# Radiation and asymptotics for spacetimes with non-isotropic mass 

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#### Abstract

We derive new results on radiation, angular momentum at future null infinity and peeling for a general class of spacetimes. For asymptotically-flat solutions of the Einstein vacuum equations with a term homogeneous of degree -1 in the initial data metric, that is it may include a non-isotropic mass term, we prove new detailed behavior of the radiation field and curvature components at future null infinity. In particular, the limit along the null hypersurface $C_{u}$ as $t \rightarrow \infty$ of the curvature component $\rho=\frac{1}{4} R_{3434}$ multiplied with $r^{3}$ tends to a function $P(u, \theta, \phi)$ on $\mathbb{R} \times S^{2}$. When taking the limit $u \rightarrow+\infty$ (which corresponds to the limit at spacelike infinity), this function tends to a function $P^{+}(\theta, \phi)$ on $S^{2}$. We prove that the latter limit does not have any $l=1$ modes. However, it has all the other modes, $l=0, l \geq 2$. Important derivatives of crucial curvature components do not decay in $u$, which is a special feature of these more general spacetimes. We show that peeling of the Weyl curvature components at future null infinity stops at the order $r^{-3}$, that is $r^{-4}|u|^{+1}$, for large data, and at order $r^{-\frac{7}{2}}$ for small data. Despite this fact, we prove that angular momentum at future null infinity is well defined for these spacetimes, due to the good behavior of the $l=1$ modes involved.


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It has been a great pleasure and honor to know Demetrios Christodoulou for over 20 years as a wonderful friend and advisor. When Demetrios arrived at ETH Zurich as a Professor in Mathematics and Physics, I started taking his classes and eventually wrote my Ph.D. thesis under his supervision. It has been a privilege to work with Demetrios. Many times throughout these years, I have witnessed how he solved tough and important problems, putting to work in a most creative way his intuition and deep knowledge of mathematics as well as physics combined with an admirable endurance. Yet one of the most inspiring aspects for me has always been Demetrios' joy in working on these questions,
his enthusiasm for mathematics and physics, and sharing all these with his students and colleagues. Christodoulou has pioneered various fields in mathematics and physics, plowing through formerly impenetrable problems, thereby opening up the doors for generations of mathematicians and physicists to work on new questions. Among his breakthrough results we find "The Formation of Black Holes in General Relativity" [10], "The global nonlinear stability of the Minkowski space" [13] together with S. Klainerman, "Nonlinear Nature of Gravitation and Gravitational-Wave Experiments" [8], "The Formation of Shocks in 3-Dimensional Fluids" [11], or the "The Shock Development Problem" [12]. Demetrios has successfully applied geometric analysis to problems in general relativity, the Euler equations and other nonlinear partial differential equations governing nature. He has developed new geometric-analytic methods to answer important questions in these fields. Christodoulou has inspired many students as well as colleagues in research. He has always had time for students and colleagues, enjoying scientific discussions. Personally, I have learned an enormous amount from Demetrios. I have always enjoyed very much our scientific discussions, but also topics about history, society and life. Demetrios' knowledge extends to a broad spectrum outside his research areas. I would like to thank Demetrios for many delightful conversations, and for being a great advisor and friend.

## 1. Introduction

In this article, we derive results on the radiation field and asymptotics for asymptotically-flat systems containing a non-isotropic mass term that evolves with retarded time $u$. Whereas we focus on solutions of the Einstein vacuum equations, the main findings will hold as well for systems of the Einstein equations coupled to other matter or energy fields. As a major consequence, it follows that for physical systems, peeling of the Weyl curvature components at future null infinity stops at the order $r^{-3}$, that is $r^{-4}|u|^{+1}$. This goes beyond the terms $r^{-4} \log r$ derived by Demetrios Christodoulou in the case treated in [9], and extends the latter scenario to more general settings. Thus, for these dynamical situations (dependence on $u$ ) there is a natural "barrier" for peeling that does not change even if one imposes stronger fall-off conditions on the tail of the initial metric and the second fundamental form. Moreover, we show that angular momentum at null infinity is well-defined despite the aforementioned properties.

We consider spacetimes $(M, g)$, which solve the Einstein vacuum (EV) equations

$$
\begin{equation*}
R_{\mu \nu}=0 \tag{1}
\end{equation*}
$$

with $\mu, \nu=0,1,2,3$, for asymptotically flat initial data $\left(H_{0}, \bar{g}_{i j}, k_{i j}\right)$ with $i, j=1,2,3$, where $\bar{g}$ and $k$ are sufficiently smooth and for which there exists a coordinate system $\left(x^{1}, x^{2}, x^{3}\right)$ in a neighborhood of infinity such that with $r=\left(\sum_{i=1}^{3}\left(x^{i}\right)^{2}\right)^{\frac{1}{2}} \rightarrow \infty$, it is, referring to this type of initial data and the corresponding spacetimes as (A):

$$
\begin{align*}
\bar{g}_{i j} & =\delta_{i j}+h_{i j}+o_{3}\left(r^{-\frac{3}{2}}\right)  \tag{2}\\
k_{i j} & =o_{2}\left(r^{-\frac{5}{2}}\right) \tag{3}
\end{align*}
$$

with $h_{i j}$ being homogeneous of degree -1 . In particular, $h$ may include a nonisotropic mass term $M(\theta, \phi)$ depending on the angles. The spacetime metric will include a resulting term, being homogeneous of degree -1 with corresponding limit $M(u, \theta, \phi)$ at future null infinity depending on the retarded time $u$.

In their pioneering result [13], Demetrios Christodoulou and Sergiu Klainerman proved the global nonlinear stability of Minkowski space using initial data of the following type, referring to this type of initial data and the corresponding spacetimes as (CK):

$$
\begin{align*}
& \bar{g}_{i j}=\left(1+\frac{2 M}{r}\right) \delta_{i j}+o_{4}\left(r^{-\frac{3}{2}}\right)  \tag{4}\\
& k_{i j}=o_{3}\left(r^{-\frac{5}{2}}\right) \tag{5}
\end{align*}
$$

where $M$ denotes the mass and is constant.
The most general spacetimes that have been shown to be stable by the present author in [1, 2] have initial data of the following type, referring to this type of initial data and the corresponding spacetimes as (B):

$$
\begin{align*}
\bar{g}_{i j} & =\delta_{i j}+o_{3}\left(r^{-\frac{1}{2}}\right)  \tag{6}\\
k_{i j} & =o_{2}\left(r^{-\frac{3}{2}}\right) \tag{7}
\end{align*}
$$

Notation: By $u$ we denote the optical function introduced in section 2 corresponding to minus the retarded time in Minkowski spacetime, and by $\underline{u}$ the corresponding advanced time. We refer to $u$ just as the retarded time with this sign convention.

### 1.0.1. New results

Small data: Under smallness assumptions on the initial data related to $((2),(3))$ we prove [6] estimates for the solution spacetimes (A) via the route of a stability proof that lies between (B) in [1, 2] and (CK) in [13]. Note that
the results $[1,2]$ imply the existence of solutions of type (A), but we need to make use of the extra structures in ((2), (3)) to prove precise estimates for (A), which is done in [6].

Large data: For large data and situation (A), the main estimates along null hypersurfaces still hold and we derive precise asymptotics.

Non-zero linear momentum and contribution of $\rho$ to gravitational wave memory: First, for the initial data we can choose a center-ofmass frame where the linear momentum is zero. Under the smallness assumptions, where the resulting spacetime tends to Minkowski spacetime at infinity, one has trivially zero linear momentum. When we consider large data, we can still start with a center-of-mass frame, and we may consider also a center-of-mass frame in the future, but these frames will typically have a non-zero relative velocity. We find that (A) spacetimes naturally exhibit non-zero linear momentum. In particular, we can state the conservation law for linear momentum which takes into account the linear momentum radiated away. We also compute a contribution from corresponding $\rho$ limits at future null infinity $\mathcal{I}^{+}$to the memory effect.

Main Results of the present article: For (A) spacetimes the following hold:

- Peeling of the Weyl curvature components at future null infinity stops at the order $r^{-3}$, that is $r^{-4}|u|^{+1}$ for large data. For small data, this limit is of the dynamical order $r^{-\frac{7}{2}}$, meaning that the leading order term depends on $u$. These orders are achieved by the curvature component $\beta$ for large, respectively small data.
- Dynamical behavior with different properties: Referring to the notation introduced in the next section 2, we find different behavior and fall-off properties at various levels, in particular, at future null infinity and spacelike infinity. We also derive different behavior of crucial curvature components and their derivatives. These include:
- The limit $\lim _{C_{u}, t \rightarrow \infty} r^{3} \rho=P(u, \theta, \phi)$ tends to a function $P^{+}(\theta, \phi)$ on $S^{2}$ when the retarded time $u \rightarrow+\infty$. In (CK) the corresponding limit is a constant (see section 3.2). (Note that we use the opposite sign convention for retarded time. Thus, $u \rightarrow+\infty$ corresponds to the limit at spacelike infinity, $u \rightarrow-\infty$ to the limit at future timelike infinity.)
- $\rho-\bar{\rho}$, respectively $P-\bar{P}$, does not decay in retarded time $u$. (Here, $\bar{\rho}$ means the mean value of $\rho$ on $S_{t, u}$, and $\bar{P}$ the mean value of $P$ on $S^{2}$.)
- Limits: Denote by $P_{H_{0}}(\theta, \phi)$ the limit of $r^{3} \rho$ at spacelike infinity. The following limits obey

$$
P_{H_{0}}(\theta, \phi) \neq P^{+}(\theta, \phi) \quad \text { in general }
$$

however,

$$
\int_{S^{2}} P_{H_{0}}(\theta, \phi)=\int_{S^{2}} P^{+}(\theta, \phi)
$$

- $\mathbf{P}_{\mathbf{H}_{\mathbf{0}}}(\theta, \phi)$, respectively $\mathbf{P}^{+}(\theta, \phi)$, do not have any $l=1$ modes.
- Energy and momenta at future null infinity are well-defined. In particular, angular momentum can be defined and is finite despite the slow decay for $\beta$ and its derivatives. The reason is that $P^{+}(\theta, \phi)$ does not have any $l=1$ modes, and that the $l=1$ modes of the involved quantities behave better than these quantities themselves. A formula in the direction of a conservation law of angular momentum is derived.

Further, we find that (see section 3 of present article and [6])

- We find that $\nabla \rho=O\left(r^{-4}\right)$ in (A), whereas in (CK) it is $\nabla \rho=$ $O\left(r^{-4} \tau_{-}^{-\frac{1}{2}}\right)$.
- $\underline{\beta}_{4}=O\left(r^{-4}\right)$ in (A) while $\underline{\beta}_{4}=O\left(r^{-4} \tau_{-}^{-\frac{1}{2}}\right)$ in (CK), and for (A) we have $\beta_{3}=O\left(r^{-4}\right)$ while for $(\mathrm{CK}) \beta_{3}=O\left(r^{-4} \tau_{-}^{-\frac{1}{2}}\right)$. Note that the "rougher energy estimates" together with the Bianchi equations would only give $\not \nabla \rho=O\left(r^{-3} \tau_{-}^{-\frac{3}{2}}\right), \beta_{4}=O\left(r^{-3} \tau_{-}^{-\frac{3}{2}}\right)$, $\beta_{3}=O\left(r^{-3} \tau_{-}^{-\frac{3}{2}}\right)$. A discussion of the energy estimates is given in section 3.4.


## 2. Setting

Next, we shall introduce the main foliations and the frames that we work with. Denote by $t$ a maximal time function foliating the spacetime into spacelike hypersurfaces $H_{t}$. In this framework, the zero-coordinate will be the timecoordinate, and indices $1,2,3$ refer to spatial coordinates. Denote by $u$ the optical function (retarded time with the sign convention above) and by $C_{u}$ the outgoing null hypersurfaces of the $u$-foliation. We denote the corresponding intersection by $S_{t, u}=H_{t} \cap C_{u}$. The $S_{t, u}$ are diffeomorphic to the sphere $S^{2}$ and we refer to $\theta, \phi$ given on $S_{t, u}$ as the spherical variables. In particular, the optical function $u$ solves the eikonal equation $g^{\alpha \beta} \frac{\partial u}{\partial x^{\alpha}} \frac{\partial u}{\partial x^{\beta}}=0$. We have $l^{\alpha}=-g^{\alpha \beta} \partial_{\beta} u$, and the integral curves of $l$ are null geodesics. The null hypersurfaces $C_{u}$ are generated by null geodesic segments. Quantities with an overline refer to $H_{t}$. The covariant differentiation on the spacetime $M$ is

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written as $D$ or $\nabla$, and the one on a spacelike hypersurface $H$ is $\bar{\nabla}$ or $\nabla$. It is clear from the context what $\nabla$ refers to. Now, we introduce $\underline{u}:=2 r-u$ with $r=r(t, u)$ being defined by $4 \pi r^{2}$ expressing the surface area of $S_{t, u}$. Define $\tau_{-}:=\sqrt{1+u^{2}}$, and $\tau_{+}:=\sqrt{1+\underline{u}^{2}}$.

We also work with the null frame $e_{4}, e_{3}, e_{2}, e_{1}$, where $e_{4}$ (outgoing null direction) and $e_{3}$ (ingoing null direction) form a null pair that is supplemented by $e_{A}, A=1,2$ being a local frame field for $S_{t, u}=H_{t} \cap C_{u}$. We have $g\left(e_{4}, e_{3}\right)=-2$. Given this null pair, $e_{3}$ and $e_{4}$, we can define the tensor of projection from the tangent space of $M$ to that of $S_{t, u}$

$$
\Pi^{\mu \nu}=g^{\mu \nu}+\frac{1}{2}\left(e_{4}^{\nu} e_{3}^{\mu}+e_{3}^{\nu} e_{4}^{\mu}\right)
$$

Denote by $N$ the outward unit normal vector of $S_{t, u}$ in $H_{t}$ and by $T$ the futuredirected unit normal to $H_{t}$, that is $T=\frac{1}{\Phi} \frac{\partial}{\partial t}$, where $\Phi$ is the lapse function. Then we see that $e_{3}=T-N$ is an incoming null vectorfield, and $e_{4}=T+N$ an outgoing null vectorfield. We make use of the expression $N=a^{-1} \frac{\partial}{\partial u}$ with lapse $a=|\nabla u|^{-1}$. Operators on the surfaces $S_{t, u}$ are written with a slash, thus di/v, cشrl are the corresponding divergence and curl operators, respectively. For a $p$-covariant tensor field $t$ that is tangent to $S$ we denote by $D_{4} t$ and $\not D_{3} t$ the projections to $S$ of $D_{4} t$, respectively $D_{3} t$.

Next, we define the components of the Weyl curvature with respect to the null foliation.

Definition 1. We define the null components of the Weyl curvature $W$ as follows:

$$
\begin{align*}
\underline{\alpha}_{\mu \nu}(W) & =\Pi_{\mu}^{\rho} \Pi_{\nu}^{\sigma} W_{\rho \gamma \sigma \delta} e_{3}^{\gamma} e_{3}^{\delta}  \tag{8}\\
\underline{\beta}_{\mu}(W) & =\frac{1}{2} \Pi_{\mu}{ }^{\rho} W_{\rho \sigma \gamma \delta} e_{3}^{\sigma} e_{3}^{\gamma} e_{4}^{\delta}  \tag{9}\\
\rho(W) & =\frac{1}{4} W_{\alpha \beta \gamma \delta} e_{3}^{\alpha} e_{4}^{\beta} e_{3}^{\gamma} e_{4}^{\delta}  \tag{10}\\
\sigma(W) & =\frac{1}{4}{ }^{*} W_{\alpha \beta \gamma \delta} e_{3}^{\alpha} e_{4}^{\beta} e_{3}^{\gamma} e_{4}^{\delta}  \tag{11}\\
\beta_{\mu}(W) & =\frac{1}{2} \Pi_{\mu}^{\rho} W_{\rho \sigma \gamma \delta} e_{4}^{\sigma} e_{3}^{\gamma} e_{4}^{\delta}  \tag{12}\\
\alpha_{\mu \nu}(W) & =\Pi_{\mu}^{\rho} \Pi_{\nu}{ }^{\sigma} W_{\rho \gamma \sigma \delta} e_{4}^{\gamma} e_{4}^{\delta} \tag{13}
\end{align*}
$$

Thus, capital indices taking the values 1,2 , we have:

$$
\begin{equation*}
W_{A 3 B 3}=\underline{\alpha}_{A B} \tag{14}
\end{equation*}
$$

$$
\begin{align*}
W_{A 334} & =2 \underline{\beta}  \tag{15}\\
W_{3434} & =4 \rho  \tag{16}\\
{ }^{*} W_{3434} & =4 \sigma  \tag{17}\\
W_{A 434} & =2 \beta_{A}  \tag{18}\\
W_{A 4 B 4} & =\alpha_{A B} \tag{19}
\end{align*}
$$

with
$\alpha, \underline{\alpha}: \quad S$-tangent, symmetric, traceless tensors
$\beta, \underline{\beta}: \quad S$-tangent 1-forms
$\rho, \sigma$ : scalars .
The Weyl tensor $W_{\alpha \beta \gamma \delta}$ is decomposed into its electric and magnetic parts, which are defined by

$$
\begin{array}{r}
E_{a b}:=W_{a T b T} \\
H_{a b}:=\frac{1}{2} \epsilon^{e f}{ }_{a} W_{e f b T} \tag{21}
\end{array}
$$

Here $\epsilon_{a b c}$ is the spatial volume element and is related to the spacetime volume element by $\epsilon_{a b c}=\epsilon_{T a b c}$.

In particular, in our notation it is

$$
E_{N N}=\rho \quad, \quad H_{N N}=\sigma
$$

We use a maximal time function. Thus, consider a foliation by a maximal time function (maximal foliation):

Constraint equations for a maximal foliation:

$$
\begin{align*}
t r k & =0  \tag{22}\\
\nabla^{i} k_{i j} & =0  \tag{23}\\
\bar{R} & =|k|^{2} . \tag{24}
\end{align*}
$$

Evolution equations for a maximal foliation:

$$
\begin{align*}
\frac{\partial \bar{g}_{i j}}{\partial t} & =-2 \Phi k_{i j}  \tag{25}\\
\frac{\partial k_{i j}}{\partial t} & =-\nabla_{i} \nabla_{j} \Phi+\left(\bar{R}_{i j}-2 k_{i m} k_{j}^{m}\right) \Phi \tag{26}
\end{align*}
$$

In view of the maximality condition, taking the trace of the second variation equations (26), yields the lapse equation:

$$
\begin{equation*}
\triangle \Phi=|k|^{2} \Phi \tag{27}
\end{equation*}
$$

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From (3) and (24) it follows that

$$
\begin{equation*}
\bar{R}=|k|^{2}=o\left(r^{-5}\right) \tag{28}
\end{equation*}
$$

The metric (2) would only yield $\bar{R}=O\left(r^{-3}\right)$. Thus the $r^{-3}$ part of $\bar{R}$ has to vanish. This gives an equation for $h_{i j}$, namely

$$
\begin{equation*}
\bar{R}=\frac{1}{2}\left(\partial_{i} \partial_{j} h_{i j}-\partial_{j} \partial_{j} h_{i i}\right)+o\left(|x|^{-\frac{7}{2}}\right) . \tag{29}
\end{equation*}
$$

Thus, the first term on the right hand side of (29) must vanish separately:

$$
\begin{equation*}
\partial_{i} \partial_{j} h_{i j}-\partial_{j} \partial_{j} h_{i i}=0 . \tag{30}
\end{equation*}
$$

Moreover, in our setting, in each spacelike $H_{t}$ of the spacetime $M$ we have the following equations

$$
\begin{align*}
\text { curl } k & =H  \tag{31}\\
\bar{R}_{i j} & =k_{i m} k_{j}^{m}+E_{i j} . \tag{32}
\end{align*}
$$

The detailed equations involving all the components show interesting structures.

## 3. Main results

### 3.1. Spacetime behavior

3.1.1. Curvature In order to put our new results in context, we recall the following two sets of results.

From [1, 2] it follows for spacetimes of type (B)

$$
\begin{align*}
\underline{\alpha} & =O\left(r^{-1} \tau_{-}^{-\frac{3}{2}}\right)  \tag{33}\\
\underline{\beta} & =O\left(r^{-2} \tau_{-}^{-\frac{1}{2}}\right)  \tag{34}\\
\rho, \sigma, \alpha, \beta & =o\left(r^{-\frac{5}{2}}\right) \tag{35}
\end{align*}
$$

From [13] it follows for spacetimes of type (CK)

$$
\begin{align*}
& \underline{\alpha}=O\left(r^{-1} \tau_{-}^{-\frac{5}{2}}\right)  \tag{36}\\
& \underline{\beta}=O\left(r^{-2} \tau_{-}^{-\frac{3}{2}}\right) \tag{37}
\end{align*}
$$

$$
\begin{align*}
\rho & =O\left(r^{-3}\right)  \tag{38}\\
\rho-\bar{\rho} & =O\left(r^{-3} \tau_{-}^{-\frac{1}{2}}\right)  \tag{39}\\
\sigma & =O\left(r^{-3} \tau_{-}^{-\frac{1}{2}}\right)  \tag{40}\\
\sigma-\bar{\sigma} & =O\left(r^{-3} \tau_{-}^{-\frac{1}{2}}\right)  \tag{41}\\
\beta & =o\left(r^{-\frac{7}{2}}\right)  \tag{42}\\
\alpha & =o\left(r^{-\frac{7}{2}}\right) \tag{43}
\end{align*}
$$

We find interesting dynamics in the new situation that are different from the situation (CK) studied in [13]. Namely, in the present situation, it follows that for spacetimes of type (A) it is

$$
\begin{align*}
\underline{\alpha} & =O\left(r^{-1} \tau_{-}^{-\frac{5}{2}}\right)  \tag{44}\\
\underline{\beta} & =O\left(r^{-2} \tau_{-}^{-\frac{3}{2}}\right)  \tag{45}\\
\rho & =O\left(r^{-3}\right)  \tag{46}\\
\rho-\bar{\rho} & =O\left(r^{-3}\right)  \tag{47}\\
\sigma & =O\left(r^{-3} \tau_{-}^{-\frac{1}{2}}\right)  \tag{48}\\
\sigma-\bar{\sigma} & =O\left(r^{-3} \tau_{-}^{-\frac{1}{2}}\right)  \tag{49}\\
\beta & =o\left(r^{-\frac{7}{2}}\right)  \tag{50}\\
\alpha & =o\left(r^{-\frac{7}{2}}\right) \tag{51}
\end{align*}
$$

In particular, we also derive for (A)

$$
\begin{equation*}
\not \nabla \rho=O\left(r^{-4}\right) \tag{52}
\end{equation*}
$$

whereas in [13] for (CK) by Christodoulou and Klainerman it is

$$
\begin{equation*}
\not \nabla \rho=O\left(r^{-4} \tau_{-}^{-\frac{1}{2}}\right) \tag{53}
\end{equation*}
$$

In [9] Christodoulou considered data with slightly stronger decay than in [13], namely the tail of the initial data metric takes an extra $r^{-\frac{1}{2}}$. He then shows that the $\beta$ curvature component takes a logarithmic term, in particular it contains a term of the order $1 /\left(r^{4} \log r\right)$. He then discusses this situation in a physical content. Christodoulou finds that

$$
\begin{equation*}
\not \nabla \rho=O\left(r^{-4} \tau_{-}^{-1}\right) \tag{54}
\end{equation*}
$$

Note that in the Newman-Penrose picture with stronger decay, $\beta$ would peel like $r^{-4}$ and $\alpha$ like $r^{-5}$. Christodoulou's article [9] shows that this does not occur for physical data. The present article and a forthcoming paper by the present author further show that dynamical spacetimes do not necessarily exhibit the full peeling, rather "spherical symmetry" adds to more decay (in the sense of (39), compare with (47)), whereas the curvature and derivatives in spacetimes for more general data tend to fall off more slowly ((52), (53)).

We point out that the differences between (39) and (47) are crucial. Thus, whereas in (CK) $\rho-\bar{\rho}$ takes extra decay in $\tau_{-}$, this is not the case for (A). The reason for the latter is that the mass depends on the angles, whereas it is a constant in the former case.

The asymptotic spherical symmetry of the (CK) spacetimes, that roots in the (CK) data (4), that is $M$ is a constant, allows in [13] for energies involving rotational vectorfields to control the decay rates of the curvature components. In particular, the extra decay for for $\rho-\bar{\rho}$ as in (39) and for $\not \subset \rho$ as (53) are obtained. The lack of this symmetry, more precisely the dependence of the mass term in (2) on the angles yields the slower fall-off of these terms in (A). Note that the Bondi mass aspect function $M(\theta, \phi, u)$ is more general in (A). We may think of the (A) spacetimes as the dynamical situations versus solutions with "non-dynamical" leading order behavior.
3.1.2. Ricci coefficients By $\widehat{\chi}, \widehat{\chi}$ we denote the shears, which are defined to be the traceless parts of the second fundamental forms with respect to the null vectorfields $L$ and $\underline{L}$ generating the corresponding outgoing, respectively incoming null hypersurfaces. Further, $\zeta$ is the torsion-one-form. Let $X, Y$ be arbitrary tangent vectors to $S_{t, u}$ at a point. Then the second fundamental forms are defined as

$$
\chi(X, Y)=g\left(\nabla_{X} L, Y\right) \quad \underline{\chi}(X, Y)=g\left(\nabla_{X} \underline{L}, Y\right) .
$$

We write for the trace of these tensors $\operatorname{tr} \chi$, respectively $\operatorname{tr} \underline{\chi}$. In general, we introduce the Ricci coefficients as follows

$$
\begin{aligned}
\chi_{A B} & =g\left(D_{A} e_{4}, e_{B}\right) \\
\underline{\chi}_{A B} & =g\left(D_{A} e_{3}, e_{B}\right) \\
\underline{\xi}_{A} & =\frac{1}{2} g\left(D_{3} e_{3}, e_{A}\right) \\
\zeta_{A} & =\frac{1}{2} g\left(D_{3} e_{4}, e_{A}\right) \\
\underline{\zeta}_{A} & =\frac{1}{2} g\left(D_{4} e_{3}, e_{A}\right)
\end{aligned}
$$

$$
\begin{aligned}
\nu & =\frac{1}{2} g\left(D_{4} e_{4}, e_{3}\right) \\
\underline{\nu} & =\frac{1}{2} g\left(D_{3} e_{3}, e_{4}\right) \\
\epsilon_{A} & =\frac{1}{2} g\left(D_{A} e_{4}, e_{3}\right)
\end{aligned}
$$

### 3.2. Behavior at future null infinity

We derive the following at future null infinity $\mathcal{I}^{+}$for (A) spacetimes:

$$
\begin{aligned}
\lim _{C_{u}, t \rightarrow \infty} r^{3} \rho= & P(u, \theta, \phi) \\
\bar{P}= & \bar{P}(u) \\
(P-\bar{P})(u, \theta, \phi): & \text { does not decay in }|u| \text { as }|u| \rightarrow \infty, \\
& \text { leading order term is dynamical, i.e. depends on } u, \\
& \text { and also depends on the angles } \theta, \phi \\
\lim _{u \rightarrow+\infty} P(u, \theta, \phi)= & P^{+}(\theta, \phi)
\end{aligned}
$$

We see that $P=P(u, \theta, \phi)$ is a function on $R \times S^{2}$, and $P^{+}=P^{+}(\theta, \phi)$ is a function on $S^{2}$. Thus, in particular, as $u \rightarrow+\infty$, the quantity $P(u, \theta, \phi)$ tends to a function $P^{+}(\theta, \phi)$ on $S^{2}$, not a constant.

Note that in [13] for (CK) spacetimes it is

$$
\begin{align*}
P-\bar{P} & =O\left(|u|^{-\frac{1}{2}}\right) \\
\lim _{u \rightarrow+\infty} P & =P^{+}=\lim _{u \rightarrow+\infty} \bar{P}=\bar{P}^{+}=-2 M^{+}=\text {constant } \\
\lim _{u \rightarrow-\infty} P & =P^{-}=\lim _{u \rightarrow-\infty} \bar{P}=\bar{P}^{-}=0
\end{align*}
$$

Thus, the leading order term in $P$ as $u \rightarrow+\infty$ is a constant in the angles $\theta, \phi$ and cancels in $P-\bar{P}$. Here, $M$ denotes the Bondi mass and $M^{+}$its limit for $u \rightarrow+\infty$, namely the ADM mass.

In both (CK) and (A) spacetimes, the Hawking mass tends to the Bondi mass $M$ at $\mathcal{I}^{+}$, the latter being one half times the mean value on $S^{2}$ of the corresponding limit of the mass aspect function. This limit of the mass aspect function obeys an equation at $\mathcal{I}^{+}$containing $P$ as a leading order term. Taking the mean value $\bar{P}$ of $P$ on $S^{2}$ gives minus twice the Bondi mass plus a term that decays for $u \rightarrow \infty$. Now, we have that $\lim _{u \rightarrow+\infty} \bar{P}=\bar{P}^{+}$give minus twice the ADM energy. This is all true in both settings (CK) and (A). However, a big difference occurs for $P$ itself as follows: Whereas in (CK), $P$

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tends to $-2 M^{+}$for $u \rightarrow \infty$ as seen in equation (55), this is not true for (A) spacetimes. Instead, $P$ includes further terms at highest order, $P^{+}$being a function on $S^{2}$ rather than a constant. Thus, in (A) the limit as $u \rightarrow \infty$ of $(P-\bar{P})$ is a non-zero function of $(\theta, \phi)$, whereas it vanishes for (CK).
3.2.1. Memory Memory. There is a natural contribution from $(P-\bar{P})$ to the gravitational wave memory effect. One may use the memory formulas from Christodoulou's paper [8] or any of the present author's derivation of memory, for instance [3, 4], but with the (A) data.

### 3.3. Comparing (A) with (CK) spacetimes

(A)

$$
\rho \quad \lim _{C_{u}, t \rightarrow \infty} r^{3} \rho=P(u, \theta, \phi)
$$

$$
(P-\bar{P}) \quad \text { does not decay in }|u| \text { as }|u| \rightarrow \infty
$$ tends to a non-zero function of $(\theta, \phi)$, for $u \rightarrow+\infty$

$\not \nabla \rho \quad O\left(r^{-4}\right)$
$O\left(r^{-4} \tau_{-}^{-\frac{1}{2}}\right)$
$\beta \quad o\left(r^{-\frac{7}{2}}\right)$

$$
o\left(r^{-\frac{7}{2}}\right)
$$

$\beta_{3} \quad O\left(r^{-4}\right)$
$O\left(r^{-4} \tau_{-}^{-\frac{1}{2}}\right)$
$\underline{\beta}_{4}$
$O\left(r^{-4}\right)$
$O\left(r^{-4} \tau_{-}^{-\frac{1}{2}}\right)$

### 3.4. Energies and control of the curvature

In [6] we use energies to control the curvature components that are between the borderline case of $[1,2]$ and the strongly asymptotically flat situation of [13]. Whereas already in the former proof the present author had to work directly with the Bianchi equations in connection with the "rougher" energies related to fewer vectorfields and with very slow decay of the data (borderline decay), the latter result by Christodoulou and Klainerman made use of the rotational vectorfields which gained them extra decay.

Whereas in [13], the vectorfields $T, S, K, \bar{K}, O_{i}$ play crucial roles, in [1, 2], in [6] and in the present situation, only the first four of these vectorfields
come into play, no rotational vectorfields $O_{i}$ are at hand. Given the decay of the data in the present article, and the vectorfields in connection with the energies, more precisely the lack of symmetry (in particular when compared to the situation in [13]), we rely directly on the Bianchi equations. The setting investigated in this article requires different energies to be introduced and controlled. The estimates close at the optimal level due to the balancing between the energy estimates and the Bianchi equations and using extra information from the structure equations. In particular, to establish the optimal behavior for the curvature term $\rho$ and its derivatives, as well as for $\beta_{3}$ and $\underline{\beta}_{4}$ extra structures of these equations are used.

## 4. Bianchi equations and structure equations

### 4.1. Bianchi equations

The Bianchi equations read as follows.
With respect to the null foliation, the Bianchi equations take the form:

$$
\begin{align*}
& \text { (56) } \not D_{3} \alpha+\frac{1}{2} \operatorname{tr} \underline{\chi} \alpha=-2 \not \mathscr{D}_{2}^{*} \beta-3 \hat{\chi} \rho-3^{*} \hat{\chi} \sigma+2 \underline{\nu} \alpha+(\epsilon+4 \zeta) \hat{\otimes} \beta  \tag{56}\\
& \text { (57) } \not D_{3} \beta+\operatorname{tr} \underline{\chi} \beta=\not D_{1}^{*}(-\rho, \sigma)+2 \hat{\chi} \underline{\beta}+3 \zeta \rho+3^{*} \zeta \sigma+\underline{\nu} \beta+\underline{\xi} \alpha  \tag{57}\\
& \text { (58) } \not D_{4} \beta+2 \operatorname{tr} \chi \beta=\operatorname{div} \alpha-\nu \beta+(2 \epsilon+\zeta) \alpha
\end{align*}
$$

(59) $\not D_{3} \rho+\frac{3}{2} \operatorname{tr} \underline{\chi} \rho=-\operatorname{div} \underline{\beta}-\frac{1}{2} \hat{\chi} \underline{\alpha}+(\epsilon-\zeta) \underline{\beta}+2 \underline{\xi} \beta$

$$
\begin{equation*}
\not D_{4} \rho+\frac{3}{2} \operatorname{tr} \chi \rho=\operatorname{ditv} \beta-\frac{1}{2} \underline{\hat{\chi}} \alpha+\epsilon \beta+2 \underline{\zeta} \beta \tag{60}
\end{equation*}
$$

$$
\begin{equation*}
\not D_{3} \sigma+\frac{3}{2} \operatorname{tr} \underline{\chi} \sigma=-\operatorname{c\psi rl} \underline{\beta}-\frac{1}{2} \hat{\chi}^{*} \underline{\alpha}+\epsilon^{*} \underline{\beta}-2 \zeta^{*} \underline{\beta}-2 \underline{\xi}^{*} \beta \tag{61}
\end{equation*}
$$

$$
\begin{equation*}
\not D_{4} \sigma+\frac{3}{2} \operatorname{tr} \chi \sigma=-c \psi r l \beta+\frac{1}{2} \underline{\hat{\chi}}^{*} \alpha+-\epsilon^{*} \beta-2 \underline{\zeta}^{*} \beta \tag{62}
\end{equation*}
$$

$$
\begin{equation*}
\not D_{3} \underline{\beta}+2 \operatorname{tr} \underline{\chi} \underline{\beta}=-\operatorname{div} \underline{\alpha}-(\zeta-2 \epsilon) \underline{\alpha}-\underline{\nu} \underline{\beta}-3 \underline{\xi} \rho+3^{*} \underline{\xi} \sigma \tag{63}
\end{equation*}
$$

$$
\begin{equation*}
\not D_{4} \underline{\beta}+\operatorname{tr} \chi \underline{\beta}=\mathcal{D}_{1}^{*}(\rho, \sigma)+\nu \underline{\beta}+2 \underline{\hat{\chi}} \beta-3\left(\underline{\zeta} \rho-^{*} \underline{\zeta} \sigma\right) \tag{64}
\end{equation*}
$$

$$
\begin{equation*}
\not D_{4} \underline{\alpha}+\frac{1}{2} \operatorname{tr} \chi \underline{\alpha}=2 \not \mathcal{D}_{2}^{*} \underline{\beta}+2 \nu \underline{\alpha}+(\epsilon-4 \underline{\zeta}) \hat{\otimes} \underline{\beta}-3\left(\underline{\hat{\chi}} \rho-{ }^{*} \underline{\hat{\chi}} \sigma\right) \tag{65}
\end{equation*}
$$

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### 4.2. Structure equations

$$
\begin{align*}
& \operatorname{div} \underline{\hat{\chi}}=\underline{\beta}+\underline{\hat{\chi}} \cdot \zeta+\frac{1}{2}(\not \nabla \operatorname{tr} \underline{\chi}-\operatorname{tr} \underline{\chi} \zeta)=\underline{\beta}+\text { l.o.t. }  \tag{66}\\
& \text { divu} \hat{\chi}=-\beta-\hat{\chi} \cdot \zeta+\frac{1}{2}(\not \nabla \operatorname{tr} \chi+\operatorname{tr} \chi \zeta) \tag{67}
\end{align*}
$$

Recall that $\zeta$ is the torsion-one-form, introduced above in subsection 3.1.2.
The shears are related to each other by the equation

$$
\begin{equation*}
\frac{\partial}{\partial u} \hat{\chi}=\frac{1}{4} \operatorname{tr} \chi \cdot \underline{\hat{\chi}}+\text { l.o.t. } \tag{68}
\end{equation*}
$$

Also, it is

$$
\begin{equation*}
\frac{\partial}{\partial u} \underline{\hat{\chi}}=\frac{1}{2} \underline{\alpha}+\text { l.o.t. } \tag{69}
\end{equation*}
$$

## 5. Limits at future null infinity $\mathcal{I}^{+}$

As a direct consequence from the behavior established in [6], see section 3 above, we obtain the following theorem.

Theorem 1. For ( $A$ ) spacetimes, the normalized curvature components $r \underline{\alpha}$, $r^{2} \underline{\beta}, r^{3} \rho, r^{3} \sigma$ have limits on $C_{u}$ as $t \rightarrow \infty$ :

$$
\begin{aligned}
\lim _{C_{u}, t \rightarrow \infty} r \underline{\alpha} & =A(u, \cdot), & & \lim _{C_{u}, t \rightarrow \infty} r^{2} \underline{\beta}=\underline{B}(u, \cdot), \\
\lim _{C_{u}, t \rightarrow \infty} r^{3} \rho & =P(u, \cdot), & & \lim _{C_{u}, t \rightarrow \infty} r^{3} \sigma=Q(u, \cdot)
\end{aligned}
$$

where the limits are on $S^{2}$ and depend on $u$. These limits satisfy

$$
\begin{array}{ll}
|A(u, \cdot)| \leq C(1+|u|)^{-5 / 2} & |\underline{B}(u, \cdot)| \leq C(1+|u|)^{-3 / 2} \\
|Q(u, \cdot)| \leq C(1+|u|)^{-1 / 2} &
\end{array}
$$

whereas $P(u, \cdot),(P(u, \cdot)-\bar{P}(u))$ do not decay in $|u|$.
Moreover, the following limits exist

$$
\begin{equation*}
\lim _{C_{u}, t \rightarrow \infty} r^{2} \widehat{\chi}=: \quad \Sigma(u, \cdot) \tag{70}
\end{equation*}
$$

$$
\begin{equation*}
-\frac{1}{2} \lim _{C_{u}, t \rightarrow \infty} r \underline{\hat{\chi}}=\lim _{C_{u}, t \rightarrow \infty} r \hat{\eta}=: \Xi(u, \cdot) \tag{71}
\end{equation*}
$$

Further, it follows from (69), respectively from (68) and from (66) that

$$
\begin{align*}
\frac{\partial \Xi}{\partial u} & =-\frac{1}{4} A  \tag{72}\\
\frac{\partial \Sigma}{\partial u} & =-\Xi  \tag{73}\\
\underline{B} & =-2 \operatorname{di} u \Xi \tag{74}
\end{align*}
$$

Another consequence is the behavior

$$
\begin{equation*}
|\Xi(u, \cdot)| \leq C(1+|u|)^{-3 / 2} \tag{75}
\end{equation*}
$$

We introduce $F / 4 \pi$, the energy radiated away per unit angle in a given direction, where

$$
\begin{equation*}
F(\cdot)=\frac{1}{2} \int_{-\infty}^{+\infty}|\Xi(u, \cdot)|^{2} d u \tag{76}
\end{equation*}
$$

And we write $F(u)$ for

$$
\begin{equation*}
F(u, \cdot)=\frac{1}{2} \int_{u}^{+\infty}\left|\Xi\left(u^{\prime}, \cdot\right)\right|^{2} d u^{\prime} \tag{77}
\end{equation*}
$$

Behaviors of $\rho$ and $P$ versus $\sigma$ and $Q$ : Whereas the curvature terms $\rho,(\rho-\bar{\rho})$ and their limits $P(u, \cdot),(P(u, \cdot)-\bar{P}(u))$ do not decay in $|u|$ as $|u| \rightarrow \infty$, the curvature terms $\sigma,(\sigma-\bar{\sigma})$ and the corresponding limits $Q(u, \cdot),(Q(u, \cdot)-\bar{Q}(u))$ do. To this end, we observe the following: Whereas in the Christodoulou-Klainerman proof [13] for (CK) spacetimes the decay of these terms follows from the energy estimates using rotational vectorfields, the latter are not available in the present non-symmetric case. Instead the decay of $\sigma$ follows from its relation to $k$. In particular, we have for Einstein-vacuum spacetimes on each spacelike hypersurface $H_{t}$

$$
\begin{equation*}
(c u r l k)_{l m}=H_{l m} \tag{78}
\end{equation*}
$$

where $H$ is the magnetic part of the Weyl curvature as defined in (21), and $k$ behaves as in (3). Decomposing this equation into parts that are tangential
to and orthogonal to the surfaces $S_{t, u}$, the $N N$-component of equation (78) reads

$$
\begin{equation*}
(\text { curl } k)_{N N}=\sigma . \tag{79}
\end{equation*}
$$

Consider the initial data for (A) spacetimes, and observe in (3) how $k$ falls off. As shown in [6], this behavior is preserved under the evolution by the Einstein equations. Thus, from (3) and (79) it follows that $\sigma$ and therefore also its limit $Q$ decay in $|u|$ as $|u| \rightarrow \infty$.

## 6. Investigating $\rho$ via Bianchi equations and structure equations

Recall that we have $T=\frac{1}{\Phi} \frac{\partial}{\partial t}$. Let $T=E_{0}$ as well as $\left(E_{1}, E_{2}, E_{3}\right)$ an orthonormal frame field for $H_{t}$. Thus we have the frame field $\left(E_{0}, E_{1}, E_{2}, E_{3}\right)$ for the spacetime $M$.

We shall make use of the Bianchi equations and the structure equations at various levels. The Bianchi identities (themselves as well as in contracted forms) are used widely in the spacetime $(M, g)$ but also on the spacelike hypersurfaces $\left(H_{t}, \bar{g}_{i j}(t), k_{i j}(t)\right)$.

Equations (22)-(27) follow easily. We recall that the Codazzi equations read

$$
\begin{equation*}
\bar{\nabla}_{i} k_{j m}-\bar{\nabla}_{j} k_{i m}=R_{m 0 i j} \tag{80}
\end{equation*}
$$

and the Gauss equations take the form

$$
\begin{equation*}
\bar{R}_{i m j n}+k_{i j} k_{m n}-k_{i n} k_{m j}=R_{i m j n} \tag{81}
\end{equation*}
$$

By overline we denote the corresponding induced quantities on $H_{t}$. Thus, $\bar{R}_{i m j n}$ are the components of the curvature tensor of $\left(H_{t}, \bar{g}(t)\right)$.

Now, we consider the initial hypersurface $\left(H_{0}, \bar{g}_{i j}, k_{i j}\right)$. Taking the trace of the Gauss equations yields

$$
\begin{equation*}
\bar{R}_{i j}+\operatorname{trk} k_{i j}-k_{i m} k_{j}^{m}=R_{i j}+R_{i 0 j 0} \tag{82}
\end{equation*}
$$

Thus, from (82) using the EV equations (1) and the constraint equation (22) follows (32)

$$
\bar{R}_{i j}=k_{i m} k_{j}^{m}+E_{i j}
$$

Using the constraint equation (24) together with the assumptions (3) on the second fundamental form $k$ on $H_{0}$, it follows from (32) that

$$
\begin{align*}
\bar{R}_{A B} & =\frac{1}{4} \underline{\alpha}_{A B}+\frac{1}{4} \alpha_{A B}-\frac{1}{2} \rho \delta_{A B}+\text { l.o.t. }  \tag{83}\\
\bar{R}_{N N} & =\rho+\text { l.o.t. }  \tag{84}\\
\bar{R}_{A N} & =-\frac{1}{2}\left(\underline{\beta}_{A}+\beta_{A}\right)+\text { l.o.t. } \tag{85}
\end{align*}
$$

We obtain from the contracted Bianchi identities

$$
\begin{equation*}
\bar{\nabla}_{m} \bar{R}_{l}^{m}=\frac{1}{2} \bar{\nabla}_{l} \bar{R} \tag{86}
\end{equation*}
$$

and from (28) that

$$
\begin{equation*}
\bar{\nabla}_{m} \bar{R}_{l}^{m}=\frac{1}{2} \bar{\nabla}_{l} \bar{R}=o\left(r^{-6}\right) . \tag{87}
\end{equation*}
$$

Therefore, up to leading order it is

$$
\begin{equation*}
\bar{\nabla}_{m} \bar{R}_{l}^{m}=0 \tag{88}
\end{equation*}
$$

From (88) and the components (83)-(85) we deduce the equations
(89) $\operatorname{tr} \overline{R i c}=\bar{R}=\bar{R}_{N}^{N}+\bar{R}_{A}^{A}$
(90) $\quad=0_{\text {leading order curvature terms }}+$ l.o.t. $=o\left(r^{-5}\right)$

Therefore, we have up to leading order

$$
\begin{equation*}
\bar{\nabla}^{i} \bar{R}_{i B}=\bar{\nabla}^{A} \bar{R}_{A B}+\bar{\nabla}^{N} \bar{R}_{N B}=0 \tag{91}
\end{equation*}
$$

with

$$
\begin{equation*}
\bar{\nabla}^{A} \bar{R}_{A B}=\frac{1}{4} \bar{\nabla}^{A} \underline{\alpha}_{A B}+\frac{1}{4} \bar{\nabla}^{A} \alpha_{A B}-\frac{1}{2} \bar{\nabla}^{A} \rho \cdot \delta_{A B} \tag{92}
\end{equation*}
$$

and

$$
\begin{equation*}
\bar{\nabla}^{N} \bar{R}_{N B}=-\frac{1}{2} \bar{\nabla}^{N} \underline{\beta}_{B}-\frac{1}{2} \bar{\nabla}^{N} \beta_{B} . \tag{93}
\end{equation*}
$$

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### 6.1. Limits at spacelike infinity

In the following, lower order terms (l.o.t.) will be $o\left(r^{-\frac{11}{2}}\right)$ or with stronger fall-off.

Theorem 2. The following equation holds:
(94) $\frac{1}{2} \not \nabla^{A} \alpha_{A B}+\frac{1}{2} \not \nabla^{A} \underline{\alpha}_{A B}-\not \nabla_{B} \rho-\left(\not \nabla^{N} \underline{\beta}_{B}+\not \nabla^{N} \beta_{B}\right)+F_{\beta, \underline{\beta}}+G(\Phi, \Psi)=0$,
where $F_{\beta, \underline{\beta}}$ denotes terms of the types $\left\{\right.$ constant $\left.\cdot \frac{1}{r} \cdot \beta_{B}\right\}$ and $\left\{\right.$ constant $\left.\cdot \frac{1}{r} \cdot \underline{\beta}_{B}\right\}$; and $G(\Phi, \Psi)$ terms of the types $\{\Phi \cdot \Psi\}$ with $\Psi$ denoting a Weyl curvature component, and $\Phi$ denoting a rotation coefficient except for the highest order term in tr $\chi$ and the highest order term in tr $\underline{\chi}$.

Remark: The $F_{\beta, \underline{\beta}}$ result from the highest order terms of products between $\operatorname{tr} \chi$ and $\operatorname{tr} \underline{\chi}$ on the one side and $\beta$ and $\underline{\beta}$ on the other side. All the other terms of these products are of lower order and are absorbed in $G(\Phi, \Psi)$.

Next, we consider $H_{0}$, thus $t=0$. By $S_{r}$ we denote surfaces in $H_{0}$ that are diffeomorphic to $S^{2}$. Let $\xi^{B}$ denote a conformal Killing vector field of $S_{r}$. The results for $S_{r}$ hold for any topological spheres. In our situation, we shall work with the $S_{r}$ that are induced by the intersections $H_{0} \cap C_{u}$ at $t=0$, where $u=r=\underline{u}$.
Theorem 3. (a) The integral of $F_{\beta_{B}, \underline{\beta}_{B}} \cdot \xi^{B}$ on $S_{r}$ is zero $\forall \xi^{B}$,

$$
\int_{S_{r}} F_{\beta_{B}, \underline{\underline{\beta}}_{B}} \cdot \xi^{B}=0
$$

(b) The integral of $G(\Phi, \Psi) \cdot \xi^{B}$ on $S_{r}$ is lower order $\forall \xi^{B}$,

$$
\int_{S_{r}} G(\Phi, \Psi) \cdot \xi^{B}=o\left(r^{-2}\right)
$$

and

$$
\lim _{r \rightarrow \infty} \int_{S_{r}} G(\Phi, \Psi) \cdot \xi^{B}=0
$$

From theorems 2 and 3 the next result immediately follows:
Theorem 4. Multiply equation (94) by $\xi^{B}$ and integrate on $S_{r}$ to obtain up to leading order:
(95) $\frac{1}{2} \int_{S_{r}} \not \nabla^{A} \alpha_{A B} \cdot \xi^{B}+\frac{1}{2} \int_{S_{r}} \not \nabla^{A} \underline{\alpha}_{A B} \cdot \xi^{B}-\int_{S_{r}} \not \nabla_{B} \rho \cdot \xi^{B}=0 \quad \forall \xi^{B}$.

Theorem 5. We have to leading order

$$
\begin{equation*}
\int_{S_{r}} \not \nabla_{B} \rho \cdot \xi^{B}=0 \quad \forall \xi^{B} . \tag{96}
\end{equation*}
$$

Proof: This follows from the following standard result for the divergence operator on any $S_{r}$ diffeomorphic to the standard sphere $S^{2}$ : The divergence operator acting on a 2-covariant, symmetric, traceless tensor $t$, thus its image is the 1-form divt, is injective, and the range consists of all $L^{2}$-integrable 1forms on $S_{r}$ that are $L^{2}$-orthogonal to the Lie algebra of the conformal group of $S_{r}$. Consequently, the first two integrals in (95) are zero, which proves the theorem.

Next, integrate (96) by parts to obtain

$$
\begin{equation*}
\int_{S_{r}} \rho \cdot \not \nabla_{B} \xi^{B}=0 \quad \forall \xi^{B} \tag{97}
\end{equation*}
$$

We want to study limits at infinity, therefore take the limit

$$
\begin{align*}
\lim _{H_{0}, r \rightarrow \infty} r \int_{S_{r}} \rho \cdot \not \nabla_{B} \xi^{B} & =0  \tag{98}\\
& =\int_{S^{2}} P_{H_{0}}(\theta, \phi) \cdot \not \nabla_{B} \xi^{B} \quad \forall \xi^{B} \tag{99}
\end{align*}
$$

where $P_{H_{0}}(\theta, \phi)$ denotes the limit of $r^{3} \rho$ at spacelike infinity.
We recall the well-known fact about the Laplace operator on the sphere $S^{2}$ and for every conformal Killing vectorfield $\xi^{B}$

$$
\begin{equation*}
\triangle \operatorname{div} \xi+2 \operatorname{div} \xi=0 \tag{100}
\end{equation*}
$$

With other words, $\operatorname{div} \xi$ for evey $\xi^{B}$ belongs to the first eigenspace, thus $l=1$, for $\not \subset$. Moreover, each $l=1$ spherical harmonic is the divergence of a unique conformal Killing vectorfield $\xi^{B}$ on $S^{2}$.

Therefore, we conclude the following theorem.
Theorem 6. $P_{H_{0}}(\theta, \phi)$ does not have any $l=1$ mode.
Next, we study the behavior at future null infinity $\mathcal{I}^{+}$. Consider

$$
\begin{equation*}
\lim _{C_{u}, r \rightarrow \infty} r \int_{S_{r}} \rho \cdot \not \nabla_{B} \xi^{B}=\int_{S^{2}} P(u, \theta, \phi) \cdot \not \nabla_{B} \xi^{B}=: \mathcal{A}(u) . \tag{101}
\end{equation*}
$$

Obviously, it is

$$
\begin{equation*}
\lim _{u \rightarrow \infty} \int_{S^{2}} P(u, \theta, \phi) \cdot \not \nabla_{B} \xi^{B}=\int_{S^{2}} P^{+}(\theta, \phi) \cdot \not \nabla_{B} \xi^{B} \tag{102}
\end{equation*}
$$

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Now, whereas in this general setting, the limits for $\rho$ taken in the spacelike slice $H_{0}$ for $r \rightarrow \infty$, respectively the limit at $\mathcal{I}^{+}$for $u \rightarrow \infty$, namely $P_{H_{0}}(\theta, \phi)$ and $P^{+}(\theta, \phi)$ do not coincide, the corresponding integrals over spheres do. The reason for the latter is that these limiting integrals do not depend on the exhaustion. See Appendix A. Thus, we have

$$
\begin{equation*}
P_{H_{0}}(\theta, \phi) \neq P^{+}(\theta, \phi) \tag{103}
\end{equation*}
$$

however

$$
\begin{equation*}
\int_{S^{2}} P_{H_{0}}(\theta, \phi) \cdot d i \psi v=\int_{S^{2}} P^{+}(\theta, \phi) \cdot d i \psi v \tag{104}
\end{equation*}
$$

From theorem 6 it follows that

$$
\begin{equation*}
\int_{S^{2}} P^{+}(\theta, \phi) \cdot \not{ }_{B} \xi^{B}=0 \quad \forall \xi^{B} \tag{105}
\end{equation*}
$$

proving the next theorem.
Theorem 7. $P^{+}(\theta, \phi)$ does not have any $l=1$ mode.
The next question is what happens at $\mathcal{I}^{+}$for general $u$ as well as for $u \rightarrow-\infty$. We shall prove the next theorem.

## Theorem 8.

(a) Regarding P: For finite u we have
(106) $\int_{S^{2}} P(u) \cdot \not \nabla_{A} \xi^{A}=+2 \int_{S^{2}} F(u) \cdot \not \nabla_{A} \xi^{A}-\int_{S^{2}} \Sigma(u) \Xi(u) \cdot \not \nabla_{A} \xi^{A}$.
(b) Regarding P: For $u \rightarrow-\infty$ it is

$$
\begin{equation*}
\int_{S^{2}} P^{-} \cdot \not \nabla_{A} \xi^{A}=+2 \int_{S^{2}} F \cdot \not \nabla_{A} \xi^{A} \tag{107}
\end{equation*}
$$

(c) Regarding Q: For $u \rightarrow-\infty$, respectively $u \rightarrow+\infty$, it is

$$
\begin{equation*}
Q^{-}=Q^{+}=0, \text { therefore trivially } Q_{l=1}^{-}=Q_{l=1}^{+}=0 \tag{108}
\end{equation*}
$$

(d) Regarding Q: For finite u we have

$$
\begin{equation*}
\int_{S^{2}} Q(u) \cdot \not \nabla_{A} \xi^{A}=-\int_{S^{2}}(\Sigma(u) \wedge \Xi(u)) \cdot \not \nabla_{A} \xi^{A} \tag{109}
\end{equation*}
$$

Proof: First, we derive a Hodge system of equations on $S^{2}$. Then we apply Hodge theory (see appendix C) to prove the statements.

Equations for $\rho$ and $P$ : Recall the Bianchi equation (59) for $\not D_{3} \rho$

$$
\not D_{3} \rho+\frac{3}{2} \operatorname{tr} \underline{\chi} \rho=-\operatorname{di} \underline{\beta} \underline{\beta}-\frac{1}{2} \hat{\chi} \underline{\alpha}+(\epsilon-\zeta) \underline{\beta}+2 \underline{\xi} \beta=-\operatorname{di} v \underline{\beta}-\frac{1}{2} \hat{\chi} \underline{\alpha}+\text { l.o.t. }
$$

which we write as

$$
\begin{equation*}
\rho_{3}=-\operatorname{div} \underline{\beta}-\frac{\partial}{\partial u}(\hat{\chi} \cdot \underline{\hat{\chi}})+\frac{1}{4} \operatorname{tr} \chi|\underline{\hat{\chi}}|^{2}+\text { l.o.t. } \tag{110}
\end{equation*}
$$

where $\rho_{3}:=\not D_{3} \rho+\frac{3}{2} \operatorname{tr} \underline{\chi} \rho$, using (68) and (69). Multiply equation (110) by $r^{3}$ and take the limit along $C_{u}$ as $t \rightarrow \infty$ to obtain

$$
\begin{equation*}
-2 \frac{\partial}{\partial u} P=-\operatorname{div} \underline{B}+2 \frac{\partial}{\partial u}(\Sigma \cdot \Xi)+2|\Xi|^{2}+\text { l.o.t. } \tag{111}
\end{equation*}
$$

Using (74) as well as (73) and integrating with respect to $u$ yields

$$
\begin{align*}
\left(P(u)-P^{+}\right)= & \operatorname{div} \operatorname{div}\left(\Sigma(u)-\Sigma^{+}\right)+\int_{u}^{+\infty}\left|\Xi\left(u^{\prime}\right)\right|^{2} d u^{\prime} \\
& -(\Sigma(u) \cdot \Xi(u)-\underbrace{\Sigma^{+} \cdot \Xi^{+}}_{=0}) \\
12)= & \operatorname{div} \operatorname{div}\left(\Sigma(u)-\Sigma^{+}\right)+\int_{u}^{+\infty}\left|\Xi\left(u^{\prime}\right)\right|^{2} d u^{\prime}-\Sigma(u) \cdot \Xi(u)  \tag{112}\\
\left(P^{-}-P^{+}\right)= & \operatorname{div} \operatorname{div}\left(\Sigma^{-}-\Sigma^{+}\right)+\int_{-\infty}^{+\infty}|\Xi(u)|^{2} d u \\
& -(\underbrace{\Sigma^{-} \cdot \Xi^{-}}_{=0}-\underbrace{\Sigma^{+} \cdot \Xi^{+}}_{=0}) \\
13)= & \operatorname{div} \operatorname{div}\left(\Sigma^{-}-\Sigma^{+}\right)+\int_{-\infty}^{+\infty}|\Xi(u)|^{2} d u .
\end{align*}
$$

Thus, we have

$$
\begin{align*}
\left(P(u)-P^{+}\right) & =\operatorname{divdiv}\left(\Sigma(u)-\Sigma^{+}\right)+2 F(u)-\Sigma(u) \cdot \Xi(u)  \tag{114}\\
\left(P^{-}-P^{+}\right) & =\operatorname{divdiv}\left(\Sigma^{-}-\Sigma^{+}\right)+2 F .
\end{align*}
$$

Equations for $\sigma$ and $Q$ : Next, we consider the Bianchi equation (61)

$$
\not D_{3} \sigma+\frac{3}{2} \operatorname{tr} \underline{\chi} \sigma=-\operatorname{c\psi } l \underline{\beta}-\frac{1}{2} \hat{\chi}^{*} \underline{\alpha}+\epsilon^{*} \underline{\beta}-2 \zeta^{*} \underline{\beta}-2 \underline{\xi}^{*} \beta
$$

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which we write as

$$
\begin{equation*}
\sigma_{3}=-c \psi r l \underline{\beta}-\frac{\partial}{\partial u}(\hat{\chi} \wedge \underline{\hat{\chi}})+\text { l.o.t. } \tag{116}
\end{equation*}
$$

where $\sigma_{3}:=\not D_{3} \sigma+\frac{3}{2} \operatorname{tr} \chi \sigma$, using (68) and (69). Multiply (116) by $r^{3}$ and take the limit on $C_{u}$ as $r \rightarrow \infty$ to obtain

$$
\begin{equation*}
Q_{3}=-c \psi r l \underline{B}+2 \frac{\partial}{\partial u}(\Sigma \wedge \Xi) \tag{117}
\end{equation*}
$$

that reads

$$
\begin{equation*}
\frac{\partial Q}{\partial u}=\frac{1}{2} \operatorname{c\psi rl} \underline{B}-\frac{\partial}{\partial u}(\Sigma \wedge \Xi) . \tag{118}
\end{equation*}
$$

We infer

$$
\begin{align*}
Q(u)-Q^{+} & =\operatorname{c\psi urldiv}\left(\Sigma(u)-\Sigma^{+}\right)-\Sigma(u) \wedge \Xi(u)  \tag{119}\\
Q^{-}-Q^{+} & =\operatorname{c\psi rldiv}\left(\Sigma^{-}-\Sigma^{+}\right) \tag{120}
\end{align*}
$$

At this point, we make use of the Hodge theory from appendix C.
From above we know that $Q=O\left(|u|^{-\frac{1}{2}}\right)$. Note that the mean value $\bar{Q}$ of $Q$ on $S^{2}$ obeys $\bar{Q}=O\left(|u|^{-\frac{3}{2}}\right)$. However, there is no power law decrease (nor increase) for the corresponding mean value $\bar{P}$ of $P$.

Derivation of equation (107): Consider the equation (115) and the independently derived equation (120). For

$$
\begin{equation*}
\mathcal{Z}=\operatorname{dik}\left(\Sigma^{-}-\Sigma^{+}\right) \tag{121}
\end{equation*}
$$

we derive the Hodge system

$$
\begin{align*}
\operatorname{div} \mathcal{Z} & =(P-\bar{P})^{-}-(P-\bar{P})^{+}-2(F-\bar{F})  \tag{122}\\
\operatorname{curl} \mathcal{Z} & =0 \tag{123}
\end{align*}
$$

On $S^{2}$, define the function $\varphi$ to be the solution of vanishing mean of the equation

$$
\begin{equation*}
\Delta \varphi=(P-\bar{P})^{-}-(P-\bar{P})^{+}-2(F-\bar{F}) . \tag{124}
\end{equation*}
$$

Then we have

$$
\begin{equation*}
\mathcal{Z}=\not \nabla \varphi \tag{125}
\end{equation*}
$$

Equations (121), (124), (125) determine the solution ( $\Sigma^{-}-\Sigma^{+}$) uniquely. The integrability condition is that $\varphi$ has vanishing projection onto the first eigenspace of $\not \subset$, namely $\varphi_{l=1}=0$. Now, we compute the $l=1$ modes, noting that the elements of the $l=1$ eigenspace are orthogonal to the constants and taking into account theorem 7. Then claim 107 follows.

Equation (108): Equation (108) trivially follows.
Derivation of equation (109): At this point, we consider equation (118):

$$
\frac{\partial Q}{\partial u}=\frac{1}{2} c \psi r l \underline{B}-\frac{\partial}{\partial u}(\Sigma \wedge \Xi)
$$

From theorem 1 we know that the first term on the right hand side is of order $O\left(|u|^{-\frac{3}{2}}\right)$, whereas the last term on the right hand side is of order $O\left(|u|^{-\frac{5}{2}}\right)$. Now, we look at the $l=1$ modes for $Q(u)$. Note that $(c \psi r l \underline{B})_{l=1}=0$. Therefore, the $l=1$ component of $Q$ will be of the form $Q_{l=1}(u)=a_{i} \xi^{i}+$ $O\left(|u|^{-\frac{3}{2}}\right)$, where $a_{i}$ are constants independent of $u$. Recall that $Q=O\left(|u|^{-\frac{1}{2}}\right)$ and $\bar{Q}=O\left(|u|^{-\frac{3}{2}}\right)$; therefore it is also $(Q-\bar{Q})=O\left(|u|^{-\frac{1}{2}}\right)$. It follows that $a_{i}=0$, that is $Q_{l=1}(u)=O\left(|u|^{-\frac{3}{2}}\right)$. We conclude from (118) that

$$
\int_{S^{2}} Q(u) \cdot \not \nabla_{A} \xi^{A}=-\int_{S^{2}}(\Sigma(u) \wedge \Xi(u)) \cdot \not \nabla_{A} \xi^{A}
$$

which is equation (109).
Derivation of equation (106): Consider the equation (114) and the independently derived equation (119). For

$$
\begin{equation*}
\mathcal{Z}=\operatorname{dijv}\left(\Sigma(u)-\Sigma^{+}\right) \tag{126}
\end{equation*}
$$

we derive the Hodge system

$$
\begin{align*}
\operatorname{div\mathcal {Z}}= & (\mathcal{P}-\overline{\mathcal{P}})(u)-(\mathcal{P}-\overline{\mathcal{P}})^{+}-2(F(u)-\bar{F}(u)) \\
& -(\Sigma \cdot \Xi(u)-\overline{\Sigma \cdot \Xi(u)})  \tag{127}\\
\operatorname{curl\mathcal {Z}=} & (\mathcal{Q}-\overline{\mathcal{Q}})(u)+(\Sigma \wedge \Xi(u)-\overline{\Sigma \wedge \Xi(u)}) . \tag{128}
\end{align*}
$$

On $S^{2}$, we define the function $\varphi$ to be the solution of vanishing mean of the equation

$$
\begin{equation*}
\Delta \varphi=(\mathcal{P}-\overline{\mathcal{P}})(u)-(\mathcal{P}-\overline{\mathcal{P}})^{+}-2(F(u)-\bar{F}(u))-(\Sigma \cdot \Xi(u)-\overline{\Sigma \cdot \Xi(u)}) \tag{129}
\end{equation*}
$$

and the function $\psi$ to be the solution of vanishing mean of the equation

$$
\begin{equation*}
\triangle \psi=(\mathcal{Q}-\overline{\mathcal{Q}})(u)+(\Sigma \wedge \Xi(u)-\overline{\Sigma \wedge \Xi(u)}) \tag{130}
\end{equation*}
$$

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Then we have

$$
\begin{equation*}
\mathcal{Z}=\not \nabla \varphi+\not \nabla^{\perp} \psi . \tag{131}
\end{equation*}
$$

It is

$$
\begin{equation*}
\int_{S^{2}} \operatorname{div}\left(\Sigma(u)-\Sigma^{+}\right) \cdot \xi=0 \tag{132}
\end{equation*}
$$

That is

$$
\begin{equation*}
\int_{S^{2}}\left(\Sigma(u)-\Sigma^{+}\right) \cdot d i v \xi=\left(\Sigma(u)-\Sigma^{+}\right)_{l=1}=0 \tag{133}
\end{equation*}
$$

Thus, we write with (126) and (131)

$$
\begin{align*}
\int_{S^{2}} Z \cdot \xi & =0  \tag{134}\\
& =\int_{S^{2}}(\not \nabla \varphi) \cdot \xi+\int_{S^{2}}\left(\not \nabla^{\perp} \psi\right) \cdot \xi  \tag{135}\\
& =-\int_{S^{2}} \varphi \cdot \operatorname{div} \xi-\int_{S^{2}} \psi \cdot \underbrace{c \psi i r l}_{=-\operatorname{di} v \xi^{\perp}} \xi  \tag{136}\\
& =-\int_{S^{2}} \varphi \cdot \operatorname{div} \xi+\int_{S^{2}} \psi \cdot \operatorname{di} \psi \xi^{\perp}
\end{align*}
$$

Using that

$$
\triangle \operatorname{di} / v \xi=-2 d i v v
$$

we further compute

$$
\begin{align*}
0 & =\int_{S^{2}} \varphi \cdot \Delta d i v \xi-\int_{S^{2}} \psi \cdot \Delta d i v \xi^{\perp}  \tag{138}\\
& =\int_{S^{2}} \Delta \varphi \cdot d i v \xi-\int_{S^{2}} \Delta \psi \cdot d i v \xi^{\perp} \tag{139}
\end{align*}
$$

We use that difu $\mathcal{Z}=\nless \varphi$ and $c \nLeftarrow r l \mathcal{Z}=\not \Delta \psi$. See equations (129)-(130). From the previous argument in the derivation of equation (109) we obtain that the second integral in (139) is zero. Then from the first integral in (139), using (129), we compute the $l=1$ modes, noting that the elements of the $l=1$ eigenspace are orthogonal to the constants and taking into account theorem 7. Then claim (106) follows. We conclude that $(P(u))_{l=1}=O\left(|u|^{-\frac{3}{2}}\right)$. This concludes the proof of theorem 8 .

## 7. Angular momentum at $\mathcal{I}^{+}$

In this section, we show that the angular momentum at future null infinity $\mathcal{I}^{+}$is well defined for (A) spacetimes. Given the behavior of the curvature components at $\mathcal{I}^{+}$, it looks as if there was not enough decay for the angular momentum at $\mathcal{I}^{+}$to be well defined. However, the corresponding $l=1$ modes of the crucial components, that enter the definition, behave better and in particular are integrable in $u$.

We recall the classical definition of angular momentum at $\mathcal{I}^{+}$:

$$
\begin{equation*}
J^{k}:=\int_{S^{2}} \epsilon^{A B} \nabla_{B} \tilde{X}^{k}\left(N_{A}-\frac{1}{4} C_{A}^{D} \nabla^{B} C_{D B}\right) \quad, \quad k=1,2,3 . \tag{140}
\end{equation*}
$$

Most physics literature work with Bondi-Sachs coordinates. In (140), $\tilde{X}^{k}$ for $k=1,2,3$ denote the standard coordinate functions in $\mathbb{R}^{3}$ restricted to $S^{2}$, $N_{A}$ is the angular momentum aspect, $C_{A B}$ the shear tensor and $\epsilon_{A B}$ the volume form of the standard round metric $\sigma_{A B}$ of $S^{2}$. Further, in the said notation, $N_{A B}$ is the news tensor and $m$ the mass aspect. In this notation, $\nabla_{A}$ in (140) is the covariant derivative with respect to $\sigma_{A B}$. Raising, lowering indices and contraction happens via the metric $\sigma_{A B}$. See for instance [14], [15]. See also [7] for a discussion of classical angular momentum and their newly introduced definition of angular momentum in a different setting than studied here. Note that (140) is also the definition in [16] but using the ChristodoulouKlainerman notation [13].

While for (CK) spacetimes angular momentum $J^{k}$ at $\mathcal{I}^{+}$is well defined and conserved [16], [7], this was not clear for (A) spacetimes. We are now going to prove that indeed this holds for the more general (A) spacetimes.

Theorem 9. Let $(M, g)$ be an (A) spacetime. Then angular momentum $J^{k}$ at $\mathcal{I}^{+}$is well defined and conserved.

Remark: In order to prove this theorem, we shall explore the ingredients in (140) and how they behave at $\mathcal{I}^{+}$of (A) spacetimes. Moreover, we use the notation as in [13] and [1], [2]. For the readers' convenience, we give the 'translation' between these notations in Appendix B. In (140), in particular regarding $N_{A}$, from (50) it might look as if this limit does not exist, that is not being finite. However, the main part of the proof is to show that there exist finite and well-behaved limits for all ingredients in (140).

Proof of Theorem 9: As in (A) spacetimes the quantity corresponding to $N_{A}$ in (140) may not have a limit at future null infinity along $C_{u}$ or not
have enough decay (that is the limit at future null infinity along $C_{u}$ of $\beta_{A}$ multiplied by corresponding weights in $r$ ), we investigate this now in detail. Use the Bianchi equation (57) for $D_{3} \beta$

$$
\begin{align*}
\not D_{3} \beta+\operatorname{tr} \underline{\chi} \beta & =\not \mathbb{D}_{1}^{*}(-\rho, \sigma)+2 \hat{\chi} \underline{\beta}+3 \zeta \rho+3^{*} \zeta \sigma+\underline{\nu} \beta+\underline{\xi} \alpha \\
& =\not \nabla \rho+\epsilon_{A B} \not 又^{B} \sigma+2 \hat{\chi} \underline{\beta}+\text { l.o.t. } \tag{141}
\end{align*}
$$

As the right hand side of (141) obeys good decay behavior (see section 3), we multiply it with $r^{4}$ and take the limit on a given $C_{u}$ as $r \rightarrow \infty$. Each of the components on the right hand side has a well-defined limit at $\mathcal{I}^{+}$. Therefore, it follows that the left hand side tends to a well-defined limit at $\mathcal{I}^{+}$. We call this limit $R(u, \theta, \phi)$ :

$$
\lim _{C_{u}, r \rightarrow \infty} r^{4}\left(\not D_{3} \beta+\operatorname{tr} \underline{\chi} \beta\right)=: R(u, \theta, \phi)
$$

And from (141) we obtain the limiting equation at $\mathcal{I}^{+}$

$$
\begin{equation*}
R=\not \nabla P+{ }^{*} \not \nabla Q+2 \Sigma \cdot \underline{B} . \tag{142}
\end{equation*}
$$

Note that equation (142) was derived in [9] and used in [7] but for different spacetimes, namely in those papers the leading order term of $\rho$ behaves differently as explained above, moreover $\not \nabla \rho$ decays in $u$. That is not the case for (A) spacetimes, for the latter are more general, in particular, the leading order term of $\rho$ includes more general terms and $\nabla \rho$ does not fall off in $u$. Further, we point out the different behavior of this spacetime outlined in the first part of the present article. Whereas the geometric quantities of the manifolds investigated in [9] and [7] either are directly controlled by the results of [13] or by a computation that can be related to quantities controlled by [13], this is not the case for (A) spacetimes. The latter can be controlled by results of [6]. In particular, various geometric quantities show rougher behavior, and it is not clear if the integrand of the integral in (140), involving quantities at $\mathcal{I}^{+}$, is defined in the (A) setting. In fact, the analogues of the estimates as in [9] or [7] would not work here because of these reasons just explained above. Here, we take a different approach and show that the integrand of the integral in (140) is well-defined for (A) spacetimes.

In the following, for a function $f$ on $S^{2}$ we write the projection of $f$ on the sum of the zeroth and first eigenspaces of $\not \Delta$ as $f_{[1]}$, and use $f_{l=0}$, $f_{l=1}$ for the corresponding projections on zeroth, respectively first eigenspace. Thus, $f_{[1]}=f_{l=0}+f_{l=1}$. Also, for a 1-form $r_{A}=\nabla_{A} f+\epsilon_{A B} \not \nabla^{B} g$ write $r_{A[1]}=\nabla_{A} f_{l=1}+\epsilon_{A B} \nabla^{B} g_{l=1}$.

Compute from (142), take the $l=1$ modes and integrate to obtain
(143) $\int_{u_{1}}^{u_{2}} R_{[1]} d u=\int_{u_{1}}^{u_{2}} \not \nabla P_{l=1} d u \int_{u_{1}}^{u_{2}}{ }^{*} \not \nabla Q_{l=1} d u+2 \int_{u_{1}}^{u_{2}}(\Sigma \cdot \underline{B})_{[1]} d u$

Let

$$
\begin{equation*}
\tilde{R}_{[1]}:=-\frac{1}{2} \int R_{[1]}(u) d u \tag{144}
\end{equation*}
$$

Then (in our sign convention for $u$ ) it is

$$
\begin{equation*}
\tilde{R}_{[1]}(u)-\tilde{R}_{[1]}^{+}=-\frac{1}{2} \int_{+\infty}^{u} R_{[1]}\left(u^{\prime}\right) d u^{\prime} \tag{145}
\end{equation*}
$$

Claim: In (143), each term on the right hand side (RHS) is integrable. This is straightforward for the last two terms.

In view of the last term on the RHS of (143) we know from theorem 1 and the statements therafter that $\Sigma \cdot \underline{B}=O\left(|u|^{-\frac{3}{2}}\right)$.

For the second term on the RHS of (143) we know from theorem 8 that $Q_{l=1}(u)=O\left(|u|^{-\frac{3}{2}}\right)$.

The integrability for the first term on the RHS of (143) follows directly from our theorem 8 above that gives $P_{l=1}(u)=O\left(|u|^{-\frac{3}{2}}\right)$. Note that this is a consequence of the $l=1$ modes behaving much better than $P$ itself. In particular, $\not \nabla P$ depending on $u$ but not decaying in $|u|$ may suggest on a first look that the integral diverges. However, using (75) and (77) in theorem 8 shows immediately that $P_{l=1}$ is integrable in $u$. This concludes the proof of theorem 9.

A Formula in the Direction of a Conservation Law of Angular Momentum: In a straightforward manner, we derive from the above the following formula:

$$
\begin{align*}
& \lim _{u \rightarrow+\infty}\left(\tilde{R}_{[1]}(u)-(\Sigma \cdot \operatorname{di} / v \Sigma)_{[1]}\right)-\lim _{u \rightarrow-\infty}\left(\tilde{R}_{[1]}(u)-(\Sigma \cdot \operatorname{di} / v \Sigma)_{[1]}\right) \\
& =\frac{1}{2} \int_{-\infty}^{+\infty}-\not \nabla_{A} P_{l=1}-\not \nabla^{*} Q_{l=1}+2(\Xi \cdot \operatorname{di} v \Sigma-\Sigma \cdot \operatorname{di} / v \Xi)_{[1]} d u \tag{146}
\end{align*}
$$

## 8. Weyl curvature behavior at future null infinity $\mathcal{I}^{+}$

### 8.1. Peeling stops

From the Bianchi equations (59) and (61) we derive the limiting equations at future null infinity $\mathcal{I}^{+}$for the limits $P$, respectively $Q$. They read

$$
\begin{align*}
\frac{\partial P}{\partial u} & =\frac{1}{2} \operatorname{div} \underline{B}-\Sigma \cdot \frac{\partial \Xi}{\partial u}  \tag{147}\\
\frac{\partial Q}{\partial u} & =\frac{1}{2} \operatorname{c\psi rl} \underline{B}-\Sigma \wedge \frac{\partial \Xi}{\partial u} \tag{148}
\end{align*}
$$

We observe that $P(\theta, \phi, u)$ at highest order does not have any power law decrease nor increase in $u$ as $|u| \rightarrow \infty$, but it depends on $u$ and changes with $u$. Then by these equations it must hold that

$$
\begin{equation*}
\frac{\partial P}{\partial u}=o\left(|u|^{-\frac{3}{2}}\right) . \tag{149}
\end{equation*}
$$

If we assume more decay, then we could also have

$$
\begin{equation*}
\frac{\partial P}{\partial u}=O\left(|u|^{-2}\right) . \tag{150}
\end{equation*}
$$

Recall equation (142) from above

$$
R=\not \nabla P+{ }^{*} \not \nabla Q+2 \Sigma \cdot \underline{B} .
$$

We obtain for $u R$ a behavior like $r^{-4}|u|^{+1}$, and correspondingly also for $\beta$ a behavior like $r^{-4}|u|^{+1}$. Thus, $\beta$ has less decay and the leading order term is dynamical.

## 9. Conclusions

Limits for $P(u, \theta, \phi)$ : Whereas $\sigma \rightarrow 0$ as $|u| \rightarrow \infty$, this is not true for $\rho$. This has the following deep implications. The fact that there are no extra constraints, other than by the constraint equations, put on the part of the initial metric that is homogeneous of degree -1 , means that the leading order $O\left(r^{-3}\right)$ portion of $\rho$ is dynamical, that is it depends on $u$. Namely, the constraint equation (24) and the conditions on the initial data give (28)

$$
\bar{R}=|k|^{2}=o\left(r^{-5}\right),
$$

yielding the fact stated in (30) which reads

$$
\partial_{i} \partial_{j} h_{i j}-\partial_{j} \partial_{j} h_{i i}=0 .
$$

Thus, the homogeneous of degree -3 part of $\bar{R}$ vanishes. See equations (28)(30) in chapter 2.

In general, this dynamical term of $\rho$ will take different limits at $\mathcal{I}^{+}$when $u \rightarrow+\infty$, respectively $u \rightarrow-\infty$. These yield (151).

$$
\begin{equation*}
P(u, \theta, \phi) \rightarrow P^{+}(\theta, \phi) \quad \text { as } \quad u \rightarrow+\infty \tag{151}
\end{equation*}
$$

In particular, the limit $P^{+}(\theta, \phi)$ is not a constant but rather a function on $S^{2}$ 。

## Appendix A. Integrals at spacelike infinity

In this appendix, we show that: The following limiting integrals are independent from the exhaustion and therefore coincide

$$
\begin{equation*}
\int_{S^{2}} P^{+}(\theta, \phi) \cdot \not \nabla_{A} \xi^{A}=\int_{S^{2}} P_{H_{0}}(\theta, \phi) \cdot \not \nabla_{A} \xi^{A} \quad \forall \xi^{A} \tag{152}
\end{equation*}
$$

First, consider $H_{0}$. Let $B_{n}$ be domains in $H_{0}$ such that $B_{n+1} \supset B_{n}$ and $\cup_{n} B_{n}=H_{0}$ with $S_{n}=\partial B_{n}$. (Naturally the $S_{n}$ are $C^{1}$.) Then from (98)-(99) we know that

$$
\lim _{H_{0}, n \rightarrow \infty} r \int_{S_{n}} \rho \cdot \not \nabla_{B} \xi^{B}=\int_{S^{2}} P_{H_{0}}(\theta, \phi) \cdot \not \nabla_{B} \xi^{B} \quad \forall \xi^{B}
$$

Now, we consider two domains $B_{2} \supset B_{1}$ in $H_{0}$ and such that $B_{1}$ contains the coordinate ball of radius $R$. We obtain

$$
\begin{equation*}
\int_{S_{2}} \rho \cdot \not \nabla_{B} \xi^{B}-\int_{S_{1}} \rho \cdot \not \nabla_{B} \xi^{B}=\int_{B_{2} \backslash B_{1}} \partial_{i}\left(\rho \cdot \not \nabla_{B} \xi^{B}\right) \tag{153}
\end{equation*}
$$

From above we know that the integrand on the right hand side is $O\left(r^{-4}\right)$. Therefore, we conclude that

$$
\begin{equation*}
\int_{B_{2} \backslash B_{1}} \partial_{i}\left(\rho \cdot \not \nabla_{B} \xi^{B}\right) \leq C R^{-1} \rightarrow 0 \text { as } R \rightarrow \infty \tag{154}
\end{equation*}
$$

Thus the limit does not depend on the exhaustion.

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Next, consider $\mathcal{I}^{+}$. From (101)-(102) we know that

$$
\begin{gathered}
\lim _{C_{u}, r \rightarrow \infty} r \int_{S_{r}} \rho \cdot \not \nabla_{B} \xi^{B}=\int_{S^{2}} P(u, \theta, \phi) \cdot \not \nabla_{B} \xi^{B}=: \mathcal{A}(u) . \\
\lim _{u \rightarrow \infty} \int_{S^{2}} P(u, \theta, \phi) \cdot \not \nabla_{B} \xi^{B}=\int_{S^{2}} P^{+}(\theta, \phi) \cdot \not \nabla_{B} \xi^{B} .
\end{gathered}
$$

Let $u_{2}>u_{1}$. Eventually, we will let both $u_{1}, u_{2} \rightarrow+\infty$. A short computation shows that it is

$$
\begin{equation*}
\mathcal{A}\left(u_{2}\right)-\mathcal{A}\left(u_{1}\right)=\int_{u_{1}}^{u_{2}} \int_{S^{2}} \frac{\partial}{\partial u} P \cdot \not \nabla_{B} \xi^{B} \tag{155}
\end{equation*}
$$

And we know from above that $\frac{\partial}{\partial u} P=O\left(|u|^{-\frac{3}{2}}\right)$ as $|u| \rightarrow \infty$. Thus, we conclude that

$$
\begin{equation*}
\int_{u_{1}}^{u_{2}} \int_{S^{2}} \frac{\partial}{\partial u} P \cdot \not \nabla_{B} \xi^{B} \rightarrow 0 \text { as } u \rightarrow \infty \tag{156}
\end{equation*}
$$

Thus the limit does not depend on the exhaustion either.
Next, we keep $u_{1}$ fixed in (155) and let $u_{2} \rightarrow \infty$. Then in $H_{0}$ the surface $S_{0, u_{2}}$ tends to infinity. Thus, as the limit from (98)-(99) in $H_{0}$ does not depend on the foliation $\left\{S_{r}\right\}$, we may pick the foliation given by $S_{0, u_{2}}=C_{u_{2}} \cap H_{0}$ as $u_{2} \rightarrow \infty$. Then equation (152) follows from equations (155) and (156).

## Appendix B. Notation

We relate the Christodoulou-Klainerman notation to the Bondi-Sachs coordinate system. For a nice derivation of further components, see [7]. But note that we use slightly different conventions in the current article than is used in the latter paper. In the following, the left hand side is given in the Christodoulou-Klainerman notation:

$$
\begin{aligned}
B_{A} & =-N_{A}=-I_{A} \\
\underline{B}_{A} & =\not \nabla^{B} N_{A B} \\
\underline{A}_{A B} & =-2 \partial_{u} N_{A B} \\
\Sigma_{A B} & =-\frac{1}{2} C_{A B} \\
\Xi_{A B} & =-\frac{1}{2} N_{A B} .
\end{aligned}
$$

## Appendix C. Hodge theory at future null infinity

The following Hodge systems and results from Hodge theory are frequently used in this article. In particular, this is in connection with the equations (114) and (119), as well as (115) and (120).

Let $Z$ be a sufficiently smooth vector field on $S^{2}$. There exist scalar fields $\varphi$ and $\psi$ such that

$$
Z=\not \nabla \varphi+\not \nabla^{\perp} \psi
$$

Then we have

$$
\operatorname{di\psi } Z=\Delta \Delta \quad, \quad c \psi r l Z=\Delta \Delta \psi .
$$

Consider now the equations on $S^{2}$

$$
\begin{align*}
& \Delta \varphi=f,  \tag{157}\\
& \Delta \psi=g, \tag{158}
\end{align*}
$$

for sufficiently smooth functions $f, g$ with vanishing mean on $S^{2}$. By the Hodge theorem there exist smooth solutions to (157), respectively (158) that are unique up to an additive constant. In our article we consider the function $\varphi$ of vanishing mean of equation (157). Analogously for $\psi$ and equation (158), where applicable.

In this paper, we consider the situation for

$$
\begin{equation*}
\mathcal{Z}=\operatorname{div}\left(\Sigma^{-}-\Sigma^{+}\right) \tag{159}
\end{equation*}
$$

as well as

$$
\begin{equation*}
\mathcal{Z}=\operatorname{div}\left(\Sigma(u)-\Sigma^{+}\right) . \tag{160}
\end{equation*}
$$

The above equations determine $\left(\Sigma^{-}-\Sigma^{+}\right)$, respectively $\left(\Sigma(u)-\Sigma^{+}\right)$uniquely.

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