# Dirac groupoids and Dirac bialgebroids 

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#### Abstract

We describe infinitesimally Dirac groupoids via geometric objects that we call Dirac bialgebroids. In the two well-understood special cases of Poisson and presymplectic groupoids, the Dirac bialgebroids are equivalent to the Lie bialgebroids and IM-2-forms, respectively. In the case of multiplicative involutive distributions on Lie groupoids, we find new properties of infinitesimal ideal systems.


1 Introduction ..... 179
2 Preliminaries ..... 187
$3 \quad A$-Manin pairs and Dirac bialgebroids ..... 199
4 The Dirac bialgebroid associated to a Dirac groupoid ..... 202
5 The Dirac bialgebroid associated to a Dirac algebroid ..... 205
6 The Lie algebroid of a multiplicative Dirac structure ..... 209
7 Examples ..... 214
Appendix A Proof of Theorem 5.5 ..... 223
References ..... 235

## 1. Introduction

Courant and Weinstein [7], and independently Dorfman [11, introduced the notion of Dirac structure in the late 1980's. Courant and Weinstein were studying work of Littlejohn on the "guiding centre of motion" of a particle in a magnetic field [26]. They introduced Dirac structures as a unified approach to presymplectic and Poisson manifolds. Dorfman showed Dirac
structures to be useful in the theory of infinite dimensional Hamiltonian systems. Because the theory of Hamiltonian systems with constraints can be well formulated using these objects, they were named after Dirac and his theory of constraints [10]. Poisson and presymplectic manifolds and involutive distributions are the corner cases of Dirac manifolds.

To be more explicit, let $M$ be a smooth manifold. Then the direct sum $T M \oplus T^{*} M$ of vector bundles over $M$ is endowed with a bracket $\llbracket \cdot, \cdot \rrbracket$ and a pairing $\langle\cdot, \cdot\rangle$ given by

$$
\llbracket\left(X_{1}, \theta_{1}\right),\left(X_{2}, \theta_{2}\right) \rrbracket=\left(\left[X_{1}, X_{2}\right], £_{X_{1}} \theta_{2}-\mathbf{i}_{X_{2}} \mathbf{d} \theta_{1}\right)
$$

and

$$
\left\langle\left(X_{1}, \theta_{1}\right),\left(X_{2}, \theta_{2}\right)\right\rangle=\theta_{1}\left(X_{2}\right)+\theta_{2}\left(X_{1}\right)
$$

for all vector fields $X_{1}, X_{2} \in \mathfrak{X}(M)$ and one-forms $\theta_{1}, \theta_{2} \in \Omega^{1}(M)$. A Dirac structure on $M$ is a subbundle $\mathrm{D} \subseteq T M \oplus T^{*} M$ that is maximally isotropic relative to the pairing, and the sections of which are closed under the bracket. The graphs of the vector bundle morphisms $\pi^{\sharp}: T^{*} M \rightarrow T M$ and $\omega^{b}: T M \rightarrow$ $T^{*} M$ associated to a Poisson bivector $\pi$ and, respectively, a closed 2-form $\omega$ on $M$ are two examples of Dirac structures.

Here we are interested in Dirac groupoids, i.e. Lie groupoids with Dirac structures that are compatible with the multiplication. As in the Lie group case, a geometric structure on a Lie groupoid, that is compatible with the multiplication, has a counterpart on the Lie algebroid of the groupoid. This counterpart can simply be understood as the differential of the structure, which is a structure of the same type but on the Lie algebroid. For instance, the counterpart of a multiplicative Poisson structure on a Lie groupoid is a Poisson structure on the Lie algebroid of the groupoid, together with some compatibility conditions between the Poisson and the Lie algebroid structures [35]. More generally, Ortiz has proved in his thesis that the Lie algebroid of a Dirac groupoid is a Dirac algebroid, i.e. a Lie algebroid with a Dirac structure that is compatible with the Lie algebroid structure (an LA-Dirac structure). This defines a bijection between multiplicative Dirac structures on a source simply connected Lie groupoid and LA-Dirac structures on its Lie algebroid.

On the other hand, we observe in the literature that the infinitesimal counterpart of a multiplicative geometric object is often described as a geometric object of completely different, to some extent more simple, nature. A multiplicative distribution on a Lie group corresponds for instance to an ideal in its Lie algebra [19, 37]. Knowing this, it would be rather cumbersome
to infinitesimally describe a multiplicative distribution on a Lie group as a distribution on the Lie algebra, together with some compatibility condition in terms of the tangent Lie algebra.

To illustrate this, let us recall how Poisson and presymplectic groupoids, and involutive multiplicative distributions on Lie groupoids can be described infinitesimally. Weinstein introduced Poisson groupoids as a simultaneous generalisation of Poisson Lie groups and symplectic groupoids 43]. He proved that a multiplicative Poisson structure on a Lie groupoid induces a Lie algebroid structure on the dual of the Lie algebroid of the Lie groupoid. Mackenzie and Xu then introduced the notion of Lie bialgebroid to encode the compatibility condition of this pair of Lie algebroids in duality [34. Then they showed that there is a one-to-one correspondence between source simply connected Poisson groupoids and integrable Lie bialgebroids ${ }^{1}$ [35]. Lie bialgebroids describe hence infinitesimally Poisson groupoids. Liu, Weinstein and Xu introduced at the same time the notion of Courant algebroid. With this new notion, a Lie bialgebroid could be defined as a pair of Lie algebroids which are two transverse Dirac structures in a Courant algebroid [27.

Presymplectic groupoids were originally introduced by Xu [44 under the name "quasi-symplectic groupoids" and then used by Bursztyn, Crainic, Weinstein and Zhu in a work motivated by the integration of Dirac structures twisted by closed 3 -forms [4]. There a presymplectic groupoid is a Lie groupoid with a multiplicative closed 2 -form satisfying some additional regularity conditions. Afterwards the terminology slightly changed and now one often calls presymplectic a Lie groupoid with any multiplicative closed 2-form. The infinitesimal description of a presymplectic groupoid is an IM-2-form, i.e. a very particular vector bundle morphism from the Lie algebroid of the groupoid to the cotangent bundle of the manifold of units [3, 4].

Infinitesimal ideal systems, the "ideals" in Lie algebroids [23], are the infinitesimal counterpart of multiplicative distributions [18, 23]. Multiplicative distributions have appeared to be useful as the polarisations in Hawkins' groupoid approach to quantisation [18, and wide multiplicative distributions on Lie groupoids were also studied in a modern approach to Cartan's work on pseudogroups [9].

Lie bialgebroids, IM-2-forms and infinitesimal ideal systems seem by nature very different, although Poisson groupoids, presymplectic groupoids and multiplicative distributions on Lie groupoids are three basic classes of Dirac groupoids.

[^0]Our goal is to understand how Lie bialgebroids, IM-2-forms and infinitesimal ideal systems are in fact the corner cases of an infinitesimal description of Dirac groupoids. In [21] we constructed a Courant algebroid B over $M$ associated to a Dirac groupoid $(G \rightrightarrows M, \mathrm{D})$, such that the space of units $U$ of the Dirac structure seen as a groupoid is naturally embedded as a Dirac structure in B . We classified ${ }^{2}$ the Dirac homogeneous spaces of $(G \rightrightarrows M, \mathrm{D})$ via Dirac structures in B , and we conjectured consequently that the whole information about D was contained in the Manin pair $(\mathrm{B}, U)$. In [20] we studied linear splittings of the double vector bundle $T A \oplus T^{*} A$ over a Lie $\operatorname{algebroid} A$, and we proved that these correspond to a certain class of Dorfman connections, which that paper introduced. We studied linear splittings adapted to LA-Dirac structures (the linearisations of multiplicative Dirac structures on Lie groupoids), and completely understood LA-Dirac structures in terms of the corresponding Dorfman connections, showing how to reconstruct an LA-Dirac structure from some simple data.

Here we build on the results in those two papers to prove how the Manin pair $(\mathrm{B}, U)$ associated to a Dirac groupoid is in fact equivalent to this Dirac groupoid, and which Manin pairs appear in this manner as the infinitesimal version of Dirac groupoids. The examples that we discuss show that our theorem provides a unified proof for the results in [3, 35].

Let us summarise our main result in a more detailed manner. Let $G$ be a Lie groupoid over $M$, with Lie algebroid $A$. Then the bundle $T G \oplus T^{*} G$ has the structure of a Lie groupoid over $T M \oplus A^{*}$. A Dirac structure D on $G$ is multiplicative if it is a subgroupoid of $T G \oplus T^{*} G$. The set of units of D seen as a groupoid is a subbundle $\iota: U \hookrightarrow T M \oplus A^{*}$. We proved in [21] that $U$ inherits a natural Lie algebroid structure with anchor the restriction to $U$ of the projection onto $T M$. The Lie algebroid $U$ is compatible with the Lie algebroid $A$ in a sense that this paper identifies. The triple $(A, U, \iota)$ is then a Dirac bialgebroid, a new geometrical notion that we now define.

Let $(A, \rho,[\cdot, \cdot])$ and $\left(U, \rho_{U}, \llbracket \cdot, \cdot \rrbracket\right)$ be two Lie algebroids over $M$ with an injective morphism $\iota: U \rightarrow T M \oplus A^{*}$ of vector bundles such that $\rho_{U}=$ $\operatorname{pr}_{T M} \circ \iota$. The triple $(A, U, \iota)$ is called a Dirac bialgebroid (over $A$ ) if there exists a Courant algebroid $C$ over $M$ such that

1) $(C, U)$ is a Manin pair [5], i.e. $U$ is a Dirac structure in $C$,

[^1]2) there exists a (degenerate) Courant morphism ${ }^{3} \Phi: A \oplus T^{*} M \rightarrow C$ such that
\[

$$
\begin{aligned}
\Phi\left(A \oplus T^{*} M\right)+U & =C \\
\text { and }\langle u, \Phi(\tau)\rangle_{C}=\langle\iota(u), \tau\rangle \text { for all }(u, \tau) & \in U \times_{M}\left(A \oplus T^{*} M\right)
\end{aligned}
$$
\]

Two Dirac bialgebroids $(A, U, \iota)$ and $\left(A, U^{\prime}, \iota^{\prime}\right)$ over $A$ are equivalent they define the same Lie algebroid $\iota(U)=\iota^{\prime}\left(U^{\prime}\right) \subseteq T M \oplus A^{*}$ with the restriction of $\mathrm{pr}_{T M}$ as anchor. Our main theorem is the following:

Theorem 1.1. Let $(G \rightrightarrows M, D)$ be a source simply connected Dirac groupoid. Let $A$ be the Lie algebroid of $G \rightrightarrows M$ and $\iota: U \hookrightarrow T M \oplus A^{*}$ the set of units of D . The triple $(A, U, \iota)$ is a Dirac bialgebroid and the map

$$
(G, \mathrm{D}) \mapsto(A, U, \iota)
$$

defines a bijection between multiplicative Dirac structures on $G \rightrightarrows M$ and equivalence classes of Dirac bialgebroids over $A$.

Recall for instance that a Lie bialgebroid $\left(A, A^{*}\right)$ is a pair of Lie algebroids in duality that are two transverse Dirac structures in a Courant algebroid; which we can hence write $A \oplus A^{*}$. Set $\iota:=\left(\rho_{\star}, \mathrm{id}_{A^{*}}\right): A^{*} \rightarrow T M \oplus$ $A^{*}$, where $\rho_{\star}$ is the anchor of the Lie algebroid $A^{*}$. Section 7.2 shows that $\left(A, A^{*}, \iota\right)$ is a Dirac bialgebroid, with ambient Courant algebroid $C=$ $A \oplus A^{*}$.

Take now an IM-2-form $\sigma: A \rightarrow T^{*} M$, i.e. with

$$
\langle\rho(a), \sigma(b)\rangle=-\langle\rho(b), \sigma(a)\rangle \quad \text { and } \quad \sigma[a, b]=£_{\rho(a)} \sigma(b)-\mathbf{i}_{\rho(b)} \mathbf{d} \sigma(a)
$$

for all $a, b \in \Gamma(A)$. Define $\iota=\left(\mathrm{id}_{T M}, \sigma^{t}\right): T M \rightarrow T M \oplus A^{*}$. Then $(A, T M, \iota)$ is a Dirac bialgebroid with ambient Courant algebroid $C$ the standard Courant-Dorfman structure on $T M \oplus T^{*} M$ (see Section 7.3).

Finally consider an infinitesimal ideal system $\left(A, F_{M}, J, \nabla\right)$, i.e. $F_{M} \subseteq$ $T M$ is an involutive subbundle, $J \subseteq A$ is a subbundle such that $\rho(J) \subseteq F_{M}$ and $\nabla$ is a flat $F_{M}$-connection on $A / J$ with the following properties:

1) If $\bar{a} \in \Gamma(A / J)$ is $\nabla$-parallel, then $[a, j] \in \Gamma(J)$ for all $j \in \Gamma(J)$.
2) If $\bar{a}, \bar{b} \in \Gamma(A / J)$ are $\nabla$-parallel, then $\overline{[a, b]}$ is also $\nabla$-parallel.

[^2]3) If $\bar{a} \in \Gamma(A / J)$ is $\nabla$-parallel, then $\overline{\rho(a)} \in \Gamma\left(T M / F_{M}\right)$ is $\nabla^{F_{M}}$-parallel, where
$$
\nabla^{F_{M}}: \Gamma\left(F_{M}\right) \times \Gamma\left(T M / F_{M}\right) \rightarrow \Gamma\left(T M / F_{M}\right)
$$
is the Bott connection associated to $F_{M}$.
Section 7.4 shows that $\left(A, F_{M}, J, \nabla\right)$ is an infinitesimal ideal system if and only if $\left(A, F_{M} \oplus J^{\circ}, \iota\right)$ is a Dirac bialgebroid with $\iota: F_{M} \oplus J^{\circ} \rightarrow T M \oplus A^{*}$ the inclusion, and the Lie algebroid bracket $[\cdot, \cdot]_{\nabla}$ on $F_{M} \oplus J^{\circ}$ defined by $\left[\left(X_{1}, \alpha_{1}\right),\left(X_{2}, \alpha_{2}\right)\right]_{\nabla}=\left(\left[X_{1}, X_{2}\right], \nabla_{X_{1}}^{*} \alpha_{2}-\nabla_{X_{2}}^{*} \alpha_{1}\right)$. In order to prove this, we construct a natural Lie algebroid structure on
$$
\bar{A}:=\left(F_{M} \oplus A\right) / \operatorname{graph}\left(-\left.\rho\right|_{J}: J \rightarrow F_{M}\right)
$$
which exists if and only if the quadruple $\left(A, F_{M}, J, \nabla\right)$ is an infinitesimal ideal system. We find this result interesting in its own right because it is a new manner of forming the quotient of an algebroid by an infinitesimal ideal system, as a generalisation of the quotient of a Lie algebra by an ideal. The ambient Courant algebroid $C$ is in this example the Courant algebroid $\bar{A} \oplus \bar{A}^{*}$ defined by the Lie bialgebroid $\left(\bar{A}, \bar{A}^{*}\right)$ with trivial Lie algebroid structure on $\bar{A}^{*}$.

Note that the two families $\left(A, A^{*},\left(\rho_{\star}, \mathrm{id}_{A^{*}}\right)\right)$ and $\left(A, T M,\left(\mathrm{id}_{T M}, \sigma^{t}\right)\right)$ of Dirac bialgebroids can be seen as extreme cases of Dirac bialgebroids, like Poisson and presymplectic groupoids are the extreme cases of Dirac groupoids. In the first family, the interesting information is in the pair $\left(A, A^{*}\right)$ and in the second one, it is rather in the embedding

$$
\left(\mathrm{id}_{T M}, \sigma^{t}\right): T M \rightarrow T M \oplus A^{*}
$$

Let us finally point out that a Dirac groupoid is an $L A$-groupoid; the space D has a Lie groupoid structure over $U$ and a Lie algebroid structure over $G$, and the structures are compatible [30. If the Lie algebroid structure is integrable, the Dirac groupoid should integrate to a presymplectic double Lie groupoid ("presymplectic" in the sense of [4]). Hence, this paper gives a class of examples of Courant algebroids (including the ones defined by Lie bialgebroids) that could be seen as integrating to "presymplectic 2-groupoids", following Mehta and Tang's proposal to integrate Courant algebroids defined by Lie bialgebroids to "symplectic 2 -groupoids" [36].

## Methodology and outline of the paper

First Section 2 recalls some background on Lie groupoids and their tangent and cotangent prolongations, on Courant algebroids and Dirac structures, on Dorfman connections and dull algebroids, and on splittings of VB-algebroids and 2 -term representations up to homotopy.

Section 3 introduces the notions of $A$-Manin pairs and Dirac bialgebroids, before showing how they are equivalent. Then Section 4 proves that the Manin pair associated in [21] to a Dirac groupoid ( $G, \mathrm{D}$ ) is an $A$-Manin pair, and so that the triple $(A, U, \iota)$ is a Dirac bialgebroid.

Section 5 studies LA-Dirac structures on Lie algebroids. First we summarise the results in [20] on linear splittings of LA-Dirac structures and we describe the two 2-term representations up to homotopy describing in a linear splitting the two VB-algebroid sides. Then we describe how this data allows us to construct an $A$-Manin pair associated to each LA-Dirac structure, and how this defines a bijection between $A$-Manin pairs and LA-Dirac structures over $A$.

Section 6 recalls a result of [38] about the one-to-one correspondence between Dirac groupoids and integrable Dirac algebroids, i.e. integrable Lie algebroids with compatible Dirac structures. Then we describe explicitly the Lie algebroid $A(\mathrm{D}) \rightarrow U$ of the multiplicative Dirac structure in terms of the Dorfman connection $£^{U}: \Gamma(U) \times \Gamma\left(U^{*}\right) \rightarrow \Gamma\left(U^{*}\right)$ that is dual to the Lie algebroid bracket on sections of $U$.

Section 6.3 finally shows that the Dirac bialgebroid associated to the Dirac algebroid $\left(A, \mathrm{D}_{A}\right)$ that is canonically isomorphic to $(A, A(\mathrm{D}))$ is the same as the Dirac bialgebroid constructed in Section 4. Section 6.4 gives as a summary a sketch of the strategy to integrate an integrable Dirac bialgebroid to a Dirac groupoid.

Section 7 shows how the notion of Dirac bialgebroid encompasses the notions of Lie bialgebroids, IM-2-forms and infinitesimal ideal systems.

Let us repeat the different steps that lead us to our main theorem:
$\S 3$ Equivalence classes of $A$-Manin pairs are in one-to-one correspondence with equivalence classes of Dirac bialgebroids.
$\S 4$ A Dirac groupoid defines an equivalence class of $A$-Manin pairs and so of Dirac bialgebroids.
$\S 5$ There is a bijection between LA-Dirac structures and equivalence classes of Dirac bialgebroids.
§6.1 The Lie algebroid of a Dirac groupoid is a Dirac algebroid. This defines a bijection between source simply connected Dirac groupoids and integrable Dirac algebroids [38.
§6.2 Explicit computation of the LA-Dirac structure defined as in Section 6.1 by a multiplicative Dirac structure.
$\S 6.3$ The Dirac bialgebroids defined by a Dirac groupoid and by the corresponding LA-Dirac structure coincide.


## Notation and conventions

In the following, $G \rightrightarrows M$ is always a (Hausdorff) Lie groupoid over the base $M$. The space of units $M$ is always considered to be a subset of the space $G$ of arrows. The structure maps of a Lie groupoid is written as $(\epsilon, \mathrm{s}, \mathrm{t}, \mathrm{m}, \mathrm{i})$, unless specified otherwise. The Lie algebroid of a Lie groupoid is constructed using right-invariant vector fields on the groupoid, and the anchor is the restriction of $T \mathrm{t}$ to $\left.T^{\mathrm{s}} G\right|_{M}$. To simplify the notation, the Lie algebroid $\left(A(G),[\cdot, \cdot]_{\mathrm{A}(G)}, \rho_{A(G)}\right)$ of a Lie groupoid $G$ is always written as $(A,[\cdot, \cdot], \rho)$.

Let $M$ be a smooth manifold. We denote by $\mathfrak{X}(M)$ and $\Omega^{1}(M)$ the spaces of smooth sections of the tangent and the cotangent bundle, respectively. For an arbitrary vector bundle $E \rightarrow M$, the space of sections of $E$ is written as $\Gamma(E)$. We write in general $q_{E}: E \rightarrow M$ for vector bundle projections, except for $p_{M}=q_{T M}: T M \rightarrow M, c_{M}=q_{T^{*} M}: T^{*} M \rightarrow M$ and $\pi_{M}=q_{T M \oplus T^{*} M}: T M \oplus T^{*} M \rightarrow M$.

Given a section $\varepsilon$ of $E^{*}$, we always write $\ell_{\varepsilon}: E \rightarrow \mathbb{R}$ for the linear function associated to it, i.e. the function defined by $e_{m} \mapsto\left\langle\varepsilon(m), e_{m}\right\rangle$ for all $e_{m} \in E$. We write $\phi^{t}: B^{*} \rightarrow A^{*}$ for the dual morphism to a morphism $\phi: A \rightarrow B$ of vector bundles over the identity, and we write $F^{*} \omega$ for the pullback of a form $\omega \in \Omega(N)$ under a smooth map $F: M \rightarrow N$ of manifolds.

Let $A$ be a Lie algebroid. For each $a \in \Gamma(A)$, we have two derivations over $\rho(a)$ :

$$
\begin{array}{ll}
£_{a}: \Gamma\left(A \oplus T^{*} M\right) \rightarrow \Gamma\left(A \oplus T^{*} M\right), & £_{a}\left(a^{\prime}, \theta\right)=\left(\left[a, a^{\prime}\right], £_{\rho(a)} \theta\right)  \tag{1.1}\\
£_{a}: \Gamma\left(T M \oplus A^{*}\right) \rightarrow \Gamma\left(T M \oplus A^{*}\right), & £_{a}(X, \alpha)=\left([\rho(a), X], £_{a} \alpha\right) .
\end{array}
$$

Note also that the anchor $\rho$ of a Lie algebroid $A$ defines a vector bundle morphism $\left(\rho, \rho^{t}\right): A \oplus T^{*} M \rightarrow T M \oplus A^{*}$.

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## 2. Preliminaries

This section collects necessary background on the Lie groupoid structure on the Pontryagin bundle $T G \oplus T^{*} G$ of a Lie groupoid $G \rightrightarrows M$, on Courant algebroids, Dirac structures and Dorfman connections, and on double vector bundles, VB-algebroids and representations up to homotopy.

### 2.1. Tangent and cotangent Lie groupoids

Let $G \rightrightarrows M$ be a Lie groupoid. Applying the tangent functor to each of the maps defining $G$ yields a Lie groupoid structure on $T G$ with base $T M$, source $T \mathrm{~s}$, target $T \mathrm{t}$ and multiplication $T \mathrm{~m}: T\left(G \times_{M} G\right) \rightarrow T G$. The identity at $v_{p} \in T_{p} M$ is $1_{v_{p}}=T_{p} \epsilon v_{p}$. This defines the tangent prolongation of $G \rightrightarrows M$.

There is also an induced Lie groupoid structure on $T^{*} G \rightrightarrows A^{*}=(T M)^{\circ}$ [6] (see also [40]). The source map $\hat{\text { s }}: T^{*} G \rightarrow A^{*}$ is given by

$$
\begin{aligned}
& \hat{\mathbf{s}}\left(\alpha_{g}\right) \in A_{\mathbf{s}(g)}^{*} G \text { for } \alpha_{g} \in T_{g}^{*} G, \\
& \hat{\mathbf{s}}\left(\alpha_{g}\right)\left(a_{\mathbf{s}(g)}\right)=\alpha_{g}\left(T_{\mathbf{s}(g)} L_{g}\left(a_{\mathbf{s}(g)}-T_{\mathbf{s}(g)} \mathrm{t} a_{\mathbf{s}(g)}\right)\right)
\end{aligned}
$$

for all $a_{\mathbf{s}(g)} \in A_{\mathbf{s}(g)} G$, and the target map $\hat{\mathrm{t}}: T^{*} G \rightarrow A^{*}$ is given by

$$
\hat{\mathfrak{t}}\left(\alpha_{g}\right) \in A_{\mathfrak{t}(g)}^{*} G, \quad \hat{\mathrm{t}}\left(\alpha_{g}\right)\left(a_{\mathrm{t}(g)}\right)=\alpha_{g}\left(T_{\mathrm{t}(g)} R_{g}\left(a_{\mathrm{t}(g)}\right)\right)
$$

for all $a_{\mathrm{t}(g)} \in A_{\mathrm{t}(g)} G$. If $\hat{\mathbf{s}}\left(\alpha_{g}\right)=\hat{\mathrm{t}}\left(\alpha_{h}\right)$, then the product $\alpha_{g} \star \alpha_{h}$ is defined by $\left(\alpha_{g} \star \alpha_{h}\right)\left(T \mathrm{~m}\left(v_{g}, v_{h}\right)\right)=\alpha_{g}\left(v_{g}\right)+\alpha_{h}\left(v_{h}\right)$ for composable pairs $\left(v_{g}, v_{h}\right) \in$ $T_{(g, h)}\left(G \times_{M} G\right)$.

The fibred product $T G \times{ }_{G} T^{*} G$ inherits an induced Lie groupoid structure over $T M \times{ }_{M} A^{*}$. We write $\mathbb{T} \mathrm{t}$ for the target map $T G \times{ }_{G} T^{*} G \rightarrow T M \times{ }_{M}$ $A^{*}$, and $\mathbb{T}$ : $T G \times_{G} T^{*} G \rightarrow T M \times_{M} A^{*}$ for the source map. Here again, we write $p_{g} \star p_{h}$ for the product of compatible $p_{g}, p_{h} \in T G \oplus T^{*} G$.

Note that the restriction to $M$ of the kernel of $\mathbb{T}$ s can be identified as follows with $A \oplus T^{*} M$. The elements of $T_{g} G \times T_{g}^{*} G$ that are sent by $\mathbb{T}$ s $0_{\mathbf{s}(g)} \in T_{\mathbf{s}(g)} M \times A_{\mathbf{s}(g)}^{*}$ are of the form $\left(\left(R_{g}\right)_{*} a_{\mathrm{t}(g)},\left(T_{g} \mathrm{t}\right)^{t} \theta_{\mathrm{t}(g)}\right)$ with $a_{\mathrm{t}(g)} \in$ $A_{\mathrm{t}(g)}=T_{\mathrm{t}(g)}^{\mathrm{s}} M$ and $\theta_{\mathrm{t}(g)} \in T_{\mathrm{t}(g)}^{*} M$. We identify $\left(a_{m},\left(T_{m} \mathrm{t}\right)^{t} \theta_{m}\right) \in \operatorname{ker}(\mathbb{T} \mathrm{s})_{m}$ with $\left(a_{m}, \theta_{m}\right)$ in $A_{m} \times T_{m}^{*} M$. Given a section $\tau=(a, \theta)$ of $A \oplus T^{*} M$, the right invariant section $\tau^{r} \in \Gamma(\operatorname{ker} \mathbb{T} \mathbf{s})$ defined by $\tau$ is given by $\tau^{r}(g)=\tau_{\mathrm{t}(g)} \times$ $\left(0_{g}, 0_{g}\right)=\left(a^{r}(g), T_{g} \mathrm{t}^{t} \theta(\mathrm{t}(g))\right) \in \operatorname{ker}(\mathbb{T} \mathbf{s})_{g}$ for all $g \in G$. Furthermore, the restriction of $\mathbb{T} t$ to $\left.\operatorname{ker}(\mathbb{T} s)\right|_{M}$ is, via the identification above, the map

$$
\left(\rho, \rho^{t}\right): A \oplus T^{*} M \rightarrow T M \oplus A^{*}
$$

### 2.2. Courant algebroids and Dirac structures

A Courant algebroid [27, 41] over a manifold $M$ is a vector bundle $C \rightarrow M$ equipped with a fibrewise nondegenerate symmetric bilinear form $\langle\cdot, \cdot\rangle$, a bilinear bracket $[\cdot, \cdot]$ on the smooth sections $\Gamma(C)$, and a vector bundle map $\rho: C \rightarrow T M$ over the identity called the anchor, which satisfy the following conditions 4

1) $\llbracket c_{1}, \llbracket c_{2}, c_{3} \rrbracket \rrbracket=\llbracket \llbracket c_{1}, c_{2} \rrbracket, c_{3} \rrbracket+\llbracket c_{2}, \llbracket c_{1}, c_{3} \rrbracket \rrbracket$,
2) $\rho\left(c_{1}\right)\left\langle c_{2}, c_{3}\right\rangle=\left\langle\llbracket c_{1}, c_{2} \rrbracket, c_{3}\right\rangle+\left\langle c_{2}, \llbracket c_{1}, c_{3} \rrbracket\right\rangle$,
3) $\llbracket c_{1}, c_{2} \rrbracket+\llbracket c_{2}, c_{1} \rrbracket=\mathcal{D}\left\langle c_{1}, c_{2}\right\rangle$
${ }^{4}$ The following conditions
4) $\rho\left(\llbracket c_{1}, c_{2} \rrbracket\right)=\left[\rho\left(c_{1}\right), \rho\left(c_{2}\right)\right]$,
5) $\llbracket c_{1}, f c_{2} \rrbracket=f \llbracket c_{1}, c_{2} \rrbracket+\left(\rho\left(c_{1}\right) f\right) c_{2}$
are then also satisfied. They are often part of the definition in the literature, but [42] observed that they follow from (1)-(3). We quickly give here a simple manner to get (4)-(5) from (1)-(3). To get (5), replace $c_{2}$ by $f c_{2}$ in (2). Then replace $c_{2}$ by $f c_{2}$ in (1) in order to get (4).
for all $c_{1}, c_{2}, c_{3} \in \Gamma(C)$ and $f \in C^{\infty}(M)$. Here, we use the notation $\mathcal{D}:=$ $\rho^{t} \circ \mathbf{d}: C^{\infty}(M) \rightarrow \Gamma(C)$, using $\langle\cdot, \cdot\rangle$ to identify $C$ with $C^{*}:\langle\mathcal{D} f, c\rangle=\rho(c)(f)$ for all $f \in C^{\infty}(M)$ and $c \in \Gamma(C)$.

If $C_{1}$ and $C_{2}$ are Courant algebroids over the same base $M$, then a Courant morphism is a vector bundle morphism $\Phi: C_{1} \rightarrow C_{2}$ over the identity on $M$, such that $\rho_{2} \circ \Phi=\rho_{1},\left\langle c, c^{\prime}\right\rangle_{C_{1}}=\left\langle\Phi(c), \Phi\left(c^{\prime}\right)\right\rangle_{C_{2}}$ and $\Phi \llbracket c, c^{\prime} \rrbracket_{C_{1}}=\llbracket \Phi(c), \Phi\left(c^{\prime}\right) \rrbracket_{C_{2}}$ for all $c, c^{\prime} \in \Gamma\left(C_{1}\right)$.

Example 2.1. The direct sum $T M \oplus T^{*} M$ with the projection on $T M$ as anchor map, $\rho=\operatorname{pr}_{T M}$, the symmetric bracket $\langle\cdot, \cdot\rangle$ given by

$$
\begin{equation*}
\left\langle\left(v_{m}, \theta_{m}\right),\left(w_{m}, \omega_{m}\right)\right\rangle=\theta_{m}\left(w_{m}\right)+\omega_{m}\left(v_{m}\right) \tag{2.1}
\end{equation*}
$$

for all $m \in M, v_{m}, w_{m} \in T_{m} M$ and $\theta_{m}, \omega_{m} \in T_{m}^{*} M$ and the CourantDorfman bracket given by

$$
\llbracket\left(X_{1}, \theta_{1}\right),\left(X_{2}, \theta_{2}\right) \rrbracket=\left(\left[X_{1}, X_{2}\right], £_{X_{1}} \theta_{2}-\mathbf{i}_{X_{2}} \mathbf{d} \theta_{1}\right)
$$

for all $\left(X_{1}, \theta_{1}\right),\left(X_{2}, \theta_{2}\right) \in \Gamma\left(T M \oplus T^{*} M\right)$, yield the standard example of a Courant algebroid (often called the standard Courant algebroid over M). The map $\mathcal{D}: C^{\infty}(M) \rightarrow \Gamma\left(T M \oplus T^{*} M\right)$ is given by $\mathcal{D} f=(0, \mathbf{d} f)$.

Example 2.2. Let $G \rightrightarrows M$ be a Lie groupoid. The Courant-Dorfman bracket and the pairing on sections of $T G \oplus T^{*} G \rightarrow G$ restrict to rightinvariant sections (defined in the previous section) and give rise to the following structure on $A \oplus T^{*} M$.

The direct sum $A \oplus T^{*} M \rightarrow M$, with the anchor $\rho \circ \mathrm{pr}_{A}: A \oplus T^{*} M \rightarrow$ $T M$, the pairing $\left\langle\left(a_{1}, \theta_{1}\right),\left(a_{2}, \theta_{2}\right)\right\rangle_{d}=\theta_{2}\left(\rho\left(a_{1}\right)\right)+\theta_{1}\left(\rho\left(a_{2}\right)\right)$ and the bracket ${ }^{5}$ $[\cdot, \cdot]_{d}$ on $\Gamma\left(A \oplus T^{*} M\right)$,

$$
\left[\left(a_{1}, \theta_{1}\right),\left(a_{2}, \theta_{2}\right)\right]_{d}=\left(\left[a_{1}, a_{2}\right], £_{\rho\left(a_{1}\right)} \theta_{2}-\mathbf{i}_{\rho\left(a_{2}\right)} \mathbf{d} \theta_{1}\right)
$$

is a degenerate Courant algebroid. That is, $\left(A \oplus T^{*} M, \rho \circ \operatorname{pr}_{A},\langle\cdot, \cdot\rangle_{d},[\cdot, \cdot]_{d}\right)$ satisfies the axioms (1)-(5) of a Courant algebroid, except the non-degeneracy of the pairing (see [22]).

A Dirac structure [7] $\mathrm{D} \subseteq C$ is a subbundle satisfying

1) $\mathrm{D}^{\perp}=\mathrm{D}$ relative to the pairing on $C$,
2) $[\Gamma(D), \Gamma(D)] \subseteq \Gamma(D)$.
[^3]The rank of the vector bundle D is then half the rank of $C$, and the triple ( $\left.\mathrm{D} \rightarrow M,\left.\rho\right|_{\mathrm{D}},\left.[\cdot, \cdot]\right|_{\Gamma(\mathrm{D}) \times \Gamma(\mathrm{D})}\right)$ is a Lie algebroid over $M$. Dirac structures appear naturally in several contexts in geometry and geometric mechanics (see for instance [2] for an introduction to the geometry and applications of Dirac structures). Three classes of great interest in this paper are collected in the following example.

Example 2.3. Let $M$ be a smooth manifold and $F \subseteq T M$ an involutive subbundle. Then $\mathrm{D}_{F}=F \oplus F^{\circ} \subseteq T M \oplus T^{*} M$ is a Dirac structure on $M$.

Now let $\pi \in \Gamma\left(\bigwedge^{2} T M\right)$ be a Poisson bivector field. Then $\mathrm{D}_{\pi} \subseteq T M \oplus$ $T^{*} M$ defined by

$$
\mathrm{D}_{\pi}=\operatorname{graph}\left(\pi^{\sharp}: T^{*} M \rightarrow T M, \pi^{\sharp}\left(\theta_{m}\right)=\pi\left(\theta_{m}, \cdot\right)\right)
$$

is a Dirac structure on $M$.
Finally let $\omega \in \Omega^{2}(M)$ be a closed 2-form on $M$. Then $\mathrm{D}_{\omega} \subseteq T M \oplus T^{*} M$ defined by

$$
\mathrm{D}_{\omega}=\operatorname{graph}\left(\omega^{b}: T M \rightarrow T^{*} M, \omega^{b}\left(v_{m}\right)=\omega\left(v_{m}, \cdot\right)\right)
$$

is a Dirac structure on $M$.

### 2.3. Dorfman connections and dull algebroids

In the following, an anchored vector bundle is a vector bundle $Q \rightarrow M$ with a vector bundle morphism $\rho_{Q}: Q \rightarrow T M$ over the identity. An anchored vector bundle $\left(Q \rightarrow M, \rho_{Q}\right)$ and a vector bundle $B \rightarrow M$ are said to be paired if there exists a fibrewise pairing $\langle\cdot, \cdot\rangle: Q \times_{M} B \rightarrow \mathbb{R}$ and a map $\mathbf{d}_{B}: C^{\infty}(M) \rightarrow \Gamma(B)$ such that

$$
\begin{equation*}
\left\langle q, \mathbf{d}_{B} f\right\rangle=\rho_{Q}(q)(f) \tag{2.2}
\end{equation*}
$$

for all $q \in \Gamma(Q)$ and $f \in C^{\infty}(M)$. Then $(Q \rightarrow M, \rho)$ and $\left(B, \mathbf{d}_{B},\langle\cdot, \cdot\rangle\right)$ are said to be paired by $\langle\cdot, \cdot\rangle$.

Definition 2.4. Let $\left(Q \rightarrow M, \rho_{Q}\right)$ be an anchored vector bundle that is paired with $\left(B \rightarrow M, \mathbf{d}_{B},\langle\cdot, \cdot\rangle\right)$. A Dorfman $(Q-)$ connection on $B$ is an
$\mathbb{R}$-linear map

$$
\Delta: \Gamma(Q) \rightarrow \operatorname{Der}(B)
$$

such that $\sqrt[6]{6}$

1) $\Delta_{q}$ is a derivation over $\rho_{Q}(q) \in \mathfrak{X}(M)$,
2) $\Delta_{f q} b=f \Delta_{q} b+\langle q, b\rangle \cdot \mathbf{d}_{B} f$ and
3) $\Delta_{q}\left(\mathbf{d}_{B} f\right)=\mathbf{d}_{B}\left(\rho_{Q}(q) f\right)$
for all $f \in C^{\infty}(M), q, q^{\prime} \in \Gamma(Q), b \in \Gamma(B)$.
Remark 2.5. If the pairing $\langle\cdot, \cdot\rangle: Q \times_{M} B \rightarrow \mathbb{R}$ is nondegenerate, then $B \simeq Q^{*}$ and the map $\mathbf{d}_{B}=\mathbf{d}_{Q^{*}}: C^{\infty}(M) \rightarrow \Gamma\left(Q^{*}\right)$ is defined by 2.2 : we have then $\mathbf{d}_{Q^{*}} f=\rho_{Q}^{t} \mathbf{d} f$ for all $f \in C^{\infty}(M)$.

The map $\Delta^{*}: \Gamma(Q) \times \Gamma(Q) \rightarrow \Gamma(Q)$ that is dual to $\Delta$ in the sense of dual derivations, i.e. $\left\langle\Delta_{q_{1}}^{*} q_{2}, \tau\right\rangle=\rho_{Q}\left(q_{1}\right)\left\langle q_{2}, \tau\right\rangle-\left\langle q_{2}, \Delta_{q_{1}} \tau\right\rangle$ for all $q_{1}, q_{2} \in \Gamma(Q)$ and $\tau \in \Gamma\left(Q^{*}\right)$ is then a dull bracket on $\Gamma(Q)$ as in the following definition.

Definition 2.6. A dull algebroid is an anchored vector bundle $(Q \rightarrow$ $\left.M, \rho_{Q}\right)$ with a bracket $[\cdot, \cdot]_{Q}$ on $\Gamma(Q)$ such that

$$
\begin{equation*}
\rho_{Q}\left[q_{1}, q_{2}\right]_{Q}=\left[\rho_{Q}\left(q_{1}\right), \rho_{Q}\left(q_{2}\right)\right] \tag{2.3}
\end{equation*}
$$

and (the Leibniz identity)

$$
\left[f_{1} q_{1}, f_{2} q_{2}\right]_{Q}=f_{1} f_{2}\left[q_{1}, q_{2}\right]_{Q}+f_{1} \rho_{Q}\left(q_{1}\right)\left(f_{2}\right) q_{2}-f_{2} \rho_{Q}\left(q_{2}\right)\left(f_{1}\right) q_{1}
$$

for all $f_{1}, f_{2} \in C^{\infty}(M), q_{1}, q_{2} \in \Gamma(Q)$.
That is, a dull algebroid is a Lie algebroid if its bracket is in addition skew-symmetric and satisfies the Jacobi identity. The following examples are crucial in this paper.

Example 2.7. 1) Let $(A \rightarrow M, \rho,[\cdot, \cdot])$ be a Lie algebroid. The Dorfman connection that is dual to the bracket on sections of $A$ is the Lie derivative

$$
£^{A}: \Gamma(A) \times \Gamma\left(A^{*}\right) \rightarrow \Gamma\left(A^{*}\right)
$$

[^4]2) Let $C$ be a Courant algebroid and $D$ a Dirac structure in $C$. The Bott-Dorfman connection
$$
\Delta^{D}: \Gamma(D) \times \Gamma(C / D) \rightarrow \Gamma(C / D)
$$
is defined by
$$
\Delta_{d}^{D} \bar{c}=\overline{\llbracket d, c \rrbracket}, \quad \text { for } d \in \Gamma(D), c \in \Gamma(C)
$$

Modulo the identification $D^{*} \simeq C / D$, this Dorfman connection is the Lie derivative $\Delta^{D}=£^{D}: \Gamma(D) \times \Gamma\left(D^{*}\right) \rightarrow \Gamma\left(D^{*}\right)$ that is dual to the Lie algebroid structure on $D$.

Let $A \rightarrow M$ be a vector bundle. The vector bundle $T M \oplus A^{*}$ is always anchored by the projection $\mathrm{pr}_{T M}$ to $T M$, and paired with $A \oplus T^{*} M$ via the obvious pairing and the map $\mathbf{d}_{A \oplus T^{*} M}: C^{\infty}(M) \rightarrow \Gamma\left(A \oplus T^{*} M\right), f \mapsto$ $(0, \mathbf{d} f)$. We are particularly interested in Dorfman connections

$$
\Delta: \Gamma\left(T M \oplus A^{*}\right) \times \Gamma\left(A \oplus T^{*} M\right) \rightarrow \Gamma\left(A \oplus T^{*} M\right)
$$

Assume that a subbundle $U \subseteq T M \oplus A^{*}$ has a Lie algebroid structure with the anchor $\mathrm{pr}_{T M}$. The Lie algebroid bracket on $\Gamma(U)$ can be extended to a dull bracket on $T M \oplus A^{*}$. The Dorfman connection $\Delta: \Gamma\left(T M \oplus A^{*}\right) \times$ $\Gamma\left(A \oplus T^{*} M\right) \rightarrow \Gamma\left(A \oplus T^{*} M\right)$ that is dual to this bracket satisfies $\Delta_{u} \tau \in$ $\Gamma\left(U^{\circ}\right)$ for all $u \in \Gamma(U)$ and $\tau \in \Gamma\left(U^{\circ}\right)$ and quotients hence to a Dorfman connection

$$
\bar{\Delta}: \Gamma(U) \times \Gamma\left(A \oplus T^{*} M / U^{\circ}\right) \rightarrow \Gamma\left(A \oplus T^{*} M / U^{\circ}\right)
$$

Note that $U^{*} \simeq A \oplus T^{*} M / U^{\circ}$ and the Dorfman connection $\bar{\Delta}$ is equal to $£^{U}: \Gamma(U) \times \Gamma\left(U^{*}\right) \rightarrow \Gamma\left(U^{*}\right)$, the Lie derivative associated to the Lie algebroid $U$. We say that the Dorfman connection $\Delta$ is an extension of $£^{U}$.

### 2.4. VB-algebroids and representations up to homotopy

We briefly recall the definitions of double vector bundles, of their linear and core sections, and of their linear splittings and lifts. We refer to [16, 32, 39] for more detailed treatments. A double vector bundle is a commutative
square

of vector bundles such that

$$
\left(d_{1}+{ }_{A} d_{2}\right)+_{B}\left(d_{3}+{ }_{A} d_{4}\right)=\left(d_{1}+{ }_{B} d_{3}\right)+_{A}\left(d_{2}+{ }_{B} d_{4}\right)
$$

for $d_{1}, d_{2}, d_{3}, d_{4} \in D$ with $\pi_{A}\left(d_{1}\right)=\pi_{A}\left(d_{2}\right), \pi_{A}\left(d_{3}\right)=\pi_{A}\left(d_{4}\right)$ and $\pi_{B}\left(d_{1}\right)=$ $\pi_{B}\left(d_{3}\right), \pi_{B}\left(d_{2}\right)=\pi_{B}\left(d_{4}\right)$. Here, $+_{A}$ and $+_{B}$ are the additions in $D \rightarrow A$ and $D \rightarrow B$, respectively. The vector bundles $A$ and $B$ are called the side bundles. The core $C$ of a double vector bundle is the intersection of the kernels of $\pi_{A}$ and of $\pi_{B}$, which has a natural vector bundle structure on $C$ over $M$. The inclusion $C \hookrightarrow D$ is denoted by $C_{m} \ni c \longmapsto \bar{c} \in \pi_{A}^{-1}\left(0_{m}^{A}\right) \cap$ $\pi_{B}^{-1}\left(0_{m}^{B}\right)$.

The space of sections $\Gamma_{B}(D)$ is generated as a $C^{\infty}(B)$-module by two distinguished classes of sections (see [33]), the linear and the core sections which we now describe. For a section $c: M_{\tilde{\sim}}^{M} \rightarrow C$, the corresponding core section $c^{\dagger}: B \rightarrow D$ is defined as $c^{\dagger}\left(b_{m}\right)=\tilde{0}_{b_{m}}+_{A} \overline{c(m)}, m \in M, b_{m} \in B_{m}$. If not specified otherwise we denote the corresponding core section $A \rightarrow D$ by $c^{\dagger}$ also, relying on the argument to distinguish between them. The space of core sections of $D$ over $B$ is written $\Gamma_{B}^{c}(D)$.

A section $\xi \in \Gamma_{B}(D)$ is called linear if $\xi: B \rightarrow D$ is a bundle morphism from $B \rightarrow M$ to $D \rightarrow A$ over a section $a \in \Gamma(A)$. The space of linear sections of $D$ over $\underset{\sim}{B}$ is denoted by $\Gamma_{B}^{\ell}(D)$. Given $\psi \in \Gamma\left(B^{*} \otimes C\right)$, there is a linear section $\tilde{\psi}: B \rightarrow D$ over the zero section $0^{A}: M \rightarrow A$ given by $\widetilde{\psi}\left(b_{m}\right)=\tilde{0}_{b_{m}}+_{A} \overline{\psi\left(b_{m}\right)}$. We call $\widetilde{\psi}$ a core-linear section.

Example 2.8. Let $A, B, C$ be vector bundles over $M$ and consider $D=$ $A \times{ }_{M} B \times_{M} C$. With the vector bundle structures $D=q_{A}^{!}(B \oplus C) \rightarrow A$ and $D=q_{B}^{!}(A \oplus C) \rightarrow B$, one finds that $(D ; A, B ; M)$ is a double vector bundle called the decomposed double vector bundle with core $C$. The core sections are given by

$$
c^{\dagger}: b_{m} \mapsto\left(0_{m}^{A}, b_{m}, c(m)\right), \text { where } m \in M, b_{m} \in B_{m}, c \in \Gamma(C),
$$

and similarly for $c^{\dagger}: A \rightarrow D$. The space of linear sections $\Gamma_{B}^{\ell}(D)$ is naturally identified with $\Gamma(A) \oplus \Gamma\left(B^{*} \otimes C\right)$ via

$$
(a, \psi): b_{m} \mapsto\left(a(m), b_{m}, \psi\left(b_{m}\right)\right), \text { where } \psi \in \Gamma\left(B^{*} \otimes C\right), a \in \Gamma(A)
$$

In particular, the fibred product $A \times_{M} B$ is a double vector bundle over the sides $A$ and $B$, with core $M \times 0$.

A linear splitting of $(D ; A, B ; M)$ is an injective morphism of double vector bundles $\Sigma: A \times_{M} B \hookrightarrow D$ over the identity on the sides $A$ and $B$. Any double vector bundle admits a linear splitting [14, 39]. A linear splitting $\Sigma$ of $D$ is also equivalent to a splitting $\sigma_{A}$ of the short exact sequence of $C^{\infty}(M)$-modules

$$
\begin{equation*}
0 \longrightarrow \Gamma\left(B^{*} \otimes C\right) \hookrightarrow \Gamma_{B}^{\ell}(D) \longrightarrow \Gamma(A) \longrightarrow 0 \tag{2.4}
\end{equation*}
$$

where the third map is the map that sends a linear section $(\xi, a)$ to its base section $a \in \Gamma(A)$. The splitting $\sigma_{A}$ is called a horizontal lift. Given $\Sigma$, the horizontal lift $\sigma_{A}: \Gamma(A) \rightarrow \Gamma_{B}^{\ell}(D)$ is given by $\sigma_{A}(a)\left(b_{m}\right)=\Sigma\left(a(m), b_{m}\right)$ for all $a \in \Gamma(A)$ and $b_{m} \in B$. By the symmetry of a linear splitting, we find that a lift $\sigma_{A}: \Gamma(A) \rightarrow \Gamma_{B}^{\ell}(D)$ is equivalent to a lift $\sigma_{B}: \Gamma(B) \rightarrow \Gamma_{A}^{\ell}(D)$, $\sigma_{B}(b)(a(m))=\sigma_{A}(a)(b(m))$.

Example 2.9. Let $q_{E}: E \rightarrow M$ be a vector bundle. Then the tangent bundle $T E$ has two vector bundle structures; one as the tangent bundle of the manifold $E$, and the second as a vector bundle over $T M$. The structure maps of $T E \rightarrow T M$ are the derivatives of the structure maps of $E \rightarrow M$.


The space $T E$ is a double vector bundle with core bundle $E \rightarrow M$. The $\operatorname{map}^{-}: E \rightarrow p_{E}^{-1}\left(0^{E}\right) \cap\left(T q_{E}\right)^{-1}\left(0^{T M}\right)$ sends $e_{m} \in E_{m}$ to $\bar{e}_{m}=\left.\frac{d}{d t}\right|_{t=0} t e_{m} \in$ $T_{0_{m}^{E}} E$. Hence the core vector field corresponding to $e \in \Gamma(E)$ is the vertical lift $e^{\uparrow}: E \rightarrow T E$, i.e. the vector field with flow $\phi: E \times \mathbb{R} \rightarrow E, \phi_{t}\left(e_{m}^{\prime}\right)=$ $e_{m}^{\prime}+t e(m)$. An element of $\Gamma_{E}^{\ell}(T E)=\mathfrak{X}^{\ell}(E)$ is called a linear vector field. It is well-known (see e.g. [32]) that a linear vector field $\xi \in \mathfrak{X}^{l}(E)$ covering $X \in \mathfrak{X}(M)$ corresponds to a derivation $D^{*}: \Gamma\left(E^{*}\right) \rightarrow \Gamma\left(E^{*}\right)$ over $X \in \mathfrak{X}(M)$. The precise correspondence is given by ${ }^{7}$

$$
\begin{equation*}
\xi\left(\ell_{\varepsilon}\right)=\ell_{D^{*}(\varepsilon)} \quad \text { and } \quad \xi\left(q_{E}^{*} f\right)=q_{E}^{*}(X(f)) \tag{2.5}
\end{equation*}
$$

[^5]for all $\varepsilon \in \Gamma\left(E^{*}\right)$ and $f \in C^{\infty}(M)$. We write $\widehat{D}$ for the linear vector field in $\mathfrak{X}^{l}(E)$ corresponding in this manner to a derivation $D$ of $\Gamma(E)$. The choice of a linear splitting $\Sigma$ for $(T E ; T M, E ; M)$ is equivalent to the choice of a connection on $E$ : we can define $\nabla: \mathfrak{X}(M) \times \Gamma(E) \rightarrow \Gamma(E)$ by $\sigma_{T M}(X)=$ $\widehat{\nabla_{X}}$ for all $X \in \mathfrak{X}(M)$. Conversely, a connection $\nabla: \mathfrak{X}(M) \times \Gamma(E) \rightarrow \Gamma(E)$ defines a lift $\sigma_{T M}^{\nabla}: \mathfrak{X}(M) \rightarrow \mathfrak{X}^{l}(E)$ and a linear splitting $\Sigma^{\nabla}: T M \times_{M} E \rightarrow$ $T E$. Given $\nabla$, it is easy to see using the equalities in (2.5) that the Lie bracket of vector fields on $E$ is given by $\left[\sigma_{T M}^{\nabla}(X), \sigma_{T M}^{\nabla}(Y)\right]=\sigma_{T M}^{\nabla}[X, Y]-$ $R_{\nabla}(X, Y)^{\uparrow},\left[\sigma_{T M}^{\nabla}(X), e^{\uparrow}\right]=\left(\nabla_{X} e\right)^{\uparrow},\left[e_{1}^{\uparrow}, e_{2}^{\uparrow}\right]=0$, for all $X, Y \in \mathfrak{X}(M)$ and $e, e_{1}, e_{2} \in \Gamma(E)$.

A double vector bundle $(D ; A, B ; M)$ is a VB-algebroid ([31]; see also [16]) if there are Lie algebroid structures on $D \rightarrow B$ and $A \rightarrow M$, such that the anchor $\Theta: D \rightarrow T B$ is a morphism of double vector bundles over $\rho_{A}: A \rightarrow T M$ on one side and if the Lie bracket is linear:

$$
\begin{aligned}
& {\left[\Gamma_{B}^{\ell}(D), \Gamma_{B}^{\ell}(D)\right] \subset \Gamma_{B}^{\ell}(D)} \\
& {\left[\Gamma_{B}^{\ell}(D), \Gamma_{B}^{c}(D)\right] \subset \Gamma_{B}^{c}(D),} \\
& {\left[\Gamma_{B}^{c}(D), \Gamma_{B}^{c}(D)\right]=0 .}
\end{aligned}
$$

The vector bundle $A \rightarrow M$ is then also a Lie algebroid, with anchor $\rho_{A}$ and bracket defined as follows: if $\xi_{1}, \xi_{2} \in \Gamma_{B}^{\ell}(D)$ are linear over $a_{1}, a_{2} \in \Gamma(A)$, then the bracket $\left[\xi_{1}, \xi_{2}\right]$ is linear over $\left[a_{1}, a_{2}\right]$.

Example 2.10. Consider a Lie algebroid $A$. For $a \in \Gamma(A)$, we have two particular types of sections of $T A \rightarrow T M$ : the linear section $T a: T M \rightarrow T A$, and the core section $a^{\dagger}: T M \rightarrow T A, a^{\dagger}\left(x_{m}\right)=T_{m} 0^{A} x_{m}+\left._{p_{A}} \frac{d}{d t}\right|_{t=0} t \cdot a(m)$. The identities $[T a, T b]=T[a, b],\left[T a, b^{\dagger}\right]=[a, b]^{\dagger},\left[a^{\dagger}, b^{\dagger}\right]=0, \rho_{T A}(T a)=$ $[\widehat{\rho(a),} \cdot] \in \mathfrak{X}^{l}(T M)$ and $\rho_{T A}\left(a^{\dagger}\right)=(\rho(a))^{\uparrow} \in \mathfrak{X}^{c}(T M)$ define a VB-algebroid structure $(T A \rightarrow T M, A \rightarrow M)$.

The cotangent space $\left(T^{*} A \rightarrow A^{*}, A \rightarrow M\right)$ also is a VB-algebroid. The projection $r_{A}: T^{*} A \rightarrow A^{*}$ is given by $r_{A}\left(\alpha_{a_{m}}\right)\left(b_{m}\right)=\alpha_{a_{m}}\left(\left.\frac{d}{d t}\right|_{t=0} a_{m}+t b_{m}\right)$ for all $b_{m} \in A_{m}$. For $\theta \in \Omega^{1}(M)$ we have

$$
\theta^{\dagger} \in \Gamma_{A^{*}}^{c}\left(T^{*} A\right), \quad \theta^{\dagger}(\alpha(m))=\mathbf{d}_{0_{m}^{A}} \ell_{\alpha}-q_{A}^{*} \theta\left(0_{m}^{A}\right)
$$

and for $a \in \Gamma(A)$, the section $a^{R} \in \Gamma_{A^{*}}^{l}\left(T^{*} A\right)$ is defined by $a^{R}(\alpha(m))=$ $\mathbf{d}_{a(m)}\left(\ell_{\alpha}-q_{A}^{*}\langle\alpha, a\rangle\right)$ for $\alpha \in \Gamma\left(A^{*}\right)$. The Lie algebroid structure on $T^{*} A \rightarrow A^{*}$ is given by $\left[a_{1}^{R}, a_{2}^{R}\right]=\left[a_{1}, a_{2}\right]^{R},\left[a^{R}, \theta^{\dagger}\right]=\left(£_{\rho(a)} \theta\right)^{\dagger},\left[\theta_{1}^{\dagger}, \theta_{2}^{\dagger}\right]=0$,
$\rho_{T^{*} A}\left(a^{R}\right)=\widehat{£_{a}} \in \mathfrak{X}\left(A^{*}\right)$ and $\rho_{T^{*} A}\left(\theta^{\dagger}\right)=\left(\rho^{*} \theta\right)^{\uparrow} \in \mathfrak{X}\left(A^{*}\right)$ for $a, a_{i} \in \Gamma(A)$ and $\theta, \theta_{i} \in \Omega^{1}(M)$.

The space $T A \times{ }_{A} T^{*} A$ has the structure of a double vector bundle:


The vertical vector bundle is the Pontryagin bundle $T A \oplus T^{*} A$ of $A$ seen as a manifold, and the horizontal projection is defined by $\Pi_{A}\left(v_{a_{m}}, \alpha_{a_{m}}\right)=$ $\left(q_{*}\left(v_{a_{m}}\right), r_{A}\left(\alpha_{a_{m}}\right)\right)$.

The Lie algebroid $T A \oplus T^{*} A \rightarrow T M \oplus A^{*}$ is defined as the pullback to the diagonals $\Delta_{A} \rightarrow \Delta_{M}$ of the Lie algebroid $T A \times T^{*} A \rightarrow T M \times A^{*}$. We have the special linear sections $a^{l}:=\left(T a, a^{R}\right): T M \oplus A^{*} \rightarrow T A \oplus T^{*} A$ for $a \in \Gamma(A)$ and $(b, \theta)^{\dagger}:=\left(b^{\dagger}, \theta^{\dagger}\right): T M \oplus A^{*} \rightarrow T A \oplus T^{*} A$ for $(b, \theta) \in \Gamma(A \oplus$ $\left.T^{*} M\right)$. We write $\Theta: T A \oplus T^{*} A \rightarrow T\left(T M \oplus A^{*}\right)$ for the anchor of $T A \oplus$ $T^{*} A \rightarrow T M \oplus A^{*}$. The Lie algebroid $\left(T A \oplus T^{*} A, \Theta,[\cdot, \cdot]\right)$ is described by the following identities

$$
\begin{aligned}
{\left[a_{1}^{l}, a_{2}^{l}\right] } & =\left[a_{1}, a_{2}\right]^{l}, \quad\left[a^{l}, \tau^{\dagger}\right]=\left(£_{a} \tau\right)^{\dagger}, \quad\left[\tau_{1}^{\dagger}, \tau_{2}^{\dagger}\right]=0 \\
\Theta\left(a^{l}\right) & =\widehat{£_{a}}, \quad \Theta\left(\tau^{\dagger}\right)=\left(\left(\rho, \rho^{t}\right) \tau\right)^{\uparrow}
\end{aligned}
$$

for $a, a_{1}, a_{2} \in \Gamma(A), \tau, \tau_{1}, \tau_{2} \in \Gamma\left(A \oplus T^{*} M\right)$.
Let $E_{0}, E_{1}$ be two vector bundles over the same base $M$ as $A$, and $\partial: E_{0} \rightarrow E_{1}$ a vector bundle morphism. A 2-term representation up to homotopy of $A$ on $\partial: E_{0} \rightarrow E_{1}$ [1, 16] is the collection of two $A$ connections, $\nabla^{0}$ and $\nabla^{1}$ on $E_{0}$ and $E_{1}$, respectively, such that $\partial \circ \nabla^{0}=$ $\nabla^{1} \circ \partial$, and an element $R \in \Omega^{2}\left(A, \operatorname{Hom}\left(E_{1}, E_{0}\right)\right)$ such that $R_{\nabla^{0}}=R \circ \partial$, $R_{\nabla^{1}}=\partial \circ R$ and $\mathbf{d}_{\nabla^{\text {Hom }}} R=0$, where $\nabla^{\text {Hom }}$ is the connection induced on $\operatorname{Hom}\left(E_{1}, E_{0}\right)$ by $\nabla^{0}$ and $\nabla^{1}$ and the operator $\mathbf{d}_{\nabla^{\text {Hom }}}$ on $\Omega^{\bullet}\left(A, \operatorname{Hom}\left(E_{1}, E_{0}\right)\right)$ is given by the Koszul formula:

$$
\begin{aligned}
\mathbf{d}_{\nabla^{\mathrm{Hom}}} \omega\left(a_{1}, \ldots, a_{k+1}\right)= & \sum_{i<j}(-1)^{i+j} \omega\left(\left[a_{i}, a_{j}\right], a_{1}, \ldots, \hat{a}_{i}, \ldots, \hat{a}_{j}, \ldots, a_{k+1}\right) \\
& +\sum_{i}(-1)^{i+1} \nabla_{a_{i}}^{\mathrm{Hom}}\left(\omega\left(a_{1}, \ldots, \hat{a}_{i}, \ldots, a_{k+1}\right)\right)
\end{aligned}
$$

for all $\omega \in \Omega^{k}\left(A, \operatorname{Hom}\left(E_{1}, E_{0}\right)\right)$ and $a_{1}, \ldots, a_{k+1} \in \Gamma(A)$.

Consider again a VB-algebroid $(D \rightarrow B, A \rightarrow M)$. The anchor $\Theta\left(c^{\dagger}\right)$ of a core section $c^{\dagger} \in \Gamma_{B}^{c}(D)$ is given by $\Theta\left(c^{\dagger}\right)=\left(\partial_{B} c\right)^{\uparrow}$, defining a vector bundle morphism $\partial_{B}: C \rightarrow B$. Choose a linear splitting $\Sigma: A \times_{M} B \rightarrow D$. Since the anchor $\Theta$ of a linear section is linear, for each $a \in \Gamma(A)$ the vector field $\Theta\left(\sigma_{A}(a)\right) \in \mathfrak{X}^{l}(B)$ defines a derivation of $\Gamma(B)$ with symbol $\rho(a)$. This defines a linear connection $\nabla^{B}: \Gamma(A) \times \Gamma(B) \rightarrow \Gamma(B): \Theta\left(\sigma_{A}(a)\right)=\widehat{\nabla_{a}^{B}}$ for all $a \in \Gamma(A)$. Since the bracket of a linear section with a core section is again a core section, we find a linear connection $\nabla^{C}: \Gamma(A) \times \Gamma(C) \rightarrow \Gamma(C)$ such that $\left[\sigma_{A}(a), c^{\dagger}\right]=\left(\nabla_{a}^{C} c\right)^{\dagger}$ for all $c \in \Gamma(C)$ and $a \in \Gamma(A)$. The difference $\sigma_{A}\left[a_{1}, a_{2}\right]-\left[\sigma_{A}\left(a_{1}\right), \sigma_{A}\left(a_{2}\right)\right]$ is a core-linear section for all $a_{1}, a_{2} \in \Gamma(A)$. This defines a vector valued form $R \in \Omega^{2}(A, \operatorname{Hom}(B, C))$ by $\left[\sigma_{A}\left(a_{1}\right), \sigma_{A}\left(a_{2}\right)\right]$ $=\sigma_{A}\left[a_{1}, a_{2}\right]-R\left(a_{1}, a_{2}\right)$, for all $a_{1}, a_{2} \in \Gamma(A)$. For more details on these constructions, see [16], where the following result is proved.

Theorem 2.11. Let $(D \rightarrow B ; A \rightarrow M)$ be a $V B$-algebroid and choose a linear splitting $\Sigma: A \times_{M} B \rightarrow D$. The triple $\left(\nabla^{B}, \nabla^{C}, R\right)$ defined as above is a 2-term representation up to homotopy of $A$ on the complex $\partial_{B}: C \rightarrow B$.

Conversely, let $(D ; A, B ; M)$ be a double vector bundle with core $C$ such that $A$ has a Lie algebroid structure, and choose a linear splitting $\Sigma: A \times_{M}$ $B \rightarrow D$. Then if $\left(\nabla^{B}, \nabla^{C}, R\right)$ is a 2-term representation up to homotopy of $A$ on a complex $\partial_{B}: C \rightarrow B$, then the equations above define a VB-algebroid structure on $(D \rightarrow B ; A \rightarrow M)$.

Example 2.12. Let $E \rightarrow M$ be a vector bundle. By Example 2.9 the tangent double $T E$ has a VB-algebroid structure ( $T E \rightarrow E, T M \rightarrow M$ ). Consider a linear splitting $\Sigma: E \times_{M} T M \rightarrow T E$ and the corresponding linear connection $\nabla: \mathfrak{X}(M) \times \Gamma(E) \rightarrow \Gamma(E)$. The representation up to homotopy corresponding to this splitting is given by $\partial_{E}=\mathrm{id}_{E}: E \rightarrow E,\left(\nabla, \nabla, R_{\nabla}\right)$.

Example 2.13. Let $A$ be a Lie algebroid and consider the VB-algebroid $(T A \rightarrow T M, A \rightarrow M)$; see Example 2.10. A linear connection $\nabla: \mathfrak{X}(M) \times$ $\Gamma(A) \rightarrow \Gamma(A)$ defines a horizontal lift $\sigma_{A}: \Gamma(A) \rightarrow \Gamma_{T M}^{l}(T A)$. The corresponding 2-term representation up to homotopy is on $\partial_{T M}=\rho: A \rightarrow T M$ and given by $\left(\nabla^{\text {bas }}, \nabla^{\text {bas }}, R_{\nabla}^{\text {bas }}\right.$ ), where $\nabla^{\text {bas }}: \Gamma(A) \times \Gamma(A) \rightarrow \Gamma(A)$ and $\nabla^{\text {bas }}: \Gamma(A) \times \mathfrak{X}(M) \rightarrow \mathfrak{X}(M)$ are the basic connections associated to $\nabla$ :

$$
\nabla_{a}^{\mathrm{bas}} a^{\prime}=\left[a, a^{\prime}\right]+\nabla_{\rho\left(a^{\prime}\right)} a, \quad \nabla_{a}^{\mathrm{bas}} X=[\rho(a), X]+\rho\left(\nabla_{X} a\right)
$$

for all $a, a^{\prime} \in \Gamma(A)$ and $X \in \mathfrak{X}(M)$ [1, 13]. The tensor

$$
R_{\nabla}^{\mathrm{bas}} \in \Omega^{2}(A, \operatorname{Hom}(T M, A))
$$

is defined by

$$
\begin{aligned}
R_{\nabla}^{\text {bas }}\left(a_{1}, a_{2}\right) X= & -\nabla_{X}\left[a_{1}, a_{2}\right]+\left[\nabla_{X} a_{1}, a_{2}\right]+\left[a_{1}, \nabla_{X} a_{2}\right] \\
& -\nabla_{\nabla_{a_{1}}^{\text {bas }} X} a_{2}+\nabla_{\nabla_{a_{2}}^{\text {bas }}} a_{1}
\end{aligned}
$$

for all $a_{1}, a_{2} \in \Gamma(A)$ and $X \in \mathfrak{X}(M)$.
Example 2.14. We now consider the VB-algebroid $\left(T A \oplus T^{*} A \rightarrow T M \oplus\right.$ $\left.A^{*}, A \rightarrow M\right)$ with core $A \oplus T^{*} M$. Dorfman connections $\square^{8} \Delta: \Gamma\left(T M \oplus A^{*}\right) \times$ $\Gamma\left(A \oplus T^{*} M\right) \rightarrow \Gamma\left(A \oplus T^{*} M\right)$ are equivalent to linear splittings $\Sigma^{\Delta}:(T M \oplus$ $\left.A^{*}\right) \times_{M} A \rightarrow T A \oplus T^{*} A ;$

$$
\Sigma^{\Delta}(X, \alpha)\left(a_{m}\right)=\left(T_{m} a X(m), \mathbf{d} \ell_{\alpha}\left(a_{m}\right)\right)-\Delta_{(X, \alpha)}(a, 0)^{\uparrow}\left(a_{m}\right)
$$

where for $b \in \Gamma(A)$ and $\theta \in \Omega^{1}(M)$, the pair $(b, \theta)^{\uparrow}\left(a_{m}\right) \in T_{a_{m}} A \times T_{a_{m}}^{*} A$ is defined by $(b, \theta)^{\uparrow}\left(a_{m}\right)=\left(b^{\uparrow}\left(a_{m}\right),\left(q_{A}^{*} \theta\right)\left(a_{m}\right)\right)$ [20].

The horizontal lift

$$
\sigma_{A}^{\Delta}: \Gamma(A) \rightarrow \Gamma_{T M \oplus A^{*}}^{l}\left(T A \oplus_{A} T^{*} A\right)
$$

is given by $\sigma_{A}^{\Delta}(a)\left(v_{m}, \alpha_{m}\right)=\left(T_{m} a v_{m}, \mathbf{d}_{a_{m}} \ell_{\alpha}\right)-\Delta_{(X, \alpha)}(a, 0)^{\uparrow}\left(a_{m}\right)$ for any choice of section $(X, \alpha) \in \Gamma\left(T M \oplus A^{*}\right)$ such that $(X, \alpha)(m)=\left(v_{m}, \alpha_{m}\right)$, or in other words by

$$
\sigma_{A}^{\Delta}(a)=\left(T a, a^{R}\right)-\widetilde{\Omega \cdot a}=a^{l}-\widetilde{\Omega \cdot a}
$$

for all $a \in \Gamma(A)$, where $\Omega: \Gamma\left(T M \oplus A^{*}\right) \times \Gamma(A) \rightarrow \Gamma\left(A \oplus T^{*} M\right)$ is defined by

$$
\begin{equation*}
\Omega_{(X, \alpha)} a=\Delta_{(X, \alpha)}(a, 0)-(0, \mathbf{d}\langle\alpha, a\rangle) \tag{2.6}
\end{equation*}
$$

The two maps $\nabla^{\text {bas }}: \Gamma(A) \times \Gamma\left(T M \oplus A^{*}\right) \rightarrow \Gamma\left(T M \oplus A^{*}\right)$,

$$
\begin{equation*}
\nabla_{a}^{\mathrm{bas}}(X, \alpha)=\left(\rho, \rho^{t}\right)\left(\Omega_{(X, \alpha)} a\right)+£_{a}(X, \alpha) \tag{2.7}
\end{equation*}
$$

and $\nabla^{\text {bas }}: \Gamma(A) \times \Gamma\left(A \oplus T^{*} M\right) \rightarrow \Gamma\left(A \oplus T^{*} M\right)$,

$$
\nabla_{a}^{\mathrm{bas}}\left(a^{\prime}, \theta\right)=\Omega_{\left(\rho, \rho^{t}\right)\left(a^{\prime}, \theta\right)} a+£_{a}\left(a^{\prime}, \theta\right)
$$

[^6]are ordinary linear $A$-connections. The formula
\[

$$
\begin{aligned}
R_{\Delta}^{\mathrm{bas}}\left(a_{1}, a_{2}\right)(X, \alpha)= & -\Omega_{(X, \alpha)}\left[a_{1}, a_{2}\right]+£_{a_{1}}\left(\Omega_{(X, \alpha)} a_{2}\right)-£_{a_{2}}\left(\Omega_{(X, \alpha)} a_{1}\right) \\
& +\Omega_{\nabla_{a_{2}}^{\text {bas }}(X, \alpha)} a_{1}-\Omega_{\nabla_{a_{1}}^{\text {bas }}(X, \alpha)} a_{2}
\end{aligned}
$$
\]

defines a tensor $R_{\Delta}^{\mathrm{bas}} \in \Omega^{2}\left(A, \operatorname{Hom}\left(T M \oplus A^{*}, A \oplus T^{*} M\right)\right)$. We prove in [20] that the 2 -term representation up to homotopy defined by the VB-algebroid $\left(T A \oplus T^{*} A \rightarrow T M \oplus A^{*}, A \rightarrow M\right)$ and the splitting $\Sigma$ is the 2-term representation of $A$ on $\left(\rho, \rho^{t}\right): A \oplus T^{*} M \rightarrow T M \oplus A^{*}$ given by ( $\left.\nabla^{\mathrm{bas}}, \nabla^{\mathrm{bas}}, R_{\Delta}^{\mathrm{bas}}\right)$. Compare this with the 2-term representation up to homotopy given by a linear splitting of $(T A \rightarrow T M, A \rightarrow M)$ as in Example 2.12 .

## 3. A-Manin pairs and Dirac bialgebroids

A Manin pair over a manifold $M$ is a pair $(C, U)$ of vector bundles over $M$, where $C$ has the structure of a Courant algebroid and $U$ is a Dirac structure in $C$ 5].

Definition 3.1. Let $(A \rightarrow M, \rho,[\cdot, \cdot])$ be a Lie algebroid.

1) An $A$-Manin pair over $M$ is a Manin pair $(C, U)$ over $M$, together with
a) an injective morphism $\iota: U \rightarrow T M \oplus A^{*}$ of vector bundles, such that $\rho_{U}:=\left.\rho_{C}\right|_{U}=\operatorname{pr}_{T M} \circ \iota$ and
b) a (degenerate) Courant morphism $\Phi: A \oplus T^{*} M \rightarrow C$ such that

$$
\begin{gathered}
\qquad\left(A \oplus T^{*} M\right)+U=C \\
\text { and }\langle u, \Phi(\tau)\rangle_{C}=\langle\iota(u), \tau\rangle \text { for all }(u, \tau) \in U \times_{M}\left(A \oplus T^{*} M\right) .
\end{gathered}
$$

2) Let $\left(U \rightarrow M, \rho_{U},[\cdot, \cdot]_{U}\right)$ be a Lie algebroid and $\iota: U \rightarrow T M \oplus A^{*}$ an injective vector bundle morphism that is compatible with the anchors: $\operatorname{pr}_{T M} \circ \iota=\rho_{U}$. The triple $(A, U, \iota)$ is a Dirac bialgebroid (over $A$ ) if $U$ is the Dirac structure and $\iota$ is the injective morphism of an $A$-Manin pair.
3) Two $A$-Manin pairs $(C, U)$ and $\left(C^{\prime}, U^{\prime}\right)$, and respectively two Dirac bialgebroids $(A, U, \iota)$ and $\left(A, U^{\prime}, \iota^{\prime}\right)$, are equivalent if they define the same Lie algebroid $\iota(U)=\iota^{\prime}\left(U^{\prime}\right)$ in the $\mathrm{pr}_{T M}$-anchored vector bundle $T M \oplus A^{*}$.

By definition, an $A$-Manin pair determines an unique Dirac bialgebroid $(A, U, \iota)$. Conversely, we show that the equivalence class of an $A$-Manin pair $(C, U)$ with structure maps $\iota, \Phi$ is completely determined by the equivalence class of the corresponding Dirac bialgebroid $(A, U, \iota)$. More precisely, given $A, U$ and $\iota$, we can reconstruct $C$ and $\Phi$ up to isomorphism. Consider a Dirac bialgebroid $(A, U, \iota)$ and identify $U$ with $\iota(U) \subseteq A \oplus T^{*} M$. If $\tau \in U^{\circ} \subseteq$ $T M \oplus A^{*}$, then $\Phi(\tau)$ satisfies

$$
\langle u, \Phi(\tau)\rangle_{C}=\langle\tau, u\rangle=0
$$

for all $u \in U$. Since $U$ is a Dirac structure, we find that $\Phi$ restricts to a map $U^{\circ} \rightarrow U$. (Conversely, we find easily that $\Phi(\tau) \in U$ if and only if $\tau \in U^{\circ}$.) Next choose $\tau_{1} \in U^{\circ}$ and $\tau_{2} \in A \oplus T^{*} M$. Then

$$
\left\langle\Phi\left(\tau_{1}\right), \tau_{2}\right\rangle=\left\langle\Phi\left(\tau_{1}\right), \Phi\left(\tau_{2}\right)\right\rangle_{C}=\left\langle\tau_{1}, \tau_{2}\right\rangle_{d}=\left\langle\left(\rho, \rho^{t}\right) \tau_{1}, \tau_{2}\right\rangle
$$

which shows that $\left.\Phi\right|_{U^{\circ}}=\left.\left(\rho, \rho^{t}\right)\right|_{U^{\circ}}: U^{\circ} \rightarrow U$. In particular, $\left(\rho, \rho^{t}\right)$ sends $U^{\circ}$ to $U$, and $U^{\circ}$ is isotropic in $A \oplus T^{*} M$. Consider the vector bundle map $U \oplus A \oplus T^{*} M \rightarrow C,(u, \tau) \mapsto u+\Phi(\tau)$. By hypothesis, this map is surjective. Its kernel is the set of pairs $(u, \tau)$ with $u=-\Phi(\tau)$, i.e. the graph of $-\left.\left(\rho, \rho^{t}\right)\right|_{U^{\circ}}: U^{\circ} \rightarrow U$. It follows that $C$ can be identified with

$$
\begin{equation*}
\frac{U \oplus A \oplus T^{*} M}{\operatorname{graph}\left(-\left.\left(\rho, \rho^{t}\right)\right|_{U^{\circ}}: U^{\circ} \rightarrow U\right)} \tag{3.1}
\end{equation*}
$$

We use the notation $u \oplus \tau$ for $u+\Phi(\tau) \in C$. The anchor of $C$ is then $c: C \rightarrow$ $T M, c(u \oplus \tau)=\operatorname{pr}_{T M}(u)+\rho \circ \operatorname{pr}_{A}(\tau)$, and the bracket is given by $\left\langle u_{1} \oplus\right.$ $\left.\tau_{1}, u_{2} \oplus \tau_{2}\right\rangle_{C}=\left\langle u_{1}+\Phi\left(\tau_{1}\right), u_{2}+\Phi\left(\tau_{2}\right)\right\rangle_{C}=\left\langle u_{1}, \tau_{2}\right\rangle+\left\langle u_{2}, \tau_{1}\right\rangle+\left\langle\tau_{1},\left(\rho, \rho^{t}\right) \tau_{2}\right\rangle$. The map $\mathcal{D}: C^{\infty}(M) \rightarrow \Gamma(C)$ is given by $\langle\langle u \oplus \tau, \mathcal{D} f\rangle\rangle_{C}=\left(\operatorname{pr}_{T M}(u)+\rho \circ\right.$ $\left.\operatorname{pr}_{A}(\tau)\right) f$ for all $u \oplus \tau \in \Gamma(C)$, i.e. $\mathcal{D} f=0 \oplus(0, \mathbf{d} f)$.

We show that the Courant algebroid bracket is uniquely determined by the Lie algebroid structure on $U$. Take an extension $\Delta: \Gamma\left(T M \oplus A^{*}\right) \times$ $\Gamma\left(A \oplus T^{*} M\right) \rightarrow \Gamma\left(A \oplus T^{*} M\right)$ of $£^{U}$. First note that since the dual dull bracket on $\Gamma\left(T M \oplus A^{*}\right)$ is anchored by $\mathrm{pr}_{T M}$, we have

$$
\begin{equation*}
\Delta_{(X, \alpha)}(a, \theta)=\Delta_{u}(a, 0)+\left(0, £_{X} \theta\right) \tag{3.2}
\end{equation*}
$$

for $X \in \mathfrak{X}(M), \alpha \in \Gamma\left(A^{*}\right), a \in \Gamma(A)$ and $\theta \in \Omega^{1}(M)$. We define the connection $\nabla^{\text {bas }}: \Gamma(A) \times \Gamma\left(T M \oplus A^{*}\right) \rightarrow \Gamma\left(T M \oplus A^{*}\right)$ associated to $\Delta$ as in (2.7), i.e. $\nabla_{a}^{\text {bas }} \nu=\left(\rho, \rho^{t}\right)\left(\Delta_{\nu}(a, 0)-(0, \mathbf{d}\langle\nu,(a, 0)\rangle)\right)+£_{a} \nu$ for $a \in \Gamma(A)$ and $\nu \in$
$\Gamma\left(T M \oplus A^{*}\right)$. We prove that the bracket on $\Gamma(C)$ is given by

$$
\begin{align*}
\llbracket u_{1} \oplus \tau_{1}, u_{2} \oplus \tau_{2} \rrbracket_{C}= & \left(\left[u_{1}, u_{2}\right]_{U}+\nabla_{\mathrm{pr}_{A} \tau_{1}}^{\mathrm{bas}} u_{2}-\nabla_{\mathrm{pr}_{A} \tau_{2}}^{\mathrm{bas}} u_{1}\right)  \tag{3.3}\\
& \oplus\left(\left[\tau_{1}, \tau_{2}\right]_{d}+\Delta_{u_{1}} \tau_{2}-\Delta_{u_{2}} \tau_{1}+\left(0, \mathbf{d}\left\langle\tau_{1}, u_{2}\right\rangle\right)\right) .
\end{align*}
$$

We know that

$$
\llbracket u_{1} \oplus 0, u_{2} \oplus 0 \rrbracket_{C}=\left[u_{1}, u_{2}\right]_{U} \oplus 0, \quad \llbracket 0 \oplus \tau_{1}, 0 \oplus \tau_{2} \rrbracket_{C}=0 \oplus\left[\tau_{1}, \tau_{2}\right]_{d}
$$

for $u_{1}, u_{2} \in \Gamma(U)$ and $\tau_{1}, \tau_{2} \in \Gamma\left(A \oplus T^{*} M\right)$.
Note that $C / U$ is isomorphic to $A \oplus T^{*} M / U^{\circ}$ via the map $\Psi: C / U \rightarrow$ $A \oplus T^{*} M / U^{\circ}, \overline{u \oplus \tau} \rightarrow \bar{\tau}$. These two vector bundles are isomorphic to $U^{*}$ and $£^{U}$ is given by

$$
£_{u}^{U} \bar{\tau}=\overline{\Delta_{u} \tau} \quad \text { in } \quad A \oplus T^{*} M / U^{\circ}
$$

and by

$$
£_{u}^{U} \overline{u^{\prime} \oplus \tau}=\overline{\llbracket u \oplus 0, u^{\prime} \oplus \tau \rrbracket_{C}} \quad \text { in } C / U .
$$

Hence $£_{u}^{U} \overline{0 \oplus \tau}=\left(\Psi^{-1} \circ £_{u}^{U} \circ \Psi\right) \overline{0 \oplus \tau}=\overline{0 \oplus \Delta_{u} \tau}$ and so

$$
\overline{\llbracket u \oplus 0,0 \oplus \tau \rrbracket_{C}}=\overline{0 \oplus \Delta_{u} \tau} .
$$

We want to compute $v=v(\tau, u) \in \Gamma(U)$ such that $\llbracket u \oplus 0,0 \oplus \tau \rrbracket_{C}=v \oplus$ $\Delta_{u} \tau$. First note that

$$
\begin{aligned}
& \llbracket u \oplus 0,0 \oplus \tau \rrbracket_{C}+\llbracket 0 \oplus \tau, u \oplus 0 \rrbracket_{C} \\
= & \mathcal{D}\langle\langle u \oplus 0,0 \oplus \tau\rangle\rangle_{C}=\mathcal{D}\langle\tau, u\rangle=(0, \mathbf{d}\langle\tau, u\rangle) .
\end{aligned}
$$

We write $u=(X, \alpha)$ and $\tau=(a, \theta)$. Then, by the Leibniz property of the Courant algebroid bracket on $C$, we find for $\tau^{\prime}=(b, \omega) \in \Gamma\left(A \oplus T^{*} M\right)$ :

$$
\begin{aligned}
& \rho(a)\left\langle u, \tau^{\prime}\right\rangle= c(0 \oplus \tau)\left\langle\left\langle u \oplus 0,0 \oplus \tau^{\prime}\right\rangle\right\rangle_{C} \\
&=\left\langle\left\langle\llbracket 0 \oplus \tau, u \oplus 0 \rrbracket, 0 \oplus \tau^{\prime}\right\rangle\right\rangle_{C}+\left\langle\left\langle u \oplus 0, \llbracket 0 \oplus \tau, 0 \oplus \tau^{\prime} \rrbracket\right\rangle\right\rangle_{C} \\
&=\left\langle\left\langle(-v) \oplus\left(-\Delta_{u} \tau+(0, \mathbf{d}\langle\tau, u\rangle)\right), 0 \oplus \tau^{\prime}\right\rangle\right\rangle_{C} \\
&+\left\langle\left\langle u \oplus 0,0 \oplus\left(£_{a} \tau^{\prime}+\left(0,-\mathbf{i}_{\rho(b)} \mathbf{d} \theta\right)\right)\right\rangle\right\rangle_{C} \\
& \stackrel{\text { 3.2 }}{=}-\left\langle v, \tau^{\prime}\right\rangle-\left\langle\left(\rho, \rho^{t}\right)\left(\Delta_{u}(a, 0)-(0, \mathbf{d}\langle a, \alpha\rangle)\right), \tau^{\prime}\right\rangle+\rho(b)\langle\theta, X\rangle \\
&-\left\langle £_{X} \theta, p(b)\right\rangle+\left\langle u, £_{a} \tau^{\prime}\right\rangle-\mathbf{d} \theta(\rho(b), X)
\end{aligned}
$$

This leads to $-\left\langle v, \tau^{\prime}\right\rangle=\left\langle\left(\rho, \rho^{t}\right)\left(\Delta_{u}(a, 0)-(0, \mathbf{d}\langle a, \alpha\rangle)\right)+£_{a} u, \tau^{\prime}\right\rangle$ and, since $\tau^{\prime}$ was arbitrary, we have shown that $\llbracket u \oplus 0,0 \oplus \tau \rrbracket=\left(-\nabla_{a}^{\text {bas }} u\right) \oplus \Delta_{u} \tau$. Note
that (3.3) does not depend on the choice of the extension $\Delta$ of $£^{U}$. We have proved the following proposition:

Proposition 3.2. The map

$$
\left\{\begin{array}{c}
\text { Equivalence classes } \\
\text { of A-Manin pairs }
\end{array}\right\} \rightarrow\left\{\begin{array}{c}
\text { Equivalence classes of } \\
\text { Dirac bialgebroids over } A
\end{array}\right\}
$$

that sends the class of $(C, U)$ (with structure maps $\iota, \Phi)$ to the class of $(A, U, \iota)$, is a bijection.

## 4. The Dirac bialgebroid associated to a Dirac groupoid

First we recall the definition of a Dirac groupoid, as well as some of their properties.

Definition 4.1 ([38]). A Dirac groupoid $(G \rightrightarrows M, \mathrm{D})$ is a Lie groupoid $G \rightrightarrows M$ with a Dirac structure D such that $\mathrm{D} \subseteq T G \oplus T^{*} G$ is a Lie subgroupoid.

The Dirac structure $D$ is then said to be multiplicative. We write $U$ for the set of units of D seen as a groupoid, i.e. for the vector bundle $U=\mathrm{D} \cap\left(T M \oplus A^{*}\right)$. The inclusion of $U$ in $T M \oplus A^{*}$ is always called $\iota: U \rightarrow$ $T M \oplus A^{*}$. We write $K$ for the vector bundle $K=\mathrm{D} \cap\left(A \oplus T^{*} M\right)$. We have $K=U^{\circ}$ and also $\left(\rho, \rho^{t}\right)(K) \subseteq U$ since $\mathbb{T} \mathbf{t}(\mathrm{D}) \subseteq U$.

Let $u$ be a section of $U$. Then there exists a smooth section $d$ of D such that $\left.d\right|_{M}=u$ and $\mathbb{T} \circ d=u \circ \mathrm{t}$ [21]. We then write $u \sim_{\epsilon} d$ and $d \sim_{\mathrm{t}} u$. A section $d$ of D satisfying these two conditions is called a star section. In [21] we proved the following two results.

Theorem 4.2. Let $(G \rightrightarrows M, D)$ be a Dirac groupoid, $d \sim_{\mathfrak{t}} u$ a star section of D and $a \in \Gamma(A)$. Then the Lie derivative $£_{a^{r}} d$ can be written as a sum

$$
£_{a^{r}} d=\mathcal{L}_{a} d+\left(\tau_{d, a}\right)^{r}
$$

with $\mathcal{L}_{a} d$ a star section and $\tau_{d, a}$ a section of $A \oplus T^{*} M$.
Theorem 4.3. Let $(G \rightrightarrows M, \mathrm{D})$ be a Dirac groupoid. Then there is an induced bracket $[\cdot, \cdot]_{U}: \Gamma(U) \times \Gamma(U) \rightarrow \Gamma(U)$ defined by $\left[u, u^{\prime}\right]_{U}=\llbracket d,\left.d^{\prime} \rrbracket\right|_{M}$ for any choice of star sections $d \sim_{\mathfrak{t}} u, d^{\prime} \sim_{\mathfrak{t}} u^{\prime}$ of D . The triple $\left(U,[\cdot, \cdot]_{U}, \rho_{U}:=\right.$ $\mathrm{pr}_{T M}$ ) is a Lie algebroid over $M$.

We shall prove that $(A, U, \iota)$ is a Dirac bialgebroid. In order to do this, we describe how an $A$-Manin pair is naturally associated to a Dirac groupoid ( $G \rightrightarrows M, \mathrm{D}$ ). The Lie algebroid $U$ is the Dirac structure in this Manin pair.

Set $\mathrm{B}=:\left(U \oplus A \oplus T^{*} M\right) / K^{\mathrm{t}}$, where we see $K^{\mathrm{t}}=\left.(\operatorname{ker} \mathbb{T} \mathrm{t} \cap \mathrm{D})\right|_{M}$ as a subbundle of $U \oplus\left(A \oplus T^{*} M\right)=\left.\mathrm{D}\right|_{M}+\left.\operatorname{ker} \mathbb{T}\right|_{M}$. We write sections of B as pairs $u \oplus \tau:=u+\tau+K^{\mathrm{t}}$, with $u \in \Gamma(U)$ and $\tau \in \Gamma\left(A \oplus T^{*} M\right)$. Since (ker $\mathbb{T}$ s) ${ }^{\perp}=$ ker $\mathbb{T}$ t relative to the canonical symmetric pairing on $T G \oplus T^{*} G$, we have $\left(U \oplus\left(A \oplus T^{*} M\right)\right)^{\perp}=\left(\left.\operatorname{ker} \mathbb{T}\right|_{M}+\left.\mathrm{D}\right|_{M}\right)^{\perp}=K^{\mathrm{t}}$, and so the pairing $\langle\cdot, \cdot\rangle$ on $T G \oplus T^{*} G$ restricts and projects to a nondegenerate symmetric pairing on B :

$$
\begin{aligned}
\left\langle u_{1} \oplus \tau_{1}, u_{2} \oplus \tau_{2}\right\rangle_{\mathrm{B}} & =\alpha_{2}\left(a_{1}\right)+\alpha_{1}\left(a_{2}\right)+\theta_{1}\left(\bar{X}_{2}+\rho\left(a_{2}\right)\right)+\theta_{2}\left(\bar{X}_{1}+\rho\left(a_{1}\right)\right) \\
& =\left\langle u_{1}, \tau_{2}\right\rangle+\left\langle u_{2}, \tau_{1}\right\rangle+\left\langle\tau_{1}, \tau_{2}\right\rangle_{d}
\end{aligned}
$$

where $u_{i}=\left(\bar{X}_{i}, \alpha_{i}\right)$ and $\tau_{i}=\left(a_{i}, \theta_{i}\right)$. We then define $\mathrm{b}: \mathrm{B} \rightarrow T M$ by $\mathrm{b}(u \oplus$ $\tau)=\operatorname{pr}_{T M}(u)+\rho \circ \operatorname{pr}_{A}(\tau)$ and, finally, $\llbracket \cdot, \cdot \rrbracket_{\mathrm{B}}: \Gamma(\mathrm{B}) \times \Gamma(\mathrm{B}) \rightarrow \Gamma(\mathrm{B})$ by

$$
\llbracket u_{1} \oplus \tau_{1}, u_{2} \oplus \tau_{2} \rrbracket_{\mathrm{B}}=\llbracket d_{1}+\tau_{1}^{r}, d_{2}+\left.\tau_{2}^{r} \rrbracket\right|_{M}+K^{\mathrm{t}}
$$

for all $\tau_{1}, \tau_{2} \in \Gamma\left(\left.\operatorname{ker} \mathbb{T} \mathbf{s}\right|_{M}\right), u_{1}, u_{2} \in \Gamma(U)$ and star sections $d_{i} \sim_{\mathrm{t}} u_{i}$ of D . Here, $\llbracket \cdot, \cdot \rrbracket$ is the Courant-Dorfman bracket on sections of $T G \oplus T^{*} G$. We have proved in [21] that $\left(\mathrm{B}, \mathrm{b}, \llbracket \cdot, \cdot \rrbracket_{\mathrm{B}},\langle\cdot, \cdot\rangle_{\mathrm{B}}\right)$ is a Courant algebroid.

Theorem 4.4. Let ( $G \rightrightarrows M, \mathrm{D}$ ) be a Dirac groupoid, and let $A$ be the Lie algebroid of $G \rightrightarrows M$. Then the pair $(\mathrm{B}, U)$ defined as above is naturally an A-Manin pair.

Proof. By construction, $U$ is a subbundle of $T M \oplus A^{*}$. We first show that $U$ is a Dirac structure in B , when we identify $U$ with its image under the injective map $U \rightarrow \mathrm{~B}, u \mapsto u \oplus 0$. A dimension count shows that $2 \operatorname{rank}(U)=$ $\operatorname{rank}(\mathrm{B})$, and $U$ is obviously isotropic relative to $\langle\cdot, \cdot\rangle_{\mathrm{B}}$. By Theorem 4.3, $\Gamma(U)$ is closed under the bracket on $\Gamma(\mathrm{B})$.

By construction again, we find immediately that the map $\Phi: A \oplus T^{*} M \rightarrow$ $\mathrm{B}, \tau \mapsto 0 \oplus \tau$ is a morphism of (degenerate) Courant algebroids: it is easy to check that $\llbracket 0 \oplus \tau_{1}, 0 \oplus \tau_{2} \rrbracket_{\mathrm{B}}=0 \oplus\left[\tau_{1}, \tau_{2}\right]_{d},\left\langle 0 \oplus \tau_{1}, 0 \oplus \tau_{2}\right\rangle_{\mathrm{B}}=\left\langle\tau_{1}, \tau_{2}\right\rangle_{d}$ and $\mathrm{b}(0 \oplus \tau)=\rho \circ \operatorname{pr}_{A}(\tau)$. The sum $\iota_{U}+\Phi: U \oplus\left(A \oplus T^{*} M\right) \rightarrow \mathrm{B},(u, \tau) \mapsto u \oplus$ $\tau$ is surjective, and we have $\langle u, \Phi(\tau)\rangle=\langle u \oplus 0,0 \oplus \tau\rangle_{\mathrm{B}}=\langle u, \tau\rangle$.

Corollary 4.5. The triple $(A, U, \iota)$, with $U$ endowed with the Lie algebroid structure defined in Theorem 4.3. is a Dirac bialgebroid.

Our goal is to show that this defines a bijection between source simply connected Dirac groupoids and integrable Dirac bialgebroids.

The following proposition shows that the Lie derivative $£^{\mathrm{D}}$ is rightinvariant and projects to the Lie derivative $£^{U}$. Note that this is in fact the key feature of a multiplicative Dirac structure, and that it resembles the right-invariance of the Bott connection corresponding to a multiplicative involutive distribution on a Lie groupoid [23].

Proposition 4.6. Let ( $G \rightrightarrows M, \mathrm{D}$ ) be a Dirac groupoid.

1) The Dorfman connection

$$
£^{\mathrm{D}}=\Delta^{\mathrm{D}}: \Gamma(\mathrm{D}) \times \Gamma\left(T G \oplus T^{*} G / \mathrm{D}\right) \rightarrow \Gamma\left(T G \oplus T^{*} G / \mathrm{D}\right)
$$

induces as follows a Dorfman connection $\Delta: \Gamma(U) \times \Gamma\left(A \oplus T^{*} M / K\right) \rightarrow$ $\Gamma\left(A \oplus T^{*} M / K\right)$. For a star section $d \sim_{\mathrm{t}} u$ of D and a right-invariant section $\tau^{r}$ of $T G \oplus T^{*} G$, we have

$$
\Delta_{d}^{\mathrm{D}} \overline{\tau^{r}}=\left(\Delta_{u} \bar{\tau}\right)^{r}
$$

2) Note that $A \oplus T^{*} M / K \simeq U^{*}$ and the Dorfman connection $\Delta$ is exactly the Dorfman connection defined by $U$ in B , or in other words the Lie derivative $£^{U}$ of $\Gamma\left(U^{*}\right)$ by sections of $U$.

Proof of Proposition 4.6. For the first claim write $\tau=(a, \theta)$, with $a \in \Gamma(A)$ and $\theta \in \Omega^{1}(M)$, and $\operatorname{pr}_{T G}(d)=X, \operatorname{pr}_{T M}(u)=\bar{X}$. Using Theorem 4.2, we get the equality

$$
\begin{aligned}
\llbracket d, \tau^{r} \rrbracket & =-\llbracket \tau^{r}, d \rrbracket+\left(0, \mathbf{d}\left\langle d, \tau^{r}\right\rangle\right)=-£_{a^{r}} d+\left(0, \mathbf{i}_{X} \mathbf{d} \mathrm{t}^{*} \theta\right)+\left(0, \mathrm{t}^{*} \mathbf{d}\langle u, \tau\rangle\right) \\
& =-\mathcal{L}_{a} d-\left(\tau_{d, a}-\left(0, \mathbf{i}_{\bar{X}} \mathbf{d} \theta+\mathbf{d}\langle u, \tau\rangle\right)\right)^{r},
\end{aligned}
$$

which implies

$$
\overline{\llbracket d, \tau^{r} \rrbracket}=\overline{-\left(\tau_{d, a}-\left(0, \mathbf{i}_{\bar{X}} \mathbf{d} \theta+\mathbf{d}\langle u, \tau\rangle\right)\right)^{r}}
$$

in $T G \oplus T^{*} G / \mathrm{D}$. This is 0 if and only if $\tau_{d, a}-\left(0, \mathbf{i}_{\bar{X}} \mathbf{d} \theta+\mathbf{d}\langle u, \tau\rangle\right) \in \Gamma(K)$.
We show that this does not depend on the choice of $d$ over the section $u \in \Gamma(U)$. If $d^{\prime} \sim_{\mathfrak{t}} u$ is an other star section of D over $u$, then we have $d-d^{\prime} \in \Gamma(\mathrm{D} \cap \operatorname{ker} \mathbb{T} \mathrm{t})$ and $\left.\left(d-d^{\prime}\right)\right|_{M}=0$. Choose a (local) basis of sections $\tau_{1}, \ldots, \tau_{r}$ of $K^{\mathrm{t}}$. Then $d-d^{\prime}$ can be written as $d-d^{\prime}=\sum_{i=1}^{r} f_{i} \tau_{i}^{l}$ with $f_{1}, \ldots, f_{r} \in C^{\infty}(G)$ vanishing on $M$. Using this, it is easy to check that $\llbracket d-d^{\prime}, \tau^{r} \rrbracket=-\sum_{i=1}^{r} a^{r}\left(f_{i}\right) \tau_{i}^{l} \in \Gamma(\mathrm{D})$ and so that $\overline{\llbracket d-d^{\prime}, \tau^{r} \rrbracket}=0$. Set
$\Delta_{u} \bar{\tau}=\overline{-\tau_{d, a}+\left(0, \mathbf{i}_{\bar{X}} \mathbf{d} \theta+\mathbf{d}\langle u, \tau\rangle\right)}$. Checking that $\Delta$ is a Dorfman connection is straightforward.

For the second claim let $u^{\prime}$ be a section of $U$ and $d^{\prime}$ a star section of D over $u^{\prime}$. We compute

$$
\begin{aligned}
\left\langle\Delta_{u} \bar{\tau}, u^{\prime}\right\rangle & =\left.\left\langle\Delta_{d}^{\mathrm{D}} \overline{\tau^{r}}, d^{\prime}\right\rangle\right|_{M}=\left.\left\langle\llbracket d, \tau^{r} \rrbracket, d^{\prime}\right\rangle\right|_{M} \\
& =\left.\left(\operatorname{pr}_{T G}(d)\left\langle\tau^{r}, d^{\prime}\right\rangle-\left\langle\tau^{r}, \llbracket d, d^{\prime} \rrbracket\right\rangle\right)\right|_{M} \\
& =\operatorname{pr}_{T M}(u)\left\langle\tau, u^{\prime}\right\rangle-\left\langle\tau,\left[u, u^{\prime}\right]_{U}\right\rangle=\left\langle £_{u} \bar{\tau}, u^{\prime}\right\rangle .
\end{aligned}
$$

## 5. The Dirac bialgebroid associated to a Dirac algebroid

Let $A$ be a Lie algebroid. Recall from Example 2.10 that the space $T A \oplus T^{*} A$ has the structure of a double vector bundle with sides $T M \oplus A^{*}$ and $A$ and with core $A \oplus T^{*} M$. The vector bundle $T A \oplus T^{*} A \rightarrow A$ is equipped with the standard Courant algebroid structure, and the vector bundle $T A \oplus T^{*} A \rightarrow$ $T M \oplus A^{*}$ is equipped with a Lie algebroid structure, which was described in Example 2.10. These two structures are compatible and $T A \oplus T^{*} A$ is an LA-Courant algebroid. (LA-Courant algebroids are defined in [25]. An alternative, perhaps more handy definition in terms of representations up to homotopy and Dorfman 2-representations is given in [22].)

Definition 5.1. A Dirac algebroid is a Lie algebroid $A$ with a Dirac structure $\mathrm{D}_{A} \subseteq T A \oplus T^{*} A$ that is also a sub-algebroid of $T A \oplus T^{*} A \rightarrow T M \oplus A^{*}$ over a subbundle $U \subseteq T M \oplus A^{*}$.

We also say that $\mathrm{D}_{A}$ is an LA-Dirac structure on $A$. It is in fact a sub-double Lie algebroid of the LA-Courant algebroid $\left(T A \oplus T^{*} A ; A, T M \oplus A^{*} ; M\right)$.

This section shows how LA-Dirac structures are equivalent to $A$-Manin pairs.

### 5.1. Decompositions of LA-Dirac structures

Let $A$ be a Lie algebroid. Recall that in 2.10 we have described linear splittings of the VB-algebroid $\left(T A \oplus T^{*} A \rightarrow T M \oplus A^{*}, A \rightarrow M\right)$. Now we consider sub-double vector bundles


We denote the core of $D$ by $K \subseteq A \oplus T^{*} M$. There exists a Dorfman connection $\Delta$ such that $D \rightarrow A$ is spanned by the sections $k^{\dagger}$, for all $k \in \Gamma(K)$ and $\sigma_{T M \oplus A^{*}}^{\Delta}(u)$ for all $u \in \Gamma(U)$ (see [20]). The Dorfman connection $\Delta$ is then said to be adapted to $D$ and the double vector subbundle $D$ is completely determined by the triple $(U, K, \Delta)$. Conversely we write $D_{(U, K, \Delta)}$ for the double vector subbundle defined in this manner by a Dorfman connection $\Delta$ and two subbundles $U \subseteq T M \oplus A^{*}, K \subseteq A \oplus T^{*} M$. The set of sections of $D \rightarrow U$ is spanned as a $C^{\infty}(U)$-module by the sections $\left.\sigma_{A}^{\Delta}(a)\right|_{U}$ and $\left.k^{\dagger}\right|_{U}$ for all $a \in \Gamma(A)$ and $k \in \Gamma(K)$. We have $D_{(U, K, \Delta)}=D_{\left(U, K, \Delta^{\prime}\right)}$ if and only if $\left(\Delta-\Delta^{\prime}\right)_{u} \tau \in \Gamma(K)$ for all $u \in \Gamma(U)$ and $\tau \in \Gamma\left(A \oplus T^{*} M\right)$.

By the results in [20], $D$ is a Dirac structure $\mathrm{D}_{A}$ over $A$, if and only if $K=U^{\circ}$, any adapted Dorfman connection $\Delta$ satisfies $\Delta_{u} k \in \Gamma(K)$ for all $u \in \Gamma(U)$ and $k \in \Gamma(K)$ and the induced quotient Dorfman connection $\bar{\Delta}: \Gamma(U) \times \Gamma\left(A \oplus T^{*} M / K\right) \rightarrow \Gamma\left(A \oplus T^{*} M / K\right), \bar{\Delta}_{u} \bar{\tau}=\overline{\Delta_{u} \tau}$ is flat. That is, since $A \oplus T^{*} M / U^{\circ} \simeq U^{*}$, the Dorfman connection $\bar{\Delta}$ is in fact dual to a Lie algebroid structure on $U$ with anchor $\mathrm{pr}_{T M}$. The Lie algebroid bracket is the restriction to $\Gamma(U) \times \Gamma(U)$ of the dull bracket $\llbracket \cdot, \cdot \rrbracket_{\Delta}$ that is dual to $\Delta$. The quotient Dorfman connection and so also the obtained Lie algebroid structure on $U$ do not depend on the choice of the adapted Dorfman connection to $\mathrm{D}_{A}$.

Next, a double vector subbundle as above defines a VB-subalgebroid $(D \rightarrow A, U \rightarrow M)$ of $\left(T A \oplus T^{*} A \rightarrow T M \oplus A^{*}, A \rightarrow M\right)$ if and only if $\left(\rho, \rho^{t}\right)(K) \subseteq U, \nabla_{a}^{\mathrm{bas}} k \in \Gamma(K)$ for all $a \in \Gamma(A)$ and $k \in \Gamma(K), \nabla_{a}^{\mathrm{bas}} u \in \Gamma(U)$ for all $u \in \Gamma(U)$ and $R_{\Delta}^{\mathrm{bas}}(a, b) u \in \Gamma(K)$ for all $a, b \in \Gamma(A)$ and $u \in \Gamma(U)$. We get the following theorem.

Theorem 5.2. [20] Consider a Lie algebroid A and a Dorfman connection

$$
\Delta: \Gamma\left(T M \oplus A^{*}\right) \times \Gamma\left(A \oplus T^{*} M\right) \rightarrow \Gamma\left(A \oplus T^{*} M\right)
$$

Let $U \subseteq T M \oplus A^{*}$ and $K \subseteq A \oplus T^{*} M$ be subbundles. Then $D_{(U, K, \Delta)}$ is a Dirac structure in $T A \oplus T^{*} A \rightarrow A$ and a subalgebroid of $T A \oplus T^{*} A \rightarrow T M \oplus$ $A^{*}$ over $U$ if and only if:

1) $K=U^{\circ}$
2) $\left(\rho, \rho^{t}\right)(K) \subseteq U$,
3) $\left.\left.\left(U, \operatorname{pr}_{T M}, \llbracket \cdot, \cdot\right]_{\Delta}\right|_{\Gamma(U) \times \Gamma(U)}\right)$ is a Lie algebroid,
4) $\nabla_{a}^{\mathrm{bas}} u \in \Gamma(U)$ for all $a \in \Gamma(A)$ and $u \in \Gamma(U)$,
5) $R_{\Delta}^{\mathrm{bas}}(a, b) u \in \Gamma(K)$ for all $u \in \Gamma(U), a, b \in \Gamma(A)$.

In the next subsection we use Theorem 5.2 to construct the Manin pair associated to the Dirac bialgebroid.

Remark 5.3. The equation

$$
\begin{align*}
& \left\langle\nabla_{a^{\prime}}^{\mathrm{bas}} \nu, \tau\right\rangle+\left\langle\nu, \nabla_{a^{\prime}}^{\mathrm{bas}} \tau\right\rangle  \tag{5.1}\\
= & \rho\left(a^{\prime}\right)\langle\nu, \tau\rangle-\left\langle\llbracket \nu,\left(\rho, \rho^{t}\right) \tau \rrbracket_{\Delta}+\llbracket\left(\rho, \rho^{t}\right) \tau, \nu \rrbracket_{\Delta}, \tau^{\prime}\right\rangle
\end{align*}
$$

for $\tau^{\prime}=\left(a^{\prime}, \theta^{\prime}\right) \in \Gamma\left(A \oplus T^{*} M\right), \nu \in \Gamma\left(T M \oplus A^{*}\right)$ and $\tau \in \Gamma\left(A \oplus T^{*} M\right)$, is easily checked.

Hence the two $A$-connections $\nabla^{\text {bas }}$ are not in duality, but if $K=U^{\circ}$ and the restriction of the dull bracket to $\Gamma(U) \times \Gamma(U)$ is skew-symmetric, then for $a \in \Gamma(A), \nabla_{a}^{\text {bas }} k \in \Gamma(K)$ for all $k \in \Gamma(K)$ if and only if $\nabla_{a}^{\text {bas }} u \in \Gamma(U)$ for all $u \in \Gamma(U)$; see [20].

Given the linear splitting given by the Dorfman connection adapted to $\mathrm{D}_{A}$, the Lie algebroid structure $\mathrm{D}_{A} \rightarrow A$ is described by the 2-term representation up to homotopy defined by the vector bundle morphism $\mathrm{pr}_{A}: K \rightarrow$ $A$, the connections $\left(\operatorname{pr}_{A} \circ \Omega\right): \Gamma(U) \times \Gamma(A) \rightarrow \Gamma(A)$ and $\Delta: \Gamma(U) \times \Gamma(K) \rightarrow$ $\Gamma(K)$, and the curvature $R_{\Delta} \in \Omega^{2}(U, \operatorname{Hom}(A, K))$.

The Lie algebroid structure of the other side $\mathrm{D}_{A} \rightarrow U$ is described by the complex $\left(\rho, \rho^{t}\right): K \rightarrow U$ with the basic connections $\nabla^{\text {bas }}: \Gamma(A) \times \Gamma(U) \rightarrow$ $\Gamma(U)$ and $\nabla^{\text {bas }}: \Gamma(A) \times \Gamma(K) \rightarrow \Gamma(K)$ and the basic curvature $R_{\Delta}^{\text {bas }} \in$ $\Omega^{2}(A, \operatorname{Hom}(U, K))$.

Remark 5.4. A long but straightforward computation shows that these two 2-term representations up to homotopy form a matched pair [15]. One of the seven equations defining the matched pair is exactly (A.4) in Lemma A. 4 , which is also the key to the most complicated equation. (A.5) is a useful tool to check that equation as well. Corollary A. 3 is another one, and most of the remaining equations follow immediately from the definition of the involved objects.

As a consequence, $\left(\mathrm{D}_{A}, U, A, M\right)$ is a double Lie algebroid [15], and the core $K$ has an induced Lie algebroid structure, which is given by the restriction of $[\cdot, \cdot]_{d}$ to $\Gamma(K)$, with Lie algebroid morphisms to $A$ and $U$. To see this, use [15, Remark 3.5] and Lemmas A. 1 and A. 3 below.

### 5.2. The $A$-Manin pair associated to an LA-Dirac structure

Consider a triple $\left(U, U^{\circ}, \Delta\right)$ as in Theorem 5.2 and define the vector bundle $C$ with base $M$ as in (3.1). We write $u \oplus \tau$ for the class in $C$ of a pair
$(u, \tau) \in \Gamma\left(U \oplus\left(A \oplus T^{*} M\right)\right)$. It is easy to check that the pairing

$$
\left\langle\left\langle u_{1} \oplus \tau_{1}, u_{2} \oplus \tau_{2}\right\rangle\right\rangle_{C}:=\left\langle u_{1}, \tau_{2}\right\rangle+\left\langle u_{2}, \tau_{1}\right\rangle+\left\langle\tau_{1},\left(\rho, \rho^{t}\right) \tau_{2}\right\rangle
$$

defines a symmetric fibrewise pairing $\langle\langle\cdot, \cdot\rangle\rangle_{C}$ on $C$. It is easy to see that this pairing $\langle\langle\cdot, \cdot\rangle\rangle_{C}$ is nondegenerate, and that the vector bundle $C$ is isomorphic to $U \oplus U^{*}$. Now set

$$
c: C \rightarrow T M, \quad c(u \oplus \tau)=\operatorname{pr}_{T M}(u)+\rho \circ \operatorname{pr}_{A}(\tau)
$$

Theorem 5.5. Let $A$ be a Lie algebroid and consider an LA-Dirac structure $\left(\mathrm{D}_{A}, U, A, M\right)$ over $A$. Choose a Dirac structure $\Delta: \Gamma\left(T M \oplus A^{*}\right) \times \Gamma(A \oplus$ $\left.T^{*} M\right) \rightarrow \Gamma\left(A \oplus T^{*} M\right)$ that is adapted to $D_{A}$. Then $C$ in (3.1) is a Courant algebroid with anchor $c$, pairing $\langle\langle\cdot, \cdot\rangle\rangle_{C}$ and bracket $\llbracket \cdot, \cdot \rrbracket: \Gamma(C) \times \Gamma(C) \rightarrow$ $\Gamma(C)$,

$$
\begin{aligned}
\llbracket u_{1} \oplus \tau_{1}, u_{2} \oplus \tau_{2} \rrbracket= & \left(\llbracket u_{1}, u_{2} \rrbracket_{\Delta}+\nabla_{\tau_{1}}^{\mathrm{bas}} u_{2}-\nabla_{\tau_{2}}^{\mathrm{bas}} u_{1}\right) \\
& \oplus\left(\left[\tau_{1}, \tau_{2}\right]_{D}+\Delta_{u_{1}} \tau_{2}-\Delta_{u_{2}} \tau_{1}+\left(0, \mathbf{d}\left\langle\tau_{1}, u_{2}\right\rangle\right)\right)
\end{aligned}
$$

The map $\mathcal{D}=c^{*} \circ \mathbf{d}: C^{\infty}(M) \rightarrow \Gamma(C)$ is given by $f \mapsto 0 \oplus(0, \mathbf{d} f)$. The bracket does not depend on the choice of $\Delta$.

The proof of this theorem can be found in the appendix.
Remark 5.6. 1) It is easy to check that the Courant algebroid structure does not depend on the choice of $\Delta$ adapted to $D_{A}$.
2) This construction has some similarities with the one of matched pairs of Courant algebroids in [17]. It would be interesting to understand the relation between the two constructions.

It is easy to see that the Lie algebroid $\left(U,\left.\operatorname{pr}_{T M}\right|_{U}, \llbracket \cdot, \cdot \rrbracket_{\Delta}\right)$ is a Dirac structure in $C$, and that $(C, U)$ is an $A$-Manin pair over $M$. Hence, we get the following corollary.

Corollary 5.7. Let $A$ be a Lie algebroid and consider an LA-Dirac structure $\left(\mathrm{D}_{A}, U, A, M\right)$ over $A$. Then the triple $(A, U, \iota)$, with $\iota$ the inclusion of $U$ in $T M \oplus A^{*}$, is a Dirac bialgebroid.

Now we can prove the following theorem.

Theorem 5.8. Let $A$ be a Lie algebroid over a manifold $M$. Then the construction above defines a one-one correspondence between LA-Dirac structures on $A$ and equivalence classes of Dirac bialgebroids on $A$.

Proof. We show here that there is a one-one correspondence between pairs $\left(U, K=U^{\circ}, \Delta\right)$ as in Theorem 5.2 and Dirac bialgebroids $(A, U, \iota)$. From the definition of the bracket, anchor and pairing in Theorem 5.5, we find immediately that $(C, U)$ is an $A$-Manin pair and so that $(A, U, \iota)$ is a Dirac bialgebroid.

Conversely, choose an $A$-Manin pair $(C, U)$. Recall from the proof of Proposition 3.2 that $C$ can be written as in (3.1) and that the anchor, pairing and brackets are defined as in Theorem 5.5, with $\Delta: \Gamma\left(T M \oplus A^{*}\right) \times$ $\Gamma\left(A \oplus T^{*} M\right) \rightarrow \Gamma\left(A \oplus T^{*} M\right)$ any extension of the Lie derivative $£^{U}$ dual to the Lie algebroid structure on $U$. The proof of Theorem 5.5 shows that all the conditions in Theorem 5.2 are then satisfied for the pair $U$ and $\Delta$.

## 6. The Lie algebroid of a multiplicative Dirac structure

In this section, we recall how the Lie algebroid of a Dirac groupoid is equipped with an LA-Dirac structure [38]. Then we compute explicitly the Dirac algebroid of a Dirac groupoid and we prove that they induce equivalent Dirac bialgebroids.

### 6.1. Dirac groupoids correspond to Dirac algebroids

Ortiz shows in [38] that modulo the canonical isomorphism (see [24])

the Lie algebroid $A(\mathrm{D}) \rightarrow U$ of a multiplicative Dirac structure D on $G \rightrightarrows M$ is an LA-Dirac structure

i.e. $\left(A, \mathrm{D}_{A}\right)$ is a Dirac algebroid. Assume that $G \rightrightarrows M$ is source simply connected. Ortiz proves that this defines a one-to-one correspondence between LA-Dirac structures over $A=A(G)$ and multiplicative Dirac structures on $G \rightrightarrows M$ 38]:

$$
\left\{\begin{array}{c}
\mathrm{D}_{A} \text { LA-Dirac structure }  \tag{6.1}\\
\text { on } A
\end{array}\right\} \stackrel{1: 1}{\leftrightarrow}\left\{\begin{array}{c}
\text { D multiplicative Dirac structure } \\
\text { on } G \rightrightarrows M
\end{array}\right\} .
$$

### 6.2. The Lie algebroid of a multiplicative Dirac structure

Now consider again a Dirac groupoid $(G \rightrightarrows M, \mathrm{D})$ and consider an extension $\Delta: \Gamma\left(T M \oplus A^{*}\right) \times \Gamma\left(A \oplus T^{*} M\right) \rightarrow \Gamma\left(A \oplus T^{*} M\right)$ of the induced Dorfman connection $£^{U}$ as in Proposition 4.6. (Recall that $U^{*} \simeq\left(A \oplus T^{*} M\right) / U^{\circ}$.) Define then $\Omega: \Gamma\left(T M \oplus A^{*}\right) \times \Gamma(A) \rightarrow \Gamma\left(A \oplus T^{*} M\right)$ as in (2.6).

Lemma 6.1. For $a \in \Gamma(A)$, the map $\phi_{a}: \Gamma(U) \rightarrow \Gamma\left(U^{*}\right)$ defined by

$$
\phi_{a}(u)=\overline{\Omega_{u} a}, \quad a \in \Gamma(A), u \in \Gamma(U)
$$

satisfies $\phi_{a}^{t}=-\phi_{a}$.
Proof. The proof is just a computation:

$$
\begin{aligned}
\left\langle\phi_{a}\left(u_{1}\right), u_{2}\right\rangle & =\left\langle\Delta_{u_{1}} a-\left(0, \mathbf{d}\left\langle u_{1}, a\right\rangle\right), u_{2}\right\rangle=\left\langle £_{u_{1}}^{U} \overline{(a, 0)}, u_{2}\right\rangle-\mathrm{pr}_{T M}\left(u_{2}\right)\left\langle u_{1}, a\right\rangle \\
& =\left\langle\llbracket u_{1} \oplus 0,0 \oplus a \rrbracket_{\mathrm{B}}, u_{2} \oplus 0\right\rangle-\mathrm{pr}_{T M}\left(u_{2}\right)\left\langle u_{1}, a\right\rangle \\
& =-\left\langle\llbracket 0 \oplus a, u_{1} \oplus 0 \rrbracket_{\mathrm{B}}, u_{2} \oplus 0\right\rangle \\
& =-\rho(a)\left\langle u_{1} \oplus 0, u_{2} \oplus 0\right\rangle+\left\langle u_{1} \oplus 0, \llbracket 0 \oplus a, u_{2} \oplus 0 \rrbracket_{\mathrm{B}}\right\rangle \\
& =-\left\langle u_{1}, \phi_{a}\left(u_{2}\right)\right\rangle
\end{aligned}
$$

for $u_{1}, u_{2} \in \Gamma(U)$ and $a \in \Gamma(A)$.
Remark 6.2. By the proof of Proposition 4.6, we have $\phi_{a}(u)=\overline{-\tau_{a, d}}$ for any star section $d \in \Gamma(\mathrm{D})$ over $u \in \Gamma(U)$.

We compute the linear and core sections of the Lie algebroid $A(T G \oplus$ $\left.T^{*} G\right) \rightarrow T M \oplus A^{*}$. Let $a$ be a section of $A, m \in M,\left(v_{m}, \alpha_{m}\right) \in U_{m}$ and consider the curve $\hat{a}\left(v_{m}, \alpha_{m}\right):(-\varepsilon, \varepsilon) \rightarrow T G \oplus T^{*} G$,

$$
\hat{a}\left(v_{m}, \alpha_{m}\right)(t)=\left(T_{m} \operatorname{Exp}(t a) v_{m},\left(T_{\operatorname{Exp}(t a)(m)} L_{\operatorname{Exp}(-t a)}\right)^{t} \alpha_{m}\right)
$$

where $\varepsilon>0$ is so that $\operatorname{Exp}(t a)(m)$ is defined for all $t \in(-\varepsilon, \varepsilon)$. Here, $L_{\operatorname{Exp}(t a)}$ is the left multiplication by the bisection $\operatorname{Exp}(t a)$ of $G \rightrightarrows M$. In the same manner, given $\tau \in \Gamma\left(A \oplus T^{*} M\right)$, consider the curve $\tau^{c}\left(v_{m}, \alpha_{m}\right): \mathbb{R} \rightarrow T G \oplus$ $T^{*} G, \tau^{c}\left(v_{m}, \alpha_{m}\right)(t)=\left(v_{m}, \alpha_{m}\right)+t \tau(m)$. We define the linear and core sections $a^{l}, \tau^{\times} \in \Gamma\left(A\left(T G \oplus T^{*} G\right)\right)$ by

$$
\begin{aligned}
& a^{l}\left(v_{m}, \alpha_{m}\right)=\left.\frac{d}{d t}\right|_{t=0} \hat{a}\left(v_{m}, \alpha_{m}\right)(t) \quad \text { and } \\
& \tau^{\times}\left(v_{m}, \alpha_{m}\right)=\left.\frac{d}{d t}\right|_{t=0} \sigma^{c}\left(v_{m}, \alpha_{m}\right)(t)
\end{aligned}
$$

for all $\left(v_{m}, \alpha_{m}\right) \in T M \oplus A^{*}$. More generally, if $\phi \in \Gamma\left(\operatorname{Hom}\left(T M \oplus A^{*}, A \oplus\right.\right.$ $\left.T^{*} M\right)$ ) and $a \in \Gamma(A)$, then the linear section $\alpha_{a, \phi} \in \Gamma\left(A\left(T G \oplus T^{*} G\right)\right)$ is given by

$$
\alpha_{a, \phi}\left(v_{m}, \alpha_{m}\right):=a^{l}\left(v_{m}, \alpha_{m}\right)+\left.\frac{d}{d t}\right|_{t=0}\left(v_{m}, \alpha_{m}\right)+t \phi\left(v_{m}, \alpha_{m}\right)
$$

for all $\left(v_{m}, \alpha_{m}\right) \in T M \oplus A^{*}$, where the sum is taken in the fibre over $\left(v_{m}, \alpha_{m}\right)$ of $A\left(T G \oplus T^{*} G\right) \rightarrow T M \oplus A^{*}$.

We find out which $a \in \Gamma(A)$ and $\phi \in \Gamma\left(\operatorname{Hom}\left(T M \oplus A^{*}, A \oplus T^{*} M\right)\right)$ lead to a section $\alpha_{a, \phi}$ that restricts to a section of $A(\mathrm{D})$ on $U$.

Proposition 6.3. For all $a \in \Gamma(A)$, we have $\left.\alpha_{a, \phi}\right|_{U} \in \Gamma(\mathrm{~A}(\mathrm{D}))$ if and only if $\overline{\left.\phi\right|_{U}}=\phi_{a}$.

Proof. Since $\mathrm{D}=\mathrm{D}^{\perp}$, a vector field $X \in \mathfrak{X}\left(T G \oplus T^{*} G\right)$ restricts to a section of $T \mathrm{D}$ if and only if $\mathbf{d} \ell_{d}(X)=0$ on D for all $d \in \Gamma(\mathrm{D})$, where $\ell_{d}: T G \oplus$ $T^{*} G \rightarrow \mathbb{R}$ is the linear function associated to $d$.

Choose $u_{m} \in U$, a star-section $d \in \Gamma(\mathrm{D}), d \sim_{\mathrm{t}} u^{\prime}$, defined in a neighbourhood of $m \in M$ and compute:

$$
\begin{aligned}
\mathbf{d} l_{d}\left(u_{m}\right)\left(\alpha_{a, \phi}\left(u_{m}\right)\right)= & \left.\frac{d}{d t}\right|_{t=0}\left\langle\hat{a}\left(u_{m}\right)(t), d(\operatorname{Exp}(t a)(m))\right\rangle \\
& +\left\langle u_{m}+t \phi\left(u_{m}\right), d(m)\right\rangle \\
= & \left.\frac{d}{d t}\right|_{t=0}\left\langle u_{m},\left(L_{\operatorname{Exp}(t a)}^{*} d\right)(m)\right\rangle+t \cdot\left\langle\phi\left(u_{m}\right), \mathbb{T} \mathrm{t}(d(m))\right\rangle \\
= & \left\langle u_{m},\left(£_{a^{r}} d\right)(m)\right\rangle+\left\langle\phi\left(u_{m}\right), u^{\prime}(m)\right\rangle \\
= & \left\langle u_{m}, \overline{\tau_{a, d}}(m)\right\rangle+\left\langle\phi\left(u_{m}\right), u^{\prime}(m)\right\rangle
\end{aligned}
$$

Since $\phi_{a}\left(u^{\prime}\right)=-\overline{\tau_{d, a}}$ (Remark 6.2) we find that this vanishes for all star sections $d \in \Gamma(D)$ if and only if $\overline{\phi_{U}}=-\phi_{a}$. By Lemma 6.1, this is equivalent to $\overline{\left.\phi\right|_{U}}=\phi_{a}$.

Corollary 6.4. The subbundle $A(\mathrm{D}) \rightarrow U$ of $A\left(T G \oplus T^{*} G\right) \rightarrow T M \oplus A^{*}$ is spanned by the sections $\left.\alpha_{a, \Omega . a}\right|_{U}$ and $\left.\tau^{\times}\right|_{U}$, for all $a \in \Gamma(A)$ and $\tau \in \Gamma\left(U^{\circ}\right)$.

This corollary allows us to describe in the next section $\mathrm{D}_{A}=I(A(\mathrm{D}))$ in terms of the Lie algebroid $U$.

### 6.3. Conclusion and main result

Consider again a Dirac groupoid $(G \rightrightarrows M, \mathrm{D})$ and an extension $\Delta: \Gamma(T M \oplus$ $\left.A^{*}\right) \times \Gamma\left(A \oplus T^{*} M\right) \rightarrow \Gamma\left(A \oplus T^{*} M\right)$ of the induced Dorfman connection $£^{U}$ as in Proposition 4.6. The Dirac groupoid $(G \rightrightarrows M, \mathrm{D})$ induces an $A$-Manin pair $(\mathrm{B}, U)$ as in Theorem 4.4 and hence a Dirac bialgebroid $(A, U, \iota)$. By Theorem 5.8 there is then an LA-Dirac structure on $A$ corresponding to $(A, U, \iota)$. Our goal is to show how this LA-Dirac structure is, via the canonical isomorphism $A\left(T G \oplus T^{*} G\right) \simeq T A \oplus T^{*} A$, the Lie algebroid $A(\mathrm{D}) \rightarrow U$ of the multiplicative Dirac structure $\mathrm{D} \rightrightarrows U$.

Note that given a Dirac groupoid ( $G \rightrightarrows M, \mathrm{D}$ ), we have found two Lie algebroid structures on the bundle $U$ of units of D . The first one is $\left(\operatorname{pr}_{T M},[\cdot, \cdot]_{U}\right)$, which was defined in Theorem 4.3, the Lie algebroid structure of $U$ as a Dirac structure in B . The second Lie algebroid structure on $U$, $\left(\operatorname{pr}_{T M}, \llbracket \cdot,\left.\cdot \rrbracket_{\Delta^{\prime}}\right|_{\Gamma(U) \times \Gamma(U)}\right)$ was defined by any Dorfman connection $\Delta^{\prime}$ that is adapted to the LA-Dirac structure $\mathrm{D}_{A}=I(A(\mathrm{D}))$ in $T A \oplus T^{*} A \rightarrow A$. In order to prove our main theorem, it remains to show that given a Dirac groupoid ( $G \rightrightarrows M, \mathrm{D}$ ), we have $[\cdot, \cdot]_{U}=\llbracket \cdot,\left.\cdot \rrbracket_{\Delta^{\prime}}\right|_{\Gamma(U) \times \Gamma(U)}$ for any Dorfman connection $\Delta^{\prime}$ that is adapted to $\mathrm{D}_{A}=I(A(\mathrm{D}))$. For this, it suffices to show that $\Delta$ is adapted to $D_{A}$.

The canonical isomorphism $I: A\left(T G \oplus T^{*} G\right) \rightarrow T A \oplus T^{*} A$ of double vector bundles can quickly be described as follows. The linear section $\alpha_{a, \phi}$ for $\underset{\sim}{a} \in \Gamma(A)$ and $\phi \in \Gamma\left(\operatorname{Hom}\left(T M \oplus A^{*}, A \oplus T^{*} M\right)\right)$ is sent by $I$ to $\left.\left(T a, a^{R}\right)\right)-$ $\widetilde{\phi}$. In particular, the image of $\alpha_{a, \Omega(\cdot, a)}$ is $\sigma_{A}^{\Delta}(a)$. The image under $I$ of the core section $\tau^{\times}$is $\tau^{\dagger}$. As a consequence, any extension $\Delta$ of the Dorfman connection $£^{U}: \Gamma(U) \times \Gamma\left(A \oplus T^{*} M / U^{\circ}\right) \rightarrow \Gamma\left(A \oplus T^{*} M / U^{\circ}\right)$ that is dual to $[\cdot, \cdot]_{U}$ is adapted to $\mathrm{D}_{A}=A(\mathrm{D})$. In other words, the double vector subbundle $\left(\mathrm{D}_{A}:=I(A(\mathrm{D})) ; U, A ; M\right)$ of $\left(T A \oplus T^{*} A ; T M \oplus A^{*}, A ; M\right)$ corresponds to the triple $\left(U, U^{\circ}, \Delta\right)$.

This yields the following proposition.
Proposition 6.5. Let $(G \rightrightarrows M, \mathrm{D})$ be a Dirac groupoid and let $A$ be the Lie algebroid of $G \rightrightarrows M$. Then the bijection defined by Theorem 5.8 associates the LA-Dirac structure $\mathrm{D}_{A}:=I(A(\mathrm{D}))$ to the class of the Dirac bialgebroid $(A, U, \iota)$, with $U$ endowed with the Lie algebroid structure $\left(\operatorname{pr}_{T M},[\cdot, \cdot]_{U}\right)$.

Corollary 4.5, Propositions 6.5 and 5.8 together with (6.1) now yield our main theorem.

Theorem 6.6. Let $G \rightrightarrows M$ be a Lie groupoid with Lie algebroid A. Then the construction in Theorem 4.4 defines a one-to-one correspondence between multiplicative Dirac structures on $G \rightrightarrows M$ and equivalence classes of Dirac bialgebroids over $A$.

Hence, it does make sense to say that a Dirac bialgebroid $(A, U, \iota)$ is integrable if the Lie algebroid $A$ integrates to a source-simply connected Lie groupoid.

Section 7 shows how the infinitesimal descriptions of Poisson groupoids, presymplectic groupoids and multiplicative distributions on Lie groupoids are special cases of Theorem 6.6.

### 6.4. Concrete integration recipe

For the convenience of the reader, let us quickly sketch how a Dirac groupoid is reconstructed from an integrable Dirac bialgebroid $(A, U, \iota)$.

Step 1: Let $(G \rightrightarrows, M)$ be the source-simply connected Lie groupoid integrating the Lie algebroid $A$ [8] and identify $U$ with the Lie algebroid $U \simeq$ $\iota(U) \subseteq T M \oplus A^{*}$ with anchor $\mathrm{pr}_{T M}$.

Step 2: Extend the bracket on $\Gamma(U)$ to a dull bracket on $T M \oplus A^{*}$, i.e. using the Leibniz identity, but possibly loosing the skew-symmetry and the

Jacobi identity. This dull bracket is dual to a Dorfman connection $\Delta: \Gamma\left(T M \oplus A^{*}\right) \times \Gamma\left(A \oplus T^{*} M\right) \rightarrow \Gamma\left(A \oplus T^{*} M\right)$.
Step 3: Take the double vector subbundle $\left(\mathrm{D}_{A} ; U, A ; M\right) \subseteq\left(T A \oplus T^{*} A ; T M \oplus\right.$ $\left.A^{*}, A ; M\right)$ that is defined by the triple $\left(U, U^{\circ}, \Delta\right)$, hence with core $U^{\circ} \subseteq A \oplus T^{*} M$.
Step 4: The space $\mathrm{D}_{A}$ is an LA-Dirac structure on $A$, which integrates by the results in [38] to a multiplicative Dirac structure D on $G \rightrightarrows M$.

## 7. Examples

This section describes the $A$-Manin pairs and Dirac bialgebroids in the special cases of Dirac Lie groups, Poisson groupoids, presymplectic groupoids, and multiplicative distributions on Lie groupoids. Of course, the obtained infinitesimal descriptions show some redundancy, as Lie bialgebroids, IM-2forms and infinitesimal ideal systems are very special cases of our general notion of Dirac bialgebroids. For instance, the Lie bialgebroid encoding a Poisson groupoid is now replaced by the pair of dual algebroids together with an inclusion (not the trivial one) of $A^{*}$ in $T M \oplus A^{*}$. On the other hand, the examples show that Lie bialgebroids, IM-2-forms and infinitesimal ideal systems are the corner cases of Dirac bialgebroids, just as Poisson structures, presymplectic structures and distributions are the corner cases of Dirac structures.

### 7.1. Dirac Lie groups

Let $G$ be a Lie group with Lie algebra $\mathfrak{g}$. The papers [19, 37] show that multiplicative Dirac structures on $G$ correspond to pairs ( $\mathfrak{i}, \delta$ ) where $\mathfrak{i} \subseteq \mathfrak{g}$ is an ideal and $\delta: \mathfrak{g} \rightarrow \bigwedge^{2} \mathfrak{g} / \mathfrak{i}$ is a Lie algebra 1-cocycl $\ell^{9}$, such that the dual $\delta^{t}: \mathfrak{i}^{\circ} \times \mathfrak{i}^{\circ} \rightarrow \mathfrak{g}^{*}$ defines a Lie bracket on $\mathfrak{i}^{\circ}$. Equivalently, the pair $\left(\mathfrak{g} / \mathfrak{i}, \mathfrak{i}^{\circ}\right)$ is a Lie bialgebra. There is then a quadratic Lie algebra structure on $\mathfrak{g} / \mathfrak{i} \times \mathfrak{i}^{\circ}$ [29, Theorem 1.12], or in other words $\mathfrak{g} / \mathfrak{i} \times \mathfrak{i}^{\circ}$ is a Courant algebroid over a point. The pair $\left(\mathfrak{g} / \mathfrak{i} \times \mathfrak{i}^{\circ}, \mathfrak{i}^{\circ}\right)$ is a $\mathfrak{g}$-Manin pair and $\left(\mathfrak{g}, \mathfrak{i}^{\circ}, \iota: \mathfrak{i}^{\circ} \hookrightarrow \mathfrak{g}^{*}\right)$ is then a Dirac bialgebroid.
${ }^{9}$ The space $\Lambda^{2} \mathfrak{g} / \mathfrak{i}$ is a $\mathfrak{g}$-module via the action

$$
x \cdot((y+\mathfrak{i}) \wedge(z+\mathfrak{i}))=([x, y]+\mathfrak{i}) \wedge(z+\mathfrak{i})+(y+\mathfrak{i}) \wedge([x, z]+\mathfrak{i}) .
$$

Conversely, note that a Dirac bialgebroid over a point is a triple $\left(\mathfrak{g}, \mathfrak{p}, \iota: \mathfrak{p} \hookrightarrow \mathfrak{g}^{*}\right)$ with $\mathfrak{g}, \mathfrak{p}$ Lie algebras and $\iota$ an injective vector space morphism such that there exists a quadratic Lie algebra $\mathfrak{m}$ with a Lie algebra morphism $\Phi: \mathfrak{g} \rightarrow \mathfrak{m}$ such that

1) $\Phi$ has isotropic image,
2) $\mathfrak{p}$ is a Lagrangian subalgebra of $\mathfrak{m}$,
3) $\langle\Phi(x), \xi\rangle=\langle\iota(x), \xi\rangle$ for $x \in \mathfrak{g}$ and $\xi \in \mathfrak{p}$,
4) $\Phi(\mathfrak{g})+\mathfrak{p}=\mathfrak{m}$.

We let the reader verify that $\mathfrak{p}^{\circ} \subseteq \mathfrak{g}$ must be an ideal and $\left(\mathfrak{g} / \mathfrak{p}^{\circ}, \mathfrak{p}\right)$ a Lie bialgebra. Hence, simply connected Dirac Lie groups are in one-to-one correspondence with Dirac bialgebroids over points, which we call Dirac bialgebras.

### 7.2. Poisson groupoids

The infinitesimal description of a Poisson groupoid $(G \rightrightarrows M, \pi)$ is known to be its Lie bialgebroid $\left(A, A^{*}\right)$ [34, 35]. In that case, our Dirac bialgebroid is $\left(A, A^{*},\left(\rho_{\star}, \operatorname{id}_{A^{*}}\right): A^{*} \rightarrow T M \oplus A^{*}\right)$. That is, $A^{*}$ is identified with the graph of its anchor $\rho_{\star}$. The $A$-Manin pair defining this Dirac bialgebroid is $\left(A \oplus A^{*}, A^{*}\right)$, where $A \oplus A^{*} \rightarrow M$ is the Courant algebroid defined by the Lie bialgebroid [27]. (Note that we have already shown in [21] that the Courant algebroid B defined by the Dirac groupoid $(G \rightrightarrows M, \pi)$ is, up to an isomorphism, $A \oplus A^{*}$.) The map $\Phi: A \oplus T^{*} M \rightarrow A \oplus A^{*}$ is $(a, \theta) \mapsto\left(a+\rho_{\star}^{t} \theta, \rho^{t} \theta\right)$.

The double $A \oplus A^{*}$ being a Courant algebroid is equivalent to $\left(A, A^{*}\right)$ being a Lie bialgebroid. By definition of the Courant bracket, the subbundle $A^{*}$ is then automatically a Dirac structure in $A \oplus A^{*}$. The surjectivity and pairing conditions for the $A$-Manin pair are then obvious. The compatibility of $\Phi$ with pairings and anchors follows easily from the equality $\rho \circ \rho_{\star}^{t}=$ $-\rho_{\star} \circ \rho^{t}$, which is always satisfied for Lie bialgebroids. We only have to check that the map $\Phi$ preserves the brackets. First, for $a_{1}, a_{2} \in \Gamma(A)$,

$$
\begin{aligned}
\llbracket \Phi\left(a_{1}, 0\right), \Phi\left(a_{2}, 0\right) \rrbracket_{A \oplus A^{*}} & =\llbracket\left(a_{1}, 0\right),\left(a_{2}, 0\right) \rrbracket_{A \oplus A^{*}}=\left(\left[a_{1}, a_{2}\right]_{A}, 0\right) \\
& =\Phi\left(\left[\left(a_{1}, 0\right),\left(a_{2}, 0\right)\right]_{d}\right) .
\end{aligned}
$$

We then have on the one hand for $\theta \in \Omega^{1}(M)$ :

$$
\begin{aligned}
\llbracket \Phi(a, 0), \Phi(0, \theta) \rrbracket_{A \oplus A^{*}} & =\llbracket(a, 0),\left(\rho_{\star}^{t} \theta, \rho^{t} \theta\right) \rrbracket_{A \oplus A^{*}} \\
& =\left(\left[a, \rho_{\star}^{t} \theta\right]_{A}-\mathbf{i}_{\rho^{t} \theta} \mathbf{d}_{A^{*}} a, £_{a} \rho^{t} \theta\right) .
\end{aligned}
$$

On the other hand, we have

$$
\Phi\left([(a, 0),(0, \theta)]_{d}\right)=\Phi\left(0, £_{\rho(a)} \theta\right)=\left(\rho_{\star}^{t} £_{a} \theta, \rho^{t} £_{\rho(a)} \theta\right)
$$

The equation $\rho^{t} £_{\rho(a)} \theta=£_{a} \rho^{t} \theta$ is verified using the definitions of $£_{a}$ and $£_{\rho(a)}$ and the compatibility of the bracket with the anchor. Then $\rho_{\star}^{t} £_{a} \theta=$ $\left[a, \rho_{\star}^{t} \theta\right]_{A}-\mathbf{i}_{\rho^{t} \theta} \mathbf{d}_{A^{*}} a$ for all $\theta \in \Omega^{1}(M)$ and $a \in \Gamma(A)$ is equivalent to Equation (11) in [32, Lemma 12.1.8], hence always satisfied if $\left(A, A^{*}\right)$ is a Lie bialgebroid. Finally we have

$$
\begin{aligned}
& \llbracket \Phi(0, \theta), \Phi(0, \omega) \rrbracket_{A \oplus A^{*}}=\llbracket\left(\rho_{\star}^{t} \theta, \rho^{t} \theta\right),\left(\rho_{\star}^{t} \omega, \rho^{t} \omega\right) \rrbracket_{A \oplus A^{*}} \\
= & \left(\left[\rho_{\star}^{t} \theta, \rho_{\star}^{t} \omega\right]_{A}+£_{\rho^{t} \theta} \rho_{\star}^{t} \omega-\mathbf{i}_{\rho^{t} \omega} \mathbf{d}_{A^{*}} \rho_{\star}^{t} \theta,\left[\rho^{t} \theta, \rho^{t} \omega\right]_{A^{*}}+£_{\rho_{\star}^{t} \theta} \rho^{t} \omega-\mathbf{i}_{\rho_{\star}^{t} \omega} \mathbf{d}_{A} \rho^{t} \theta\right)
\end{aligned}
$$

and on the other hand $\Phi\left([(0, \theta),(0, \omega)]_{d}\right)=\Phi(0)=0$. Hence, by symmetry of the Lie bialgebroid $\left(A, A^{*}\right)$, we only have to check that

$$
\left[\rho_{\star}^{t} \theta, \rho_{\star}^{t} \omega\right]_{A}=-£_{\rho^{t} \theta} \rho_{\star}^{t} \omega+\mathbf{i}_{\rho^{t} \omega} \mathbf{d}_{A^{*}} \rho_{\star}^{t} \theta
$$

for all $\theta, \omega \in \Omega^{1}(M)$. If $\omega=\mathbf{d} f$ with some $f \in C^{\infty}(M)$, this is [32, Lemma 12.1.5]. To see this, note that

$$
\rho_{\star}^{t} \mathbf{d}\left(\left(\rho \circ \rho_{\star}\right)^{t} \theta(f)\right)=-£_{\rho^{t} \theta}\left(\mathbf{d}_{\star} f\right) .
$$

The general case (with $\omega$ not necessarily exact) follows easily.
Let us now quickly describe a Dorfman connection adapted to the Dirac algebroid $\left(A, A\left(D_{\pi}\right)\right)$. Via the canonical isomorphism $T A \oplus T^{*} A \simeq A(T G \oplus$ $T^{*} G$ ), the Lie algebroid of the Dirac structure $D_{\pi}$ is $D_{\pi_{A}}$, where $\pi_{A}$ is the linear Poisson structure on $A$ that is equivalent to the Lie algebroid structure on $A^{*}$ [35]. The sides of $D_{\pi_{A}}$ are $A$ and $U=\operatorname{graph}\left(\rho_{\star}: A^{*} \rightarrow\right.$ $T M)$ and its core is $K=\operatorname{graph}\left(-\rho_{\star}^{t}: T^{*} M \rightarrow A\right)$. Choose any connection $\nabla: \mathfrak{X}(M) \times \Gamma(A) \rightarrow \Gamma(A)$, denote by $\nabla^{*}: \mathfrak{X}(M) \times \Gamma\left(A^{*}\right) \rightarrow \Gamma\left(A^{*}\right)$ the dual connection and construct the basic $A^{*}$-connection on $A^{*}: \nabla^{* \mathrm{bas}}: \Gamma\left(A^{*}\right) \times$ $\Gamma\left(A^{*}\right) \rightarrow \Gamma\left(A^{*}\right), \quad \nabla_{\alpha_{1}}^{* \text { bas }} \alpha_{2}=\nabla_{\rho_{\star} \alpha_{2}} \alpha_{1}+\left[\alpha_{1}, \alpha_{2}\right]_{A^{*}} \quad$ for all $\alpha_{1}, \alpha_{2} \in \Gamma\left(A^{*}\right)$. The Dorfman connection $\Delta: \Gamma\left(T M \oplus A^{*}\right) \times \Gamma\left(A \oplus T^{*} M\right) \rightarrow \Gamma\left(A \oplus T^{*} M\right)$
defined by

$$
\Delta_{(X, \alpha)}(a, \theta)=\left(\left\langle a, \nabla_{\cdot}^{* \mathrm{bas}} \alpha\right\rangle+\nabla_{X} a-\rho_{\star}^{t}\left\langle\nabla_{\cdot}^{*} \alpha, a\right\rangle, £_{X} \theta+\left\langle\nabla^{*} \cdot \alpha, a\right\rangle\right)
$$

is adapted to $D_{\pi_{A}}$. The corresponding dull bracket $\llbracket \cdot, \cdot \rrbracket_{\Delta}$ on sections of $T M \oplus A^{*}$ is given by

$$
\begin{align*}
\llbracket\left(X_{1}, \alpha_{1}\right),\left(X_{2}, \alpha_{2}\right) \rrbracket_{\Delta}= & \left(\left[X_{1}, X_{2}\right], \nabla_{X_{1}} \alpha_{2}-\nabla_{X_{2}} \alpha_{1}\right.  \tag{7.1}\\
& \left.+\nabla_{\rho_{\star}\left(\alpha_{2}\right)} \alpha_{1}-\nabla_{\rho_{\star}\left(\alpha_{1}\right)} \alpha_{2}+\left[\alpha_{1}, \alpha_{2}\right]_{A^{*}},\right)
\end{align*}
$$

which restricts to $\llbracket\left(\rho_{\star}\left(\alpha_{1}\right), \alpha_{1}\right),\left(\rho_{\star}\left(\alpha_{2}\right), \alpha_{2}\right) \rrbracket_{\Delta}=\left(\rho_{\star}\left[\alpha_{1}, \alpha_{2}\right]_{A^{*}},\left[\alpha_{1}, \alpha_{2}\right]_{A^{*}}\right)$ on sections of $U$. For more details, see [20].

### 7.3. Presymplectic groupoids

Presymplectic groupoids are described infinitesimally in [3, 4] by IM-2-forms: Let $(A \rightarrow M,[\cdot, \cdot], \rho)$ be a Lie algebroid. A vector bundle map $\sigma: A \rightarrow T^{*} M$ is an IM-2-form if

1) $\left\langle\rho\left(a_{1}\right), \sigma\left(a_{2}\right)\right\rangle=-\left\langle\rho\left(a_{2}\right), \sigma\left(a_{1}\right)\right\rangle$ and
2) $\sigma\left[a_{1}, a_{2}\right]=£_{\rho\left(a_{1}\right)} \sigma\left(a_{2}\right)-\mathbf{i}_{\rho\left(a_{2}\right)} \mathbf{d} \sigma\left(a_{1}\right)$
for all $a_{1}, a_{2} \in \Gamma(A)$.
We show that the Dirac bialgebroid corresponding to this example is $\left(A, T M,\left(\mathrm{id}_{T M}, \sigma^{t}\right): T M \rightarrow T M \oplus A^{*}\right)$. Consider a vector bundle morphism $\sigma: A \rightarrow T^{*} M$ on a Lie algebroid $A \rightarrow M$. We want to define an $A$ Maninpair $\left(T M \oplus T^{*} M, T M\right)$, where $T M \oplus T^{*} M$ is the standard Courant algebroid (see also [21], where we check that $B$ is in this case isomorphic to $\left.T M \oplus T^{*} M\right), T M$ is seen as isomorphic to $\operatorname{graph}\left(\sigma^{t}: T M \rightarrow A^{*}\right) \subseteq T M \oplus$ $A^{*}$ and the map $\Phi: A \oplus T^{*} M \rightarrow T M \oplus T^{*} M$ is $(a, \theta) \mapsto(\rho(a), \sigma(a)+\theta)$. We quickly check that $\Phi$ is a morphism of degenerate Courant algebroids if and only if $\sigma$ is an IM-2-form.

The map $\Phi$ is obviously compatible with the anchors. Choose $\left(a_{1}, \theta_{1}\right)$, $\left(a_{2}, \theta_{2}\right) \in \Gamma\left(A \oplus T^{*} M\right)$. Then

$$
\begin{aligned}
\left\langle\Phi\left(a_{1}, \theta_{1}\right), \Phi\left(a_{2}, \theta_{2}\right)\right\rangle & =\left\langle\left(\rho\left(a_{1}\right), \sigma\left(a_{1}\right)+\theta_{1}\right),\left(\rho\left(a_{2}\right), \sigma\left(a_{2}\right)+\theta_{2}\right)\right\rangle \\
& =\left\langle\left(a_{1}, \theta_{1}\right),\left(a_{2}, \theta_{2}\right)\right\rangle_{d}+\left\langle\sigma\left(a_{1}\right), \rho\left(a_{2}\right)\right\rangle+\left\langle\sigma\left(a_{2}\right), \rho\left(a_{1}\right)\right\rangle
\end{aligned}
$$

and

$$
\begin{aligned}
& \llbracket \Phi\left(a_{1}, \theta_{1}\right), \Phi\left(a_{2}, \theta_{2}\right) \rrbracket=\llbracket\left(\rho\left(a_{1}\right), \sigma\left(a_{1}\right)+\theta_{1}\right),\left(\rho\left(a_{2}\right), \sigma\left(a_{2}\right)+\theta_{2}\right) \rrbracket \\
= & \left(\rho\left[a_{1}, a_{2}\right], £_{\rho\left(a_{1}\right)}\left(\sigma\left(a_{2}\right)+\theta_{2}\right)-\mathbf{i}_{\rho\left(a_{2}\right.} \mathbf{d}\left(\sigma\left(a_{1}\right)+\theta_{1}\right)\right) \\
= & \Phi\left[\left(a_{1}, \theta_{1}\right),\left(a_{2}, \theta_{2}\right)\right]_{d}+\left(0, £_{\rho\left(a_{1}\right)} \sigma\left(a_{2}\right)-\mathbf{i}_{\rho\left(a_{2}\right)} \mathbf{d} \sigma\left(a_{1}\right)-\sigma\left[a_{1}, a_{2}\right]\right) .
\end{aligned}
$$

Hence, $\Phi$ is a morphism of Courant algebroids if and only if $\left\langle\rho\left(a_{1}\right), \sigma\left(a_{2}\right)\right\rangle=$ $-\left\langle\rho\left(a_{2}\right), \sigma\left(a_{1}\right)\right\rangle$ and $\sigma\left[a_{1}, a_{2}\right]=£_{\rho\left(a_{1}\right)} \sigma\left(a_{2}\right)-\mathbf{i}_{\rho\left(a_{2}\right)} \mathbf{d} \sigma\left(a_{1}\right)$ for all $a_{1}, a_{2} \in \Gamma(A)$.

The Dirac algebroid corresponding to a presymplectic groupoid ( $G \rightrightarrows$ $M, \omega)$ is $\left(A, A\left(D_{\omega}\right)\right) \simeq\left(A, D_{\sigma^{*}} \omega_{\text {can }}\right)$, where $\omega_{\text {can }}$ is the canonical symplectic structure on $T^{*} M$. The vector bundles $U$ and $K$ over $M$ are

$$
U=\operatorname{graph}\left(-\sigma^{t}: T M \rightarrow A^{*}\right) \quad \text { and } \quad K=\operatorname{graph}\left(\sigma: A \rightarrow T^{*} M\right)
$$

The Dorfman connection $\Delta: \Gamma\left(T M \oplus A^{*}\right) \times \Gamma\left(A \oplus T^{*} M\right) \rightarrow \Gamma\left(A \oplus T^{*} M\right)$ defined by

$$
\Delta_{(X, \alpha)}(a, \theta)=\left(\nabla_{X} a, £_{X}(\theta-\sigma(a))+\left\langle\nabla^{*}\left(\sigma^{t} X+\alpha\right), a\right\rangle+\sigma\left(\nabla_{X} a\right)\right)
$$

The dual dull bracket $\llbracket \cdot, \cdot \rrbracket_{\Delta}$ on sections of $T M \oplus A^{*}$ is given by

$$
\begin{aligned}
& \llbracket\left(X_{1}, \alpha_{1}\right),\left(X_{2}, \alpha_{2}\right) \rrbracket_{\Delta} \\
= & \left(\left[X_{1}, X_{2}\right], \nabla_{X_{1}}^{*}\left(\alpha_{2}+\sigma^{t} X_{2}\right)-\nabla_{X_{2}}^{*}\left(\alpha_{1}+\sigma^{t} X_{1}\right)-\sigma^{t}\left[X_{1}, X_{2}\right]\right)
\end{aligned}
$$

and restricts to $\llbracket\left(X_{1},-\sigma^{t} X_{1}\right),\left(X_{2},-\sigma^{t} X_{2}\right) \rrbracket_{\Delta}=\left(\left[X_{1}, X_{2}\right],-\sigma^{t}\left[X_{1}, X_{2}\right]\right)$ on sections of $U$.

### 7.4. Multiplicative distributions

Multiplicative distributions on Lie groupoids are described infinitesimally in [18, 23] via infinitesimal ideal systems:

Definition 7.1. [23] Let $(q: A \rightarrow M, \rho,[\cdot, \cdot])$ be a Lie algebroid, $F_{M} \subseteq T M$ an involutive subbundle, $J \subseteq A$ a subbundle such that $\rho(J) \subseteq F_{M}$ and $\nabla$ a flat partial $F_{M}$-connection on $A / J$ with the following properties ${ }^{10}$,

1) If $a \in \Gamma(A)$ is $\nabla$-parallel, then $[a, j] \in \Gamma(J)$ for all $j \in \Gamma(J)$.
2) If $a_{1}, a_{2} \in \Gamma(A)$ are $\nabla$-parallel, then $\left[a_{1}, a_{2}\right]$ is also $\nabla$-parallel.

[^7]3) If $a \in \Gamma(A)$ is $\nabla$-parallel, then $\rho(a)$ is $\nabla^{F_{M}}$-parallel, where
$$
\nabla^{F_{M}}: \Gamma\left(F_{M}\right) \times \Gamma\left(T M / F_{M}\right) \rightarrow \Gamma\left(T M / F_{M}\right)
$$
is the Bott connection associated to $F_{M}$.
The triple $\left(F_{M}, J, \nabla\right)$ is an infinitesimal ideal system in $A$.
We prove the following theorem.
Theorem 7.2. Let $(q: A \rightarrow M, \rho,[\cdot, \cdot])$ be a Lie algebroid, $F_{M} \subseteq T M$ an involutive subbundle, $J \subseteq A$ a subbundle such that
$$
\rho(J) \subseteq F_{M} \quad \text { and } \quad \tilde{\nabla}: \mathfrak{X}(M) \times \Gamma(A) \rightarrow \Gamma(A)
$$
be a connection such that $\tilde{\nabla}_{X} j \in \Gamma(J)$ for all $j \in \Gamma(J)$ and $X \in \Gamma\left(F_{M}\right)$, and which thus defines a connection $\nabla: \Gamma\left(F_{M}\right) \times \Gamma(A / J) \rightarrow \Gamma(A / J)$. Then $\left(A, F_{M}, J, \nabla\right)$ is an infinitesimal ideal system if and only if $\left(A, F_{M} \oplus J^{\circ}, \iota\right)$ is a Dirac bialgebroid, where $\iota: F_{M} \oplus J^{\circ} \hookrightarrow T M \oplus A^{*}$ is the inclusion and $F_{M} \oplus J^{\circ}$ has the anchor $\mathrm{pr}_{T M}$ and the bracket
$$
\left[\left(X_{1}, \alpha_{1}\right),\left(X_{2}, \alpha_{2}\right)\right]_{F_{M} \oplus J^{\circ}}=\left(\left[X_{1}, X_{2}\right], \tilde{\nabla}_{X_{1}}^{*} \alpha_{2}-\tilde{\nabla}_{X_{2}}^{*} \alpha_{1}\right)
$$
$X_{1}, X_{2} \in \Gamma\left(F_{M}\right), \alpha_{1}, \alpha_{2} \in \Gamma\left(J^{\circ}\right)$.
First note that $F_{M} \oplus J^{\circ}$ is a Lie algebroid with this structure if and only if $\nabla$ is flat. To prove this theorem, we construct a Manin pair associated to the infinitesimal ideal system.

We have shown in [23] that if the quotients are smooth and $\nabla$ has no holonomy, there is an induced Lie algebroid structure on $(A / J) / \nabla \rightarrow M / F_{M}$ such that the canonical projection $A \rightarrow(A / J) / \nabla$ over $M \rightarrow M / F_{M}$ is a fibration of Lie algebroids. In the case of a Lie algebra $\mathfrak{g}$, an ideal system is just an ideal $\mathfrak{i}$, and this quotient is the usual quotient of the Lie algebra by its ideal $\mathfrak{i}$. We show that there is an alternative construction of a quotient Lie algebroid, that simplifies as well to the usual quotient $\mathfrak{g} / \mathfrak{i}$ in the Lie algebra case.

The paper [12] shows that an infinitesimal ideal system can alternatively be defined as follows. Let $A$ be a Lie algebroid over the base $M$, $J$ a subbundle of $A$ and $F_{M}$ an involutive subbundle of $T M$ such that $\rho(J) \subseteq F_{M}$. Let $\tilde{\nabla}: \mathfrak{X}(M) \times \Gamma(A) \rightarrow \Gamma(A)$ be a connection such that $\tilde{\nabla}_{X} j \in$ $\Gamma(J)$ for all $j \in \Gamma(J)$ and $X \in \Gamma\left(F_{M}\right)$, and which thus defines a connection
$\nabla: \Gamma\left(F_{M}\right) \times \Gamma(A / J) \rightarrow \Gamma(A / J){ }^{11}$ The triple $\left(F_{M}, J, \nabla\right)$ is an infinitesimal ideal system if

1) $\nabla$ is flat,
2) $\nabla_{a}^{\text {bas }} X \in \Gamma\left(F_{M}\right)$,
3) $\nabla_{a}^{\mathrm{bas}} j \in \Gamma(J)$ and
4) $R_{\tilde{\nabla}}^{\mathrm{bas}}\left(a_{1}, a_{2}\right)(X) \in \Gamma\left(F_{M}\right)$
for all $X \in \Gamma\left(F_{M}\right), a_{1}, a_{2} \in \Gamma(A)$ and $j \in \Gamma(J)$, where the two connections $\nabla^{\text {bas }}$ and the tensor $R_{\tilde{\nabla}}^{\text {bas }}$ are defined by $\tilde{\nabla}$ as in Example 2.12 .

Now consider the direct sum $F_{M} \oplus A$ of vector bundles over $M$. Since the anchor $\rho$ restricts to a map $\left.\rho\right|_{J}: J \rightarrow F_{M}$, the vector bundle

$$
\bar{A}:=\frac{F_{M} \oplus A}{\operatorname{graph}\left(-\left.\rho\right|_{J}\right)} \rightarrow M
$$

inherits the anchor $\bar{\rho}(X \oplus a)=X+\rho(a)$. (Given $X \in \Gamma\left(F_{M}\right)$ and $a \in \Gamma(A)$, we write $X \oplus a$ for the class of $(X, a)$ in $\bar{A}$.) Define $[\cdot, \cdot]_{\bar{A}}: \Gamma(\bar{A}) \times \Gamma(\bar{A}) \rightarrow$ $\Gamma(\bar{A})$ by

$$
\begin{aligned}
{\left[X_{1} \oplus a_{1}, X_{2} \oplus a_{2}\right]_{\bar{A}}=} & \left(\left[X_{1}, X_{2}\right]+\nabla_{a_{1}}^{\mathrm{bas}} X_{2}-\nabla_{a_{2}}^{\mathrm{bas}} X_{1}\right) \\
& \oplus\left(\left[a_{1}, a_{2}\right]+\tilde{\nabla}_{X_{1}} a_{2}-\tilde{\nabla}_{X_{2}} a_{1}\right)
\end{aligned}
$$

This is skew-symmetric and well-defined because $[X \oplus a,(-\rho(j)) \oplus j]_{\bar{A}}=$ $\left(-\rho\left(\tilde{\nabla}_{X} j+\nabla_{a}^{\text {bas }} j\right)\right) \oplus\left(\tilde{\nabla}_{X} j+\nabla_{a}^{\text {bas }} j\right)$ and $\tilde{\nabla}_{X} j+\nabla_{a}^{\text {bas }} j \in \Gamma(J)$ for all $j \in$ $\Gamma(J)$. It is easy to check that it is compatible with the anchor, i.e. that is satisfies the Leibniz identity. To see that the Jacobi identity is satisfied, one can check that

$$
\begin{aligned}
& {\left[\left[X_{1} \oplus a_{1}, X_{2} \oplus a_{2}\right]_{\bar{A}}, X_{3} \oplus a_{3}\right]_{\bar{A}}} \\
& +\left[\left[X_{2} \oplus a_{2}, X_{3} \oplus a_{3}\right]_{\bar{A}}, X_{1} \oplus a_{1}\right]_{\bar{A}} \\
& +\left[\left[X_{3} \oplus a_{3}, X_{1} \oplus a_{1}\right]_{\bar{A}}, X_{2} \oplus a_{2}\right]_{\bar{A}}=(-\rho(j)) \oplus j
\end{aligned}
$$

with

$$
j:=\left[R_{\tilde{\nabla}}^{\mathrm{bas}}\left(a_{1}, a_{2}\right) X_{3}-R_{\tilde{\nabla}}\left(X_{1}, X_{2}\right) a_{3}\right]+\text { c.p. } \in \Gamma(\mathrm{J})
$$

[^8]The maps $A \rightarrow \bar{A}, a \mapsto 0 \oplus a$ and $F_{M} \rightarrow \bar{A}, X \mapsto X \oplus 0$ are easily seen to be morphisms of Lie algebroids over the identity. Note that the second map is injective. We let the reader complete the proof of the following theorem.

Theorem 7.3. Let $(q: A \rightarrow M, \rho,[\cdot, \cdot])$ be a Lie algebroid, $F_{M} \subseteq T M$ an involutive subbundle, $J \subseteq A$ a subbundle and $\nabla$ a partial $F_{M}$-connection on $A / J$. Consider any extension $\tilde{\nabla}: \mathfrak{X}(M) \times \Gamma(A) \rightarrow \Gamma(A)$ of $\nabla$. Then $\left(A, F_{M}\right.$, $\left.J^{\circ}, \nabla\right)$ is an infinitesimal ideal system if and only if

$$
\bar{A}=\frac{F_{M} \oplus A}{\operatorname{graph}\left(-\left.\rho\right|_{J}\right)} \rightarrow M
$$

with the anchor $\bar{\rho}(X \oplus a)=X+\rho(a)$ and the bracket $\left[X_{1} \oplus a_{1}, X_{2} \oplus a_{2}\right]_{\bar{A}}=$ $\left(\left[X_{1}, X_{2}\right]+\nabla_{a_{1}}^{\text {bas }} X_{2}-\nabla_{a_{2}}^{\text {bas }} X_{1}\right) \oplus\left(\left[a_{1}, a_{2}\right]+\tilde{\nabla}_{X_{1}} a_{2}-\tilde{\nabla}_{X_{2}} a_{1}\right)$ is a Lie algebroid, which does not depend on the choice of the extension $\tilde{\nabla}$ of the connection $\nabla$.

Consider now the Courant algebroid $\bar{A} \oplus \bar{A}^{*}$ defined by the trivial Lie bialgebroid $\left(\bar{A}, \bar{A}^{*}\right)$, i.e. with the trivial Lie algebroid structure on $\bar{A}^{*}$. The vector bundle $\bar{A}^{*}$ can be described as follows: sections of $\bar{A}^{*}$ are pairs $\left(\bar{\theta}, \rho^{t} \theta+\alpha\right) \in \Gamma\left(F_{M}^{*} \oplus A^{*}\right)$ with $\theta \in \Omega^{1}(M)$ and $\alpha \in \Gamma\left(J^{\circ}\right)$. Here, $\bar{\theta}$ is the class of $\theta$ in $T^{*} M / F_{M}^{\circ} \simeq F_{M}^{*}$. Hence, there is a natural inclusion of $J^{\circ}$ in $\bar{A}^{*}$, and so a natural inclusion $i$ of $F_{M} \oplus J^{\circ}$ in $\bar{A} \oplus \bar{A}^{*}$. Elements of $i\left(F_{M} \oplus J^{\circ}\right) \subseteq$ $\bar{A} \oplus \bar{A}^{*}$ can be written $(X \oplus 0,(0, \alpha))$ with $X \in F_{M}$ and $\alpha \in J^{\circ}$. It is easy to see that $F_{M} \oplus J^{\circ}$ is isotropic in $\bar{A} \oplus \bar{A}^{*}$. To see that it is maximal isotropic, take $\left(X^{\prime} \oplus a,\left(\bar{\theta}, \rho^{t} \theta+\alpha^{\prime}\right)\right) \in \bar{A} \oplus \bar{A}^{*}$ such that $\left\langle\left(X^{\prime} \oplus a,\left(\bar{\theta}, \rho^{t} \theta+\alpha^{\prime}\right)\right),(X \oplus\right.$ $0,(0, \alpha))\rangle=0$ for all $(X \oplus 0,(0, \alpha)) \in F_{M} \oplus J^{\circ}$. Since this is $\theta(X)+\alpha(a)$, we find that $a \in J$ and $\theta \in F_{M}^{\circ}$. Hence, $\left(X^{\prime} \oplus a,\left(\bar{\theta}, \rho^{t} \theta+\alpha^{\prime}\right)\right)=\left(\left(X^{\prime}+\rho(a)\right) \oplus\right.$ $\left.0,\left(0, \rho^{t} \theta+\alpha^{\prime}\right)\right) \in F_{M} \oplus J^{\circ}\left(\right.$ recall that $\rho(J) \subseteq F_{M}$ and so $\left.\rho^{t}\left(F_{M}^{\circ}\right) \subseteq J^{\circ}\right)$. The Courant bracket of $\left(X_{1} \oplus 0,\left(0, \alpha_{1}\right)\right)$ and $\left(X_{2} \oplus 0,\left(0, \alpha_{2}\right)\right) \in F_{M} \oplus J^{\circ}$ equals

$$
\begin{aligned}
& \llbracket\left(X_{1} \oplus 0,\left(0, \alpha_{1}\right)\right),\left(X_{2} \oplus 0,\left(0, \alpha_{2}\right)\right) \rrbracket_{\bar{A} \oplus \bar{A}^{*}} \\
= & \left(\left[X_{1}, X_{2}\right] \oplus 0,\left(0, \tilde{\nabla}_{X_{1}}^{*} \alpha_{2}-\tilde{\nabla}_{X_{2}}^{*} \alpha_{1}\right)\right),
\end{aligned}
$$

which is again an element of $F_{M} \oplus J^{\circ}$. This shows that $F_{M} \oplus J^{\circ}$ is a Dirac structure in $\bar{A} \oplus \bar{A}^{*}$.

Next we define the map $\Phi: A \oplus T^{*} M \rightarrow \bar{A} \oplus \bar{A}^{*}, \Phi(a, \theta)=\left(0 \oplus a,\left(\bar{\theta}, \rho^{t} \theta\right)\right)$. The equality $i\left(F_{M} \oplus J^{\circ}\right)+\Phi\left(A \oplus T^{*} M\right)=\bar{A} \oplus \bar{A}^{*}$ is immediate, as well as the equality $\langle i(X, \alpha), \Phi(a, \theta)\rangle=\left\langle(X \oplus 0,(0, \alpha)),\left(0 \oplus a,\left(\bar{\theta}, \rho^{t} \theta\right)\right)\right\rangle=\theta(X)+$
$\alpha(a)$ for all $(X, \alpha) \in F_{M} \oplus J^{\circ}$ and $(a, \theta) \in A \oplus T^{*} M$. To see that $\Phi$ is a morphism of (degenerate) Courant algebroids, note first that

$$
£_{0 \oplus a}\left(\bar{\theta}, \rho^{t} \theta\right)=\left(\overline{£_{\rho(a)} \theta}, \rho^{t}\left(£_{\rho(a)} \theta\right)\right)
$$

and

$$
\mathbf{i}_{0 \oplus a} \mathbf{d}_{\bar{A}}\left(\bar{\theta}, \rho^{t} \theta\right)=\left(\overline{\mathbf{i}_{\rho(a)} \mathbf{d} \theta}, \rho^{t}\left(\mathbf{i}_{\rho(a)} \mathbf{d} \theta\right)\right)
$$

for $a \in \Gamma(A)$ and $\theta \in \Omega^{1}(M)$. Then we can compute

$$
\begin{aligned}
\llbracket \Phi(a, \theta), \Phi(b, \omega) \rrbracket_{\bar{A} \oplus \bar{A}^{*}} & =\llbracket\left(0 \oplus a,\left(\bar{\theta}, \rho^{t} \theta\right)\right),\left(0 \oplus b,\left(\bar{\omega}, \rho^{t} \omega\right)\right) \rrbracket_{\bar{A} \oplus \bar{A}^{*}} \\
& =\left(0 \oplus[a, b],\left(£_{\rho(a)} \omega-\mathbf{i}_{\rho(b)} \mathbf{d} \theta, \rho^{t}\left(£_{\rho(a)} \omega-\mathbf{i}_{\rho(b)} \mathbf{d} \theta\right)\right)\right) \\
& =\Phi\left([(a, \theta),(b, \omega)]_{d}\right) .
\end{aligned}
$$

The compatibility of $\Phi$ with the anchors is immediate and compatibility with the pairing is checked as follows:

$$
\begin{aligned}
\langle\Phi(a, \theta), \Phi(b, \omega)\rangle & =\left\langle\left(0 \oplus a,\left(\rho^{t} \theta, \bar{\theta}\right)\right),\left(0 \oplus b,\left(\rho^{t} \omega, \bar{\omega}\right)\right)\right\rangle=\theta(\rho(b))+\omega(\rho(a)) \\
& =\left\langle(a, \theta),\left(\rho, \rho^{t}\right)(b, \omega)\right\rangle=\langle(a, \theta),(b, \omega)\rangle_{d}
\end{aligned}
$$

We have hence shown that $\left(\bar{A} \oplus \bar{A}^{*}, i\left(F_{M} \oplus J^{\circ}\right)\right)$ is an $A$-Manin pair.
The Dirac algebroid corresponding to a Lie groupoid with a multiplicative distribution $\left(G \rightrightarrows M, F \oplus F^{\circ}\right)$ is $\left(A, A\left(F \oplus F^{\circ}\right)\right) \simeq\left(A, F_{A} \oplus F_{A}^{\circ}\right)$, with $F_{A} \simeq A(F)$. This double vector subbundle of $T A$ has sides $A$ and $F_{M} \subseteq$ $T M$, and core $J \subseteq A$. Choose any connection $\nabla: \mathfrak{X}(M) \times \Gamma(A) \rightarrow \Gamma(A)$ that is adapted to $F_{A}$, i.e. $T_{m} a\left(v_{m}\right)-\left.\frac{d}{d t}\right|_{t=0} a(m)+t \nabla_{v_{m}} a \in F_{A}(a(m))$ for all $v_{m} \in F_{M}$ and $a \in \Gamma(A)$ (see [23]), and consequently $\nabla_{X} j \in \Gamma(J)$ for all $X \in \Gamma\left(F_{M}\right)$ and $j \in \Gamma(J)$. Then the Dorfman connection $\Delta: \Gamma\left(T M \oplus A^{*}\right) \times$ $\Gamma\left(A \oplus T^{*} M\right) \rightarrow \Gamma\left(A \oplus T^{*} M\right)$,

$$
\Delta_{(X, \alpha)}(a, \theta)=\left(\nabla_{X} a, £_{X} \theta+\left\langle\nabla_{\cdot}^{*} \alpha, a\right\rangle\right)
$$

is adapted to $F_{A} \oplus F_{A}^{\circ}$ and the dual dull bracket given by

$$
\llbracket\left(X_{1}, \alpha_{1}\right),\left(X_{2}, \alpha_{2}\right) \rrbracket=\left(\left[X_{1}, X_{2}\right], \nabla_{X_{1}}^{*} \alpha_{2}-\nabla_{X_{2}}^{*} \alpha_{1}\right)
$$

restricts to the Lie algebroid bracket found above on sections of $F_{M} \oplus J^{\circ}$.

## Appendix A. Proof of Theorem 5.5

Note that the equality

$$
\begin{equation*}
\nabla_{a}^{\mathrm{bas}} \circ\left(\rho, \rho^{t}\right)=\left(\rho, \rho^{t}\right) \circ \nabla_{a}^{\mathrm{bas}} \tag{A.1}
\end{equation*}
$$

is easily verified. The connection $\nabla_{a}^{\text {bas }}: \Gamma(A) \times \Gamma\left(A \oplus T^{*} M\right) \rightarrow \Gamma\left(A \oplus T^{*} M\right)$ defines a connection $\nabla_{a}^{\text {bas }}: \Gamma\left(A \oplus T^{*} M\right) \times \Gamma\left(A \oplus T^{*} M\right) \rightarrow \Gamma\left(A \oplus T^{*} M\right)$, $\nabla_{\tau}^{\mathrm{bas}} \tau^{\prime}=\nabla_{\mathrm{pr}_{A}(\tau)}^{\mathrm{bas}} \tau^{\prime}$. Recall also (3.2) $\Delta_{(X, \alpha)}(a, \theta)=\Delta_{u}(a, 0)+\left(0, £_{X} \theta\right)$ for all $(X, \alpha) \in \Gamma\left(T M \oplus A^{*}\right)$ and $(a, \theta) \in \Gamma\left(A \oplus T^{*} M\right)$. First we prove a few lemmas.

Lemma A.1. The equality

$$
\begin{equation*}
\left[\tau_{1}, \tau_{2}\right]_{d}=\Delta_{\left(\rho, \rho^{t}\right)\left(\tau_{1}\right)} \tau_{2}-\nabla_{\tau_{2}}^{\mathrm{bas}} \tau_{1} \tag{A.2}
\end{equation*}
$$

holds for all $\tau_{1}, \tau_{2} \in \Gamma\left(A \oplus T^{*} M\right)$.
Proof. Write $\tau_{1}=\left(a_{1}, \theta_{1}\right)$ and $\tau_{2}=\left(a_{2}, \theta_{2}\right) \in \Gamma\left(A \oplus T^{*} M\right)$. Then:

$$
\begin{aligned}
\nabla_{\tau_{2}}^{\mathrm{bas}} \tau_{1} & =\nabla_{a_{2}}^{\mathrm{bas}} \tau_{1}=\Omega_{\left(\rho, \rho^{t}\right) \tau_{1}} a_{2}+£_{a_{2}} \tau_{1} \\
& =\Delta_{\left(\rho, \rho^{t}\right) \tau_{1}} \tau_{2}-\left(0, \mathbf{d}\left\langle\theta_{1}, \rho\left(a_{2}\right)\right\rangle\right)-\left(0, £_{\rho\left(a_{1}\right)} \theta_{2}\right)+\left(\left[a_{2}, a_{1}\right], £_{\rho\left(a_{2}\right)} \theta_{1}\right) \\
& =\Delta_{\left(\rho, \rho^{t}\right) \tau_{1}} \tau_{2}-\left[\tau_{1}, \tau_{2}\right]_{d}
\end{aligned}
$$

Lemma A.2. Let $A$ be a Lie algebroid and choose a Dorfman connection $\Delta: \Gamma\left(T M \oplus A^{*}\right) \times \Gamma\left(A \oplus T^{*} M\right) \rightarrow \Gamma\left(A \oplus T^{*} M\right)$. Then, for all $\nu \in \Gamma(T M \oplus$ $\left.A^{*}\right)$ and $\tau, \tau^{\prime} \in \Gamma\left(A \oplus T^{*} M\right)$ :

$$
\begin{equation*}
\left\langle\left(\rho, \rho^{t}\right) \Delta_{\nu} \tau-\llbracket \nu,\left(\rho, \rho^{t}\right) \tau \rrbracket_{\Delta}-\nabla_{\tau}^{\text {bas }} \nu, \tau^{\prime}\right\rangle=\left\langle\nabla_{\tau^{\prime}}^{\text {bas }} \nu, \tau\right\rangle . \tag{A.3}
\end{equation*}
$$

This yields the following corollary.
Corollary A.3. Assume that $(U, K, \Delta)$ defines an LA-Dirac structure in $T A \oplus T^{*} A$. Then, for all $u \in \Gamma(U)$ and $k \in \Gamma(K)$ :

$$
\left(\rho, \rho^{t}\right) \Delta_{u} k=\llbracket u,\left(\rho, \rho^{t}\right) k \rrbracket_{\Delta}+\nabla_{k}^{\mathrm{bas}} u .
$$

Proof. By Lemma A.2, we have

$$
\left\langle\left(\rho, \rho^{t}\right) \Delta_{u} k-\llbracket u,\left(\rho, \rho^{t}\right) k \rrbracket_{\Delta}-\nabla_{k}^{\mathrm{bas}} u, \tau\right\rangle=\left\langle\nabla_{\tau}^{\mathrm{bas}} u, k\right\rangle
$$

for all $\tau \in \Gamma\left(A \oplus T^{*} M\right)$. Since $\nabla_{\tau}^{\text {bas }}$ preserves $\Gamma(U)$ by Theorem 5.2, the right-hand side vanishes.

Proof of Lemma A.2. We write $\tau=(a, \theta)$ and $\nu=(X, \alpha)$. Then for any $\tau^{\prime}=$ $\left(a^{\prime}, \theta^{\prime}\right) \in \Gamma\left(A \oplus T^{*} M\right)$ we have

$$
\begin{aligned}
&\left\langle\left(\rho, \rho^{t}\right) \Delta_{\nu} \tau-\llbracket \nu,\left(\rho, \rho^{t}\right) \tau \rrbracket_{\Delta}-\nabla_{a}^{\mathrm{bas}} \nu, \tau^{\prime}\right\rangle-\left\langle\nabla_{a^{\prime}}^{\mathrm{bas}} \nu, \tau\right\rangle \\
& \stackrel{5.1}{=}\left\langle\Delta_{\nu} \tau-\Omega_{\nu} a,\left(\rho, \rho^{t}\right) \tau^{\prime}\right\rangle-\left\langle £_{a} \nu, \tau^{\prime}\right\rangle+\left\langle\nu, \nabla_{a^{\prime}}^{\mathrm{bas}} \tau\right\rangle \\
&\left.-\rho\left(a^{\prime}\right)\langle\nu, \tau\rangle+\llbracket\left(\rho, \rho^{t}\right) \tau, \nu \rrbracket_{\Delta}, \tau^{\prime}\right\rangle \\
&=\left\langle\left(0, £_{X} \theta+\mathbf{d}\langle\alpha, a\rangle\right),\left(\rho, \rho^{t}\right) \tau^{\prime}\right\rangle-\left\langle £_{a} \nu, \tau^{\prime}\right\rangle-\rho\left(a^{\prime}\right)\langle\nu, \tau\rangle+\rho(a)\left\langle\nu, \tau^{\prime}\right\rangle \\
&-\left\langle\nu, \Delta_{\left(\rho, \rho^{t}\right) \tau} \tau^{\prime}-\nabla_{a^{\prime}}^{\mathrm{bas}} \tau\right\rangle \\
& \stackrel{\text { A. } 22}{-}\left\langle £_{X} \theta, \rho\left(a^{\prime}\right)\right\rangle+\rho\left(a^{\prime}\right)\langle\alpha, a\rangle+\left\langle\nu, £_{a} \tau^{\prime}\right\rangle-\rho\left(a^{\prime}\right)\langle\nu, \tau\rangle-\left\langle\nu,\left[\tau, \tau^{\prime}\right]_{d}\right\rangle \\
&=\left\langle £_{X} \theta, \rho\left(a^{\prime}\right)\right\rangle-\rho\left(a^{\prime}\right)\langle\theta, X\rangle+\left\langle\nu, £_{a}\left(a^{\prime}, \theta^{\prime}\right)\right\rangle \\
&-\left\langle\nu,\left(\left[a, a^{\prime}\right], £_{\rho(a)}^{\theta^{\prime}}-\mathbf{i}_{\rho\left(a^{\prime}\right)} \mathbf{d} \theta\right)\right\rangle \\
&=\left\langle\mathbf{i}_{X} \mathbf{d} \theta, \rho\left(a^{\prime}\right)\right\rangle+\left\langle\mathbf{i}_{\rho\left(a^{\prime}\right)} \mathbf{d} \theta, X\right\rangle=0 .
\end{aligned}
$$

We also need the following lemma, which is proved at the end of this section.

Lemma A.4. Let $A \rightarrow M$ be a Lie algebroid and $(K, U, \Delta)$ an LA-Dirac triple. Then Condition (5) of Theorem 5.2 is equivalent to:

$$
\begin{align*}
& \nabla_{\tau}^{\mathrm{bas}} \llbracket u, v \rrbracket_{\Delta}-\llbracket \nabla_{\tau}^{\mathrm{bas}} u, v \rrbracket_{\Delta}-\llbracket u, \nabla_{\tau}^{\mathrm{bas}} v \rrbracket_{\Delta}+\nabla_{\Delta_{u} \tau}^{\mathrm{bas}} v-\nabla_{\Delta_{v} \tau}^{\mathrm{bas}} u  \tag{A.4}\\
= & -\left(\rho, \rho^{t}\right) R_{\Delta}(u, v) \tau
\end{align*}
$$

for all $u, v \in \Gamma(U)$ and $\tau \in \Gamma\left(A \oplus T^{*} M\right)$.
The equality

$$
\begin{align*}
& \Delta_{u}\left[\tau_{1}, \tau_{2}\right]_{d}-\left[\Delta_{u} \tau_{1}, \tau_{2}\right]_{d}-\left[\tau_{1}, \Delta_{u} \tau_{2}\right]_{d}+\Delta_{\nabla_{a_{1}}^{\mathrm{bas}} u} \tau_{2}-\Delta_{\nabla_{a_{2}}^{\mathrm{bas}} u} \tau_{1}  \tag{A.5}\\
& +\left(0, \mathbf{d}\left\langle\tau_{1}, \nabla_{a_{2}}^{\mathrm{bas}} u\right\rangle\right) \\
= & -R_{\Delta}^{\mathrm{bas}}\left(a_{1}, a_{2}\right) u
\end{align*}
$$

holds for all $\tau_{1}, \tau_{2} \in \Gamma\left(A \oplus T^{*} M\right)$ with $\operatorname{pr}_{A}\left(\tau_{i}\right)=: a_{i}$ and all $u \in \Gamma(U)$.
Proof of Theorem 5.5. We start by checking that $\llbracket \cdot, \cdot \rrbracket$ is well-defined. Choose $k \in \Gamma(K), \tau \in \Gamma\left(A \oplus T^{*} M\right)$ with $\operatorname{pr}_{A}(k)=a, \operatorname{pr}_{A}(\tau)=a^{\prime}$, and $u \in \Gamma(U)$. We
have then

$$
\begin{aligned}
\llbracket u \oplus \tau,\left(\rho, \rho^{t}\right)(-k) \oplus k \rrbracket= & \left(-\llbracket u,\left(\rho, \rho^{t}\right) k \rrbracket_{\Delta}-\nabla_{a^{\prime}}^{\mathrm{bas}}\left(\rho, \rho^{t}\right) k-\nabla_{a}^{\mathrm{bas}} u\right) \\
& \oplus\left([\tau, k]_{d}+\Delta_{u} k+\Delta_{\left(\rho, \rho^{t}\right) k} \tau-\left(0, \mathbf{d}\left\langle\tau,\left(\rho, \rho^{t}\right) k\right\rangle\right)\right) .
\end{aligned}
$$

Using Lemma A.1, we see immediately that the second term of this sum equals $\nabla_{a^{\prime}}^{\text {bas }} k+\Delta_{u} k$. We verify that this is a section of $K$. By Remark 5.3 or the considerations before Theorem 5.2 , we know that $\nabla_{a^{\prime}}^{\text {bas }} k \in \Gamma(K)$, and $\Delta_{u} k \in \Gamma(K)$ follows from $K=U^{\circ}$ and the fact that $\llbracket \cdot, \cdot \rrbracket_{\Delta}$, which is dual to $\Delta$, preserves sections of $U$.

Recall A.1) and $\left(\rho, \rho^{t}\right) \Delta_{u} k=\llbracket u,\left(\rho, \rho^{t}\right) k \rrbracket_{\Delta}+\nabla_{a^{\prime}}^{\text {bas }} u$ by Lemma A. 3 . These yield

$$
\llbracket u \oplus \tau,\left(\rho, \rho^{t}\right)(-k) \oplus k \rrbracket=\left(-\left(\rho, \rho^{t}\right)\left(\nabla_{a}^{\mathrm{bas}} k+\Delta_{u} k\right)\right) \oplus\left(\nabla_{a}^{\mathrm{bas}} k+\Delta_{u} k\right),
$$

which is 0 in $C$. The equality $\llbracket\left(\rho, \rho^{t}\right)(-k) \oplus k, u \oplus \tau \rrbracket=0$ follows with

$$
\begin{aligned}
& \llbracket\left(\rho, \rho^{t}\right)(-k) \oplus k, u \oplus \tau \rrbracket_{C}+\llbracket u \oplus \tau,\left(\rho, \rho^{t}\right)(-k) \oplus k \rrbracket_{C} \\
= & \mathcal{D}\left\langle\left\langle u \oplus \tau,\left(\rho, \rho^{t}\right)(-k)\right\rangle\right\rangle_{C}
\end{aligned}
$$

proved below and $\left\langle\left\langle u \oplus \tau,\left(\rho, \rho^{t}\right)(-k) \oplus k\right\rangle\right\rangle_{C}=\langle u, k\rangle=0$ since $U=K^{\circ}$.
Choose $u, u_{i} \in \Gamma(U)$ and $\tau=(a, \theta), \tau_{i}=\left(a_{i}, \theta_{i}\right) \in \Gamma\left(A \oplus T^{*} M\right), i=$ $1,2,3$. We check (1)-(3) in the definition of a Courant algebroid, in reverse order. First we have

$$
\begin{aligned}
& \llbracket u_{1} \oplus \tau_{1}, u_{2} \oplus \tau_{2} \rrbracket_{C}+\llbracket u_{2} \oplus \tau_{2}, u_{1} \oplus \tau_{1} \rrbracket_{C} \\
= & \left(\llbracket u_{1}, u_{2} \rrbracket_{\Delta}+\llbracket u_{2}, u_{1} \rrbracket_{\Delta}\right) \oplus\left(\left[\tau_{1}, \tau_{2}\right]_{d}+\left[\tau_{2}, \tau_{1}\right]_{d}+\left(0, \mathbf{d}\left\langle\tau_{1}, u_{2}\right\rangle+\mathbf{d}\left\langle\tau_{2}, u_{1}\right\rangle\right)\right. \\
= & 0 \oplus\left(0, \mathbf{d}\left(\left\langle\tau_{1}, \tau_{2}\right\rangle_{d}+\left\langle\tau_{1}, u_{2}\right\rangle+\left\langle\tau_{2}, u_{1}\right\rangle\right)\right) \\
= & \mathcal{D}\left\langle\left\langle u_{1} \oplus \tau_{1}, u_{2} \oplus \tau_{2}\right\rangle\right\rangle_{C} .
\end{aligned}
$$

We denote by $\operatorname{Skew}_{\Delta}\left(\nu_{1}, \nu_{2}\right)$ the anti-commutator $\llbracket \nu_{1}, \nu_{2} \rrbracket_{\Delta}+\llbracket \nu_{2}, \nu_{1} \rrbracket_{\Delta}$, $\nu_{1}, \nu_{2} \in \Gamma\left(T M \oplus A^{*}\right)$. We check the equality

$$
\begin{aligned}
& c\left(u_{1} \oplus \tau_{1}\right)\left\langle\left\langle u_{2} \oplus \tau_{2}, u_{3} \oplus \tau_{3}\right\rangle\right\rangle_{C} \\
= & \left\langle\left\langle\llbracket u_{1} \oplus \tau_{1}, u_{2} \oplus \tau_{2} \rrbracket_{C}, u_{3} \oplus \tau_{3}\right\rangle\right\rangle_{C}+\left\langle\left\langle u_{2} \oplus \tau_{2}, \llbracket u_{1} \oplus \tau_{1}, u_{3} \oplus \tau_{3} \rrbracket_{C}\right\rangle\right\rangle_{C} .
\end{aligned}
$$

The bracket $\llbracket u_{1} \oplus \tau_{1}, u_{2} \oplus \tau_{2} \rrbracket$ equals

$$
\left(\llbracket u_{1}, u_{2} \rrbracket_{\Delta}+\nabla_{\tau_{1}}^{\text {bas }} u_{2}-\nabla_{\tau_{2}}^{\mathrm{bas}} u_{1}\right) \oplus\left(\left[\tau_{1}, \tau_{2}\right]_{d}+\Delta_{u_{1}} \tau_{2}-\Delta_{u_{2}} \tau_{1}+\left(0, \mathbf{d}\left\langle\tau_{1}, u_{2}\right\rangle\right)\right)
$$

Using A.2 , we can replace $\left[\tau_{1}, \tau_{2}\right]_{d}$ by

$$
\nabla_{\tau_{1}}^{\mathrm{bas}} \tau_{2}-\Delta_{\left(\rho, \rho^{t}\right) \tau_{2}} \tau_{1}+\left(0, \mathbf{d}\left\langle\tau_{1},\left(\rho, \rho^{t}\right) \tau_{2}\right\rangle\right)
$$

in this expression and we find that $\left\langle\left\langle\llbracket u_{1} \oplus \tau_{1}, u_{2} \oplus \tau_{2} \rrbracket, u_{3} \oplus \tau_{3}\right\rangle\right\rangle_{C}$ equals

$$
\begin{aligned}
& \left\langle\llbracket u_{1}, u_{2} \rrbracket_{\Delta}+\nabla_{\tau_{1}}^{\text {bas }} u_{2}-\nabla_{\tau_{2}}^{\mathrm{bas}} u_{1}, \tau_{3}\right\rangle+X_{3}\left\langle\tau_{1}, u_{2}\right\rangle+X_{3}\left\langle\tau_{1},\left(\rho, \rho^{t}\right) \tau_{2}\right\rangle \\
& +\left\langle\nabla_{\tau_{1}}^{\mathrm{bas}} \tau_{2}-\Delta_{\left(\rho, \rho^{t}\right) \tau_{2}} \tau_{1}+\Delta_{u_{1}} \tau_{2}-\Delta_{u_{2}} \tau_{1}, u_{3}\right\rangle+\rho\left(a_{3}\right)\left\langle\tau_{1}, u_{2}\right\rangle \\
& +\rho\left(a_{3}\right)\left\langle\tau_{1},\left(\rho, \rho^{t}\right) \tau_{2}\right\rangle+\left\langle\nabla_{\tau_{1}}^{\mathrm{bas}} \tau_{2}-\Delta_{\left(\rho, \rho^{t}\right) \tau_{2}} \tau_{1}+\Delta_{u_{1}} \tau_{2}-\Delta_{u_{2}} \tau_{1},\left(\rho, \rho^{t}\right) \tau_{3}\right\rangle
\end{aligned}
$$

Using A.3) we replace $\left\langle-\nabla_{\tau_{2}}^{\text {bas }} u_{1}+\left(\rho, \rho^{t}\right) \Delta_{u_{1}} \tau_{2}, \tau_{3}\right\rangle$ in this equation by

$$
\left\langle\nabla_{\tau_{3}}^{\mathrm{bas}} u_{1}, \tau_{2}\right\rangle+\left\langle\llbracket u_{1},\left(\rho, \rho^{t}\right) \tau_{2} \rrbracket_{\Delta}, \tau_{3}\right\rangle
$$

Now we sum $\left\langle\left\langle\llbracket u_{1} \oplus \tau_{1}, u_{2} \oplus \tau_{2} \rrbracket, u_{3} \oplus \tau_{3}\right\rangle\right\rangle_{C}$ with $\left\langle\left\langle\llbracket u_{1} \oplus \tau_{1}, u_{3} \oplus \tau_{3} \rrbracket, u_{2} \oplus\right.\right.$ $\left.\left.\tau_{2}\right\rangle\right\rangle_{C}$. The terms $\left\langle\llbracket u_{1}, u_{2} \rrbracket_{\Delta}, \tau_{3}\right\rangle,\left\langle\llbracket u_{1}, u_{3} \rrbracket_{\Delta}, \tau_{2}\right\rangle,\left\langle\Delta_{u_{1}} \tau_{2}, u_{3}\right\rangle$ and $\left\langle\Delta_{u_{1}} \tau_{3}, u_{2}\right\rangle$ add up to

$$
X_{1}\left\langle\left\langle u_{2} \oplus \tau_{2}, u_{3} \oplus \tau_{3}\right\rangle\right\rangle_{C}-X_{1}\left\langle\tau_{2},\left(\rho, \rho^{t}\right) \tau_{3}\right\rangle
$$

The terms $X_{3}\left\langle\tau_{1}, u_{2}\right\rangle$ and $-\left\langle\Delta_{u_{3}} \tau_{1}, u_{2}\right\rangle$ add up to $\left\langle\tau_{1}, \llbracket u_{2}, u_{3} \rrbracket_{\Delta}\right\rangle$ and the terms $X_{2}\left\langle\tau_{1}, u_{3}\right\rangle$ and $-\left\langle\Delta_{u_{2}} \tau_{1}, u_{3}\right\rangle$ add up to $\left\langle\tau_{1}, \llbracket u_{3}, u_{2} \rrbracket_{\Delta}\right\rangle$, which cancels out $\left\langle\tau_{1}, \llbracket u_{2}, u_{3} \rrbracket_{\Delta}\right\rangle$ since $\llbracket \cdot, \cdot \rrbracket_{\Delta}$ is skew-symmetric on sections of $U$. In a similar manner,

$$
\begin{align*}
X_{3}\left\langle\tau_{1},\left(\rho, \rho^{t}\right) \tau_{2}\right\rangle & -\left\langle\Delta_{u_{2}} \tau_{1},\left(\rho, \rho^{t}\right) \tau_{3}\right\rangle  \tag{A.6}\\
& +X_{2}\left\langle\tau_{1},\left(\rho, \rho^{t}\right) \tau_{3}\right\rangle-\left\langle\Delta_{u_{3}} \tau_{1},\left(\rho, \rho^{t}\right) \tau_{2}\right\rangle
\end{align*}
$$

is $\left\langle\tau_{1}, \llbracket u_{3},\left(\rho, \rho^{t}\right) \tau_{2} \rrbracket_{\Delta}+\llbracket u_{2},\left(\rho, \rho^{t}\right) \tau_{3} \rrbracket \Delta\right\rangle$, and
(A.7) $-\left\langle\Delta_{\left(\rho, \rho^{t}\right) \tau_{2}} \tau_{1}, u_{3}\right\rangle+\rho\left(a_{3}\right)\left\langle\tau_{1}, u_{2}\right\rangle-\left\langle\Delta_{\left(\rho, \rho^{t}\right) \tau_{3}} \tau_{1}, u_{2}\right\rangle+\rho\left(a_{2}\right)\left\langle\tau_{1}, u_{3}\right\rangle$
is $\left\langle\tau_{1}, \llbracket\left(\rho, \rho^{t}\right) \tau_{2}, u_{3} \rrbracket_{\Delta}+\llbracket\left(\rho, \rho^{t}\right) \tau_{3}, u_{2} \rrbracket_{\Delta}\right\rangle$. As a consequence, A.6) and A.7) add up to

$$
\left\langle\tau_{1}, \operatorname{Skew}_{\Delta}\left(u_{2},\left(\rho, \rho^{t}\right) \tau_{3}\right)+\operatorname{Skew}_{\Delta}\left(u_{3},\left(\rho, \rho^{t}\right) \tau_{2}\right)\right\rangle
$$

By (5.1), this adds up with

$$
\left\langle\nabla_{\tau_{1}}^{\mathrm{bas}} u_{2}, \tau_{3}\right\rangle+\left\langle\nabla_{\tau_{1}}^{\mathrm{bas}} \tau_{2}, u_{3}\right\rangle+\left\langle\nabla_{\tau_{1}}^{\mathrm{bas}} u_{3}, \tau_{2}\right\rangle+\left\langle\nabla_{\tau_{1}}^{\mathrm{bas}} \tau_{3}, u_{2}\right\rangle
$$

to $\rho\left(a_{1}\right)\left\langle u_{2}, \tau_{3}\right\rangle+\rho\left(a_{1}\right)\left\langle u_{3}, \tau_{2}\right\rangle$. Similarly, using (5.1) and A.1), the terms $\left\langle\nabla_{\tau_{1}}^{\text {bas }} \tau_{2},\left(\rho, \rho^{t}\right) \tau_{3}\right\rangle$ and $\left\langle\nabla_{\tau_{1}}^{\text {bas }} \tau_{3},\left(\rho, \rho^{t}\right) \tau_{2}\right\rangle$ add up to

$$
\rho\left(a_{1}\right)\left\langle\tau_{2},\left(\rho, \rho^{t}\right) \tau_{3}\right\rangle-\left\langle\tau_{1}, \operatorname{Skew}_{\Delta}\left(\left(\rho, \rho^{t}\right) \tau_{2},\left(\rho, \rho^{t}\right) \tau_{3}\right)\right\rangle
$$

The terms $\rho\left(a_{3}\right)\left\langle\tau_{1},\left(\rho, \rho^{t}\right) \tau_{2}\right\rangle, \rho\left(a_{2}\right)\left\langle\tau_{1},\left(\rho, \rho^{t}\right) \tau_{3}\right\rangle,-\left\langle\Delta_{\left(\rho, \rho^{t}\right) \tau_{2}} \tau_{1},\left(\rho, \rho^{t}\right) \tau_{3}\right\rangle$ and $-\left\langle\Delta_{\left(\rho, \rho^{t}\right) \tau_{3}} \tau_{1},\left(\rho, \rho^{t}\right) \tau_{2}\right\rangle$ sum up to $\left\langle\tau_{1}, \operatorname{Skew}_{\Delta}\left(\left(\rho, \rho^{t}\right) \tau_{2},\left(\rho, \rho^{t}\right) \tau_{3}\right)\right\rangle$.

Putting everything together, we get

$$
\begin{aligned}
& c\left(u_{1} \oplus \tau_{1}\right)\left\langle\left\langle u_{2} \oplus \tau_{2}, u_{3} \oplus \tau_{3}\right\rangle\right\rangle_{C}-X_{1}\left\langle\tau_{2},\left(\rho, \rho^{t}\right) \tau_{3}\right\rangle \\
& +\left\langle\nabla_{\tau_{3}}^{\mathrm{bas}} u_{1}, \tau_{2}\right\rangle+\left\langle\llbracket u_{1},\left(\rho, \rho^{t}\right) \tau_{2} \rrbracket_{\Delta}, \tau_{3}\right\rangle+\left\langle\nabla_{\tau_{2}}^{\mathrm{bas}} u_{1}, \tau_{3}\right\rangle+\left\langle\llbracket u_{1},\left(\rho, \rho^{t}\right) \tau_{3} \rrbracket_{\Delta}, \tau_{2}\right\rangle
\end{aligned}
$$

By A.3) the third, fourth and fifth term add up to $\left\langle\Delta_{u_{1}} \tau_{2},\left(\rho, \rho^{t}\right) \tau_{3}\right\rangle$, which cancels out the second and the sixth.

For the Jacobi identity, we check that

$$
\begin{aligned}
& \mathrm{Jac}_{\llbracket \cdot \cdot \cdot \rrbracket_{\Delta}}\left(u_{1} \oplus \tau_{1}, u_{2} \oplus \tau_{2}, u_{3} \oplus \tau_{3}\right) \\
:= & \llbracket u_{1} \oplus \tau_{1}, u_{2} \oplus \tau_{2} \rrbracket, u_{3} \oplus \tau_{3} \rrbracket+\llbracket u_{2} \oplus \tau_{2}, \llbracket u_{1} \oplus \tau_{1}, u_{3} \oplus \tau_{3} \rrbracket \rrbracket \\
& -\llbracket u_{1} \oplus \tau_{1}, \llbracket u_{2} \oplus \tau_{2}, u_{3} \oplus \tau_{3} \rrbracket \rrbracket \\
= & -\left(\rho, \rho^{t}\right)(k) \oplus k,
\end{aligned}
$$

with $k:=\left[R_{\Delta}^{\mathrm{bas}}\left(a_{1}, a_{2}\right) u_{3}-R_{\Delta}\left(u_{1}, u_{2}\right) \tau_{3}\right]+$ c.p.
To see that $k$ is a section of $K$, recall from Theorem 5.2 that since $u_{i}=\left(X_{i}, \alpha_{i}\right) \in \Gamma(U), i=1,2,3$, we have $R_{\Delta}\left(u_{1}, u_{2}\right) \tau_{3}+$ c.p. $\in \Gamma(K)$. By the same theorem, we find $R_{\Delta}^{\text {bas }}\left(a_{1}, a_{2}\right) u_{3}+$ c.p. $\in \Gamma(K)$. We write $\tau_{i}=\left(a_{i}, \theta_{i}\right)$ for $i=1,2,3$. Since $\llbracket u_{1} \oplus \tau_{1}, u_{2} \oplus \tau_{2} \rrbracket$ is

$$
\left(\llbracket u_{1}, u_{2} \rrbracket_{\Delta}+\nabla_{\tau_{1}}^{\mathrm{bas}} u_{2}-\nabla_{\tau_{2}}^{\mathrm{bas}} u_{1}\right) \oplus\left(\left[\tau_{1}, \tau_{2}\right]_{d}+\Delta_{u_{1}} \tau_{2}-\Delta_{u_{2}} \tau_{1}+\left(0, \mathbf{d}\left\langle\tau_{1}, u_{2}\right\rangle\right)\right),
$$

its bracket $\llbracket \llbracket u_{1} \oplus \tau_{1}, u_{2} \oplus \tau_{2} \rrbracket, u_{3} \oplus \tau_{3} \rrbracket$ with $u_{3} \oplus \tau_{3}$ is

$$
\begin{aligned}
& \left(\llbracket \llbracket u_{1}, u_{2} \rrbracket_{\Delta}, u_{3} \rrbracket_{\Delta}+\llbracket \nabla_{\tau_{1}}^{\text {bas }} u_{2}-\nabla_{\tau_{2}}^{\text {bas }} u_{1}, u_{3} \rrbracket_{\Delta}\right. \\
& +\nabla_{\left[\tau_{1}, \tau_{2}\right]_{d}+\Delta_{u_{1}} \tau_{2}-\Delta_{u_{2}} \tau_{1}+\left(0, \mathbf{d}\left\langle\tau_{1}, u_{2}\right\rangle\right)}^{\text {bas }} u_{3} \\
& \left.-\nabla_{\tau_{3}}^{\text {bas }}\left(\llbracket u_{1}, u_{2} \rrbracket_{\Delta}+\nabla_{\tau_{1}}^{\text {bas }} u_{2}-\nabla_{\tau_{2}}^{\text {bas }} u_{1}\right)\right) \\
& \oplus\left(\left[\left[\tau_{1}, \tau_{2}\right]_{d}, \tau_{3}\right]_{d}+\left[\Delta_{u_{1}} \tau_{2}-\Delta_{u_{2}} \tau_{1}, \tau_{3}\right]_{d}+\left[\left(0, \mathbf{d}\left\langle\tau_{1}, u_{2}\right\rangle\right), \tau_{3}\right]_{d}\right. \\
& \quad+\Delta_{\llbracket u_{1}, u_{2} \rrbracket \Delta}+\nabla_{\tau_{1}}^{\text {bas } u_{2}-\nabla_{\tau_{2}}^{\text {bas }} u_{1}} \tau_{3}-\Delta_{u_{3}}\left(\left[\tau_{1}, \tau_{2}\right]_{d}+\Delta_{u_{1}} \tau_{2}-\Delta_{u_{2}} \tau_{1}\right. \\
& \left.\quad+\left(0, \mathbf{d}\left\langle\tau_{1}, u_{2}\right\rangle\right)\right)+\left(0, \mathbf{d}\left\langle\left[\tau_{1}, \tau_{2}\right]_{d}+\Delta_{u_{1}} \tau_{2}-\Delta_{u_{2}} \tau_{1}\right.\right. \\
& \left.\left.\left.\quad+\left(0, \mathbf{d}\left\langle\tau_{1}, u_{2}\right\rangle\right), u_{3}\right\rangle\right)\right) .
\end{aligned}
$$

Since $\left[\left(0, \mathbf{d}\left\langle\tau_{1}, u_{2}\right\rangle\right), \tau_{3}\right]_{d}=0$ and

$$
\begin{aligned}
& \operatorname{pr}_{A}\left(\left[\tau_{1}, \tau_{2}\right]_{d}+\Delta_{u_{1}} \tau_{2}-\Delta_{u_{2}} \tau_{1}+\left(0, \mathbf{d}\left\langle\tau_{1}, u_{2}\right\rangle\right)\right. \\
= & {\left[a_{1}, a_{2}\right]+\operatorname{pr}_{A}\left(\Omega_{u_{1}} a_{2}-\Omega_{u_{2}} a_{1}\right) }
\end{aligned}
$$

this is

$$
\begin{aligned}
& \llbracket \llbracket u_{1} \oplus \tau_{1}, u_{2} \oplus \tau_{2} \rrbracket, u_{3} \oplus \tau_{3} \rrbracket \\
= & \left(\llbracket \llbracket u_{1}, u_{2} \rrbracket_{\Delta}, u_{3} \rrbracket_{\Delta}+\llbracket \nabla_{\tau_{1}}^{\mathrm{bas}} u_{2}-\nabla_{a_{2}}^{\mathrm{bas}} u_{1}, u_{3} \rrbracket_{\Delta}\right. \\
& +\nabla_{\left[a_{1}, a_{2}\right]+\mathrm{pr}_{A}\left(\Omega_{u_{1}} a_{2}-\Omega_{u_{2}} a_{1}\right)}^{\mathrm{bas}} u_{3} \\
& \left.-\nabla_{a_{3}}^{\mathrm{bas}}\left(\llbracket u_{1}, u_{2} \rrbracket_{\Delta}+\nabla_{a_{1}}^{\mathrm{bas}} u_{2}-\nabla_{a_{2}}^{\mathrm{bas}} u_{1}\right)\right) \\
& \oplus\left(\left[\left[\tau_{1}, \tau_{2}\right]_{d}, \tau_{3}\right]_{d}+\left[\Delta_{u_{1}} \tau_{2}-\Delta_{u_{2}} \tau_{1}, \tau_{3}\right]_{d}+\Delta_{\llbracket u_{1}, u_{2} \rrbracket} \rrbracket_{\Delta}+\nabla_{a_{1}}^{\text {bas } u_{2}-\nabla_{a_{2}}^{\text {bas }} u_{1}} \tau_{3}\right. \\
& -\Delta_{u_{3}}\left(\left[\tau_{1}, \tau_{2}\right]_{d}+\Delta_{u_{1}} \tau_{2}-\Delta_{u_{2}} \tau_{1}+\left(0, \mathbf{d}\left\langle\tau_{1}, u_{2}\right\rangle\right)\right) \\
& \left.+\left(0, \mathbf{d}\left\langle\left[\tau_{1}, \tau_{2}\right]_{d}+\Delta_{u_{1}} \tau_{2}-\Delta_{u_{2}} \tau_{1}+\left(0, \mathbf{d}\left\langle\tau_{1}, u_{2}\right\rangle\right), u_{3}\right\rangle\right)\right) .
\end{aligned}
$$

In the same manner, we get

$$
\begin{aligned}
& \llbracket u_{2} \oplus \tau_{2}, \llbracket u_{1} \oplus \tau_{1}, u_{3} \oplus \tau_{3} \rrbracket \rrbracket \\
= & \left(\llbracket u_{2}, \llbracket u_{1}, u_{3} \rrbracket_{\Delta} \rrbracket_{\Delta}+\llbracket u_{2}, \nabla_{a_{1}}^{\mathrm{bas}} u_{3}-\nabla_{a_{3}}^{\mathrm{bas}} u_{1} \rrbracket_{\Delta}\right. \\
& +\nabla_{a_{2}}^{\mathrm{bas}}\left(\llbracket u_{1}, u_{3} \rrbracket_{\Delta}+\nabla_{a_{1}}^{\mathrm{bas}} u_{3}-\nabla_{a_{3}}^{\mathrm{bas}} u_{1}\right)-\nabla_{\left[a_{1}, a_{3}\right]+\mathrm{pr}_{A}}^{\mathrm{bas}}\left(\Omega_{\left.u_{1} a_{3}-\Omega_{u_{3}} a_{1}\right)} u_{2}\right) \\
\oplus & \left(\left[\tau_{2},\left[\tau_{1}, \tau_{3}\right]_{d}\right]_{d}+\left[\tau_{2}, \Delta_{u_{1}} \tau_{3}-\Delta_{u_{3}} \tau_{1}\right]_{d}+\left[\tau_{2},\left(0, \mathbf{d}\left\langle\tau_{1}, u_{3}\right\rangle\right)\right]_{d}\right. \\
& +\Delta_{u_{2}}\left(\left[\tau_{1}, \tau_{3}\right]_{d}+\Delta_{u_{1}} \tau_{3}-\Delta_{u_{3}} \tau_{1}+\left(0, \mathbf{d}\left\langle\tau_{1}, u_{3}\right\rangle\right)\right) \\
& \left.\quad-\Delta_{\llbracket u_{1}, u_{3} \rrbracket \rrbracket_{\Delta}+\nabla_{a_{1}}^{\mathrm{bas}} u_{3}-\nabla_{a_{3}}^{\mathrm{bas}} u_{1}} \tau_{2}+\left(0, \mathbf{d}\left\langle\tau_{2}, \llbracket u_{1}, u_{3} \rrbracket_{\Delta}+\nabla_{a_{1}}^{\mathrm{bas}} u_{3}-\nabla_{a_{3}}^{\mathrm{bas}} u_{1}\right\rangle\right)\right) .
\end{aligned}
$$

We start by studying the $U$-part of $\mathrm{Jac}_{\llbracket} \cdot, \mathbb{\rrbracket}_{\Delta}\left(u_{1} \oplus \tau_{1}, u_{2} \oplus \tau_{2}, u_{3} \oplus \tau_{3}\right)$. By the computations above, this equals

$$
\begin{aligned}
& \llbracket \llbracket u_{1}, u_{2} \rrbracket_{\Delta}, u_{3} \rrbracket_{\Delta}+\llbracket u_{2}, \llbracket u_{1}, u_{3} \rrbracket_{\Delta} \rrbracket_{\Delta}-\llbracket u_{1}, \llbracket u_{2}, u_{3} \rrbracket_{\Delta} \rrbracket_{\Delta} \\
& -R_{\nabla^{\text {bas }}}\left(a_{1}, a_{2}\right) u_{3}+R_{\nabla^{\text {bas }}}\left(a_{1}, a_{3}\right) u_{2}-R_{\nabla^{\text {bas }}}\left(a_{2}, a_{3}\right) u_{1} \\
& +\llbracket \nabla_{a_{1}}^{\text {bas }} u_{2}-\nabla_{a_{2}}^{\mathrm{bas}} u_{1}, u_{3} \rrbracket_{\Delta}+\nabla_{\mathrm{pr}_{A}\left(\Omega_{u_{1}} a_{2}-\Omega_{u_{2}} a_{1}\right)}^{u_{3}-\nabla_{a_{3}}^{\mathrm{bas}} \llbracket u_{1}, u_{2} \rrbracket_{\Delta}} \\
& +\llbracket u_{2}, \nabla_{a_{1}}^{\mathrm{bas}} u_{3}-\nabla_{a_{3}}^{\mathrm{bas}} u_{1} \rrbracket_{\Delta}+\nabla_{a_{2}}^{\mathrm{bas}} \llbracket u_{1}, u_{3} \rrbracket_{\Delta}-\nabla_{\mathrm{pr}_{A}\left(\Omega_{u_{1}} a_{3}-\Omega_{u_{3}} a_{1}\right)}^{u_{2}} \\
& -\llbracket u_{1}, \nabla_{a_{2}}^{\mathrm{bas}} u_{3}-\nabla_{a_{3}}^{\mathrm{bas}} u_{2} \|_{\Delta}-\nabla_{a_{1}}^{\mathrm{bas}} \llbracket u_{2}, u_{3} \rrbracket_{\Delta}+\nabla_{\mathrm{pr}_{A}\left(\Omega_{u_{2}} a_{3}-\Omega_{u_{3}} a_{2}\right)}^{u_{1}}
\end{aligned}
$$

Since $\left(U, \operatorname{pr}_{T M}, \llbracket \cdot, \cdot \rrbracket_{\Delta}\right)$ is a Lie algebroid, the first three terms vanish together. Next note that since $\left(\nabla^{\text {bas }}, \nabla^{\text {bas }}, R_{\Delta}^{\text {bas }}\right)$ is a representation up to homotopy of $A$ on $\left(\rho, \rho^{t}\right): A \oplus T^{*} M \rightarrow T M \oplus A^{*}$, the basic curvature satisfies

$$
\begin{equation*}
R_{\nabla_{\text {bas }}}\left(a_{1}, a_{2}\right) \nu=\left(\rho, \rho^{t}\right) \circ R_{\Delta}^{\mathrm{bas}}\left(a_{1}, a_{2}\right) \nu \tag{A.8}
\end{equation*}
$$

for all $a_{1}, a_{2} \in \Gamma(A), \nu \in \Gamma\left(T M \oplus A^{*}\right)$. Using this, A.4, (4) in Theorem 5.2, the skew-symmetry of $\llbracket \cdot, \cdot \rrbracket_{\Delta}$ on $\Gamma(U)$, and the equality $\operatorname{pr}_{A} \Omega_{u_{1}} a_{2}=$ $\operatorname{pr}_{A} \Delta_{u_{1}} \tau_{2}$, we find easily that the $U$-part of $\mathrm{Jac}_{\llbracket \cdot, \cdot \rrbracket_{\Delta}}\left(u_{1} \oplus \tau_{1}, u_{2} \oplus \tau_{2}, u_{3} \oplus\right.$ $\tau_{3}$ ) is

$$
\begin{aligned}
& -\left(\rho, \rho^{t}\right)\left(R_{\Delta}^{\mathrm{bas}}\left(a_{1}, a_{2}\right) u_{3}+R_{\Delta}^{\mathrm{bas}}\left(a_{3}, a_{1}\right) u_{2}+R_{\Delta}^{\mathrm{bas}}\left(a_{2}, a_{3}\right) u_{1}\right) \\
& +\left(\rho, \rho^{t}\right)\left(R_{\Delta}\left(u_{1}, u_{2}\right) \tau_{3}+R_{\Delta}\left(u_{2}, u_{3}\right) \tau_{1}+R_{\Delta}\left(u_{3}, u_{1}\right) \tau_{2}\right)
\end{aligned}
$$

Now we look more carefully at the $A \oplus T^{*} M$-part of $\mathrm{Jac}_{\llbracket \cdot, \cdot{ }^{\cdot}}\left(u_{1} \oplus \tau_{1}, u_{2} \oplus\right.$ $\left.\tau_{2}, u_{3} \oplus \tau_{3}\right)$. Sorting out the terms yields that this is

$$
\begin{aligned}
& {\left[\left[\tau_{1}, \tau_{2}\right]_{d}, \tau_{3}\right]_{d}+\left[\tau_{2},\left[\tau_{1}, \tau_{3}\right]_{d}\right]_{d}-\left[\tau_{1},\left[\tau_{2}, \tau_{3}\right]_{d}\right]_{d}} \\
& -\Delta_{u_{1}}\left[\tau_{2}, \tau_{3}\right]_{d}+\left[\Delta_{u_{1}} \tau_{2}, \tau_{3}\right]_{d}+\left[\tau_{2}, \Delta_{u_{1}} \tau_{3}\right]_{d}+\Delta_{\nabla_{a_{3}}^{\text {bas }} u_{1}} \tau_{2}-\Delta_{\nabla_{a_{2}}^{\text {bas }} u_{1}} \tau_{3} \\
& -\left(0, \mathbf{d}\left\langle\tau_{2}, \nabla_{a_{3}}^{\text {bas }} u_{1}\right\rangle\right)+\Delta_{u_{2}}\left[\tau_{1}, \tau_{3}\right]_{d}-\left[\Delta_{u_{2}} \tau_{1}, \tau_{3}\right]_{d}-\left[\tau_{1}, \Delta_{u_{2}} \tau_{3}\right]_{d}-\Delta_{\nabla_{a_{3}}^{\text {bas }} u_{2}} \tau_{1} \\
& +\Delta_{\nabla_{a_{1}}^{\text {bas }}{ }_{2} \tau_{3}+\left(0, \mathbf{d}\left\langle\tau_{1}, \nabla_{a_{3}}^{\text {bas }} u_{2}\right\rangle\right)-\Delta_{u_{3}}\left[\tau_{1}, \tau_{2}\right]_{d}-\left[\tau_{2}, \Delta_{u_{3}} \tau_{1}\right]_{d}+\left[\tau_{1}, \Delta_{u_{3}} \tau_{2}\right]_{d}}^{+\Delta_{\nabla_{a_{2}}^{\text {bas }} u_{3}} \tau_{1}-\Delta_{\nabla_{a_{1}}^{\text {bas }} u_{3}} \tau_{2}-\left(0, \mathbf{d}\left\langle\tau_{1}, \nabla_{a_{2}}^{\text {bas }} u_{3}\right\rangle\right)} \\
& -R_{\Delta}\left(u_{1}, u_{2}\right) \tau_{3}-R_{\Delta}\left(u_{2}, u_{3}\right) \tau_{1}-R_{\Delta}\left(u_{3}, u_{1}\right) \tau_{2} \\
& -\Delta_{u_{3}}\left(0, \mathbf{d}\left\langle\tau_{1}, u_{2}\right\rangle\right)+\left(0, \mathbf{d}\left\langle\left[\tau_{1}, \tau_{2}\right]_{d}+\Delta_{u_{1}} \tau_{2}-\Delta_{u_{2}} \tau_{1}+\left(0, \mathbf{d}\left\langle\tau_{1}, u_{2}\right\rangle\right), u_{3}\right\rangle\right) \\
& +\left[\tau_{2},\left(0, \mathbf{d}\left\langle\tau_{1}, u_{3}\right\rangle\right)\right]_{d}+\Delta_{u_{2}}\left(0, \mathbf{d}\left\langle\tau_{1}, u_{3}\right\rangle\right)+\left(0, \mathbf{d}\left\langle\tau_{2}, \llbracket u_{1}, u_{3} \rrbracket_{\Delta}+\nabla_{a_{1}}^{\text {bas }} u_{3}\right\rangle\right) \\
& -\left[\tau_{1},\left(0, \mathbf{d}\left\langle\tau_{2}, u_{3}\right\rangle\right)\right]_{d}-\Delta_{u_{1}}\left(0, \mathbf{d}\left\langle\tau_{2}, u_{3}\right\rangle\right)-\left(0, \mathbf{d}\left\langle\tau_{1}, \llbracket u_{2}, u_{3} \rrbracket_{\Delta}\right\rangle\right) .
\end{aligned}
$$

By the Jacobi identity for $[\cdot, \cdot]_{d}$ and three times A.5 together with $-\left[\tau_{2}, \Delta_{u_{3}} \tau_{1}\right]_{d}=\left[\Delta_{u_{3}} \tau_{1}, \tau_{2}\right]_{d}-\left(0, \mathbf{d}\left\langle\left(\rho, \rho^{t}\right) \Delta_{u_{3}} \tau_{1}, \tau_{2}\right\rangle\right)$, we get

$$
\begin{aligned}
& \quad R_{\Delta}^{\text {bas }}\left(a_{2}, a_{3}\right) u_{1}-R_{\Delta}^{\mathrm{bas}}\left(a_{1}, a_{3}\right) u_{2}+R_{\Delta}^{\mathrm{bas}}\left(a_{1}, a_{2}\right) u_{3} \\
& \quad-R_{\Delta}\left(u_{1}, u_{2}\right) \tau_{3}-R_{\Delta}\left(u_{2}, u_{3}\right) \tau_{1}-R_{\Delta}\left(u_{3}, u_{1}\right) \tau_{2} \\
& \quad-\left(0, \mathbf{d} X_{3}\left(\tau_{1}, u_{2}\right\rangle\right)+\left(0, \mathbf{d}\left\langle\left[\tau_{1}, \tau_{2}\right]_{d}+\Delta_{u_{1}} \tau_{2}-\Delta_{u_{2} \tau}, u_{3}\right\rangle\right)+\left(0, \mathbf{d} X_{3}\left(\tau_{1}, u_{2}\right\rangle\right) \\
& \quad+\left(0, \mathbf{d} \rho\left(a_{2}\right)\left\langle\tau_{1}, u_{3}\right\rangle\right)+\underline{\left(0, \mathbf{d} X_{2}\left(\tau_{1}, u_{3}\right\rangle\right)}+\left(0, \mathbf{d}\left\langle\tau_{2}, \llbracket u_{4}, u_{3} \rrbracket \Delta \Delta+\nabla_{a_{1}}^{\text {bas }} u_{3}\right\rangle\right) \\
& \quad-\left(0, \mathbf{d} \rho\left(a_{1}\right)\left\langle\tau_{2}, u_{3}\right\rangle\right)-\left(0, \mathbf{d} X_{1}\left(\tau_{2}, u_{3}\right\rangle\right)-\left(0, \mathbf{d}\left\langle\tau_{1}, \llbracket u_{2}, u_{3} \rrbracket_{\Delta}\right\rangle\right) \\
& \quad-\left(0, \mathbf{d}\left\langle\left(\rho, \rho^{t}\right) \Delta_{u_{3}} \tau_{1}, \tau_{2}\right\rangle\right) \\
& =R_{\Delta}^{\text {bas }}\left(a_{2}, a_{3}\right) u_{1}+R_{\Delta}^{\text {bas }}\left(a_{3}, a_{1}\right) u_{2}+R_{\Delta}^{\text {bas }}\left(a_{1}, a_{2}\right) u_{3} \\
& \quad-R_{\Delta}\left(u_{1}, u_{2}\right) \tau_{3}-R_{\Delta}\left(u_{2}, u_{3}\right) \tau_{1}-R_{\Delta}\left(u_{3}, u_{1}\right) \tau_{2}+(0, \mathbf{d} f),
\end{aligned}
$$

with (using A.2))

$$
\begin{aligned}
& f=\left\langle\Delta_{\left(\rho, \rho^{t}\right) \tau_{1}} \tau_{2}-\nabla_{\tau_{2}}^{\text {bas }} \tau_{1}, u_{3}\right\rangle+\rho\left(a_{2}\right)\left\langle\tau_{1}, u_{3}\right\rangle \\
&+\left\langle\tau_{2}, \nabla_{a_{1}}^{\text {bas }} u_{3}-\left(\rho, \rho^{t}\right) \Delta_{u_{3}} \tau_{1}\right\rangle-\rho\left(a_{1}\right)\left\langle\tau_{2}, u_{3}\right\rangle \\
&=-\left\langle\nabla_{\tau_{2}}^{\text {bas }} \tau_{1}, u_{3}\right\rangle+\rho\left(a_{2}\right)\left\langle\tau_{1}, u_{3}\right\rangle \\
&+\left\langle\tau_{2}, \nabla_{a_{1}}^{\text {bas }} u_{3}-\left(\rho, \rho^{t}\right) \Delta_{u_{3}} \tau_{1}-\llbracket\left(\rho, \rho^{t}\right) \tau_{1}, u_{3} \rrbracket \Delta\right\rangle \\
& \stackrel{\text { A.33 }}{=}-\left\langle\nabla_{\tau_{2}}^{\text {bas }} \tau_{1}, u_{3}\right\rangle+\rho\left(a_{2}\right)\left\langle\tau_{1}, u_{3}\right\rangle-\left\langle\nabla_{\tau_{2}}^{\text {bas }} u_{3}, \tau_{1}\right\rangle \\
&-\left\langle\text { Skew }_{\Delta}\left(u_{3},\left(\rho, \rho^{t}\right) \tau_{1}\right), a_{2}\right\rangle
\end{aligned}
$$

(5.1) 0 .

We have used Theorem A. 4 for the Jacobi identity. For completeness, we prove this theorem here.

Proof of Theorem A.4. We start with the first equation. For simplicity, we write here $a$ for $(a, 0), \Delta_{u} a:=\Delta_{u}(a, 0)$ and $\mathbf{d} f:=(0, \mathbf{d} f)$ for $a \in \Gamma(A)$, $f \in C^{\infty}(M)$ and $u \in \Gamma(U)$. First, we find that for $a_{1}, a_{2} \in \Gamma(A)$ and $u_{1}=$ $\left(X_{1}, \alpha_{1}\right), u_{2}=\left(X_{2}, \alpha_{2}\right) \in \Gamma(U)$, the equation $0=\left\langle R_{\Delta}^{\text {bas }}\left(a_{1}, a_{2}\right) u_{1}, u_{2}\right\rangle$ can be written

$$
\begin{aligned}
0= & -\left\langle\Delta_{u_{1}}\left[a_{1}, a_{2}\right]-\mathbf{d}\left\langle\alpha_{1},\left[a_{1}, a_{2}\right]\right\rangle, u_{2}\right\rangle \\
& +\rho\left(a_{1}\right)\left\langle\Delta_{u_{1}} a_{2}-\mathbf{d}\left\langle\alpha_{1}, a_{2}\right\rangle, u_{2}\right\rangle-\left\langle\Delta_{u_{1}} a_{2}-\mathbf{d}\left\langle\alpha_{1}, a_{2}\right\rangle, £_{a_{1}} u_{2}\right\rangle \\
& -\rho\left(a_{2}\right)\left\langle\Delta_{u_{1}} a_{1}-\mathbf{d}\left\langle\alpha_{1}, a_{1}\right\rangle, u_{2}\right\rangle+\left\langle\Delta_{u_{1}} a_{1}-\mathbf{d}\left\langle\alpha_{1}, a_{1}\right\rangle, £_{a_{2}} u_{2}\right\rangle \\
& +\left\langle\Delta_{\left.\left(\rho, \rho^{t}\right) \Omega_{u_{1}} a_{2}+£_{a_{2} u_{1}} a_{1}-\mathbf{d}\left\langle\left(\rho, \rho^{t}\right) \Omega_{u_{1}} a_{2}+£_{a_{2}} u_{1}, a_{1}\right\rangle, u_{2}\right\rangle}\right. \\
& -\left\langle\Delta_{\left.\left(\rho, \rho^{t}\right) \Omega_{u_{1}} a_{1}+£_{a_{1} u_{1}} a_{2}-\mathbf{d}\left\langle\left(\rho, \rho^{t}\right) \Omega_{u_{1}} a_{1}+£_{a_{1}} u_{1}, a_{2}\right\rangle, u_{2}\right\rangle}\right.
\end{aligned}
$$

$$
\begin{aligned}
= & -\left\langle\Delta_{u_{1}}\left[a_{1}, a_{2}\right], u_{2}\right\rangle+X_{2}\left\langle\alpha_{1},\left[a_{1}, a_{2}\right]\right\rangle \\
& +\rho\left(a_{1}\right)\left\langle\Delta_{u_{1}} a_{2}, u_{2}\right\rangle-\rho\left(a_{1}\right) X_{2}\left\langle\alpha_{1}, a_{2}\right\rangle \\
& -\left\langle\Delta_{u_{1}} a_{2}, £_{a_{1}} u_{2}\right\rangle+\left[\rho\left(a_{1}\right), X_{2}\right]\left\langle\alpha_{1}, a_{2}\right\rangle \\
& -\rho\left(a_{2}\right)\left\langle\Delta_{u_{1}} a_{1}, u_{2}\right\rangle+\rho\left(a_{2}\right) X_{2}\left\langle\alpha_{1}, a_{1}\right\rangle \\
& +\left\langle\Delta_{u_{1}} a_{1}, £_{a_{2}} u_{2}\right\rangle-\left[\rho\left(a_{2}\right), X_{2}\right]\left\langle\alpha_{1}, a_{1}\right\rangle \\
& +\left\langle\Delta_{\left(\rho, \rho^{t}\right) \Omega_{u_{1}} a_{2}} a_{1}, u_{2}\right\rangle+\left[\rho\left(a_{2}\right), X_{1}\right]\left\langle a_{1}, \alpha_{2}\right\rangle-\left\langle a_{1}, \llbracket £_{a_{2}} u_{1}, u_{2} \rrbracket \Delta\right\rangle \\
& -X_{2}\left\langle\left(\rho, \rho^{\prime}\right) \Omega_{u_{1}} a_{2}+£_{a_{2}} u_{1}, a_{1}\right\rangle \\
& -\left\langle\Delta_{\left.\left(\rho, \rho^{t}\right) \Omega_{u_{1}} a_{1} a_{2}, u_{2}\right\rangle-\left[\rho\left(a_{1}\right), X_{1}\right]\left\langle a_{2}, \alpha_{2}\right\rangle+\left\langle a_{2}, \llbracket £_{a_{1}} u_{1}, u_{2} \rrbracket_{\Delta}\right\rangle}\right. \\
& +X_{2}\left\langle\left(\rho, \rho^{t}\right) \Omega_{u_{1}} a_{1}+£_{a_{1}} u_{1}, a_{2}\right\rangle .
\end{aligned}
$$

We use

$$
\begin{aligned}
& X_{2}\left\langle\alpha_{1},\left[a_{1}, a_{2}\right]\right\rangle+\rho\left(a_{2}\right) X_{2}\left\langle\alpha_{1}, a_{1}\right\rangle-\left[\rho\left(a_{2}\right), X_{2}\right]\left\langle\alpha_{1}, a_{1}\right\rangle-X_{2}\left\langle £_{a_{2}} u_{1}, a_{1}\right\rangle \\
= & X_{2}\left(-\left\langle\alpha_{1},\left[a_{2}, a_{1}\right]\right\rangle+\rho\left(a_{2}\right)\left\langle\alpha_{1}, a_{1}\right\rangle-\left\langle £_{a_{2}} \alpha_{1}, a_{1}\right\rangle\right)=0,
\end{aligned}
$$

similarly

$$
-\rho\left(a_{1}\right) X_{2}\left\langle\alpha_{1}, a_{2}\right\rangle+\left[\rho\left(a_{1}\right), X_{2}\right]\left\langle\alpha_{1}, a_{2}\right\rangle+X_{2}\left\langle £_{a_{1}} u_{1}, a_{2}\right\rangle=-X_{2}\left\langle\alpha_{1},\left[a_{1}, a_{2}\right]\right\rangle
$$

and, by A.2 and (5.1),

$$
\begin{aligned}
& \left\langle\Delta_{\left(\rho, \rho^{t}\right) \Omega_{u_{1}} a_{2}} a_{1}, u_{2}\right\rangle-X_{2}\left\langle\left(\rho, \rho^{t}\right) \Omega_{u_{1}} a_{2}, a_{1}\right\rangle \\
& =\left\langle\nabla_{a_{1}}^{\text {bas }} \Omega_{u_{1}} a_{2}+\left[\Omega_{u_{1}} a_{2}, a_{1}\right]_{d}, u_{2}\right\rangle-X_{2}\left\langle\left(\rho, \rho^{t}\right) \Omega_{u_{1}} a_{2}, a_{1}\right\rangle \\
& =\rho\left(a_{1}\right)\left\langle\Omega_{u_{1}} a_{2}, u_{2}\right\rangle-\left\langle\Omega_{u_{1}} a_{2}, \nabla_{a_{1}}^{\mathrm{bas}} u_{2}\right\rangle \\
& -\left\langle\text { Skew }_{\Delta}\left(u_{2},\left(\rho, \rho^{t}\right) \Omega_{u_{1}} a_{2}\right), a_{1}\right\rangle-\left\langle £_{a_{1}} \Omega_{u_{1}} a_{2}, u_{2}\right\rangle \\
& =-\left\langle\Omega_{u_{1}} a_{2},\left(\rho, \rho^{t}\right) \Omega_{u_{2}} a_{1}\right\rangle-\left\langle\operatorname{Skew}_{\Delta}\left(u_{2},\left(\rho, \rho^{t}\right) \Omega_{u_{1}} a_{2}\right), a_{1}\right\rangle
\end{aligned}
$$

to get

$$
\begin{aligned}
0= & -X_{2}\left\langle\alpha_{1},\left[a_{1}, a_{2}\right]\right\rangle-X_{1}\left\langle\alpha_{2},\left[a_{1}, a_{2}\right]\right\rangle+\left\langle\left[a_{1}, a_{2}\right], \llbracket u_{1}, u_{2} \rrbracket_{\Delta}\right\rangle \\
& -\left\langle a_{1}, \llbracket £_{a_{2}} u_{1}, u_{2} \rrbracket_{\Delta}\right\rangle+\left\langle a_{2}, \llbracket £_{a_{1}} u_{1}, u_{2} \rrbracket_{\Delta}\right\rangle \\
& +\rho\left(a_{1}\right)\left\langle\Delta_{u_{1}} a_{2}, u_{2}\right\rangle-X_{1}\left\langle a_{2}, £_{a_{1}} u_{2}\right\rangle+\left\langle a_{2}, \llbracket u_{1}, £_{a_{1}} u_{2} \rrbracket_{\Delta}\right\rangle \\
& -\rho\left(a_{2}\right)\left\langle\Delta_{u_{1}} a_{1}, u_{2}\right\rangle+X_{1}\left\langle a_{1}, £_{a_{2}} u_{2}\right\rangle-\left\langle a_{1}, \llbracket u_{1}, £_{a_{2}} u_{2} \rrbracket_{\Delta}\right\rangle \\
& +\left[\rho\left(a_{2}\right), X_{1}\right]\left\langle a_{1}, \alpha_{1}\right\rangle-\left[\rho\left(a_{1}\right), X_{1}\right]\left\langle a_{2}, \alpha_{2}\right\rangle \\
& -\left\langle\Omega_{u_{1}} a_{2},\left(\rho, \rho^{t}\right) \Omega_{u_{2}} a_{1}\right\rangle-\left\langle\operatorname{Skew}_{\Delta}\left(u_{2},\left(\rho, \rho^{t}\right) \Omega_{u_{1}} a_{2}\right), a_{1}\right\rangle \\
& +\left\langle\Omega_{u_{1}} a_{1},\left(\rho, \rho^{t}\right) \Omega_{u_{2}} a_{2}\right\rangle+\left\langle\operatorname{Skew}_{\Delta}\left(u_{2},\left(\rho, \rho^{t}\right) \Omega_{u_{1}} a_{1}\right), a_{2}\right\rangle .
\end{aligned}
$$

But since

$$
\begin{aligned}
& \rho\left(a_{1}\right)\left\langle\Delta_{u_{1}} a_{2}, u_{2}\right\rangle-\left[\rho\left(a_{1}\right), X_{1}\right]\left\langle a_{2}, \alpha_{2}\right\rangle-X_{1}\left\langle a_{2}, £_{a_{1}} u_{2}\right\rangle \\
= & -\rho\left(a_{1}\right)\left\langle a_{2}, \llbracket u_{1}, u_{2} \rrbracket_{\Delta}\right\rangle+X_{1}\left\langle\left[a_{1}, a_{2}\right], \alpha_{2}\right\rangle \\
= & -\left\langle\left[a_{1}, a_{2}\right], \llbracket u_{1}, u_{2} \rrbracket \Delta\right\rangle-\left\langle a_{2}, £_{a_{1}} \llbracket u_{1}, u_{2} \rrbracket \Delta\right\rangle+X_{1}\left\langle\left[a_{1}, a_{2}\right], \alpha_{2}\right\rangle,
\end{aligned}
$$

we find

$$
\begin{align*}
0= & -X_{2}\left\langle\alpha_{1},\left[a_{1}, a_{2}\right]\right\rangle+X_{1}\left\langle\alpha_{1},\left[a_{1}, a_{2}\right]\right\rangle-\left\langle\left[a_{1}, a_{2}\right], \llbracket u_{1}, u_{2} \rrbracket_{\Delta}\right\rangle  \tag{A.9}\\
& -\left\langle a_{1}, \llbracket £_{a_{2}} u_{1}, u_{2} \rrbracket_{\Delta}\right\rangle+\left\langle a_{2}, \llbracket £_{a_{1}} u_{1}, u_{2} \rrbracket_{\Delta}\right\rangle+\left\langle a_{2}, \llbracket u_{1}, £_{a_{1}} u_{2} \rrbracket_{\Delta}\right\rangle \\
& -\left\langle a_{1}, \llbracket u_{1}, £_{a_{2}} u_{2} \rrbracket_{\Delta}\right\rangle-\left\langle a_{2}, £_{a_{1}} \llbracket u_{1}, u_{2} \rrbracket_{\Delta}\right\rangle+\left\langle a_{1}, £_{a_{2}} \llbracket u_{1}, u_{2} \rrbracket_{\Delta}\right\rangle \\
& -\left\langle\Omega_{u_{1}} a_{2},\left(\rho, \rho^{t}\right) \Omega_{u_{2}} a_{1}\right\rangle-\left\langle\operatorname{Skew}_{\Delta}\left(u_{2},\left(\rho, \rho^{t}\right) \Omega_{u_{1}} a_{2}\right), a_{1}\right\rangle \\
& +\left\langle\Omega_{u_{1}} a_{1},\left(\rho, \rho^{t}\right) \Omega_{u_{2}} a_{2}\right\rangle+\left\langle\operatorname{Skew}_{\Delta}\left(u_{2},\left(\rho, \rho^{t}\right) \Omega_{u_{1}} a_{1}\right), a_{2}\right\rangle .
\end{align*}
$$

Now, writing $\tau=(a, \theta)$, we compute:

$$
\begin{aligned}
& \nabla_{\tau}^{\mathrm{bas}} \llbracket u_{1}, u_{2} \rrbracket_{\Delta}-\llbracket \nabla_{\tau}^{\mathrm{bas}} u_{1}, u_{2} \rrbracket_{\Delta}-\llbracket u_{1}, \nabla_{\tau}^{\mathrm{bas}} u_{2} \rrbracket_{\Delta}+\nabla_{\Delta_{u_{1}} \tau}^{\mathrm{bas}} u_{2}-\nabla_{\Delta_{u_{2}} \tau}^{\mathrm{bas}} u_{1} \\
&=\left(\rho, \rho^{t}\right) \Omega_{\llbracket u_{1}, u_{2} \rrbracket_{\Delta}} a+£_{a} \llbracket u_{1}, u_{2} \rrbracket_{\Delta}-\llbracket\left(\rho, \rho^{t}\right) \Omega_{u_{1}} a+£_{a} u_{1}, u_{2} \rrbracket_{\Delta} \\
&-\llbracket u_{1},\left(\rho, \rho^{t}\right) \Omega_{u_{2}} a+£_{a} u_{2} \rrbracket_{\Delta}+\nabla_{\mathrm{pr}_{A}}^{\mathrm{bas}} \Omega_{u_{1}} a u_{2}-\nabla_{\mathrm{pr}_{A}}^{\mathrm{bas}} \Omega_{u_{2} a} u_{1} \\
& \stackrel{\text { A.3! }}{-}\left(\rho, \rho^{t}\right)\left(\Delta_{\llbracket u_{1}, u_{2} \rrbracket_{\Delta}} a-\mathbf{d}\left\langle a, \llbracket u_{1}, u_{2} \rrbracket_{\Delta}\right\rangle\right)+£_{a} \llbracket u_{1}, u_{2} \rrbracket_{\Delta}-\llbracket £_{a} u_{1}, u_{2} \rrbracket_{\Delta} \\
&-\llbracket u_{1}, £_{a} u_{2} \rrbracket_{\Delta}+\left(\rho, \rho^{t}\right) \Delta_{u_{2}} \Omega_{u_{1}} a-\left\langle\nabla^{\mathrm{bas}} u_{2}, \Omega_{u_{1}} a\right\rangle-\left(\rho, \rho^{t}\right) \Delta_{u_{1}} \Omega_{u_{2}} a \\
&+\left\langle\nabla^{\mathrm{bas}} u_{1}, \Omega_{u_{2}} a\right\rangle-\operatorname{Skew}_{\Delta}\left(\left(\rho, \rho^{t}\right) \Omega_{u_{1}} a, u_{2}\right) \\
&=-\left(\rho, \rho^{t}\right) R_{\Delta}\left(u_{1}, u_{2}\right) a-\rho^{t} \mathbf{d}\left\langle a, \llbracket u_{1}, u_{2} \rrbracket_{\Delta}\right\rangle+£_{a} \llbracket u_{1}, u_{2} \rrbracket_{\Delta}-\llbracket £_{a} u_{1}, u_{2} \rrbracket_{\Delta} \\
&-\llbracket u_{1}, £_{a} u_{2} \rrbracket_{\Delta}-\rho^{t} \mathbf{d}\left(X_{2}\left\langle\alpha_{1}, a\right\rangle\right)-\left\langle\nabla_{\cdot}^{\mathrm{bas}} u_{2}, \Omega_{u_{1}} a\right\rangle+\rho^{t} \mathbf{d}\left(X_{1}\left\langle\alpha_{2}, a\right\rangle\right) \\
&+\left\langle\nabla^{\text {bas }} u_{1}, \Omega_{u_{2}} a\right\rangle-\operatorname{Skew}_{\Delta}\left(\left(\rho, \rho^{t}\right) \Omega_{u_{1}} a, u_{2}\right) .
\end{aligned}
$$

We write the right-hand side of this equation

$$
-\left(\rho, \rho^{t}\right) R_{\Delta}\left(u_{1}, u_{2}\right) a+\tau^{\prime}
$$

with $\tau^{\prime} \in \Gamma\left(T M \oplus A^{*}\right)$. Since

$$
\operatorname{pr}_{T M}\left(£_{a} \llbracket u_{1}, u_{2} \rrbracket_{\Delta}-\llbracket £_{a} u_{1}, u_{2} \rrbracket_{\Delta}-\llbracket u_{1}, £_{a} u_{2} \rrbracket_{\Delta}\right)
$$

is $\left[\rho(a),\left[X_{1}, X_{2}\right]\right]-\left[\left[\rho(a), X_{1}\right], X_{2}\right]-\left[X_{1},\left[\rho(a), X_{2}\right]\right]$, which vanishes, we observe that $\operatorname{pr}_{T M} \tau^{\prime}=0$. Hence, we just have to show that $\left\langle\tau^{\prime}, a^{\prime}\right\rangle=0$ for any
section $a^{\prime} \in \Gamma(A)$. We have

$$
\begin{aligned}
\left\langle\tau^{\prime}, a^{\prime}\right\rangle= & -\rho\left(a^{\prime}\right)\left\langle a, \llbracket u_{1}, u_{2} \rrbracket_{\Delta}\right\rangle+\left\langle £_{a} \llbracket u_{1}, u_{2} \rrbracket_{\Delta}-\llbracket £_{a} u_{1}, u_{2} \rrbracket_{\Delta}\right. \\
& \left.-\llbracket u_{1}, £_{a} u_{2} \rrbracket_{\Delta}, a^{\prime}\right\rangle-\rho\left(a^{\prime}\right) X_{2}\left\langle\alpha_{1}, a\right\rangle-\left\langle\nabla_{a^{\prime}}^{\mathrm{bas}} u_{2}, \Omega_{u_{1}} a\right\rangle \\
& +\rho\left(a^{\prime}\right) X_{1}\left\langle\alpha_{2}, a\right\rangle+\left\langle\nabla_{a^{\prime}}^{\mathrm{bas}} u_{1}, \Omega_{u_{2}} a\right\rangle \\
& -\left\langle\operatorname{Skew}_{\Delta}\left(\left(\rho, \rho^{t}\right) \Omega_{u_{1}} a, u_{2}\right), a^{\prime}\right\rangle \\
= & \left\langle\left[a, a^{\prime}\right], \llbracket u_{1}, u_{2} \rrbracket_{\Delta}\right\rangle-\left\langle a, £_{a^{\prime}} \llbracket u_{1}, u_{2} \rrbracket_{\Delta}\right\rangle \\
& +\left\langle £_{a} \llbracket u_{1}, u_{2} \rrbracket_{\Delta}-\llbracket £_{a} u_{1}, u_{2} \rrbracket_{\Delta}-\llbracket u_{1}, £_{a} u_{2} \rrbracket_{\Delta}, a^{\prime}\right\rangle \\
& -\rho\left(a^{\prime}\right) X_{2}\left\langle\alpha_{1}, a\right\rangle-\left\langle\left(\rho, \rho^{t}\right) \Omega_{u_{2}} a^{\prime}+£_{a^{\prime}} u_{2}, \Omega_{u_{1}} a\right\rangle \\
& +\rho\left(a^{\prime}\right) X_{1}\left\langle\alpha_{2}, a\right\rangle+\left\langle\left(\rho, \rho^{t}\right) \Omega_{u_{1}} a^{\prime}+£_{a^{\prime}} u_{1}, \Omega_{u_{2}} a\right\rangle \\
& -\left\langle\operatorname{Skew}_{\Delta}\left(\left(\rho, \rho^{t}\right) \Omega_{u_{1}} a, u_{2}\right), a^{\prime}\right\rangle .
\end{aligned}
$$

Since the definition of $\Omega$ and the duality of $\Delta$ and $\llbracket \cdot, \cdot \rrbracket_{\Delta}$ yield

$$
\begin{aligned}
& \left\langle £_{a^{\prime}} u_{1}, \Omega_{u_{2}} a\right\rangle+\rho\left(a^{\prime}\right) X_{1}\left\langle\alpha_{2}, a\right\rangle \\
= & \left\langle £_{a^{\prime}} u_{1}, \Delta_{u_{2}} a\right\rangle+X_{1} \rho\left(a^{\prime}\right)\left\langle\alpha_{2}, a\right\rangle \\
= & X_{2}\left\langle £_{a^{\prime}} u_{1}, a\right\rangle-\left\langle\llbracket u_{2}, £_{a^{\prime}} u_{1} \rrbracket_{\Delta}, a\right\rangle+X_{1} \rho\left(a^{\prime}\right)\left\langle\alpha_{2}, a\right\rangle,
\end{aligned}
$$

we get

$$
\begin{aligned}
\left\langle\tau^{\prime}, a^{\prime}\right\rangle= & \left\langle\left[a, a^{\prime}\right], \llbracket u_{1}, u_{2} \rrbracket_{\Delta}\right\rangle-\left\langle a, £_{a^{\prime}} \llbracket u_{1}, u_{2} \rrbracket_{\Delta}\right\rangle \\
& +\left\langle £_{a} \llbracket u_{1}, u_{2} \rrbracket_{\Delta}-\llbracket £_{a} u_{1}, u_{2} \rrbracket_{\Delta}-\llbracket u_{1}, £_{a} u_{2} \rrbracket_{\Delta}, a^{\prime}\right\rangle \\
& +\left\langle\left(\rho, \rho^{t}\right) \Omega_{u_{1}} a^{\prime}, \Omega_{u_{2}} a\right\rangle-\left\langle\left(\rho, \rho^{t}\right) \Omega_{u_{2}} a^{\prime}, \Omega_{u_{1}} a\right\rangle \\
& -\left\langle\operatorname{Skew}_{\Delta}\left(\left(\rho, \rho^{t}\right) \Omega_{u_{1}} a, u_{2}\right), a^{\prime}\right\rangle \\
& -X_{1}\left\langle £_{a^{\prime}} \alpha_{2}, a\right\rangle+\left\langle\llbracket u_{1}, £_{a^{\prime}} u_{2} \rrbracket_{\Delta}, a\right\rangle-X_{2} \rho\left(a^{\prime}\right)\left\langle\alpha_{1}, a\right\rangle \\
& +X_{2}\left\langle £_{a^{\prime}} \alpha_{1}, a\right\rangle-\left\langle\llbracket u_{2}, £_{a^{\prime}} u_{1} \rrbracket_{\Delta}, a\right\rangle+X_{1} \rho\left(a^{\prime}\right)\left\langle\alpha_{2}, a\right\rangle \\
= & \left\langle\left[a, a^{\prime}\right], \llbracket u_{1}, u_{2} \rrbracket_{\Delta}\right\rangle-\left\langle a, £_{a^{\prime}} \llbracket u_{1}, u_{2} \rrbracket_{\Delta}-\llbracket u_{1}, £_{a^{\prime}} u_{2} \rrbracket_{\Delta}+\llbracket u_{2}, £_{a^{\prime}} u_{1} \rrbracket_{\Delta}\right\rangle \\
& +\left\langle £_{a} \llbracket u_{1}, u_{2} \rrbracket_{\Delta}-\llbracket £_{a} u_{1}, u_{2} \rrbracket_{\Delta}-\llbracket u_{1}, £_{a} u_{2} \rrbracket_{\Delta}, a^{\prime}\right\rangle \\
& +\left\langle\left(\rho, \rho^{t}\right) \Omega_{u_{1}} a^{\prime}, \Omega_{u_{2}} a\right\rangle-\left\langle\left(\rho, \rho^{t}\right) \Omega_{u_{2}} a^{\prime}, \Omega_{u_{1}} a\right\rangle \\
& -\left\langle\operatorname{Skew}_{\Delta}\left(\left(\rho, \rho^{t}\right) \Omega_{u_{1}} a, u_{2}\right), a^{\prime}\right\rangle-X_{1}\left\langle\alpha_{2},\left[a, a^{\prime}\right]\right\rangle+X_{2}\left\langle\alpha_{1},\left[a, a^{\prime}\right]\right\rangle .
\end{aligned}
$$

We have

$$
-\left\langle a, \llbracket u_{2}, £_{a^{\prime}} u_{1} \rrbracket_{\Delta}\right\rangle=\left\langle a, \llbracket £_{a^{\prime}} u_{1}, u_{2} \rrbracket_{\Delta}\right\rangle-\left\langle\operatorname{Skew}_{\Delta}\left(£_{a^{\prime}} u_{1}, u_{2}\right), a\right\rangle
$$

and since $\nabla_{a^{\prime}}^{\mathrm{bas}} u_{1} \in \Gamma(U)$ by hypothesis, we find

$$
\begin{aligned}
-\operatorname{Skew}_{\Delta}\left(£_{a^{\prime}} u_{1}, u_{2}\right) & =-\operatorname{Skew}_{\Delta}\left(£_{a^{\prime}} u_{1}-\nabla_{a^{\prime}}^{\mathrm{bas}} u_{1}, u_{2}\right) \\
& =\operatorname{Skew}_{\Delta}\left(\left(\rho, \rho^{t}\right) \Omega_{u_{1}} a^{\prime}, u_{2}\right)
\end{aligned}
$$

This shows that $\left\langle\tau^{\prime}, a^{\prime}\right\rangle$ is equal to the right-hand side of A.9) (with $a=a_{1}$, $a^{\prime}=a_{2}$ ), which vanishes.

For the second equation we write $u=(X, \alpha)$ and $\tau_{i}=\left(a_{i}, \theta_{i}\right)$ for $i=1,2$ :

$$
\begin{aligned}
& \Delta_{u}\left[\tau_{1}, \tau_{2}\right]_{d}-\left[\Delta_{u} \tau_{1}, \tau_{2}\right]_{d}-\left[\tau_{1}, \Delta_{u} \tau_{2}\right]_{d} \\
& +\Delta_{\nabla_{a_{1}}^{\text {bas }} u} \tau_{2}-\Delta_{\nabla_{a_{2}}^{\text {bas }} u} \tau_{1}+\left(0, \mathbf{d}\left\langle\tau_{1}, \nabla_{a_{2}}^{\text {bas }} u\right\rangle\right) \\
= & \Omega_{u}\left[a_{1}, a_{2}\right]+\left(0, £_{X}\left(£_{\rho\left(a_{1}\right)} \theta_{2}-\mathbf{i}_{\rho\left(a_{2}\right)} \mathbf{d} \theta_{1}\right)+\mathbf{d}\left\langle\alpha,\left[a_{1}, a_{2}\right]\right\rangle\right) \\
& -\left[\Omega_{u} a_{1}+\left(0, £_{X} \theta_{1}+\mathbf{d}\left\langle\alpha, a_{1}\right\rangle\right), \tau_{2}\right]_{d} \\
& -\left[\tau_{1}, \Omega_{u} a_{2}+\left(0, £_{X} \theta_{2}+\mathbf{d}\left\langle\alpha, a_{2}\right\rangle\right)\right]_{d} \\
& +\Omega_{\nabla_{a_{1}} \text { bas } u} a_{2}+\left(0, £_{\operatorname{pr}_{T M}\left(\nabla_{a_{1}}^{\text {bas }} u\right)} \theta_{2}+\mathbf{d}\left\langle\nabla_{a_{1}}^{\text {bas }} u,\left(a_{2}, 0\right)\right\rangle\right) \\
& -\Omega_{\nabla_{a_{2}}^{\text {bas }} u} a_{1}-\left(0, £_{\operatorname{pr}_{T M}\left(\nabla_{a_{2}}^{\text {bas }} u\right)} \theta_{1}+\mathbf{d}\left\langle\nabla_{a_{2}}^{\text {bas }} u,\left(a_{1}, 0\right)\right\rangle\right)+\left(0, \mathbf{d}\left\langle\tau_{1}, \nabla_{a_{2}}^{\text {bas }} u\right\rangle\right) \\
= & -R_{\Delta}^{\text {bas }}\left(a_{1}, a_{2}\right) u+\left(0, £_{X}\left(£_{\rho\left(a_{1}\right)} \theta_{2}-\mathbf{i}_{\rho\left(a_{2}\right)} \mathbf{d} \theta_{1}\right)+\mathbf{d}\left\langle\alpha,\left[a_{1}, a_{2}\right]\right\rangle\right) \\
& +\left(0, \mathbf{i}_{\rho\left(a_{2}\right)} \mathbf{d} £_{X} \theta_{1}-£_{\rho o \mathrm{pr}_{A}} \Omega_{u} a_{1} \theta_{2}-\mathbf{d}\left\langle\left(\rho, \rho^{t}\right) \Omega_{u} a_{1},\left(a_{2}, 0\right)\right\rangle\right) \\
& -\left(0, £_{\rho\left(a_{1}\right)} £_{X} \theta_{2}+£_{\rho\left(a_{1}\right)} \mathbf{d}\left\langle\alpha, a_{2}\right\rangle+\mathbf{i}_{\rho \rho \mathrm{pr}_{A}} \Omega_{u} a_{2} \mathbf{d} \theta_{1}\right) \\
& +\left(0, £_{\operatorname{pr}_{T M}\left(\nabla_{a_{1}}^{\text {bas }} u\right)} \theta_{2}+\mathbf{d}\left\langle\nabla_{a_{1}}^{\text {bas }} u,\left(a_{2}, 0\right)\right\rangle\right) \\
& -\left(0, £_{\operatorname{pr}_{T M}\left(\nabla_{a_{2}}^{\text {bas }} u\right)} \theta_{1}+\mathbf{d}\left\langle\nabla_{a_{2}}^{\text {bas }} u,\left(a_{1}, 0\right)\right\rangle\right)+\left(0, \mathbf{d}\left\langle\tau_{1}, \nabla_{a_{2}}^{\text {bas }} u\right\rangle\right) .
\end{aligned}
$$

But we have

$$
\begin{aligned}
& £_{X} £_{\rho\left(a_{1}\right)} \theta_{2}-£_{\rho \circ \operatorname{pr}_{A} \Omega_{u} a_{1}} \theta_{2}-£_{\rho\left(a_{1}\right)} £_{X} \theta_{2}+£_{\mathrm{pr}_{T M}\left(\nabla_{a_{1}}^{\text {bas }} u\right)} \theta_{2} \\
= & £_{\left[X, \rho\left(a_{1}\right)\right]-\rho \operatorname{pr}_{A} \Omega_{u} a_{1}+\operatorname{pr}_{T M}\left(\nabla_{a_{1}}^{\text {bas } u}\right)} \theta_{2}=0
\end{aligned}
$$

since $\operatorname{pr}_{T M}\left(\nabla_{a_{1}}^{\text {bas }} u\right)=\left[\rho\left(a_{1}\right), X\right]+\rho \circ \operatorname{pr}_{A} \Omega_{u} a_{1}$, and in the same manner

$$
\begin{aligned}
& -£_{X} \mathbf{i}_{\rho\left(a_{2}\right)} \mathbf{d} \theta_{1}+\mathbf{i}_{\rho\left(a_{2}\right)} \mathbf{d} £_{X} \theta_{1}+\mathbf{i}_{\rho \circ \mathrm{pr}_{A}} \Omega_{u} a_{2} \mathbf{d} \theta_{1}-£_{\mathrm{pr}_{T M}\left(\nabla_{a_{2}}^{\text {bas }} u\right)} \theta_{1} \\
& +\mathbf{d}\left\langle\nabla_{a_{2}}^{\text {bas }} u,\left(a_{1}, 0\right)\right\rangle-\mathbf{d}\left\langle\tau_{1}, \nabla_{a_{2}}^{\text {bas }} u\right\rangle \\
= & \mathbf{i}_{\left[\rho\left(a_{2}\right), X\right]+\rho \mathrm{opr}_{A} \Omega_{u} a_{2}} \mathbf{d} \theta_{1}-£_{\operatorname{pr}_{T M}\left(\nabla_{a_{2}}^{\text {bas }} u\right)} \theta_{1}-\mathbf{d}\left\langle\left(0, \theta_{1}\right), \nabla_{a_{2}}^{\mathrm{bas}} u\right\rangle=0 .
\end{aligned}
$$

Since

$$
-\left\langle\left(\rho, \rho^{t}\right) \Omega_{u} a_{1},\left(a_{2}, 0\right)\right\rangle+\left\langle\nabla_{a_{1}}^{\mathrm{bas}} u,\left(a_{2}, 0\right)\right\rangle=\left\langle £_{a_{1}} u,\left(a_{2}, 0\right)\right\rangle=\left\langle £_{a_{1}} \alpha, a_{2}\right\rangle
$$

and

$$
£_{\rho\left(a_{1}\right)} \mathbf{d}\left\langle\alpha, a_{2}\right\rangle=\mathbf{d}\left(\rho\left(a_{1}\right)\left\langle\alpha, a_{2}\right\rangle\right)=\mathbf{d}\left(\left\langle £_{a_{1}} \alpha, a_{2}\right\rangle+\left\langle\alpha,\left[a_{1}, a_{2}\right]\right\rangle\right),
$$

the remaining sum

$$
\mathbf{d}\left\langle\alpha,\left[a_{1}, a_{2}\right]\right\rangle-\mathbf{d}\left\langle\left(\rho, \rho^{t}\right) \Omega_{u} a_{1},\left(a_{2}, 0\right)\right\rangle-£_{\rho\left(a_{1}\right)} \mathbf{d}\left\langle\alpha, a_{2}\right\rangle+\mathbf{d}\left\langle\nabla_{a_{1}}^{\text {bas }} u,\left(a_{2}, 0\right)\right\rangle
$$

vanishes as well.

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[^0]:    ${ }^{1}$ A Lie bialgebroid $\left(A, A^{*}\right)$ is integrable if $A$ is an integrable Lie algebroid.

[^1]:    ${ }^{2}$ This result extends the classification of Poisson homogeneous spaces of Poisson groupoids ( $G \rightrightarrows M, \pi$ ) via a certain class of Dirac structures in the Courant algebroid $A \oplus A^{*}$ defined by the Lie bialgebroid $\left(A, A^{*}\right)$ of the Poisson groupoid [28.

[^2]:    ${ }^{3}$ If $A$ is a Lie algebroid over $M$, then the vector bundle $A \oplus T^{*} M$ inherits the structure of a degenerate Courant algebroid, see Example 2.2 .

[^3]:    5 "d" stands for degenerate.

[^4]:    ${ }^{6}$ Note that the map $\langle q, \cdot\rangle \cdot \mathbf{d}_{B} f$ can be seen as a section of $\operatorname{Hom}(B, B)$, i.e. as a derivation over $0 \in \mathfrak{X}(M)$.

[^5]:    ${ }^{7}$ Since its flow is a flow of vector bundle morphisms, a linear vector field sends linear functions to linear functions and pullbacks to pullbacks.

[^6]:    ${ }^{8} T M \oplus A^{*}$ is always anchored by $\mathrm{pr}_{T M}$.

[^7]:    ${ }^{10}$ We say by abuse of notation that a section $a \in \Gamma(A)$ is $\nabla$-parallel if its class $\bar{a}$ in $\Gamma(A / J)$ is $\nabla$-parallel.

[^8]:    ${ }^{11}$ Conversely, given $\nabla$, there always exists a connection $\tilde{\nabla}$ projecting in this manner to $\nabla$. We say that $\tilde{\nabla}$ is an extension of $\nabla$.

