# A Gibbs sampler for estimating the graded item response model with Likert-scale data via the Pólya–Gamma distribution: a calculationally efficient data-augmentation scheme

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This paper reports the use of a highly effective Pólya-Gamma Gibbs sampling algorithm [32] based on auxiliary variables to estimate the parameters of the graded response model (GRM; [34]) that has been used widely in educational and psychological assessments. As its name suggests, the algorithm can be viewed as an extension of the traditional Gibbs sampling algorithm, overcoming the defect that the latter is ineffective for Bayesian non-conjugate models. By introducing auxiliary variables, non-conjugate models are transformed into conjugate ones, and posterior sampling is easier to implement with the help of the traditional Gibbs sampling algorithm. Also, the algorithm avoids the Metropolis-Hastings sampling algorithm's tedious adjustment of tuning parameters to achieve an appropriate acceptance probability. Two simulation studies are conducted, and data from the Sexual Compulsivity Scale are subjected to detailed analysis to further illustrate the proposed methodology.

KEYWORDS AND PHRASES: Auxiliary variables, Bayesian estimation methods, Graded response model, Item response theory, Pólya–Gamma Gibbs sampling algorithm.

#### 1. INTRODUCTION

In educational and psychological assessments, many researchers prefer to use surveys, questionnaires, and scales with Likert-type items that often consist of multiple, ordered response categories, such as "strongly disagree", "disagree", "undecided", "agree", and "strongly agree" ([7], [10], [35], [40]). To analyze these items with a polytomous format, various complex nonlinear item response theory (IRT) models have also been developed, such as the graded response model (GRM; [34]), nominal response model [8], rating scale model [3], partial credit model [26], generalized partial credit model [28], and sequential response model ([43], [44]). Of these

models, we focus on the GRM as the most widely used IRT model for ordinal polytomous response data in psychological measurements. However, parameter estimation has been a major concern in the application of the GRM. In fact, simultaneous estimations of items and examinee's latent ability result in statistical complexities in the estimation task.

Within the fully Bayesian framework, Markov-chain Monte Carlo (MCMC) methods are extremely general and flexible and have proved useful in parameter estimation and model comparisons. Bayesian procedures have been developed for dichotomous IRT models ([1], [6], [23], [25], [30], [31], [33], [37], [38], [39], [40], [47], [49], [50]), and the polytomous GRM ([2], [15], [23], [28], [46], [51]). In fact, two Bayesian methods are often used to estimate the parameters of the GRM. One is the Gibbs sampling algorithm ([17], [19], [42]) based on auxiliary variables to estimate the parameters of the GRM with probit link function ([2], [15], [23]), and the other is the Metropolis–Hastings (MH) sampling algorithm ([12], [13], [21], [27]) to estimate the parameters of the GRM with logit link function ([30], [31], [46]).

In the present study, an efficient Pólya-Gamma Gibbs sampling algorithm [32] in a fully Bayesian framework is proposed for estimating the parameters of the GRM. Compared with the traditional MH and Gibbs sampling algorithms, we analyze the advantages of the Pólya-Gamma Gibbs sampling algorithm from multiple perspectives. First, the Pólya–Gamma Gibbs sampling algorithm avoids the retrospective tuning in the MH sampling algorithm if either we do not know how to choose a proper tuning parameter or no value for the tuning parameter is appropriate. Second, the Pólya–Gamma Gibbs sampling algorithm can transform a non-conjugate model into a conjugate one by using augmented auxiliary variables, and posterior sampling is easier to implement with the help of the traditional Gibbs sampling algorithm. Third, the prior specifications and prior sensitivity are important aspects of Bayesian inferences [20]. In fact, the Pólya-Gamma Gibbs sampling algorithm is insensitive to the specification of prior distribution and can still obtain satisfactory results even if the improper or misspecification priors are adopted. For a discussion about

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different types of prior distributions, please see the supplementary material, http://intlpress.com/site/pub/files/supp/sii/2022/0015/0004/SII-2022-0015-0004-s001.pdf.

The rest of this paper is organized as follows. In Section 2, the GRM is presented to explain the polytomous item response data. In Section 3, we discuss how the Pólya–Gamma Gibbs sampling algorithm implement sampling on the GRM. In Section 4, we present two simulation examples that focus on the performance of the Pólya–Gamma Gibbs sampling algorithm in parameter recovery based on different sample sizes, and we present the accuracy of parameter estimation for the Pólya–Gamma Gibbs sampling algorithm and the MH sampling algorithm. In Section 5, the performance of the Pólya–Gamma Gibbs sampling algorithm in a practical situation is shown by means of an empirical example. Finally, some concluding remarks are presented in Section 6.

## 2. MODEL AND MODEL IDENTIFICATION

# 2.1 Graded response model

The GRM [34], is used to fit polytomous item response data. The probability that examinee i scores in category k on item j is modeled by the GRM as

(1)
$$P_{jk}(\theta_i) = p\left(Y_{ij} = k \mid \theta_i, a_j, \boldsymbol{b}_j\right) = \Psi_{i,k}^*(\theta_i) - \Psi_{i,k+1}^*(\theta_i).$$

In Eq. (1),  $Y_{ij}$  is the response of examinee i answering item j, where  $i=1,\ldots,N,\ j=1,\ldots,J,$  and  $k=0,1,\ldots,K.$   $\theta_i$  is the latent ability for examinee i.  $a_j$  is the discrimination parameter for item j, and  $\mathbf{b}_j$  is a (K+1)-dimensional vector of threshold parameters for item j, i.e.,  $\mathbf{b}_j=(b_{j,0},b_{j,1},b_{j,2},\ldots,b_{j,K})^{'}$ .  $\Psi_{j,k}^*(\theta_i)$  is the boundary probability for examinee i having a score larger or equal to k on item j, and the boundary curve is given by

(2) 
$$\Psi_{j,k}^{*}(\theta_{i}) = \frac{\exp\left(a_{j}\theta_{i} - b_{j,k}\right)}{1 + \exp\left(a_{i}\theta_{i} - b_{j,k}\right)},$$

where k = 0, ..., K,  $\Psi_{j,0}^{*}(\theta_{i}) = 1$ , and  $\Psi_{j,K}^{*}(\theta_{i}) = 0$ . Furthermore, the boundaries between the response categories are represented by an ordered vector of thresholds

(3) 
$$b_{j,0} < b_{j,1} < b_{j,2} < \dots < b_{j,k} < \dots < b_{j,K}$$

where  $b_{j,0} = -\infty$ ,  $b_{j,K} = +\infty$ . Therefore, in total there are K-1 threshold parameters and one discrimination parameter for each item.

## 2.2 Model identification

In Eq. (2), the linear parts of the GRM can be written as

$$a_i \theta_i - b_{ik}, k = 1, 2, \dots, K,$$

where we fix the mean population level of ability to zero to eliminate the trade-off between ability  $\theta$  and threshold

parameter b in location, i.e.,  $\mu_{\theta} = 0$ . Meanwhile, to eliminate the trade-off between ability  $\theta$  and discrimination parameter a in scale, we restrict the variance population level of ability to one, i.e.,  $\sigma_{\theta}^2 = 1$ . For a similar identification limitation method, see [9], [15], [16] and [24].

## 3. BAYESIAN ESTIMATION METHODS

# 3.1 Pólya-Gamma Gibbs sampling algorithm

[32] proposed a new data-augmentation strategy for fully Bayesian inference in logistic regression. The data-augmentation approach appeals to a new class of Pólya–Gamma distribution rather than the data-augmentation algorithm by [2] based on a truncated normal distribution. Next, we introduce the Pólya–Gamma distribution.

**Definition.** Let  $\{T_k\}_{k=1}^{+\infty}$  be a sequence of i.i.d. random variables from a Gamma distribution with parameters  $\lambda$  and 1, i.e.,  $T_k \sim \text{Gamma}(\lambda, 1)$ . A random variable W follows a Pólya–Gamma distribution with parameters  $\lambda > 0$  and  $\tau \in R$ , denoted  $W \sim \text{PG}(\lambda, \tau)$ , if

$$W \stackrel{D}{=} \frac{1}{2\pi} \sum_{k=1}^{+\infty} \frac{T_k}{\left(k - \frac{1}{2}\right)^2 + \frac{\tau^2}{4\pi^2}},$$

where  $\stackrel{D}{=}$  denotes equality in distribution. In fact, the Pólya-Gamma distribution is an infinite mixture of Gamma distributions, thereby providing the plausibility for sampling from such distributions. Within the Bayesian framework, in the method of auxiliary variables, realizations from a complicated distribution can be obtained by augmenting the auxiliary variables of interest by one or more additional variables such that the full conditional posterior distributions are tractable and easy to simulate from. Next, we give the full conditional posterior distribution based on the auxiliary variable  $Z_{ij}$ :

$$p(\mathbf{Z} | \mathbf{a}, \mathbf{b}, \boldsymbol{\theta}, \mathbf{W}, \mathbf{Y})$$

$$\propto p(\mathbf{Z} | \mathbf{a}, \boldsymbol{\theta}) p(\mathbf{Y} | \mathbf{b}, \mathbf{Z}, \mathbf{W})$$

$$\propto \prod_{i=1,j=1}^{N} \left\{ f(Z_{ij}) \sum_{k=1}^{K} I(Y_{ij} = k) I(b_{j,k-1} < Z_{ij} \le b_{j,k}) \right\}$$

$$\propto \prod_{i=1,j=1}^{N} \left\{ \frac{\exp(-Z_{ij} + a_{j}\theta_{i})}{[1 + \exp(-Z_{ij} + a_{j}\theta_{i})]^{2}}$$

$$\times \sum_{k=1}^{K} I(Y_{ij} = k) I(b_{j,k-1} < Z_{ij} \le b_{j,k}) \right\}$$

$$\propto \prod_{i=1,j=1}^{N} \left\{ \left(\frac{1}{2}\right)^{2} \int_{0}^{+\infty} \exp\left[-\frac{W_{ij}(-Z_{ij} + a_{j}\theta_{i})^{2}}{2}\right] p(W_{ij}) dW_{ij}$$

$$\times \sum_{k=1}^{K} I(Y_{ij} = k) I(b_{j,k-1} < Z_{ij} \le b_{j,k}) \right\},$$

where the indicator function I(A) equals 1 if A is true or 0 if A is false.  $p(W_{ij})$  is  $p(W_{ij}; \beta=2, d=0)$ , where  $p(W; \beta=2, d=0)$  denotes the density of the auxiliary random variable  $W \sim \text{PG}(\beta=2, d=0)$ . The last inequality can be obtained by the Pólya–Gamma method [36], which is useful when working with logistic likelihoods, and has the form

$$\frac{\left[\exp\left(\psi\right)\right]^{\eta}}{\left[1 + \exp\left(\psi\right)\right]^{\beta}} = \left(\frac{1}{2}\right)^{\beta} \exp\left(\kappa\psi\right) \int_{0}^{+\infty} \exp\left(-\frac{W\beta^{2}}{2}\right) p\left(W;\beta,0\right) dW,$$

where  $\kappa = \eta - \frac{\beta}{2}$ . The specific expression of  $p(W; \beta, d)$  is

$$p(W; \beta, d) = \left\{ \cosh^{\beta} \left( \frac{d}{2} \right) \right\} \frac{2^{\beta - 1}}{\Gamma(\beta)}$$

$$\times \sum_{m=1}^{+\infty} \left\{ \frac{(-1)^m \Gamma(m + \beta) (2m + \beta)}{\Gamma(m + 1) \sqrt{2\pi W^3}} \right\}$$

$$\times \exp \left[ -\frac{(2m + \beta)^2}{8W} - \frac{W d^2}{2} \right],$$

where cosh denotes the hyperbolic cosine. Then the joint posterior distribution of  $Z_{ij}$  and  $W_{ij}$  is

$$\begin{split} & p\left(\boldsymbol{Z}, \boldsymbol{W} \mid \boldsymbol{a}, \boldsymbol{b}, \boldsymbol{\theta}, \boldsymbol{Y}\right) \\ & \propto \prod_{i=1}^{N} \prod_{j=1}^{J} \left\{ \left(\frac{1}{2}\right)^{2} \exp\left[-\frac{W_{ij}\left(-Z_{ij} + a_{j}\theta_{i}\right)^{2}}{2}\right] \\ & \times p\left(W_{ij}; \beta = 2, d = 0\right) \sum_{k=1}^{K} \operatorname{I}\left(Y_{ij} = k\right) \operatorname{I}\left(b_{j,k-1} < Z_{ij} \leq b_{j,k}\right) \right\}. \end{split}$$

Therefore, the full conditional posterior distribution of the auxiliary variable  $Z_{ij}$  is a truncated normal distribution, i.e.,

$$\begin{split} &Z_{ij} \mid W_{ij}, a_j, \theta_i, \boldsymbol{b}_j, Y_{ij} = k \\ &\sim N \left( a_j \theta_i, \ \frac{1}{W_{ij}} \right) \mathbf{I} \left( b_{j,k-1} < Z_{ij} \le b_{j,k} \right). \end{split}$$

We use the inverse transform technique to sample the auxiliary variable  $Z_{ij}$  based on the truncated normal distribution. First, we sample the random variable  $U_{ij}$  from a uniform distribution, i.e.,  $U_{ij} \sim \text{Uniform}(0,1)$ . When the response  $Y_{ij} = k$ , the following equation can be established:

$$U_{ij} = \frac{\Phi\left[\sqrt{W_{ij}}\left(Z_{ij} - a_j\theta_i\right)\right] - \Phi\left[\sqrt{W_{ij}}\left(b_{j,k-1} - a_j\theta_i\right)\right]}{\Phi\left[\sqrt{W_{ij}}\left(b_{j,k} - a_j\theta_i\right)\right] - \Phi\left[\sqrt{W_{ij}}\left(b_{j,k-1} - a_j\theta_i\right)\right]},$$

or equivalently

$$\begin{split} Z_{ij} \\ &= \Phi^{-1} \Big\{ U_{ij} \left\{ \Phi \left[ \sqrt{W_{ij}} \left( b_{j,k} - a_j \theta_i \right) \right] \right. \\ &\left. - \Phi \left[ \sqrt{W_{ij}} \left( b_{j,k-1} - a_j \theta_i \right) \right] \right\} \\ &+ \Phi \left[ \sqrt{W_{ij}} \left( b_{j,k-1} - a_j \theta_i \right) \right] \Big\} \times \frac{1}{\sqrt{W_{ij}}} + a_j \theta_i, \end{split}$$

where  $\Phi(\bullet)$  is a normal cumulative distribution with mean 0 and variance 1. The full conditional posterior distribution of the auxiliary variable  $W_{ij}$  is

$$p\left(W_{ij} \mid Z_{ij}, a_j, \theta_i\right)$$

$$\propto \left(\frac{1}{2}\right)^2 \exp\left[-\frac{W_{ij} \left(-Z_{ij} + a_j \theta_i\right)^2}{2}\right] p\left(W_{ij}; \beta = 2, d = 0\right).$$

Based on [32], we obtain

$$W_{ij} | Z_{ij}, a_j, \theta_i \sim PG(2, -Z_{ij} + a_j \theta_i).$$

Next, we update the discrimination parameter  $a_j$  for each item j in the GRM. The prior of  $a_j$  is assumed to follow a truncated normal distribution, i.e.,  $a_j \sim N\left(\mu_a, \sigma_a^2\right) I\left(a_j > 0\right)$ . The full conditional posterior distribution of the discrimination parameter  $a_j$  is

$$\prod_{i=1}^{N} \left\{ \exp\left[ -\frac{W_{ij} \left( -Z_{ij} + a_{j} \theta_{i} \right)^{2}}{2} - \frac{\left( a_{j} - \mu_{a} \right)^{2}}{2 \sigma_{a}^{2}} \right] \right\} \mathbf{I} \left( a_{j} > 0 \right).$$

Therefore, the full conditional posterior distribution of  $a_j$  follows a truncated normal distribution with mean

$$\operatorname{Var}_{a_{j}} \times \left( \mu_{a} \sigma_{a}^{-2} + \left( \sum_{i=1}^{N} \theta_{i}^{2} W_{ij} \right) \left[ \frac{\left( \sum_{i=1}^{N} \theta_{i} Z_{ij} W_{ij} \right)}{\left( \sum_{i=1}^{N} \theta_{i}^{2} W_{ij} \right)} \right] \right)$$

and variance

$$\operatorname{Var}_{a_j} = \left(\sigma_a^{-2} + \left(\sum_{i=1}^N \theta_i^2 W_{ij}\right)\right)^{-1}.$$

Similarly, we update the ability parameter  $\theta_i$  for each examinee i. The prior distribution of  $\theta_i$  is assumed to follow a normal distribution with mean  $\mu_{\theta}$  and variance  $\sigma_{\theta}^2$ . The full conditional posterior distribution of the discrimination parameter  $\theta_i$  is

$$\prod_{j=1}^{J} \left\{ \exp \left[ -\frac{W_{ij} \left( -Z_{ij} + a_j \theta_i \right)^2}{2} - \frac{\left( \theta_i - \mu_\theta \right)^2}{2\sigma_\theta^2} \right] \right\}.$$

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Therefore, the full conditional posterior distribution of  $\theta_i$  follows a normal distribution with mean

$$\operatorname{Var}_{\theta_{i}} \times \left( \mu_{\theta} \sigma_{\theta}^{-2} + \left( \sum_{j=1}^{J} a_{j}^{2} W_{ij} \right) \left[ \frac{\left( \sum_{j=1}^{J} a_{j} Z_{ij} W_{ij} \right)}{\left( \sum_{j=1}^{J} a_{j}^{2} W_{ij} \right)} \right] \right)$$

and variance

$$\operatorname{Var}_{\theta_i} = \left(\sigma_{\theta}^{-2} + \left(\sum_{j=1}^{J} a_j^2 W_{ij}\right)\right)^{-1}.$$

In fact, two methods are often used to update the threshold parameters. One is the Gibbs sampling algorithm based on auxiliary variables to draw the posterior samples from a uniform distribution ([2], [15], [41]). The specific implementation process is to derive the full conditional distribution using a conjugate prior that takes the order constraint in Eq. (3) into account. Define a uniformly distributed variable  $V_{ij}$  over [0, 1] such that

$$V_{ij} \leq p\left(Z_{ij} \leq b_{j,k} \mid \boldsymbol{Y}, \boldsymbol{b}_{j}, \theta_{i}, a_{j}\right) I\left(i \in \Delta_{1}\right),$$
  

$$V_{ij} > p\left(Z_{ij} > b_{j,k} \mid \boldsymbol{Y}, \boldsymbol{b}_{j}, \theta_{i}, a_{j}\right) I\left(i \in \Delta_{2}\right),$$

where the set  $\Delta_1 = \{i : Y_{ij} = k\}$  and the set  $\Delta_2 = \{i : Y_{ij} = k + 1\}$ . Accordingly, the full conditional distribution of  $b_{j,k}$  is uniform using a diffuse prior with equal probability for each possible parameter value, i.e.,

$$b_{j,k} | \boldsymbol{Z}, \boldsymbol{b}_{j,(-k)}, \boldsymbol{\theta}_i, a_j \sim \text{Uniform} (\Omega_L, \Omega_U),$$

where  $\Omega_L = \max\left(\max_{i:Y_{ij}=k} Z_{ij}, b_{j,k-1}\right)$ ,  $\Omega_U = \min\left(\min_{i:Y_{ij}=k+1} Z_{ij}, b_{j,k+1}\right)$ , and  $\boldsymbol{b}_{j,(-k)}$  is the set of threshold parameters for item j without  $b_{j,k}$ . In fact, any prior distribution for  $b_{j,k}$  can be used as long as the values sampled from it satisfy a reasonable range of parameter support set, i.e.,

$$b_{j,k} \mid \mathbf{Z}, \mathbf{b}_{j,(-k)}, \boldsymbol{\theta}_i, a_j \sim f_{prior}(b_{j,k}) \operatorname{I}(\Omega_L, \Omega_U),$$

where  $\Omega_L$  and  $\Omega_U$  are respectively the upper and lower bounds of the truncated prior distribution  $f_{prior}\left(b_{j,k}\right)$ . The R code for implementing the Pólya–Gamma Gibbs sampling algorithm is given in the supplementary material, http://intlpress.com/site/pub/files/\_supp/sii/2022/0015/0004/SII-2022-0015-0004-s001.pdf.

#### 4. SIMULATION STUDIES

#### 4.1 Simulation 1

This simulation study was conducted to evaluate the recovery performance of the combined MCMC sampling algorithm based on different simulation conditions.

#### Simulation designs

The following manipulated conditions were considered: (a) three-point, four-point, and five-point Likert-type response scales, i.e., K = 3, 4, 5; (b) test length J = 20, 30, 40; (c) number of examinees N = 500, 1000, 2000. Fully crossing the different levels of these three factors yields 27 conditions (3 response scales  $\times$  3 test lengths  $\times$  3 sample sizes). For the GRMs, true values of item discrimination parameters  $a_i$  were generated from a uniform distribution [29], i.e.,  $a_i \sim \text{Uniform}(0.5, 1.5), j = 1, 2, \dots, J.$  It is known that the values of threshold parameters usually lie between -3 and 3 ([4], [5], [29]), i.e., (i) when K = 3,  $b_{i1} \sim \text{Uniform}(-3,0)$ and  $b_{j2} \sim \text{Uniform}(0,3), j = 1,2,...,J;$  (ii) when K =4,  $b_{j1} \sim \text{Uniform}(-3, -1), b_{j2} \sim \text{Uniform}(-1, 1), \text{ and}$  $b_{j3} \sim \text{Uniform}(1,3), j = 1,2,...,J; (iii) \text{ when } K = 5,$  $b_{j1} \sim \text{Uniform}(-3, -1.5), b_{j2} \sim \text{Uniform}(-1.5, 0), b_{j3} \sim$ Uniform (0, 1.5), and  $b_{j4} \sim \text{Uniform } (1.5, 3), j = 1, 2, ..., J$ . The true values of ability parameter were generated from a standard normal distribution. The polytomous item response data were generated from the GRM.

#### Prior distributions

The prior distributions of the GRM parameters for different response categories were set as follows. We used noninformative prior distributions for the item parameters, i.e.,  $a_j \sim N(0, 10^5) I(0, +\infty);$  (i)  $b_{j1} \sim N(0, 10^5) I(-3, 3)$  and  $b_{j2} \sim N(0, 10^5) I(b_{j1}, 3);$  (ii)  $b_{j1} \sim N(0, 10^5) I(-3, 3),$  $b_{j2} \sim N(0, 10^5) I(b_{j1}, 3)$ , and  $b_{j3} \sim N(0, 10^5) I(b_{j2}, 3)$ ; (iii)  $b_{j1} \sim N(0, 10^5) I(-3, 3), b_{j2} \sim N(0, 10^5) I(b_{j1}, 3),$  $b_{i3} \sim N(0, 10^5) I(b_{i2}, 3)$ , and  $b_{i4} \sim N(0, 10^5) I(b_{i3}, 3)$ . The prior of ability parameters was assumed to follow a standardized normal distribution. We considered 25 replications in each simulation condition. This choice was based on previous research in educational psychological assessments; for example, [45] used 10 replications for each simulation condition, and [48] used 30. In fact, in the present study, the accuracy of parameter estimation was guaranteed in 25 replications. If we were to consider too many replications, then it would be difficult to check the  $\hat{R}$  values (potential scale reduction factor (PSRF, [11]) calculated from each simulated dataset (replication) to ensure the parameter convergence. The work becomes huge when the simulated conditions increase.

# Convergence diagnostics

To evaluate the convergence of parameter estimations, as an illustration, we consider only the case in which the response scale involves three-point Likert-type response data, the test length is fixed at 30, and there are 1000 examinees. We used two methods to check the convergence of our algorithm. One was the "eyeball" method of monitoring the convergence by visually inspecting the history plots of the generated sequences, and the other was the Gelman–Rubin method ([11], [18]) for checking the convergence of the parameters.

The convergence of the Bayesian algorithm was checked by monitoring the trace plots of the parameters for consecutive sequences of 20000 iterations. The first 10000 iterations

Table 1. Accuracy of parameters based on four different simulated conditions in simulation study 1

				3-Point Like	rt-Type Re	sponse Scale				
	Test Length 20			T	Test Length 30			Test Length 40		
Sample Size	500	1000	2000	500	1000	2000	500	1000	2000	
Bias										
$\boldsymbol{a}$	-0.018	-0.026	-0.021	0.014	-0.012	-0.026	-0.004	-0.012	-0.014	
$\boldsymbol{b}_{\bullet 1}$	-0.005	-0.022	0.009	-0.011	0.006	-0.003	-0.012	0.005	-0.006	
$\boldsymbol{b_{\bullet 2}}$	-0.000	-0.025	0.002	-0.002	0.000	-0.002	0.003	0.013	-0.013	
RMSE										
$oldsymbol{a}$	0.144	0.100	0.077	0.137	0.094	0.077	0.144	0.104	0.070	
$\boldsymbol{b}_{\bullet 1}$	0.118	0.089	0.063	0.118	0.083	0.054	0.130	0.089	0.070	
$\boldsymbol{b_{\bullet 2}}$	0.122	0.094	0.063	0.130	0.089	0.063	0.141	0.089	0.077	
$\operatorname{SD}$										
$\boldsymbol{a}$	0.136	0.096	0.067	0.132	0.092	0.064	0.131	0.092	0.064	
$\boldsymbol{b}_{\bullet 1}$	0.102	0.072	0.049	0.101	0.071	0.049	0.108	0.075	0.052	
$\boldsymbol{b_{\bullet 2}}$	0.106	0.073	0.051	0.110	0.077	0.052	0.114	0.079	0.054	
SE										
$\boldsymbol{a}$	0.140	0.094	0.069	0.132	0.093	0.068	0.140	0.101	0.066	
$\boldsymbol{b}_{\bullet 1}$	0.110	0.084	0.064	0.113	0.081	0.058	0.119	0.086	0.067	
$\boldsymbol{b_{\bullet 2}}$	0.114	0.086	0.064	0.124	0.085	0.064	0.135	0.088	0.073	
$\overline{\mathrm{CP}}$										
$\boldsymbol{a}$	0.940	0.942	0.902	0.941	0.937	0.989	0.915	0.912	0.913	
$\boldsymbol{b}_{\bullet 1}$	0.988	0.987	0.981	0.989	0.989	0.984	0.989	0.988	0.981	
$\boldsymbol{b_{\bullet 2}}$	0.989	0.983	0.984	0.989	0.989	0.984	0.988	0.989	0.980	

Note that the Bias, RMSE, SD, SE and CP denote the average Bias, RMSE, SD, SE and CP for the item parameters.  $\boldsymbol{a}$  represents all discrimination parameters,  $\boldsymbol{b}_{\bullet 1}$  represents all  $b_{j1}$   $(j=1,\ldots,J.)$ , and  $\boldsymbol{b}_{\bullet 2}$  represents all  $b_{j2}$   $(j=1,\ldots,J.)$ .

were set as the burn-in period. As an illustration, four chains started at overdispersed starting values were run for each replication. The trace plots and posterior histograms for randomly selected item parameters are shown in the supplementary material, <a href="http://intlpress.com/site/pub/files/\_supp/sii/2022/0015/0004/SII-2022-0015-0004-s001">http://intlpress.com/site/pub/files/\_supp/sii/2022/0015/0004/SII-2022-0015-0004-s001</a>. pdf, where the posterior histograms are based on 10000 simulated values after a 10000 burn-in period. In addition, the PSRF values of all item parameters were less than 1.2. Accuracy evaluation criteria

The accuracy of the parameter estimates was measured using four evaluation criteria, i.e., bias, root mean squared error (RMSE), standard deviation (SD), standard error (SE), and coverage probability of the 95% highest posterior density (HPD) intervals (CP). Let  $\eta$  be the parameter of interest. Assume that M=25 data sets were generated. Also, let  $\widehat{\eta}^{(m)}$  and  $\mathrm{SD}^{(m)}(\eta)$  denoted the posterior mean and the posterior standard deviation of  $\eta$  obtained from the mth simulated data set for  $m=1,\ldots,M$ . The bias for the parameter is defined as  $\mathrm{Bias}(\eta)=\frac{1}{M}\sum_{m=1}^{M}\left(\widehat{\eta}^{(m)}-\eta\right)$ . The RMSE for the parameter is defined as RMSE  $(\eta)=\sqrt{\frac{1}{M}\sum_{m=1}^{M}\left(\widehat{\eta}^{(m)}-\eta\right)^2}$ . The simulation SE is the square root of the sample variance of the posterior estimates over different simulated data sets and is defined as

Simulation 
$$SE(\eta) = \sqrt{\frac{1}{M} \sum_{m=1}^{M} \left( \widehat{\eta}^{(m)} - \frac{1}{M} \sum_{\ell=1}^{M} \widehat{\eta}^{(\ell)} \right)^2},$$

the average of the posterior standard deviation is defined as

$$SD(\eta) = \frac{1}{M} \sum_{m=1}^{M} SD^{(m)}(\eta),$$

and the coverage probability is defined as

 $CP(\eta)$ 

=  $\frac{\text{\# of 95\% HPD intervals containing } \eta \text{ in } M \text{ simulated data sets}}{M}$ 

## Recovery of item parameters

The average bias, RMSE, SD, SE, and CP for item parameters based on 27 different simulation conditions are given in Tables 1, 2, and 3. The following conclusions can be drawn. 1) Given the total test length and response scale, when the number of individuals increases from 500 to 2000, the average RMSE, SD, and SE for discrimination and threshold parameters decrease. For example, for a total test length of 20 items and a fixed three-point Likert response scale, when the number of examinees increases from 500 to 2000, the average RMSE of all discrimination parameters decreases from 0.144 to 0.077, the average SD of all discrimination parameters decreases from 0.136 to 0.067, and the average SE of all discrimination parameters decreases from 0.140 to 0.069. For the threshold parameters, the average RMSE of all  $b_{i1}$  (j = 1, ..., 20) parameters decreases from 0.118 to 0.063, the average SD of all  $b_{i1}$  (j = 1, ..., 20) parameters decreases from 0.102 to 0.049, and the average SE of all  $b_{j1}$  (j = 1, ..., 20) parameters decreases from 0.110 to

Table 2. Accuracy of parameters based on the different simulated conditions in simulation study 1

				4-Point Lik	ert-Type Re	esponse Scale				
	T	est Length 2	20	r	Test Length	30	Т	Test Length 40		
Sample Size	500	1000	2000	500	1000	2000	500	1000	2000	
Bias										
$\boldsymbol{a}$	-0.006	-0.018	-0.030	0.003	-0.019	-0.026	0.008	-0.016	-0.013	
$\boldsymbol{b}_{\bullet 1}$	-0.040	0.009	0.019	0.018	-0.010	0.006	-0.020	-0.012	-0.004	
$\boldsymbol{b}_{\bullet 2}$	-0.021	0.011	0.017	0.027	-0.004	0.005	0.003	-0.003	-0.003	
$oldsymbol{b_{ullet 3}}$	0.005	0.012	0.008	0.049	0.000	-0.002	0.027	0.004	-0.001	
RMSE										
$\boldsymbol{a}$	0.126	0.100	0.070	0.130	0.100	0.070	0.130	0.089	0.063	
$\boldsymbol{b}_{\bullet 1}$	0.158	0.114	0.083	0.126	0.100	0.070	0.126	0.094	0.063	
$\boldsymbol{b}_{\bullet 2}$	0.122	0.089	0.063	0.104	0.083	0.054	0.104	0.077	0.054	
$oldsymbol{b_{ullet 3}}$	0.118	0.094	0.077	0.141	0.100	0.070	0.126	0.094	0.063	
SD										
$\boldsymbol{a}$	0.119	0.084	0.059	0.117	0.082	0.057	0.117	0.082	0.058	
$\boldsymbol{b}_{\bullet 1}$	0.131	0.090	0.061	0.114	0.082	0.056	0.110	0.078	0.053	
$\boldsymbol{b}_{\bullet 2}$	0.098	0.069	0.047	0.093	0.066	0.045	0.093	0.066	0.045	
$oldsymbol{b_{ullet 3}}$	0.106	0.078	0.054	0.120	0.083	0.058	0.111	0.078	0.053	
SE										
$\boldsymbol{a}$	0.122	0.095	0.066	0.125	0.093	0.063	0.128	0.083	0.064	
$\boldsymbol{b}_{\bullet 1}$	0.145	0.107	0.076	0.114	0.096	0.069	0.113	0.089	0.060	
$\boldsymbol{b}_{\bullet 2}$	0.114	0.084	0.063	0.095	0.078	0.057	0.098	0.074	0.056	
$oldsymbol{b_{ullet 3}}$	0.114	0.092	0.073	0.126	0.092	0.069	0.113	0.088	0.061	
CP										
$\boldsymbol{a}$	0.926	0.987	0.985	0.982	0.989	0.989	0.922	0.925	0.989	
$\boldsymbol{b}_{\bullet 1}$	0.987	0.986	0.981	0.984	0.986	0.982	0.926	0.988	0.987	
$\boldsymbol{b}_{\bullet 2}$	0.985	0.986	0.978	0.985	0.986	0.982	0.936	0.988	0.984	
$oldsymbol{b_{ullet 3}}$	0.989	0.986	0.980	0.983	0.988	0.985	0.928	0.988	0.986	

Note that the Bias, RMSE, SD, SE and CP denote the average Bias, RMSE, SD, SE and CP for the item parameters.  $\boldsymbol{a}$  represents all discrimination parameters,  $\boldsymbol{b}_{\bullet 1}$  represents all  $b_{j1}$   $(j=1,\ldots,J.)$ ,  $\boldsymbol{b}_{\bullet 2}$  represents all  $b_{j2}$   $(j=1,\ldots,J.)$  and  $\boldsymbol{b}_{\bullet 3}$  represents all  $b_{j3}$   $(j=1,\ldots,J.)$ .

0.064. The average RMSE of all  $b_{j2}$  (j = 1, ..., 20) parameters decreases from 0.122 to 0.063, the average SD of all  $b_{i2}$   $(j=1,\ldots,20)$  parameters decreases from 0.106 to 0.051, and the average SE of all  $b_{j2}$  (j = 1, ..., 20) parameters decreases from 0.114 to 0.064. 2) Under the 27 simulated conditions, the average CPs of the discrimination and threshold parameters are about 0.970. 3) When the number of examinees is fixed at 500 (1000 or 2000), the Likert response scale is fixed at three points (four or five points), and the number of items is fixed at 20, the average RMSE, SD, and SE show that the recovery results of the discrimination and threshold parameters are close to those in the case that the total test length is 30 (40), which indicates that the Bayesian algorithm is stable and does not reduce the accuracy because of the increase in the number of items. In summary, the Pólya-Gamma Gibbs sampling algorithm provides accurate estimates of the item parameters in terms of various numbers of examinees and items.

#### Recovery of ability parameters

Next, we evaluate the recovery of the latent ability parameter using five accuracy evaluation criteria in Table 3. The following conclusions can be drawn from Table 4. 1) For 500 (1000 or 2000) examinees and the Likert response scale

fixed at three points (four or five points), when the number of items increases from 20 to 40, the average RMSE, SD, and SE for ability parameters decrease. 2) Under the 27 simulated conditions, the average CPs of the ability parameters are about 0.950. In summary, it is shown again that the Pólya–Gamma Gibbs sampling algorithm is effective and the estimates of the parameters are accurate under various simulation conditions.

#### 4.2 Simulation 2

In this simulation study, we compared the MH sampling algorithm and the Pólya–Gamma Gibbs sampling algorithm from two perspectives: accuracy and convergence.

### Simulation designs

In this simulation, the number of examinees was N=1000, a five-point Likert-type response scale was used, and the test length was J=40. The true values of the item and person parameters in the GRM were the same as those in simulation study 1. We specified the following non-informative priors to the MH and Pólya–Gamma Gibbs sampling algorithms, i.e.,  $a_j \sim N\left(0,10^5\right) I\left(0,+\infty\right)$ ,  $b_{j1} \sim N\left(0,10^5\right) I\left(-3,3\right)$ ,  $b_{j2} \sim N\left(0,10^5\right) I\left(b_{j1},3\right)$ ,  $b_{j3} \sim N\left(0,10^5\right) I\left(b_{j2},3\right)$ , and  $b_{j4} \sim N\left(0,10^5\right) I\left(b_{j3},3\right)$ , j=1

Table 3. Accuracy of parameters based on the different simulated conditions in simulation study 1

				5-Point Like	ert-Type Res	sponse Scale			
	Test Length 20			Т	est Length 3	30	Test Length 40		
Sample Size	500	1000	2000	500	1000	2000	500	1000	2000
Bias									
$\boldsymbol{a}$	-0.004	-0.009	-0.021	0.021	-0.018	-0.027	-0.000	-0.009	-0.010
$\boldsymbol{b}_{\bullet 1}$	-0.013	-0.009	0.005	-0.038	-0.022	-0.011	-0.039	-0.013	-0.009
$\boldsymbol{b_{\bullet 2}}$	0.001	-0.001	-0.002	-0.021	-0.020	-0.013	-0.019	-0.012	-0.011
$oldsymbol{b_{ullet 3}}$	0.019	0.006	-0.006	0.002	-0.012	-0.016	0.006	0.000	-0.012
$\boldsymbol{b_{\bullet 4}}$	0.047	0.011	-0.010	0.021	-0.008	-0.017	0.038	0.011	-0.010
RMSE									
$\boldsymbol{a}$	0.118	0.083	0.063	0.122	0.083	0.063	0.122	0.077	0.054
$oldsymbol{b_{ullet 1}}$	0.141	0.100	0.077	0.144	0.104	0.070	0.137	0.094	0.070
$\boldsymbol{b}_{\bullet 2}$	0.109	0.077	0.063	0.109	0.083	0.054	0.104	0.077	0.054
$oldsymbol{b_{ullet 3}}$	0.114	0.077	0.063	0.109	0.089	0.063	0.114	0.083	0.054
$\boldsymbol{b_{\bullet 4}}$	0.144	0.100	0.077	0.137	0.104	0.077	0.141	0.104	0.070
$\operatorname{SD}$									
$\boldsymbol{a}$	0.112	0.079	0.055	0.109	0.077	0.053	0.109	0.077	0.054
$\boldsymbol{b}_{\bullet 1}$	0.125	0.090	0.062	0.123	0.088	0.061	0.116	0.083	0.058
$\boldsymbol{b_{\bullet 2}}$	0.092	0.065	0.045	0.092	0.066	0.045	0.091	0.065	0.044
$oldsymbol{b_{ullet 3}}$	0.093	0.066	0.045	0.096	0.067	0.045	0.098	0.069	0.047
$\boldsymbol{b_{\bullet 4}}$	0.124	0.086	0.058	0.123	0.086	0.060	0.125	0.088	0.060
SE									
$\boldsymbol{a}$	0.114	0.083	0.059	0.116	0.083	0.055	0.118	0.076	0.055
$\boldsymbol{b_{\bullet 1}}$	0.131	0.096	0.074	0.129	0.097	0.071	0.119	0.087	0.065
$\boldsymbol{b}_{\bullet 2}$	0.102	0.071	0.058	0.102	0.078	0.057	0.094	0.074	0.055
$oldsymbol{b_{ullet 3}}$	0.103	0.073	0.059	0.102	0.082	0.057	0.105	0.080	0.056
$\boldsymbol{b_{\bullet 4}}$	0.125	0.094	0.071	0.125	0.098	0.071	0.126	0.097	0.066
CP									
$\boldsymbol{a}$	0.928	0.917	0.988	0.924	0.901	0.987	0.921	0.943	0.918
$\boldsymbol{b}_{\bullet 1}$	0.924	0.989	0.984	0.926	0.989	0.985	0.907	0.919	0.986
$\boldsymbol{b_{\bullet 2}}$	0.988	0.989	0.979	0.989	0.984	0.982	0.915	0.988	0.983
$\boldsymbol{b_{ullet 3}}$	0.988	0.989	0.978	0.985	0.984	0.983	0.908	0.988	0.984
$oldsymbol{b_{ullet 4}}$	0.918	0.989	0.981	0.925	0.988	0.984	0.937	0.989	0.987

Note that the Bias, RMSE, SD, SE and CP denote the average Bias, RMSE, SD, SE and CP for the item parameters.  $\boldsymbol{a}$  represents all discrimination parameters,  $\boldsymbol{b}_{\bullet 1}$  represents all  $b_{j1}$   $(j=1,\ldots,J)$ ,  $\boldsymbol{b}_{\bullet 2}$  represents all  $b_{j2}$   $(j=1,\ldots,J)$ ,  $\boldsymbol{b}_{\bullet 3}$  represents all  $b_{j3}$   $(j=1,\ldots,J)$  and  $\boldsymbol{b}_{\bullet 4}$  represents all  $b_{j4}$   $(j=1,\ldots,J)$ .

 $1,2,\ldots,40$ , and the prior of ability parameters was assumed to follow a standardized normal distribution because of the model identification limitation, i.e.,  $\theta_i \sim N\left(0,1\right)$ ,  $i=1,\ldots,1000$ . In fact, we know that an improper proposal distribution for the MH sampling algorithm can seriously reduce the acceptance probability of sampling, with most of the posterior samples being rejected. Therefore, low sampling efficiency is usually unavoidable, and the reduction in the number of valid samples may lead to incorrect inference results. In contrast, the Pólya–Gamma Gibbs sampling algorithm takes the acceptance probability as 1 to draw the samples from full conditional posterior distributions. The following proposal distributions for the discrimination, threshold, and ability parameters were considered in the process of implementing the MH sampling algorithm:

$$\begin{array}{l} \bullet \text{ Case 1: } a_{j}^{*} \sim N(a_{j}^{(r-1)},0.1), \ b_{j,k}^{*} \sim N\big(b_{j,k}^{(r-1)},0.1\big) \times \\ \mathrm{I}\big(b_{j,k-1}^{*} < b_{j,k}^{*} < b_{j,k+1}^{(r-1)}\big), \ j=1,\ldots,J. \ k=1,\ldots,K-1, \\ \text{and } \theta_{i}^{*} \sim N(\theta_{i}^{(r-1)},0.1), \ i=1,\ldots,N; \end{array}$$

• Case 2: 
$$a_j^* \sim N(a_j^{(r-1)}, 1), b_{j,k}^* \sim N(b_{j,k}^{(r-1)}, 1) \mathbf{I}(b_{j,k-1}^* < b_{j,k}^* < b_{j,k+1}^{(r-1)}), j = 1, ..., J. \ k = 1, ..., K-1,$$
and  $\theta_i^* \sim N(\theta_i^{(r-1)}, 1), \ i = 1, ..., N.$ 

To compare the convergence of all parameters for the MH sampling algorithm with different proposal distributions and the Pólya–Gamma Gibbs sampling algorithm, the convergence of item and person parameters was evaluated by judging whether the PSRF values were less than 1.2. Figure 1 shows that the discrimination and threshold parameters had already converged by 2000 iterations for the Pólya–Gamma Gibbs sampling algorithm. For the MH sampling algorithm, some parameters had not converged after 5000 iterations with the proposal distributions with a variance of 0.1. The convergence with the proposal distributions with a variance of 1 was worse than that with those with a variance of 0.1, with some parameters not even having converged after 8000 iterations. Moreover, the bias and RMSE are used to evaluate the performances of the two algorithms in Table 5. It

Table 4. Accuracy of person parameters based on four different simulated conditions in simulation study 1

Category	No. of examinees	No. of items	Bias	RMSE	SD	SE	CP
	500	20	0.004	0.313	0.295	0.279	0.943
		30	0.003	0.264	0.245	0.217	0.953
		40	0.000	0.225	0.210	0.192	0.963
	1000	20	-0.012	0.311	0.295	0.262	0.943
3		30	0.008	0.262	0.248	0.214	0.964
		40	0.011	0.221	0.210	0.199	0.963
	2000	20	0.009	0.309	0.294	0.276	0.940
		30	0.000	0.258	0.248	0.238	0.954
		40	-0.004	0.221	0.210	0.197	0.940
	500	20	-0.019	0.284	0.264	0.261	0.931
		30	0.015	0.236	0.223	0.242	0.963
		40	0.003	0.207	0.191	0.189	0.943
	1000	20	0.004	0.279	0.265	0.280	0.938
4		30	-0.009	0.236	0.225	0.243	0.953
		40	-0.001	0.202	0.193	0.218	0.973
	2000	20	0.010	0.277	0.266	0.277	0.944
		30	-0.000	0.232	0.225	0.232	0.984
		40	-0.000	0.202	0.192	0.185	0.963
	500	20	0.009	0.266	0.252	0.266	0.973
		30	-0.000	0.225	0.210	0.230	0.952
		40	0.008	0.197	0.181	0.195	0.953
	1000	20	0.002	0.266	0.253	0.241	0.943
5		30	-0.010	0.223	0.214	0.201	0.973
		40	0.004	0.192	0.182	0.178	0.963
	2000	20	-0.003	0.262	0.254	0.259	0.944
		30	-0.007	0.223	0.215	0.198	0.954
D: DMGE		40	-0.001	0.189	0.182	0.175	0.953

Note that the Bias, RMSE, SD, SE and CP denote the average Bias, RMSE, SD, SE and CP for the ability parameters.

Table 5. Accuracy of parameter estimation using the two algorithms in the simulation study 2

	Pólya–Gamma Gibbs algorithm		MH algorit	hm under Case 1	MH algorithm under Case 2		
	Bias	RMSE	Bias	RMSE	Bias	RMSE	
$\overline{a}$	-0.009	0.077	0.103	0.170	0.185	0.219	
$\boldsymbol{b}_{\bullet 1}$	-0.013	0.094	0.089	0.167	0.129	0.178	
$\boldsymbol{b}_{\bullet 2}$	-0.012	0.077	0.027	0.094	0.027	0.070	
$oldsymbol{b_{ullet 3}}$	0.000	0.083	-0.047	0.089	-0.061	0.094	
$\boldsymbol{b_{\bullet 4}}$	0.011	0.104	-0.123	0.176	-0.173	0.214	
$oldsymbol{ heta}$	0.004	0.192	-0.016	0.254	-0.016	0.225	
. 1 1	D.	I DMOD I I	D: 1 D I	TOTAL C 11 11		, 11 11 1	

Note that the Bias and RMSE denote the average Bias and RMSE for the item parameters.  $\boldsymbol{a}$  represents all discrimination parameters,  $\boldsymbol{b}_{\bullet 1}$  represents all  $b_{j1}$   $(j=1,\ldots,40)$ ,  $\boldsymbol{b}_{\bullet 2}$  represents all  $b_{j2}$   $(j=1,\ldots,40)$ ,  $\boldsymbol{b}_{\bullet 3}$  represents all  $b_{j3}$   $(j=1,\ldots,40)$ ,  $\boldsymbol{b}_{\bullet 4}$  represents all  $b_{j4}$   $(j=1,\ldots,40)$ , and  $\boldsymbol{\theta}$  represents all ability parameters.

has been shown that the selection of the proposal distribution has an important influence on the accuracy of parameter estimation, and the process of finding the proper tuning parameter is time consuming. In addition, we investigate the efficiency of the two algorithms from the perspective of the time consumed in implementing them. On a desktop computer (Intel(R) Xeon(R) E5-2695 V2 CPU) with a 2.4-GHz dual-core processor and 192 GB of RAM memory, the Pólya–Gamma Gibbs sampling algorithm and MH algorithm respectively consumed 3.8573 hours and 4.7456 hours when MCMC was run for 20 000 iterations for a replication

experiment, where the MH algorithm was used to implement Case 1. In summary, the Pólya–Gamma Gibbs sampling algorithm is more effective than the MH algorithm in estimating model parameters.

#### 5. EMPIRICAL EXAMPLE

To illustrate the applicability of the GRM in psychological assessment, we analyzed data from the Sexual Compulsivity Scale (SCS). Item response data were obtained from the Open Source Psychometrics Project (https://openpsychometrics.org), with the respondents constituting

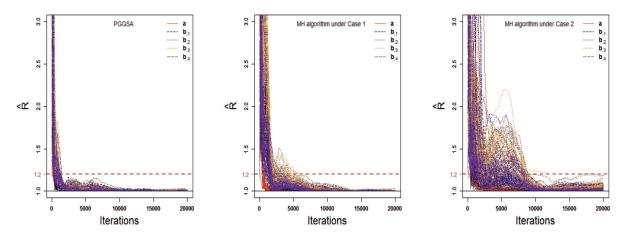


Figure 1. The trace plots of PSRF values for the simulation study 2.

	· · · ·
Item	Question
1	My sexual appetite has gotten in the way of my relationships
2	My sexual thoughts and behaviors are causing problems in my life
3	My desires to have sex have disrupted my daily life
4	I sometimes fail to meet my commitments and responsibilities because of my sexual behaviors
5	I sometimes get so horny I could lose control
6	I find myself thinking about sex while at work
7	I feel that sexual thoughts and feelings are stronger than I am
8	I have to struggle to control my sexual thoughts and behavior
9	I think about sex more than I would like to
10	It has been difficult for me to find sex partners who desire having sex as much as I want to

Table 6. The sexual compulsivity scale items

a self-selected sample who had agreed to their responses being stored and made publicly available. All test items can be viewed on the aforementioned website, and the questions for all the test items are given in Table 6. The Sexual Compulsivity Scale [22] includes 10 items and was administered to N=3243 respondents (with median age 33 and 55% male). All items were presented based on a four-point Likert-type response scale, with options 1 ('Not at all like me'), 2 ('Slightly like me'), 3 ('Mainly like me'), and 4 ('Very much like me').

In the Bayesian computation, we used 20000 MCMC samples after a burn-in of 10000 iterations to compute all posterior estimates. The convergence of the chains was checked by PSRF, and we found that the PSRF values of all item parameters were less than 1.2.

#### Analysis of item parameters

The estimates of the item parameters are given in Table 7, from which we find that the expected a posteriori (EAP) estimations of the six item discrimination parameters are less than 2. This indicates that these items perform poorly at distinguishing among abilities compared with the other four items. The five items with the highest discrimination are items 8, 3, 7, 2, and 5 in turn. The EAP estimations of discrimination parameters for the five items are 2.714,

2.509, 2.379, 1.682, and 1.779, respectively. In addition, the EAP estimations of the threshold parameters  $(b_{j1}, b_{j2}, b_{j3})$  are greatest for items 4, 7, and 2 in turn, which indicates that these items pose more difficulty than do the other seven items. This means that most respondents chose the first option ('Not at all like me') for these three items. By contrast, based on the EAP estimations of the threshold parameters, we find that most respondents chose the fourth option ('Very much like me') for items 6, 10, and 9. The SD range is 0.005–0.009 for the discrimination parameters and 0.000–0.005 for the threshold parameters.

#### Analysis of person parameters

The frequency histograms of the response scores and the posterior estimates of ability parameters for the 3243 respondents are shown in Figure 2. Most of the estimates of the ability parameters are near zero, and there are slightly fewer examinees with high ability (estimates between 0 and 2) than those with low ability (estimates between -2 and 0). The histogram of the EAPs of ability parameters is consistent with the frequency histogram of response scores, i.e., there are slightly more examinees with low response scores than those with high ones. Once again, it is verified that the estimation results are accurate.

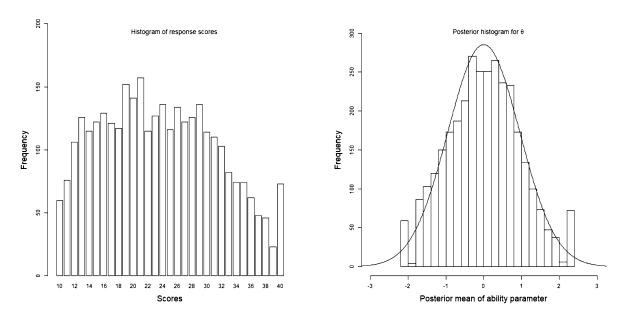


Figure 2. The frequency histograms of the response scores and the posterior estimates of ability parameters for 3243 respondents.

Table 7. The results of item parameter estimation in empirical example analysis

			<u> </u>		•	-	
Parameter	EAP	SD	HPDI	Parameter	EAP	SD	HPDI
$a_1$	1.682	0.005	[1.539, 1.824]	$b_{1,1}$	-1.303	0.001	[-1.379, -1.204]
$a_2$	2.231	0.007	[2.060, 2.410]	$b_{2,1}$	-1.162	0.002	[-1.225, -1.073]
$a_3$	2.509	0.009	[2.320, 2.700]	$b_{3,1}$	-1.386	0.002	[-1.470, -1.298]
$a_4$	1.779	0.006	[1.620, 1.936]	$b_{4,1}$	-0.370	0.000	[-0.420, -0.306]
$a_5$	1.903	0.007	[1.745, 2.070]	$b_{5,1}$	-1.309	0.001	[-1.391, -1.223]
$a_6$	1.308	0.005	[1.177, 1.448]	$b_{6,1}$	-2.983	0.000	[-2.999, -2.953]
$a_7$	2.379	0.007	[2.219, 2.549]	$b_{7,1}$	-1.092	0.001	[-1.169, -1.022]
$a_8$	2.714	0.008	[2.535, 2.888]	$b_{8,1}$	-1.368	0.002	[-1.464, -1.267]
$a_9$	1.546	0.006	[1.398, 1.696]	$b_{9,1}$	-1.520	0.002	[-1.610, -1.425]
$a_{10}$	1.147	0.005	[1.011, 1.280]	$b_{10,1}$	-1.744	0.001	[-1.858, -1.638]
Parameter	EAP	SD	HPDI	Parameter	EAP	SD	HPDI
$b_{1,2}$	0.531	0.002	[0.445, 0.606]	$b_{1,3}$	2.021	0.002	[1.943, 2.162]
$b_{2,2}$	0.896	0.001	[0.865, 1.009]	$b_{2,3}$	2.851	0.004	[2.718, 2.953]
$b_{3,2}$	0.851	0.001	[0.784, 1.000]	$b_{3,3}$	2.769	0.005	[2.656, 2.932]
$b_{4,2}$	1.456	0.002	[1.392, 1.570]	$b_{4,3}$	2.919	0.003	[2.845, 2.999]
$b_{5,2}$	0.773	0.001	[0.699, 0.841]	$b_{5,3}$	2.209	0.004	[2.101, 2.359]
$b_{6,2}$	-1.175	0.001	[-1.252, -1.094]	$b_{6,3}$	0.301	0.001	[0.224, 0.376]
$b_{7,2}$	0.938	0.003	[0.802, 0.924]	$b_{7,3}$	2.888	0.002	[2.790, 2.999]
$b_{8,2}$	0.694	0.003	[0.612, 0.819]	$b_{8,3}$	2.664	0.003	[2.554, 2.821]
$b_{9,2}$	0.045	0.001	[-0.021, 0.130]	$b_{9,3}$	1.451	0.002	[1.365, 1.534]
$b_{10,2}$	-0.051	0.000	[-0.107, -0.005]	$b_{10,3}$	1.050	0.001	[0.985, 1.134]

Note: EAP is the expected a posteriori estimation, SD denotes the standard deviation, and HPDI denotes the 95% highest probability density interval.

## 6. CONCLUDING REMARKS

In this study, a novel and effective Pólya–Gamma Gibbs sampling algorithm based on auxiliary variables was used to estimate the parameters of the GRM. The Bayesian algorithm avoids the tedious multidimensional integral operation of marginal maximum likelihood estimation. Within

a fully Bayesian framework, compared with the traditional Gibbs sampling algorithm and the MH sampling algorithm, the Pólya–Gamma Gibbs sampling algorithm (i) avoids the problem that the MH sampling algorithm relies heavily on the tuning parameters of the proposal distribution for different data sets and (ii) overcomes the disadvantage of the MH algorithm being sensitive to step size. It

is known that the Gibbs sampling algorithm becomes ineffective for Bayesian non-conjugate models. By comparison, the Pólya–Gamma Gibbs sampling algorithm transforms a non-conjugate model into a conjugate one by using augmented auxiliary variables. With the help of the traditional Gibbs sampling algorithm, posterior sampling is easier to implement. Moreover, the Pólya–Gamma Gibbs sampling algorithm allows the use of informative and non-informative prior distributions, with satisfactory results being obtained even if an inappropriate prior distribution is used.

However, the computational burden of the Pólya–Gamma Gibbs sampling algorithm can be great, especially if many examinees, items, or missing data are considered or a large MCMC sample size is used. Therefore, would be desirable to develop a stand alone R package associated with C++ or Fortran software for a more-extensive large-scale assessment program.

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