilde{\rho}-1)\right\|_{L^{\infty}} \\
& +\left\|\left(1-\partial_{x}^{2}\right)^{-1}\left(R+R^{p}\right)_{x}(\tilde{\rho}-1)-R_{x} \tilde{\rho}\right\|_{L^{\infty}}+\left\|R_{x} \tilde{\rho}-U_{x} \tilde{\rho}\right\|_{L^{\infty}}
\end{aligned}
$$

The first and the third terms are controlled by $\|U-R\|_{H^{2}} \leqslant C e^{-\gamma_{1} t}$. For the second term, we have $\left(1-\partial_{x}^{2}\right)^{-1}\left(\tilde{R}_{j}+\tilde{R}_{j}^{p}\right)=c_{j} \tilde{R}_{j}$, so that

$$
\begin{aligned}
& \left\|\left(1-\partial_{x}^{2}\right)^{-1}\left(R+R^{p}\right)_{x}(\tilde{\rho}-1)-R_{x} \tilde{\rho}\right\|_{L^{\infty}} \\
& \leqslant C\left\|\left(1-\partial_{x}^{2}\right)^{-1}\left(R^{p}-\sum_{j=1}^{N} \tilde{R}_{j}^{p}\right)_{x}\right\|_{L^{\infty}}+\sum_{j=1}^{N}\left\|c_{j}(\tilde{\rho}-1) \tilde{R}_{j x}-\tilde{\rho} \tilde{R}_{j x}\right\|_{L^{\infty}} \leqslant C e^{-\gamma_{1} t} .
\end{aligned}
$$

-Fifth, we consider $2 \int\left(1-\partial_{x}^{2}\right)^{-1}\left((z+U)^{p}-U^{p}\right)_{x}\left((z+U)^{p}-U^{p}\right)(\tilde{\rho}-1)$. Setting $b=\left(1-\partial_{x}^{2}\right)^{-1}\left((z+U)^{p}-U^{p}\right)$, this term is equal to

$$
2 \int b_{x}\left(-b_{x x}+b\right)(\tilde{\rho}-1)=\int\left(b_{x}^{2}-b^{2}\right) \tilde{\rho}_{x} \geqslant-\int b_{x}^{2}\left|\tilde{\rho}_{x}\right|
$$

Moreover, as before, we have

$$
\int b_{x}^{2}\left|\tilde{\rho}_{x}\right| \leqslant 2 \int\left((z+U)^{p}-U^{p}\right)_{x}^{2}\left|\tilde{\rho}_{x}\right| \leqslant C e^{-\gamma_{1} t}\|z(t)\|_{H^{1}}^{2}
$$

- Finally, there remains only the following term:

$$
\begin{equation*}
2 \int U_{x}\left((z+U)^{p}-p U^{p-1} z-U^{p}\right) \tilde{\rho} \tag{5.47}
\end{equation*}
$$

We have to combine it with (5.46). Indeed, if we sum them, terms which are at least cubic in $z$ are controlled by $C\|z\|_{L^{\infty}}\|z\|_{H^{1}}^{2} \leqslant C e^{-\gamma_{1} t}\|z(t)\|_{H^{1}}^{2}$. On the other hand, the quadratic terms in $z$ are

$$
2 \int p z U^{p-1} z_{x} \tilde{\rho}+2 \int U_{x} \frac{p(p-1)}{2} U^{p-2} z^{2} \tilde{\rho}=p \int\left(z^{2} U^{p-1}\right)_{x} \tilde{\rho}=-p \int z^{2} U^{p-1} \tilde{\rho}_{x}
$$

and this is controlled by $C e^{-\gamma_{1} t}\|z(t)\|_{H^{1}}^{2}$.
In conclusion of these estimates, we have

$$
\frac{d \tilde{H}}{d t} \geqslant-C e^{-\gamma_{1} t}\|z(t)\|_{H^{1}}^{2} \geqslant-C e^{-\gamma_{1} t} \sup _{t^{\prime}>t}\|z(t)\|_{H^{1}}^{2}
$$

which proves Lemma 5.3 by integration between $t_{1}$ and $+\infty$, and using the fact that $\lim _{t \rightarrow+\infty} \tilde{H}(t)=0$.

Step 2. Control of the $\left(1-\partial_{x}^{2}\right) \tilde{R}_{j}$ directions. We claim the following estimate: for all $t \geqslant T_{0}$,

$$
\begin{equation*}
\sum_{j=1}^{N}\left|\int z(t)\left(1-\partial_{x}^{2}\right) \tilde{R}_{j}(t)\right| \leqslant C e^{-\gamma_{1} t} \sup _{t^{\prime} \geqslant t}\left\|z\left(t^{\prime}\right)\right\|_{L^{2}} \tag{5.48}
\end{equation*}
$$

We prove (5.48) by using the equation of $z(t)$. By $\frac{d}{d t} \tilde{R}_{j}(t)=-c_{j}^{0} \tilde{R}_{j x}(t)$, and the equation of $z(t)$, we have

$$
\begin{aligned}
\frac{d}{d t} \int z(t)\left(1-\partial_{x}^{2}\right) \tilde{R}_{j}(t) & =\int\left(1-\partial_{x}^{2}\right) z_{t} \tilde{R}_{j}+\int\left(1-\partial_{x}^{2}\right) z R_{j t} \\
& =\int\left(c_{j}^{0} z_{x x}-\left(c_{j}^{0}-1\right) z+\left[(z+U)^{p}-U^{p}\right]\right) \tilde{R}_{j x}
\end{aligned}
$$

Next, note that by differentiating equation (1.5), we have $-c\left(\varphi_{c x}\right)_{x x}+(c-1) \varphi_{c x}-$ $p \varphi_{c}^{p-1} \varphi_{c x}=0$. Thus,

$$
\begin{aligned}
& \left|\int\left(-c_{j}^{0} z_{x x}+\left(c_{j}^{0}-1\right) z-\left[(z+U)^{p}-U^{p}\right]\right) \tilde{R}_{j x}\right| \\
& \leqslant\left|\int z\left(-c_{j}^{0}\left(\tilde{R}_{j x}\right)_{x x}+\left(c_{j}^{0}-1\right) \tilde{R}_{j x}-p R_{j}^{p-1} \tilde{R}_{j x}\right)\right|+p\left|\int z\left(\tilde{R}_{j}^{p-1}-R^{p-1}\right) \tilde{R}_{j x}\right| \\
& \quad+p\left|\int z\left(R^{p-1}-U^{p-1}\right) \tilde{R}_{j x}\right|+\left|\int\left((z+U)^{p}-U^{p}-p U^{p-1} z\right) \tilde{R}_{j x}\right| \\
& \leqslant C e^{-\gamma_{1} t}\|z(t)\|_{L^{2}}+\|z(t)\|_{L^{2}}^{2} \leqslant C e^{-\gamma_{1} t}\|z(t)\|_{L^{2}} .
\end{aligned}
$$

Therefore, $\left|\frac{d}{d t} \int z(t)\left(1-\partial_{x}^{2}\right) \tilde{R}_{j}(t)\right| \leqslant C e^{-\gamma_{1} t}\|z(t)\|_{L^{2}}$. By integration in time between $t$ and $+\infty$, since $\lim _{t \rightarrow+\infty} \int z(t)\left(1-\partial_{x}^{2}\right) \tilde{R}_{j}(t)=0$, we obtain (5.48).

Step 3. Control of the $\left(1-\partial_{x}^{2}\right) \tilde{R}_{j x}$ directions and conclusion. Now, we define

$$
\tilde{z}(t)=z(t)+\sum_{j=1}^{N} a_{j}(t) \tilde{R}_{j x}(t), \quad \text { where } \quad a_{j}(t)=-\frac{\int z(t)\left(1-\partial_{x}^{2}\right) \tilde{R}_{j x}(t)}{\int \tilde{R}_{j x x}^{2}(t)+\tilde{R}_{j x}^{2}(t)}
$$

so that $\int \tilde{z}(t)\left(1-\partial_{x}^{2}\right) \tilde{R}_{j x}(t)=0$. Note that for some $C_{1}, C_{2}>0$,

$$
C_{1}\|z\|_{H^{1}} \leqslant\|\tilde{z}\|_{H^{1}}+\sum_{j=1}^{N}\left|a_{j}(t)\right| \leqslant C_{2}\|z\|_{H^{1}}
$$

We claim the following lemma.
Lemma 5.4. For all $t \geqslant 0$,

$$
\begin{equation*}
\|\tilde{z}(t)\|_{H^{1}}+\sum_{j=1}^{N}\left|a_{j}(t)\right| \leqslant C e^{-\gamma_{1} t} \sup _{t^{\prime}>t}\left\|z\left(t^{\prime}\right)\right\|_{H^{1}} . \tag{5.49}
\end{equation*}
$$

Assuming this claim, we have $\|z(t)\|_{H^{1}} \leqslant C e^{-\frac{\gamma_{1}}{2} t} \sup _{t^{\prime}>t}\left\|z\left(t^{\prime}\right)\right\|_{H^{1}}$ for all $t$ large enough, which implies $z \equiv 0$ and thus $u(t) \equiv U(t)$.
Proof of Lemma 5.4. This proof proceeds in two steps. First, we prove the estimate of $\|\tilde{z}(t)\|$, and second we consider $\left|a_{j}(t)\right|$.

Let

$$
\mathcal{L}_{\tilde{\rho}} z=-\tilde{\rho} z_{x x}-(\tilde{\rho}-1) p R^{p-1} z+z
$$

where $\tilde{\rho}$ is defined in Step 1. We have, by direct calculations

$$
\begin{aligned}
& \int \tilde{\rho} z_{x}^{2}-p(\tilde{\rho}-1) R^{p-1} z^{2}+z^{2}=\int\left(\mathcal{L}_{\tilde{\rho}} z\right) z+\frac{1}{2} \int z^{2} \tilde{\rho}_{x x}=\int\left(\mathcal{L}_{\tilde{\rho}} \tilde{z}\right) \tilde{z} \\
& -\sum_{j=1}^{N} a_{j} \int\left(\mathcal{L}_{\tilde{\rho}} \tilde{z}\right) \tilde{R}_{j x}-\sum_{j=1}^{N} a_{j} \int \tilde{z}\left(\mathcal{L}_{\tilde{\rho}} \tilde{R}_{j x}\right)+\sum_{j, k=1}^{N} a_{j} a_{k} \int\left(\mathcal{L}_{\tilde{\rho}} \tilde{R}_{j x}\right) \tilde{R}_{k x} \\
& \quad+\frac{1}{2} \int \tilde{z}^{2} \tilde{\rho}_{x x}-\sum_{j=1}^{N} a_{j} \int \tilde{z} \tilde{R}_{j x} \tilde{\rho}_{x x}+\frac{1}{2} \int\left(\sum_{j=1}^{N} a_{j} \tilde{R}_{j x}\right)^{2} \tilde{\rho}_{x x}
\end{aligned}
$$

Now, we have

$$
\begin{aligned}
\mathcal{L}_{\tilde{\rho}} \tilde{R}_{j x}= & -\frac{c_{j}^{0}}{c_{j}^{0}-1}\left(\tilde{R}_{j x}\right)_{x x}-\frac{1}{c_{j}^{0}-1} p \tilde{R}_{j}^{p-1} \tilde{R}_{j x}+\tilde{R}_{j x} \\
& -\left(\tilde{\rho}-\frac{c_{j}^{0}}{c_{j}^{0}-1}\right)\left(\tilde{R}_{j x}\right)_{x x}-\left((\tilde{\rho}-1)-\frac{1}{c_{j}^{0}-1}\right) p \tilde{R}_{j}^{p-1} \tilde{R}_{j x} \\
& -p\left(R^{p-1}-R_{j}^{p-1}\right) \tilde{R}_{j x}(\tilde{\rho}-1)
\end{aligned}
$$

Since $-c_{j}^{0}\left(\tilde{R}_{j x}\right)_{x x}+\left(c_{j}^{0}-1\right) \tilde{R}_{j x}-p \tilde{R}_{j}^{p-1} \tilde{R}_{j x}=0$, and $\left|c_{j}^{0} \tilde{\rho}-\left(c_{j}^{0}-1\right)\right| e^{-\sqrt{\sigma_{0}}\left|x-x_{j}^{0}-c_{j}^{0} t\right|} \leqslant$ $C e^{-\gamma_{1} t} e^{-\frac{\sqrt{\sigma_{0}}}{2}\left|x-x_{j}^{0}-c_{j}^{0} t\right|}$, we have

$$
\begin{equation*}
\left|\mathcal{L}_{\tilde{\rho}}\left(\tilde{R}_{j x}\right)\right| \leqslant C e^{-\gamma_{1} t} e^{-\frac{\sqrt{\sigma 0}}{2}\left|x-x_{j}^{0}-c_{j}^{0} t\right|} \tag{5.50}
\end{equation*}
$$

Note also that

$$
\int\left(\mathcal{L}_{\tilde{\rho}} \tilde{z}\right) \tilde{R}_{j x}=\int \tilde{z}\left(\mathcal{L}_{\tilde{\rho}} \tilde{R}_{j x}\right)-\int \tilde{z}\left(\tilde{\rho}_{x x} \tilde{R}_{j x}+2 \tilde{\rho}_{x} \tilde{R}_{j x x}\right)
$$

so that by the properties of $\tilde{\rho}_{x}$ and $\tilde{\rho}_{x x}$, and (5.50),

$$
\left|\int\left(\mathcal{L}_{\tilde{\rho}} \tilde{z}\right) \tilde{R}_{j x}\right|+\left|\int \tilde{z}\left(\mathcal{L}_{\tilde{\rho}} \tilde{R}_{j x}\right)\right| \leqslant C e^{-\gamma_{1} t}\|\tilde{z}\|_{L^{2}}
$$

Finally, we obtain

$$
\begin{aligned}
& \int \tilde{\rho} \tilde{z}_{x}^{2}-p(\tilde{\rho}-1) R^{p-1} \tilde{z}^{2}+\tilde{z}^{2} \\
& \leqslant \int\left[\tilde{\rho} z_{x}^{2}-p(\tilde{\rho}-1) R^{p-1} z^{2}+z^{2}\right]+C e^{-\gamma_{1} t} \sum_{j=1}^{N} a_{j}^{2}+C e^{-\gamma_{1} t}\|\tilde{z}\|_{L^{2}}^{2} \\
& \leqslant \tilde{H}(z)+C e^{-\gamma_{1} t} \sum_{j=1}^{N} a_{j}^{2}+C e^{-\gamma_{1} t}\|\tilde{z}\|_{L^{2}}^{2},
\end{aligned}
$$

and so by step 1 ,

$$
\begin{equation*}
\int \tilde{\rho} \tilde{z}_{x}^{2}-p(\tilde{\rho}-1) R^{p-1} \tilde{z}^{2}+\tilde{z}^{2} \leqslant C e^{-\gamma_{1} t} \sup _{t^{\prime} \geqslant t}\left\|z\left(t^{\prime}\right)\right\|_{H^{1}}^{2} \tag{5.51}
\end{equation*}
$$

Since $\int \tilde{R}_{j} \tilde{R}_{j x}=0$ by parity properties, we have

$$
\int \tilde{z}(t) \tilde{R}_{j}(t)=\int z(t) \tilde{R}_{j}(t)+\sum_{k=1, \ldots, N ; k \neq j} a_{k}(t) \int \tilde{R}_{j}(t) \tilde{R}_{k x}(t)
$$

and so $\sum_{j=1}^{N}\left|\int \tilde{z}(t) \tilde{R}_{j}(t)\right| \leqslant C e^{-\gamma_{1} t} \sup _{t^{\prime} \geqslant t}\left\|z\left(t^{\prime}\right)\right\|_{H^{1}}$. By a property similar to Lemma 2.3, we have, for $\lambda_{2}>0$,

$$
\begin{aligned}
& \int \tilde{\rho} \tilde{z}_{x}^{2}-p(\tilde{\rho}-1) R^{p-1} \tilde{z}^{2}+\tilde{z}^{2} \geqslant \lambda_{2}\|\tilde{z}\|_{H^{1}}^{2} \\
& \quad-\frac{1}{\lambda_{2}} \sum_{j=1}^{N}\left(\left|\int \tilde{z}\left(1-\partial_{x}^{2}\right) \tilde{R}_{j}\right|^{2}+\left|\int \tilde{z}\left(1-\partial_{x}^{2}\right) \tilde{R}_{j x}\right|^{2}\right)
\end{aligned}
$$

Therefore by (5.51), the orthogonality $\int \tilde{z}\left(1-\partial_{x}^{2}\right) \tilde{R}_{j x}=0$, and the control on $\int \tilde{z}\left(1-\partial_{x}^{2}\right) \tilde{R}_{j}$, we obtain

$$
\|\tilde{z}(t)\|_{H^{1}}^{2} \leqslant C e^{-\gamma_{1} t} \sup _{t^{\prime} \geqslant t}\left\|z\left(t^{\prime}\right)\right\|_{H^{1}}^{2}
$$

Second, we prove (5.49) for $a_{j}(t)$, using the equation of $\tilde{z}$ and integration in time. Note that $\tilde{z}$ satisfies

$$
\begin{aligned}
& \left(1-\partial_{x}^{2}\right) \tilde{z}_{t}+\left(\tilde{z}+p U^{p-1} \tilde{z}\right)_{x}=\sum_{k=1}^{N} a_{k}^{\prime}(t)\left(1-\partial_{x}^{2}\right) \tilde{R}_{k x} \\
& +\sum_{k=1}^{N} a_{k}(t)\left(c_{k}^{0}\left(\tilde{R}_{k x}\right)_{x x}-\left(c_{k}^{0}-1\right) \tilde{R}_{k x}+p U^{p-1} \tilde{R}_{k x}\right)_{x} \\
& -\left((z+U)^{p}-p U^{p-1} z-U^{p}\right)_{x}
\end{aligned}
$$

Since $\int \tilde{z}\left(1-\partial_{x}^{2}\right) \tilde{R}_{j x}=0$, we have

$$
0=\frac{d}{d t} \int \tilde{z}\left(1-\partial_{x}^{2}\right) \tilde{R}_{j x}=\int\left(1-\partial_{x}^{2}\right) \tilde{z}_{t} \tilde{R}_{j x}-c_{j}^{0} \int \tilde{z}\left(1-\partial_{x}^{2}\right) \tilde{R}_{j x x}
$$

thus, by integration by parts, and using $\left|c_{j}^{0}\left(\tilde{R}_{k x}\right)_{x x}-\left(c_{j}^{0}-1\right) \tilde{R}_{j x}+p U^{p-1} \tilde{R}_{j x}\right| \leqslant$ $C e^{-\gamma_{1} t}$, as before, we have

$$
\begin{aligned}
& \left|a_{j}^{\prime}(t) \int\left(\tilde{R}_{j x x}^{2}+\tilde{R}_{j x}^{2}\right)+\sum_{k=1, \ldots, N ; k \neq j} a_{k}^{\prime}(t) \int \tilde{R}_{j x}\left(1-\partial_{x}^{2}\right) \tilde{R}_{k x}\right| \\
& \leqslant C\|\tilde{z}(t)\|_{H^{1}}+C e^{-\gamma_{1} t} \sum_{k=1}^{N}\left|a_{k}\right|+C\|z(t)\|_{H^{1}}^{2} \leqslant C e^{-\gamma_{1} t}\|z(t)\|_{H^{1}}
\end{aligned}
$$

Thus, $\left|a_{j}^{\prime}(t)\right| \leqslant C e^{-\gamma_{1} t}\|z(t)\|_{H^{1}}$, for any $j \in\{1, \ldots, N\}$, and by integration between $t$ and $+\infty$, since $\lim _{t \rightarrow+\infty} a_{j}(t)=0$, we obtain

$$
\left|a_{j}(t)\right| \leqslant C e^{-\gamma_{1} t} \sup _{t^{\prime} \geqslant t}\left\|z\left(t^{\prime}\right)\right\|_{H^{1}}
$$

which completes the proof of (5.49).

## Appendix A. Proof of Lemma 2.3

Lemma 2.3 is a generalization of the positivity of the "orbital stability operator"

$$
\begin{equation*}
\mathcal{L}_{c}=\left(-E^{\prime \prime}+c m^{\prime \prime}\right)\left(\varphi_{c}\right)=-c \partial_{x}^{2}+(c-1)-p \varphi_{c}^{p-1} \tag{A.1}
\end{equation*}
$$

under suitable orthogonality conditions ; the proof uses the "continuity" of this family of self-adjoint operators with respect to perturbations of their potentials and coefficients, the arguments are very similar to those used in [14]. We present here a complete proof for the reader's convenience.

Let $c>c^{\star}(p)$, from Proposition 5.2 in $[\mathbf{2 1}]$ there exists $C>0$ such that if $v \in H^{1}(\mathbb{R})$ satisfies

$$
\begin{equation*}
\left(v,\left(1-\partial_{x}^{2}\right) \varphi_{c}\right)=\left(v,\left(1-\partial_{x}^{2}\right) \partial_{x} \varphi_{c}\right)=0 \tag{A.2}
\end{equation*}
$$

then

$$
\begin{equation*}
\left(\mathcal{L}_{c} v, v\right) \geqslant C\|v\|_{H^{1}}^{2} \tag{A.3}
\end{equation*}
$$

First we give a local version of $(A .3)$. Let $\Phi \in C^{2}(\mathbb{R}), \Phi(x)=\Phi(-x), \Phi^{\prime} \leqslant 0$ on $\mathbb{R}^{+}$, be such that $e^{-x} \leqslant \Phi(x) \leqslant 3 e^{-x}$ for all $x \in \mathbb{R}^{+}$and

$$
\Phi(x)=1 \text { on }[0,1], \Phi(x)=e^{-x} \text { on }[2,+\infty]
$$

Let $\Phi_{B}(x)=\Phi\left(\frac{x}{B}\right)$. There exists $B_{0}>0$, such that for all $B>B_{0}$, if $v \in H^{1}(\mathbb{R})$ satisfies (A.2) then

$$
\begin{equation*}
\int \Phi_{B}(x)\left(c v_{x}^{2}+(c-1) v^{2}-p U_{c}^{p-1} v^{2}\right) d x \geqslant C / 2 \int \Phi_{B}(x)\left(v_{x}^{2}+v^{2}\right) d x \tag{A.4}
\end{equation*}
$$

In order to prove (A.4), we need a perturbed version of $(A .3)$. We set $\mathcal{V}_{1}(c)=$ $\left(1-\partial_{x}^{2}\right) \varphi_{c}$ and $\mathcal{V}_{2}(c)=\left(1-\partial_{x}^{2}\right) \partial_{x} \varphi_{c}$, note that $\left(\mathcal{V}_{1}(c), \mathcal{V}_{2}(c)\right)=0$. One can easily prove, using the orthogonal projection on $\operatorname{span}\left(\mathcal{V}_{1}(c), \mathcal{V}_{2}(c)\right)^{\perp}$, that there exists $\delta>0$ such that if

$$
\begin{equation*}
\left|\left(v, \mathcal{V}_{1}(c)\right)\right|+\left|\left(v, \mathcal{V}_{2}(c)\right)\right| \leqslant \delta\|v\|_{H^{1}} \tag{A.5}
\end{equation*}
$$

then

$$
\begin{equation*}
\left(\mathcal{L}_{c} v, v\right) \geqslant \frac{3 C}{4}\|v\|_{H^{1}}^{2} \tag{A.6}
\end{equation*}
$$

Now, we write

$$
\begin{align*}
& \int \Phi_{B}(x)\left(c v_{x}^{2}+(c-1) v^{2}-p \varphi_{c}^{p-1} v^{2}\right) d x \\
& =\left(\mathcal{L}_{c}\left(\sqrt{\Phi_{B}} v\right), \sqrt{\Phi_{B}} v\right)-\frac{c}{4} \int \frac{\left(\Phi_{B}^{\prime}\right)^{2}}{\Phi_{B}} v^{2} d x+\frac{c}{2} \int \Phi_{B}^{\prime \prime} v^{2} d x \tag{A.7}
\end{align*}
$$

and

$$
\begin{equation*}
\left\|\sqrt{\Phi_{B}} v\right\|_{H^{1}}^{2}=\int \Phi_{B}(x)\left(v_{x}^{2}+v^{2}\right) d x+\frac{1}{4} \int \frac{\left(\Phi_{B}^{\prime}\right)^{2}}{\Phi_{B}} v^{2} d x-\frac{1}{2} \int \Phi_{B}^{\prime \prime} v^{2} d x \tag{A.8}
\end{equation*}
$$

Note that for $B>0$ large enough $\sqrt{\Phi_{B}} v$ satisfies $(A .5)$, thus $(A .6)$ and the identities (A.7), (A.8) imply

$$
\begin{align*}
& \int \Phi_{B}(x)\left(c v_{x}^{2}+(c-1) v^{2}-p \varphi_{c}^{p-1} v^{2}\right) d x \\
& \geqslant \frac{3 C}{4} \int \Phi_{B}(x)\left(v_{x}^{2}+v^{2}\right) d x+\frac{3 C / 4-c}{4} \int \frac{\left(\Phi_{B}^{\prime \prime}\right)^{2}}{\Phi_{B}} v^{2} d x-\frac{3 C / 4-c}{2} \int \Phi_{B}^{\prime \prime} v^{2} d x \tag{A.9}
\end{align*}
$$

Now, note that for $B \geqslant 1,\left|\Phi_{B}{ }^{\prime}(x)\right|+\left|\Phi_{B}^{\prime \prime}(x)\right| \leqslant \frac{C_{1}}{B} \Phi_{B}(x)$, where $C_{1}>0$ does not depend on $B$. Hence, taking $B>0$ sufficiently large, (A.9) implies (A.4).

Now, remark that $c(t, x)=\sum_{j=1}^{N} c_{j}(t) \zeta_{j}(t, x)$, where $\zeta_{1}(t, x)=1-\psi\left(x-y_{2}(t)\right)$, for $j \in[[2, N]] \zeta_{1}(t, x)=\psi\left(x-y_{j}(t)\right)-\psi\left(x-y_{j+1}(t)\right), \zeta_{N}(t, x)=\psi\left(x-y_{N}(t)\right)$, hence

$$
\begin{align*}
& \left(\mathcal{L}_{N} \varepsilon, \varepsilon\right)=  \tag{A.10}\\
& =\int\left(c(t, x) \varepsilon_{x}^{2}(t, x)+(c(t, x)-1) \varepsilon^{2}(t, x)-p R^{p-1}(t) \varepsilon^{2}(t)\right) d x \\
& =\sum_{j=1}^{N} \int\left(\zeta_{j}(t) c_{j}(t) \varepsilon_{x}^{2}(t)+\left(\zeta_{j}(t) c_{j}(t)-1\right) \varepsilon^{2}(t)-p R_{j}^{p-1}(t) \varepsilon^{2}(t)\right) d x
\end{align*}
$$

Thus it is clear that $\mathcal{L}_{N}$ is the sum of $N$ local operators similar to (A.4), which leads us to the following decomposition :

$$
\begin{aligned}
\left(\mathcal{L}_{N} \varepsilon, \varepsilon\right)= & \sum_{j=1}^{N} \int \Phi_{B}\left(x-x_{j}(t)\right)\left(c_{j}(t) \varepsilon_{x}^{2}+\left(c_{j}(t)-1\right) \varepsilon^{2}-p R_{j}^{p-1} \varepsilon^{2}\right) d x \\
& -p \int\left(R^{p-1}-\sum_{j=1}^{N} \Phi_{B}\left(x-x_{j}(t)\right) R_{j}^{p-1}\right) \varepsilon^{2}(t) d x \\
& +\sum_{j=1}^{N}\left(\Phi_{B}\left(x-x_{j}(t)\right)\left(c(t, x)-c_{j}(t)\right)\left(\varepsilon_{x}^{2}(t)+\varepsilon^{2}(t)\right) d x\right. \\
& +\int\left(1-\sum_{j=1}^{N} \Phi_{B}\left(x-x_{j}(t)\right)\right)\left(c(t, x) \varepsilon_{x}^{2}+(c(t, x)-1) \varepsilon^{2}\right) d x
\end{aligned}
$$

Recall that $c_{j}(t) \geqslant c^{\star}(p)+\sigma_{0}$, hence there exists $C_{0}>0$ depending only on $\sigma_{0}$ such that (A.4) holds with $c_{j}(t)$ for all $j$, this and the orthogonality conditions satisfied by $\varepsilon$ imply that for all $j$

$$
\begin{aligned}
& \int \Phi_{B}\left(x-x_{j}\right)\left(c_{j} \varepsilon_{x}^{2}+\left(c_{j}-1\right) \varepsilon^{2}-p R_{j}^{p-1} \varepsilon^{2}\right) d x \\
& \geqslant \frac{C_{0}}{2} \int \Phi_{B}\left(x-x_{j}\right)\left(\varepsilon_{x}^{2}+\varepsilon^{2}\right) d x
\end{aligned}
$$

Let $B>B_{0}>0$ and $L_{4}=4 k B$, where $B_{0}$ and the integer $k$ are to be chosen later. Recall that $\Phi_{B}(x)=1$ for $|x| \leqslant B$, hence the exponential decay of $R_{j}$ implies that

$$
\begin{aligned}
0 & \leqslant R^{p-1}-\sum_{j=1}^{N} \Phi_{B}\left(x-x_{j}(t)\right) R_{j}^{p-1} \\
& \leqslant\|R\|_{L^{\infty}\left(\left|x-x_{j}(t)\right|>B\right)}^{p-1}+C \sum_{i \neq j} R_{i} R_{j} \leqslant C e^{-\sigma_{0} B} .
\end{aligned}
$$

Let us estimate the third term in the above decomposition. Remark that $\mid x-$ $x_{j}(t) \mid \leqslant k B$ implies that for all $i\left|x-y_{i}(t)\right| \geqslant k B$ since $\left|x_{j}-y_{j}(t)\right| \geqslant L_{4} / 2 \geqslant 2 k B$; hence the decay of $\psi$ and $1-\psi$ imply that for $\left|x-x_{j}(t)\right| \leqslant k B$

$$
\left|\zeta_{j}(t, x)-1\right|+\sum_{i \neq j}\left|\zeta_{i}(t, x)\right| \leqslant C e^{-\sigma_{0} k B}
$$

Finally, this inequality and the decay of $\Phi_{B}(x)$ imply

$$
\begin{aligned}
\left|\Phi_{B}\left(x-x_{j}(t)\right)\left(c(t, x)-c_{j}(t)\right)\right| & \leqslant\left\|c(t, x)-c_{j}(t)\right\|_{L^{\infty}\left(\left|x-x_{j}(t)\right| \leqslant k B\right)}+C e^{-k} \\
& \leqslant C e^{-\sigma_{0} k B}+C e^{-k} .
\end{aligned}
$$

Let $\lambda_{0}=1 / 2 \min \left(\sigma_{0}, C_{0} / 2\right)$, gathering the above estimates and taking $B$ and $k$ large enough imply

$$
\begin{aligned}
\left(\mathcal{L}_{N} \varepsilon, \varepsilon\right) & \geqslant 2 \lambda_{0} \int\left(\varepsilon_{x}^{2}+\varepsilon^{2}\right) d x-C\left(e^{-\sigma_{0} B}+C e^{-k}\right) \int\left(\varepsilon_{x}^{2}+\varepsilon^{2}\right) d x \\
& \geqslant \lambda_{0} \int\left(\varepsilon_{x}^{2}+\varepsilon^{2}\right) d x
\end{aligned}
$$

This achieves the proof of Lemma 2.3.

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